

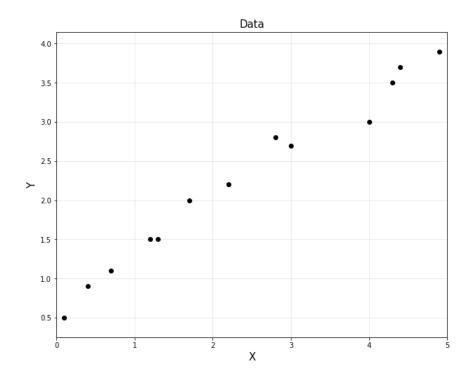
Regression

Prof. Seungchul Lee Industrial AI Lab.



Assumption: Linear Model

$$\hat{y}_i = f(x_i; \theta)$$
 in general



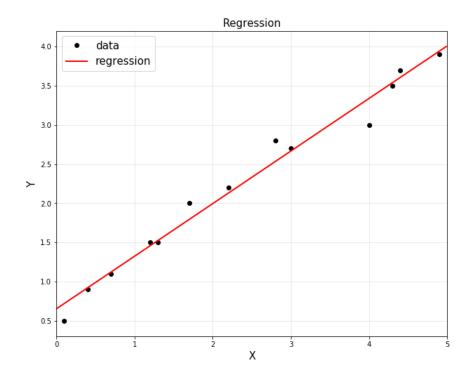
• In many cases, a linear model is used to predict y_i

$$\hat{y}_i = heta_1 x_i + heta_2$$



Assumption: Linear Model

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 in general



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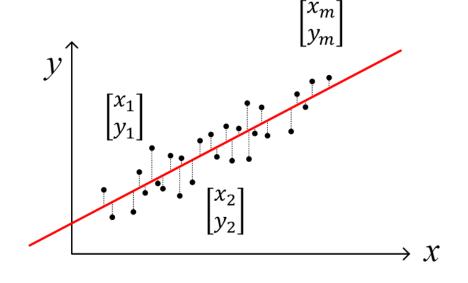


Linear Regression

- $\hat{y}_i = f(x_i, \theta)$ in general
- In many cases, a linear model is assumed to predict y_i

Given
$$\left\{egin{array}{l} x_i: ext{inputs} \ y_i: ext{outputs} \end{array}
ight.$$
 , Find $heta_0$ and $heta_1$

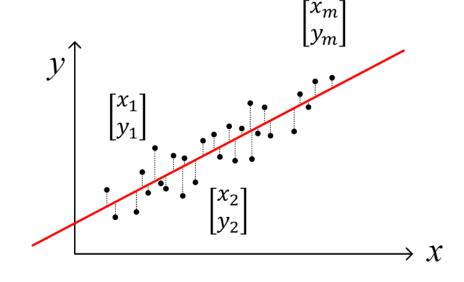
$$x = egin{bmatrix} x_1 \ x_2 \ dots \ x_m \end{bmatrix}, \qquad y = egin{bmatrix} y_1 \ y_2 \ dots \ y_m \end{bmatrix} pprox \hat{y}_i = heta_0 + heta_1 x_i$$



- \hat{y}_i : predicted output
- $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$: model parameters

Linear Regression as Optimization

$$x = egin{bmatrix} x_1 \ x_2 \ dots \ x_m \end{bmatrix}, \qquad y = egin{bmatrix} y_1 \ y_2 \ dots \ y_m \end{bmatrix} pprox \hat{y}_i = heta_0 + heta_1 x_i \ y_1 \ y_1 \end{pmatrix}$$



- How to find model parameters $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$
- Optimization problem

$$\hat{y}_i = heta_0 + heta_1 x_i \quad ext{ such that } \quad \min_{ heta_0, heta_1} \sum_{i=1}^m (\hat{y}_i - y_i)^2$$

