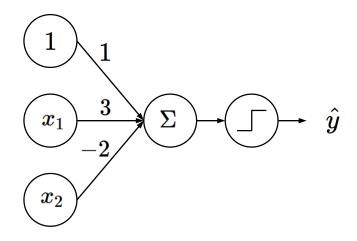


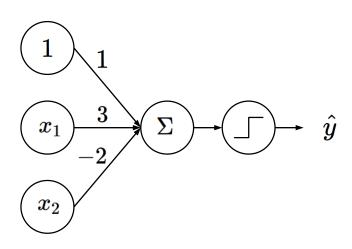
# (Artificial) Neural Networks: From Perceptron to MLP

Prof. Seungchul Lee Industrial AI Lab.

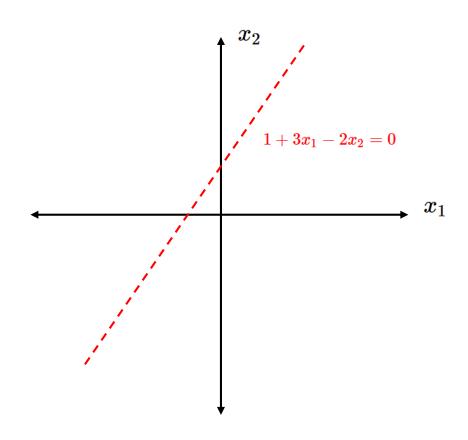


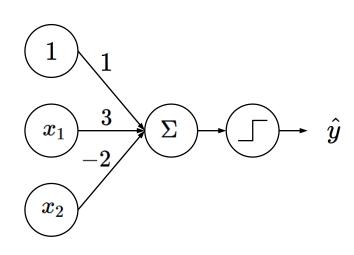


$$egin{aligned} \hat{y} &= g\left(\omega_0 + X^T\omega
ight) \ &= g\left(1 + egin{bmatrix} x_1 \ x_2 \end{bmatrix}^T egin{bmatrix} 3 \ -2 \end{bmatrix}
ight) \ &= g\left(1 + 3x_1 - 2x_2
ight) \end{aligned}$$



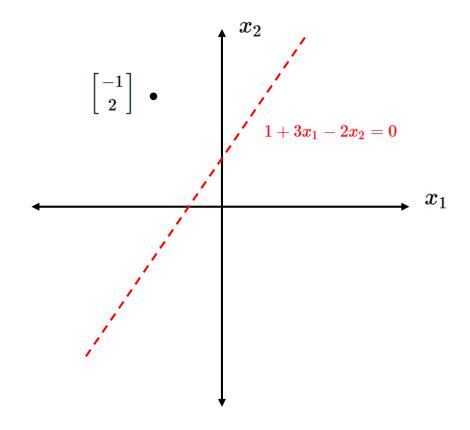
$$\hat{y}=g\left(1+3x_{1}-2x_{2}
ight)$$

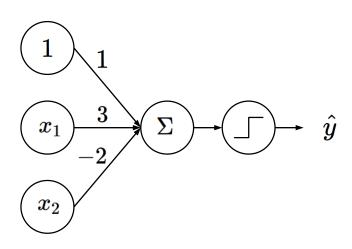




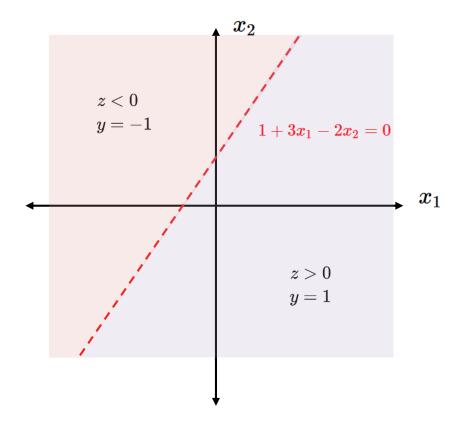
$$\hat{y} = g \, (1 + 3 imes (-1) - 2 imes 2) = g (-6) = -1$$

$$\hat{y}=g\left(1+3x_{1}-2x_{2}
ight)$$

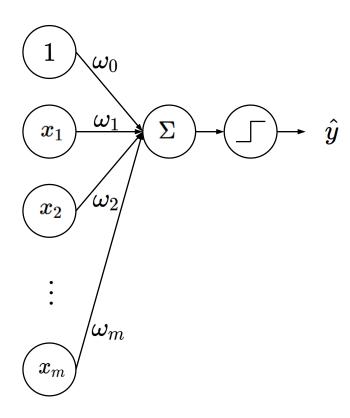




$$\hat{y}=g\left(1+3x_{1}-2x_{2}
ight)$$



# **Perceptron: Forward Propagation**



$$\hat{y} = g\left(\omega_0 + X^T\omega
ight)$$

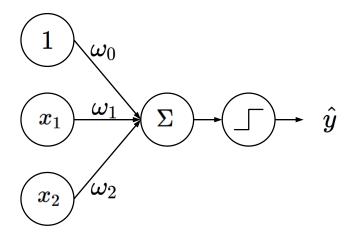
$$f = g \left( \omega_0 + \left[egin{array}{c} x_1 \ dots \ x_m \end{array}
ight]^T \left[egin{array}{c} \omega_1 \ dots \ \omega_m \end{array}
ight] 
ight).$$

# From Perceptron to MLP



# **Artificial Neural Networks: Perceptron**

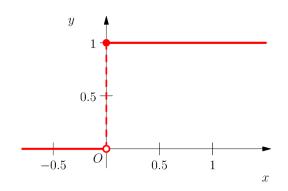
- Perceptron for  $h(\theta)$  or  $h(\omega)$ 
  - Neurons compute the weighted sum of their inputs
  - A neuron is activated or fired when the sum a is positive



- A step function is not differentiable
- One neuron is often not enough
  - One hyperplane

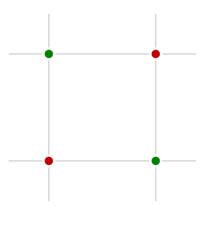
$$a=\omega_0+\omega_1x_1+\omega_2x_2$$

$$\hat{y} = g(a) = egin{cases} 1 & a > 0 \ 0 & ext{otherwise} \end{cases}$$



## **XOR Problem**

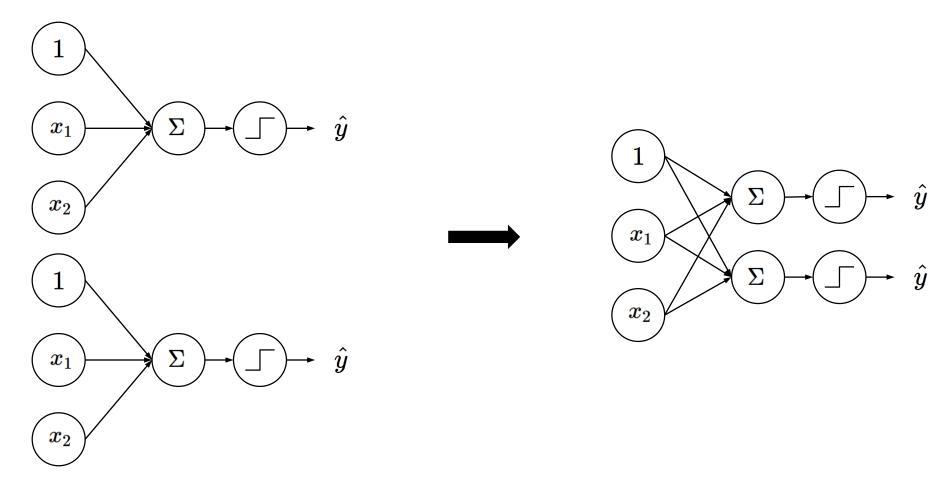
- The main weakness of linear predictors is their lack of capacity.
- For classification, the populations have to be linearly separable.



"xor"

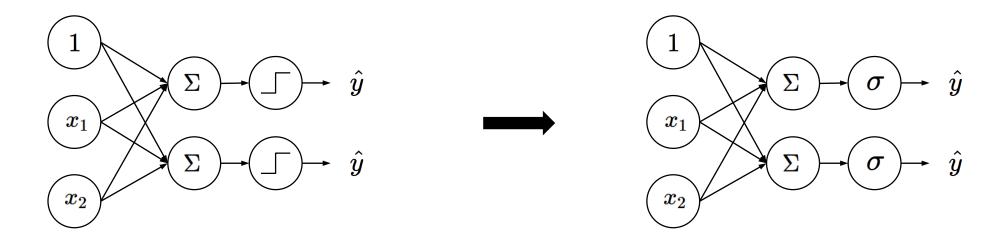
## **Artificial Neural Networks: MLP**

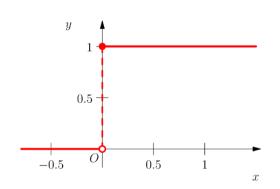
- Multi-layer Perceptron (MLP) = Artificial Neural Networks (ANN)
  - Multi neurons = multiple linear classification boundaries