Re-cast Problem as Least Squares

• For convenience, we define a function that maps inputs to feature vectors, ϕ

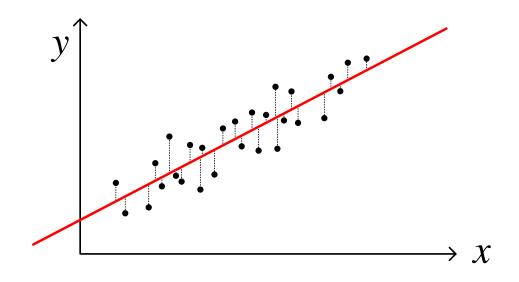
$$\begin{split} \hat{y}_i &= \theta_0 + x_i \theta_1 = 1 \cdot \theta_0 + x_i \theta_1 \\ &= \begin{bmatrix} 1 & x_i \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} \\ &= \begin{bmatrix} 1 \\ x_i \end{bmatrix}^T \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} \\ &= \phi^T(x_i) \theta \end{split}$$
 feature vector $\phi(x_i) = \begin{bmatrix} 1 \\ x_i \end{bmatrix}$

$$\Phi = egin{bmatrix} 1 & x_1 \ 1 & x_2 \ dots & 1 \ 1 & x_m \end{bmatrix} = egin{bmatrix} \phi^T(x_1) \ \phi^T(x_2) \ dots \ \phi^T(x_m) \end{bmatrix} \quad \Longrightarrow \quad \hat{y} = egin{bmatrix} \hat{y}_1 \ \hat{y}_2 \ dots \ \hat{y}_m \end{bmatrix} = \Phi heta$$

Optimization

$$\min_{ heta_0, heta_1} \sum_{i=1}^m (\hat{y}_i - y_i)^2 = \min_{ heta} \lVert \Phi heta - y
Vert_2^2 \qquad \qquad \left(ext{same as } \min_{x} \lVert Ax - b
Vert_2^2
ight)$$

solution
$$\theta^* = (\Phi^T \Phi)^{-1} \Phi^T y$$



Solve using Gradient Descent

$$f = (A heta - y)^T(A heta - y) = (heta^TA^T - y^T)(A heta - y) \ = heta^TA^TA heta - heta^TA^Ty - y^TA heta + y^Ty$$

$$\min_{ heta} \ \|\hat{y}-y\|_2^2 = \min_{ heta} \ \|A heta-y\|_2^2$$

$$abla f = A^TA heta + A^TA heta - A^Ty - A^Ty = 2(A^TA heta - A^Ty)$$

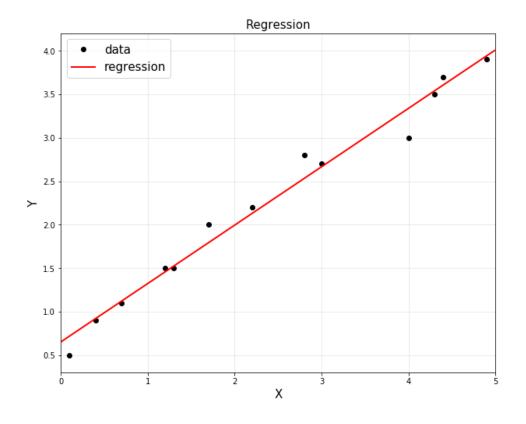
$$\theta \leftarrow \theta - \alpha \nabla f$$

```
theta = np.random.randn(2,1)
theta = np.asmatrix(theta)

alpha = 0.001

for _ in range(1000):
    df = 2*(A.T*A*theta - A.T*y)
    theta = theta - alpha*df

print (theta)
```