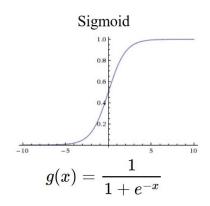


## **Artificial Neural Networks: Activation Function**

• Differentiable nonlinear activation function

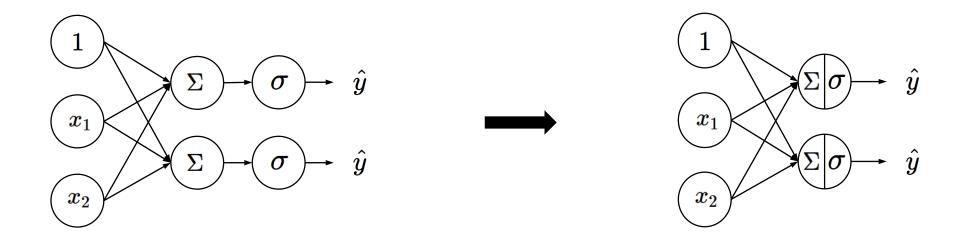






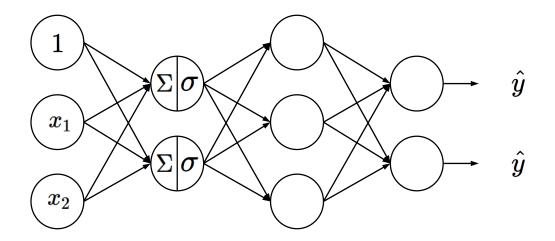
## **Artificial Neural Networks**

• In a compact representation



## **Artificial Neural Networks**

- A single layer is not enough to be able to represent complex relationship between input and output
  - ⇒ perceptron with many layers and units



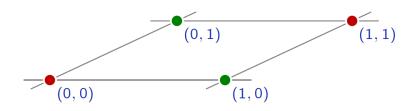
- Multi-layer perceptron
  - Features of features
  - Mapping of mappings

# Another Perspective: ANN as Kernel Learning



# **Nonlinear Mapping**

• The XOR example can be solved by pre-processing the data to make the two populations linearly separable.

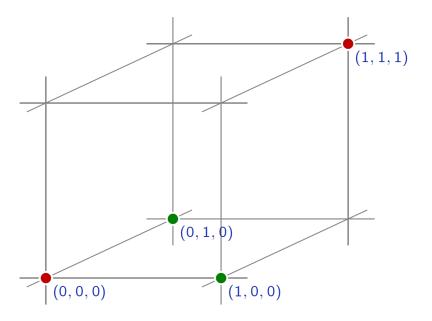




## **Nonlinear Mapping**

• The XOR example can be solved by pre-processing the data to make the two populations linearly separable.

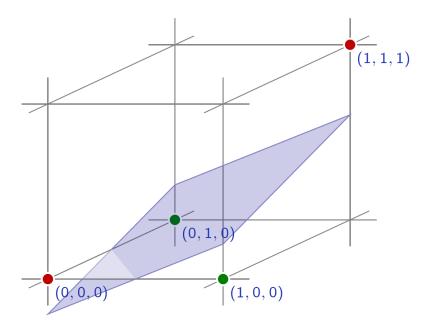
$$\phi:(x_u,x_v) o (x_u,x_v,x_ux_v)$$



## **Nonlinear Mapping**

• The XOR example can be solved by pre-processing the data to make the two populations linearly separable.

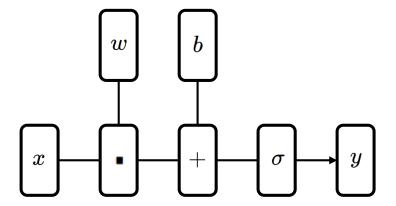
$$\phi:(x_u,x_v) o (x_u,x_v,x_ux_v)$$



### **Neuron**

• We can represent this "neuron" as follows:

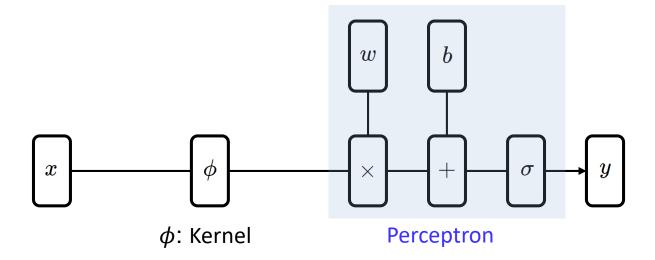
$$f(x) = \sigma(w \cdot x + b)$$



## **Kernel + Neuron**

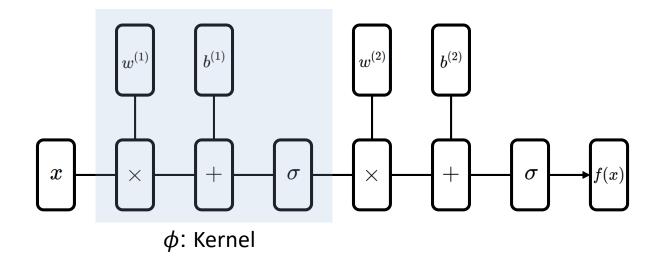
• Nonlinear mapping + neuron

$$\phi:(x_u,x_v) o (x_u,x_v,x_ux_v)$$



## **Neuron + Neuron**

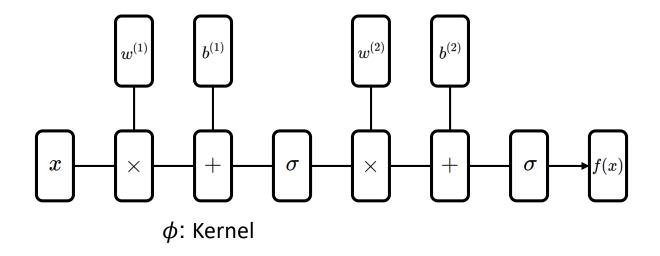
Nonlinear mapping can be represented by another neurons



- Nonlinear Kernel
  - Nonlinear activation functions

# **Multi Layer Perceptron**

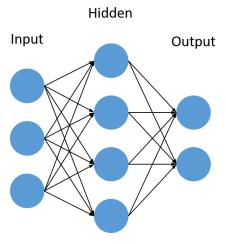
- Nonlinear mapping can be represented by another neurons
- We can generalize an MLP



## **Summary**

- Universal function approximator
- Universal function classifier

Parameterized

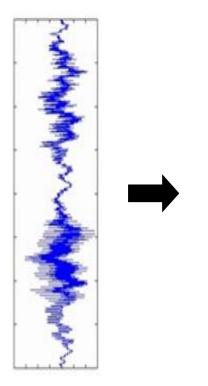


$$\hat{y} = f_{\omega_1, \cdots, \omega_k}(x) \hspace{1cm} \longrightarrow \hspace{1cm} y$$

### **Artificial Neural Networks**

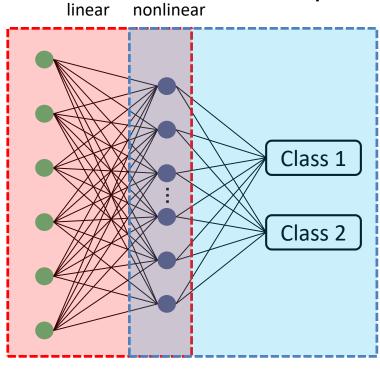
- Complex/Nonlinear universal function approximator
  - Linearly connected networks
  - Simple nonlinear neurons

#### Input









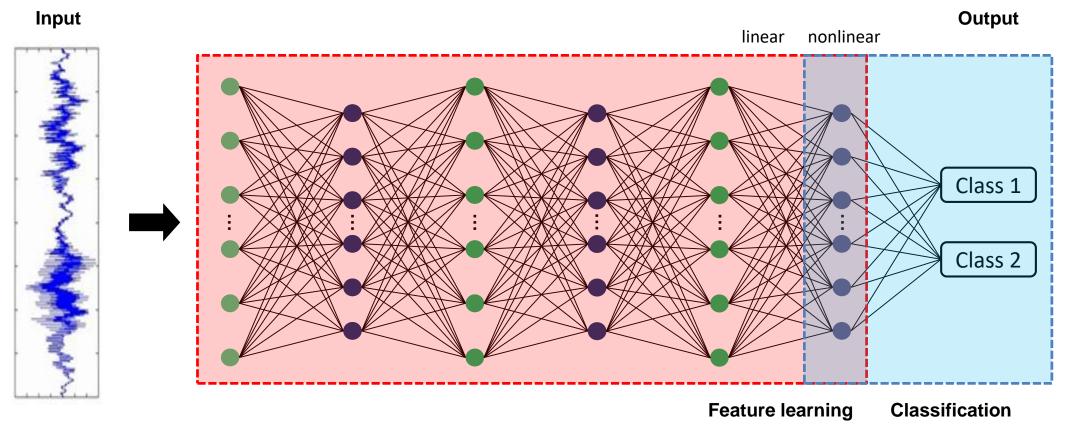
**Feature learning** 

Classification

## **Deep Artificial Neural Networks**

- Complex/Nonlinear universal function approximator
  - Linearly connected networks
  - Simple nonlinear neurons

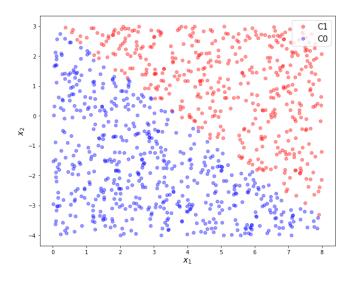




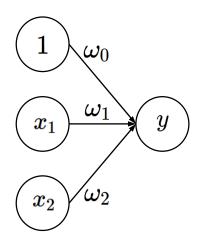
# **Looking at Parameters**

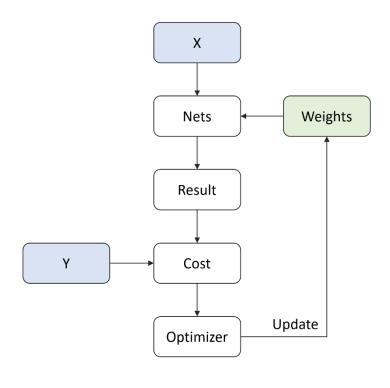


# **Logistic Regression in a Form of Neural Network**



$$y = \sigma \left( \omega_0 + \omega_1 x_1 + \omega_2 x_2 
ight)$$





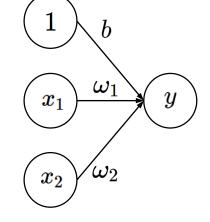


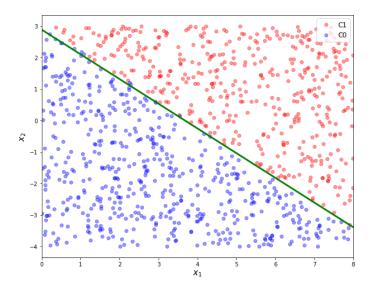
## **Logistic Regression in a Form of Neural Network**

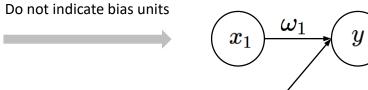
Neural network convention

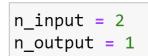
$$y = \sigma \left(\omega_0 + \omega_1 x_1 + \omega_2 x_2\right)$$

$$y=\sigma\left(b+\omega_{1}x_{1}+\omega_{2}x_{2}
ight)$$





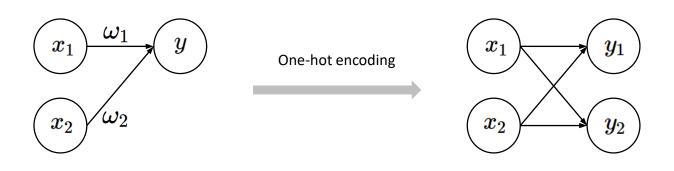


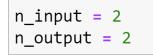


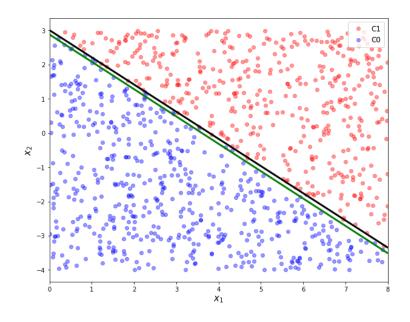
## **Logistic Regression in a Form of Neural Network**

- One-hot encoding
  - One-hot encoding is a conventional practice for a multi-class classification