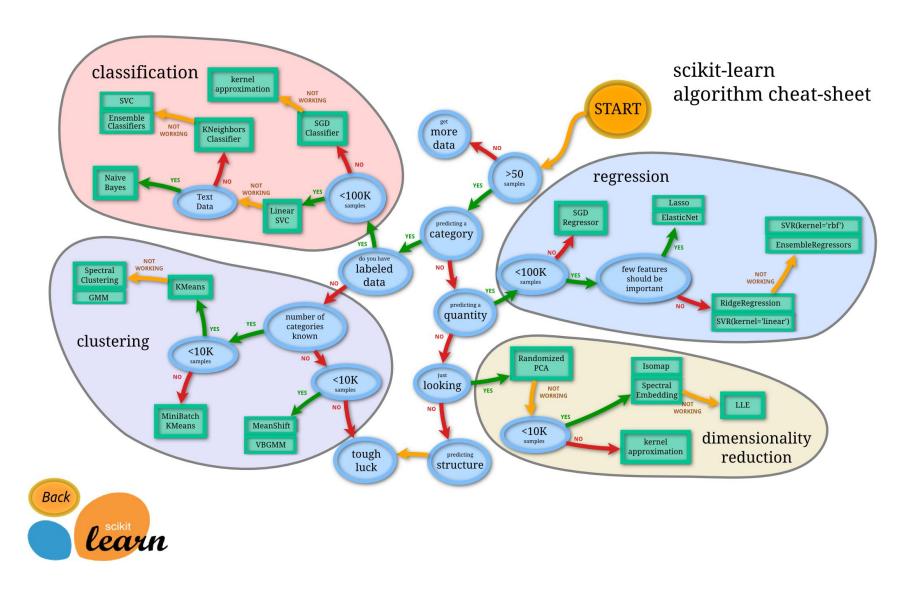
Scikit-Learn

- Machine Learning in Python
- Simple and efficient tools for data mining and data analysis
- Accessible to everybody, and reusable in various contexts
- Built on NumPy, SciPy, and matplotlib
- Open source, commercially usable BSD license
- https://scikit-learn.org/stable/index.html#





Scikit-Learn





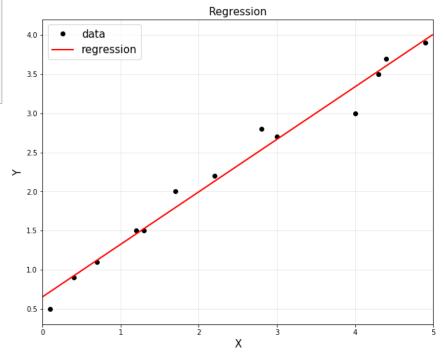
Scikit-Learn: Regression



Scikit-Learn: Regression

```
# to plot
plt.figure(figsize=(10, 8))
plt.title('Regression', fontsize=15)
plt.xlabel('X', fontsize=15)
plt.ylabel('Y', fontsize=15)
plt.plot(x, y, 'ko', label="data")

# to plot a straight line (fitted line)
plt.plot(xp, reg.predict(xp), 'r', linewidth=2, label="regression")
plt.legend(fontsize=15)
plt.axis('equal')
plt.grid(alpha=0.3)
plt.xlim([0, 5])
plt.show()
```





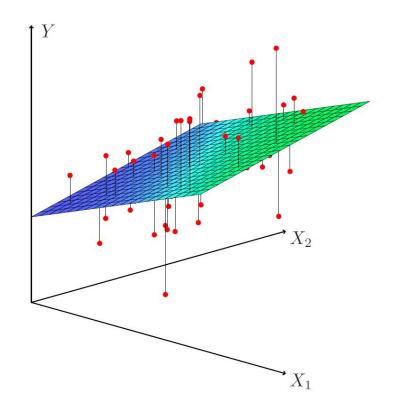
Multivariate Linear Regression

• Linear regression for multivariate data

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2$$

$$\phi\left(x^{(i)}
ight) = egin{bmatrix} 1 \ x_1^{(i)} \ x_2^{(i)} \end{bmatrix} \qquad \Longrightarrow \; heta^* = (\Phi^T\Phi)^{-1}\Phi^T y$$

$$\Phi = egin{bmatrix} 1 & x_1^{(1)} & x_2^{(1)} \ 1 & x_1^{(2)} & x_2^{(2)} \ dots & & & \ dots & & \ 1 & x_1^{(m)} & x_2^{(m)} \ \end{pmatrix} \quad \implies \quad \hat{y} = egin{bmatrix} \hat{y}^{(1)} \ \hat{y}^{(2)} \ dots \ \hat{y}^{(m)} \ \end{bmatrix} = \Phi heta$$



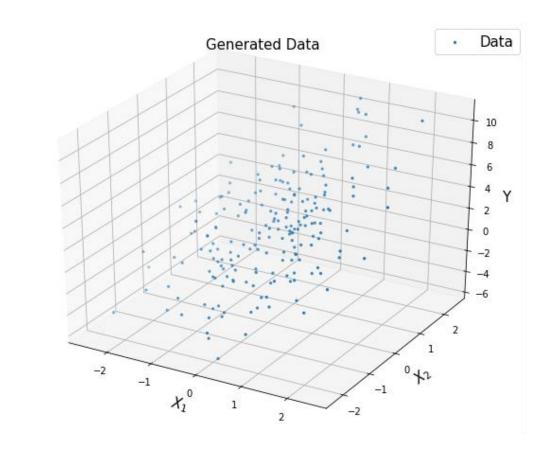
Same in matrix representation

Multivariate Linear Regression

```
# y = theta0 + theta1*x1 + theta2*x2 + noise

n = 200
x1 = np.random.randn(n, 1)
x2 = np.random.randn(n, 1)
noise = 0.5*np.random.randn(n, 1);

y = 2 + 1*x1 + 3*x2 + noise
```