$$y^{(i)} \in \{1,0\} \quad \implies \quad y^{(i)} \in \{[0,1],[1,0]\}$$

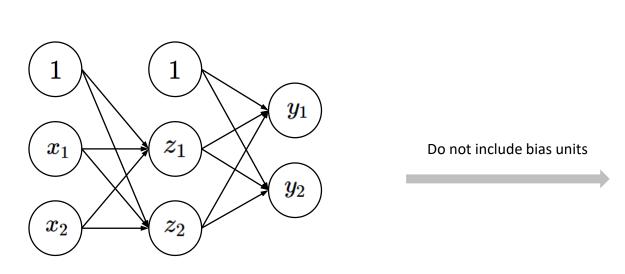


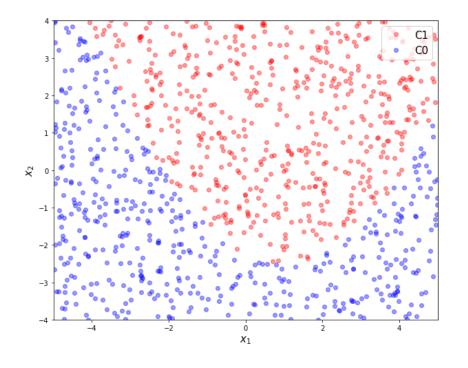


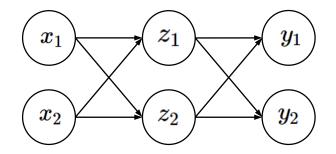


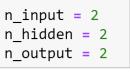
## **Nonlinearly Distributed Data**

- Example to understand network's behavior
  - Include a hidden layer



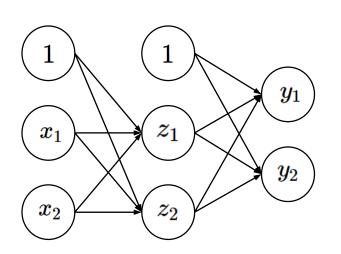




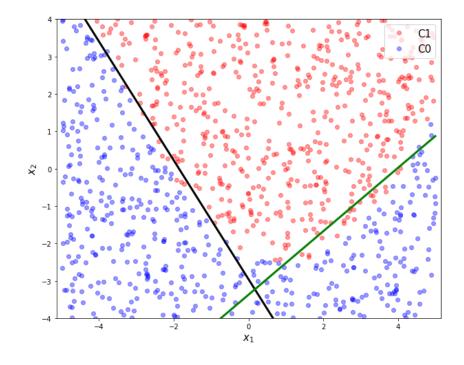


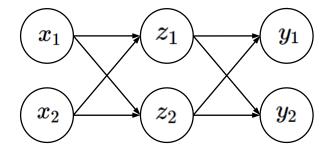
# **Multi Layers**

• x space



Do not include bias units

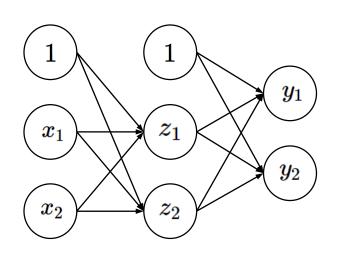




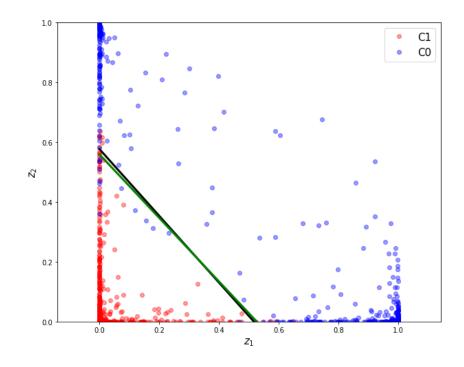
n\_input = 2
n\_hidden = 2
n\_output = 2

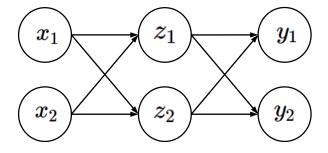
# **Multi Layers**

• z space



Do not include bias units

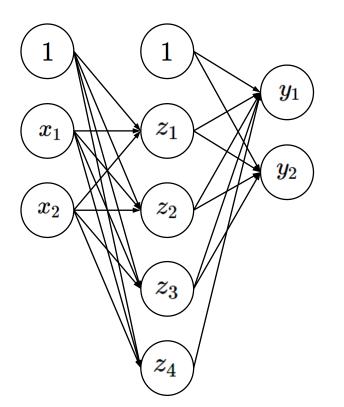




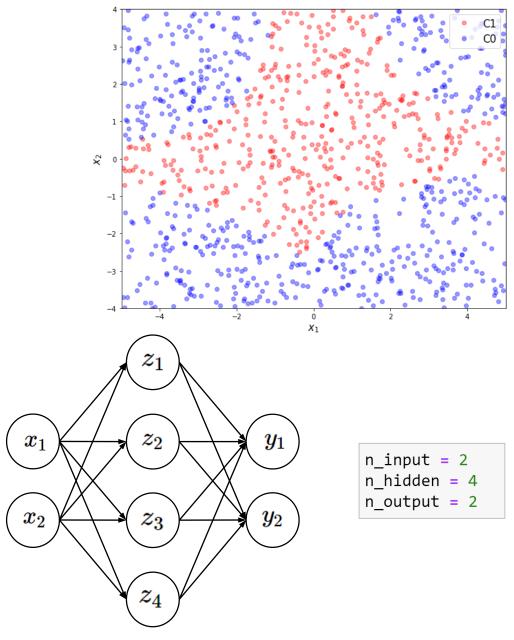
n\_input = 2
n\_hidden = 2
n\_output = 2

## **Nonlinearly Distributed Data**

• More neurons in hidden layer

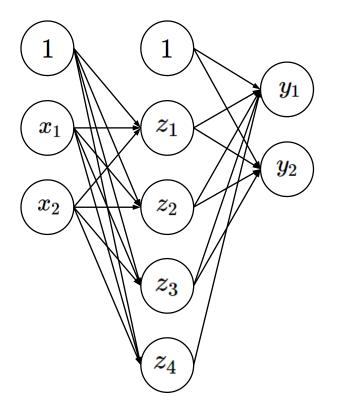


Do not include bias units

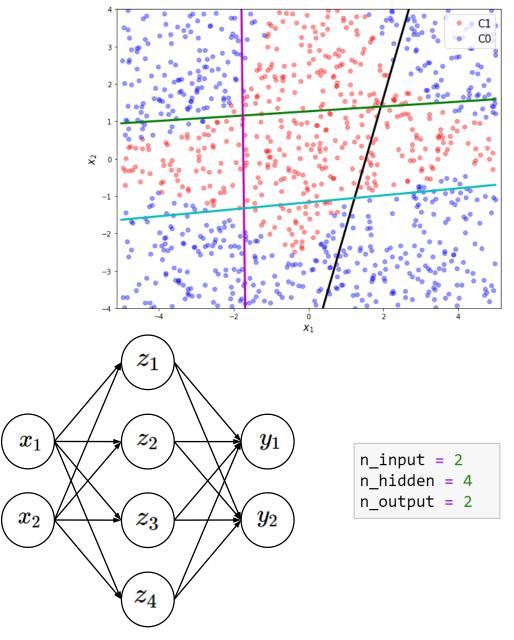


# **Multi Layers**

• Multiple linear classification boundaries



Do not include bias units



# (Artificial) Neural Networks: Training



## **Training Neural Networks: Loss Function**

Measures error between target values and predictions

$$\min_{\omega} \sum_{i=1}^{m} \ell\left(h_{\omega}\left(x^{(i)}
ight), y^{(i)}
ight)$$

- Example
  - Squared loss (for regression):

$$rac{1}{m}\sum_{i=1}^{m}\left(h_{\omega}\left(x^{(i)}
ight)-y^{(i)}
ight)^{2}$$

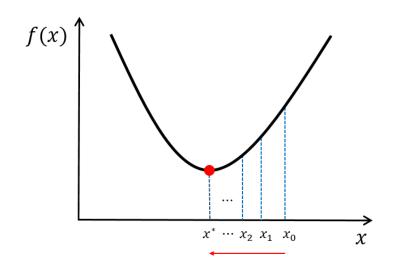
— Cross entropy (for classification):

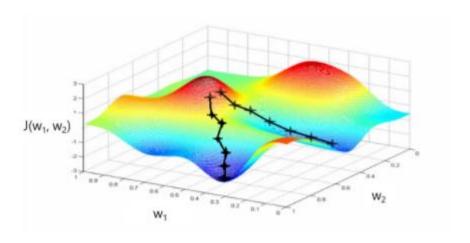
$$-rac{1}{m}\sum_{i=1}^{m}y^{(i)}\log\Bigl(h_{\omega}\left(x^{(i)}
ight)\Bigr)+\Bigl(1-y^{(i)}\Bigr)\log\Bigl(1-h_{\omega}\left(x^{(i)}
ight)\Bigr)$$

## **Training Neural Networks: Gradient Descent**

- Negative gradients points directly downhill of the cost function
- We can decrease the cost by moving in the direction of the negative gradient ( $\alpha$  is a learning rate)

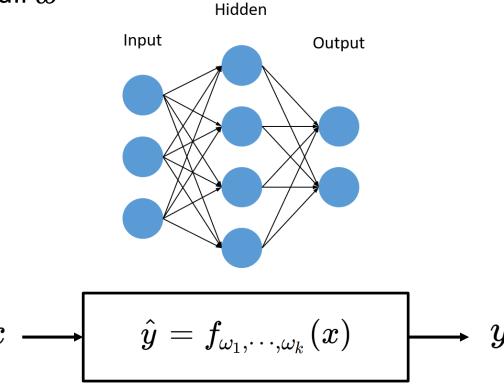
$$\omega \Leftarrow \omega - lpha 
abla_\omega \ell \left( h_\omega \left( x^{(i)} 
ight), y^{(i)} 
ight)$$