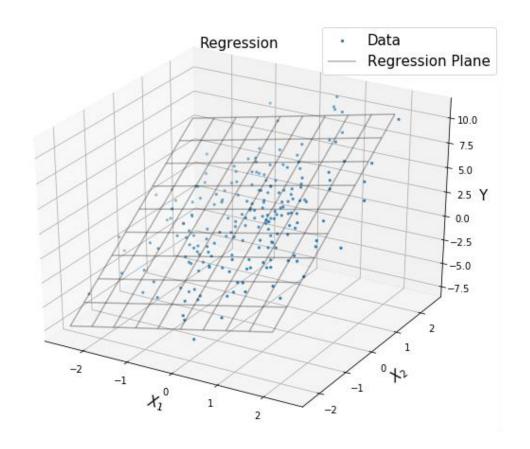




Multivariate Linear Regression

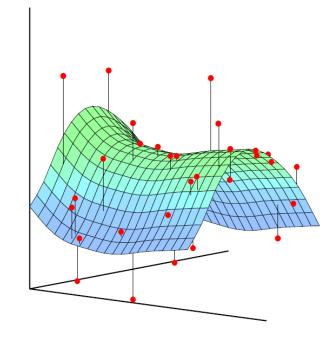
$$\Phi = egin{bmatrix} 1 & x_1^{(1)} & x_2^{(1)} \ 1 & x_1^{(2)} & x_2^{(2)} \ dots & & & \ dots & & \ 1 & x_1^{(m)} & x_2^{(m)} \end{bmatrix} \quad \Longrightarrow \quad \hat{y} = egin{bmatrix} \hat{y}^{(1)} \ \hat{y}^{(2)} \ dots \ \hat{y}^{(m)} \end{bmatrix} = \Phi heta \ \end{pmatrix}$$

$$\implies \theta^* = (\Phi^T \Phi)^{-1} \Phi^T y$$



Nonlinear Regression

• Linear regression for non-linear data



- Same as linear regression, just with non-linear features
- Method 1: constructing explicit feature vectors
 - polynomial features
 - Radial basis function (RBF) features
- Method 2: implicit feature vectors, kernel trick (optional)

Nonlinear Regression

Polynomial (here, quad is used as an example)

$$y = \theta_0 + \theta_1 x + \theta_2 x^2 + \text{noise}$$

$$\phi(x_i) = egin{bmatrix} 1 \ x_i \ x_i^2 \end{bmatrix}$$

$$\Phi = egin{bmatrix} 1 & x_1 & x_1^2 \ 1 & x_2 & x_2^2 \ dots & \ 1 & x_m & x_m^2 \end{bmatrix} \quad \Longrightarrow \quad \hat{y} = egin{bmatrix} \hat{y}_1 \ \hat{y}_2 \ dots \ \hat{y}_m \end{bmatrix} = \Phi heta$$

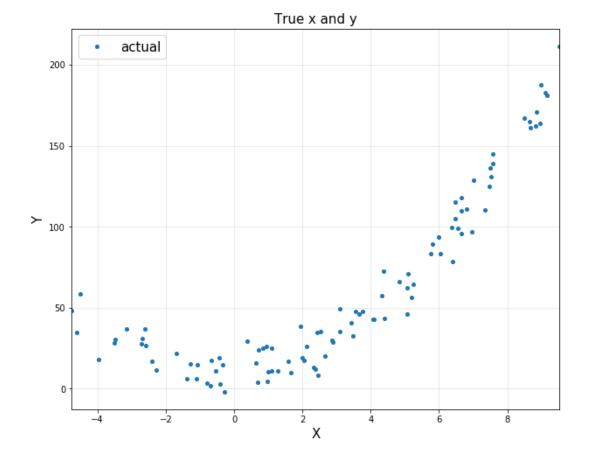
$$\implies \theta^* = (\Phi^T \Phi)^{-1} \Phi^T y$$

Polynomial Regression

```
# y = theta0 + theta1*x + theta2*x^2 + noise

n = 100
x = -5 + 15*np.random.rand(n, 1)
noise = 10*np.random.randn(n, 1)

y = 10 + 1*x + 2*x**2 + noise
```



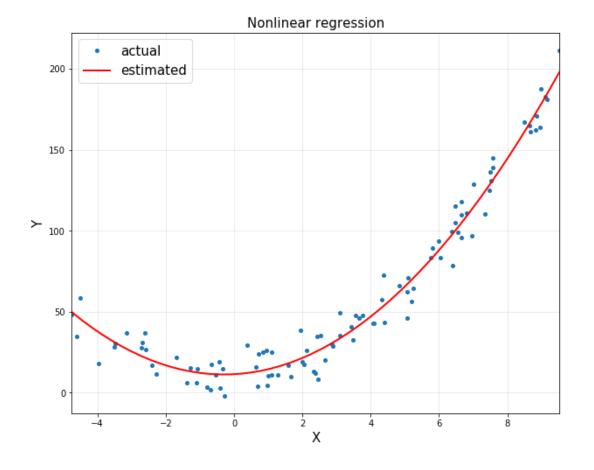


Polynomial Regression

$$heta = (A^TA)^{-1}A^Ty$$

```
A = np.hstack([x**0, x, x**2])
A = np.asmatrix(A)

theta = (A.T*A).I*A.T*y
print('theta:\n', theta)
```





Summary: Linear Regression

- Though linear regression may seem limited, it is very powerful, since the input features can themselves include non-linear features of data
- Linear regression on non-linear features of data
- For least-squares loss, optimal parameters still are

$$\theta^* = (\Phi^T \Phi)^{-1} \Phi^T y$$

Overfitting



Overfitting: Start with Linear Regression

```
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
# 10 data points
n = 10
x = np.linspace(-4.5, 4.5, 10).reshape(-1, 1)
y = np.array([0.9819, 0.7973, 1.9737, 0.1838, 1.3180, -0.8361, -0.6591, -2.4701, -2.8122, -6.2512]).reshape(-1, 1)
plt.figure(figsize=(10, 8))
plt.plot(x, y, 'o', label = 'Data')
                                                                          Linear Regression
plt.xlabel('X', fontsize = 15)
                                                                                                     Data
plt.ylabel('Y', fontsize = 15)
                                                                                                     Linear
plt.grid(alpha = 0.3)
plt.show()
A = np.hstack([x**0, x])
A = np.asmatrix(A)
                                                  ≻ -2
theta = (A.T*A).I*A.T*y
print(theta)
[[-0.7774
[-0.71070424]]
```



Recap: Nonlinear Regression

Polynomial (here, quad is used as an example)

$$y = \theta_0 + \theta_1 x + \theta_2 x^2 + \text{noise}$$

$$\phi(x_i) = egin{bmatrix} 1 \ x_i \ x_i^2 \end{bmatrix}$$

$$\Phi = egin{bmatrix} 1 & x_1 & x_1^2 \ 1 & x_2 & x_2^2 \ dots & \ 1 & x_m & x_m^2 \end{bmatrix} \quad \Longrightarrow \quad \hat{y} = egin{bmatrix} \hat{y}_1 \ \hat{y}_2 \ dots \ \hat{y}_m \end{bmatrix} = \Phi heta$$

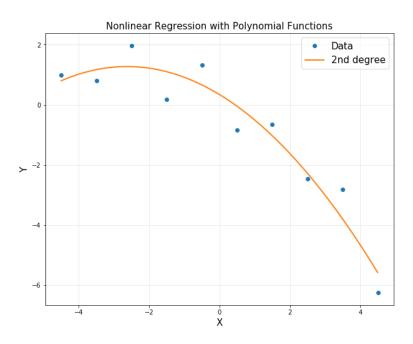
$$\implies \theta^* = (\Phi^T \Phi)^{-1} \Phi^T y$$