### **Gradients in ANN**

- Learning weights and biases from data using gradient descent
- $\frac{\partial \ell}{\partial \omega}$ : too many computations are required for all  $\omega$
- Structural constraint of NN:
  - Composition of functions
  - Chain rule
  - Dynamic programming

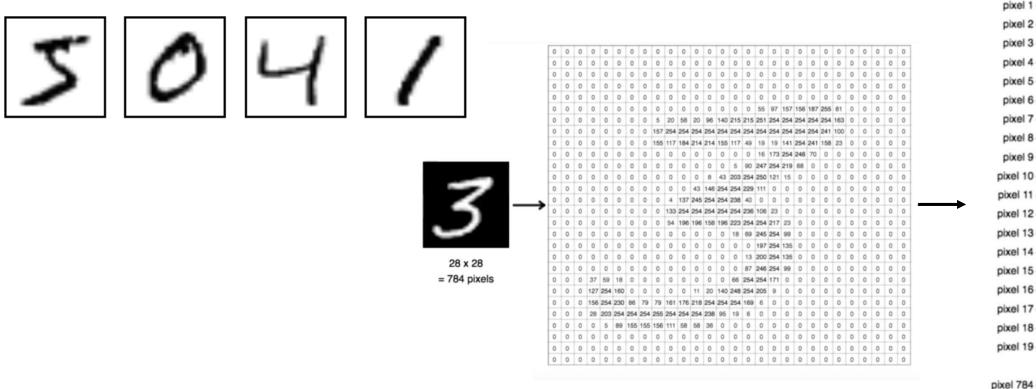


# ANN in TensorFlow: MNIST

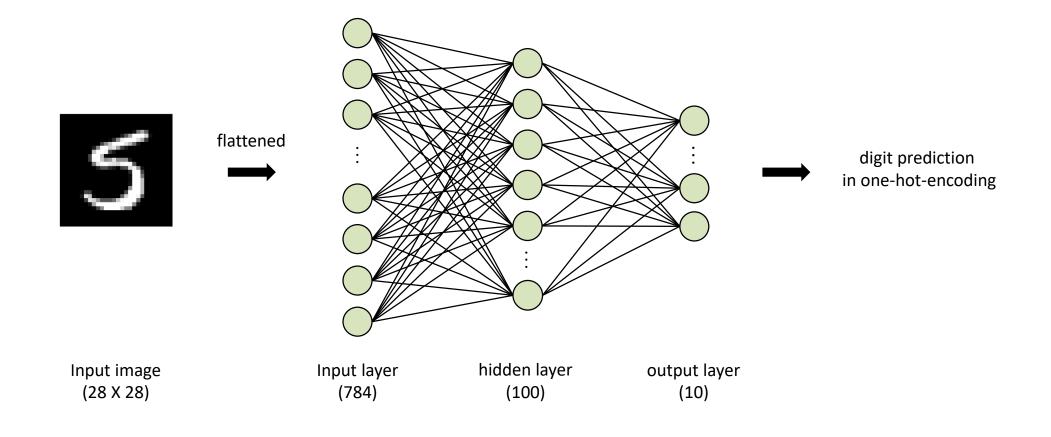


### **MNIST** database

- Mixed National Institute of Standards and Technology database
- Handwritten digit database
- $28 \times 28$  gray scaled image
- Flattened matrix into a vector of  $28 \times 28 = 784$



## **Our Network Model**

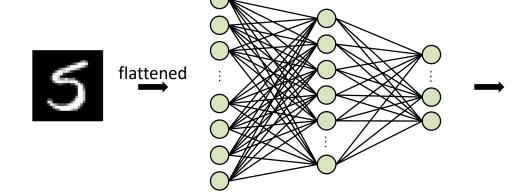




## **Implementation in Python**

```
mnist = tf.keras.datasets.mnist
(train_x, train_y), (test_x, test_y) = mnist.load_data()
train_x, test_x = train_x/255.0, test_x/255.0
```

```
test_loss, test_acc = model.evaluate(test_x, test_y)
```



Input image (28 X 28)

Input layer hidden layer output layer (784) (100) (10)



## **Evaluation**

```
test_img = test_x[np.random.choice(test_x.shape[0], 1)]
predict = model.predict_on_batch(test_img)
mypred = np.argmax(predict, axis = 1)
```