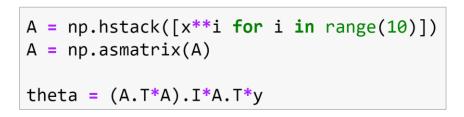
Nonlinear Regression

```
A = np.hstack([x**0, x, x**2])
A = np.asmatrix(A)

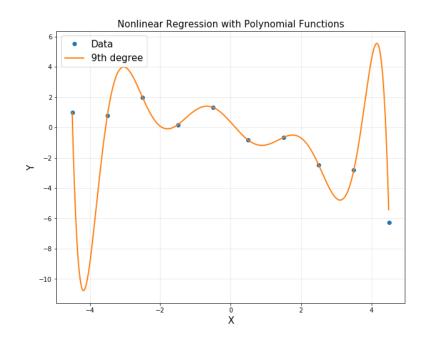
theta = (A.T*A).I*A.T*y
print(theta)
```

```
[[ 0.33669062]
[-0.71070424]
[-0.13504129]]
```





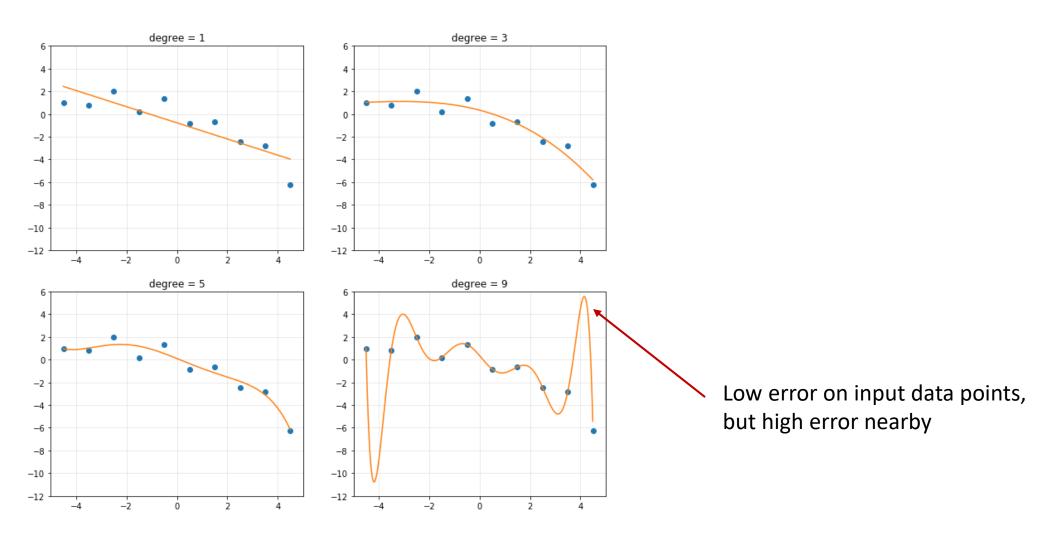
10 input points with degree 9 (or 10)





Polynomial Fitting with Different Degrees

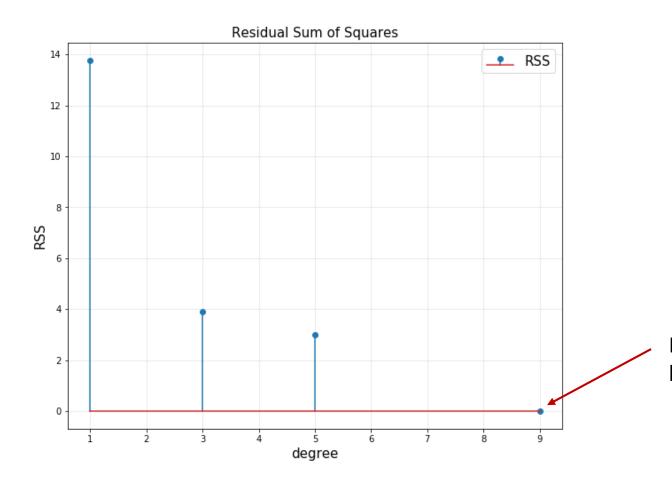






Loss

• Loss: Residual Sum of Squares (RSS)



$$\min_{ heta} \ \|\hat{y} - y\|_2^2$$

Minimizing loss in training data is often not the best



Low error on input data points, but high error nearby

Issue with Rich Representation

- Low error on input data points, but high error nearby
- Low error on training data, but high error on testing data

