

# DoPE

## Default Remote Control Handling

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## 1 RMC Default Handling

DoPE provides a standardized handling of buttons and LED's on the DOLI RMC1, RMC5 and RMC7 remote control. Basic functions of the EDC stand-alone operation are simulated:

- • turning the drive ON and OFF
- • positioning of the x-head (Up, Down, Stop)
- • changing control mode (position, load, extension control, open loop)
- • High / Low pressure switching

The DoPE user can emulate the buttons on the RMC via a simple interface. The RMC event handler provides the reactions of the keys by the status of the LED's. The error handling is done via the runtime error event handler.

The RMC event handler reports any changes to the buttons and LED's that are relevant for the RMC default handling. The key state is built by the buttons on the RMC, the IO keys configured in the setup and the keys emulated by software with the DoPERmcSetKeys command.

To turn the drive ON or OFF the DoPEOn DoPEOff function are used. In open loop mode, a control-off sequence (DoPESetCtrl False / True) is used.

Stopping the x-head is done by the DoPESHalt command. In open loop mode, a control-off sequence is applied.

The positioning of the x-head is done with the DoPEFDPoti command. A distinction is made between the DigiPoti speed mode (EXT\_SPEED\_UP EXT\_SPEED\_DOWN) and position mode (EXT\_POS\_UP\_DOWN). The active mode is displayed on the UP and DOWN LED's. In speed mode, the direction of movement is visualized by an active corresponding LED. In position mode, both LED's light up constantly. Since the DPOTI\_CONTROL LED is used by the EDC stand-alone software for viewing the High-Pressure mode, it can't be used for the Position mode.

The UP and DOWN LED's show the transverse movement, even if it was caused by DoPE users directly via a positioning command. The UP and DOWN LED's light up constantly if the frequency of a cycle command exceeds 1 / 4 Hz.

## 1.1 DoPERmcEnable

Enable / disable the remote control default handling for keys and LED's.  
(Sets the PushMode and RmcDPoti settings to the default values defined in the setup RMC definition)

| Function declaration   | Description  |
|--|--|
| extern unsigned DLLAPI<br>DoPE_HANDLE DoPEHdl,<br>unsigned __int64 EnableKeys,<br>unsigned __int64 EnableLeds )  | Function returns Error constant (DoPERR_XXXX)<br>DoPE link handle<br>mask of enabled RMC emulation keys<br>mask of enabled RMC emulation LED's   |
| <b>Supported keys:</b><br><br>DoPE_KEY_CTRL_POS<br>DoPE_KEY_CTRL_LOAD<br>DoPE_KEY_CTRL_EXTENSION<br>DoPE_KEY_HALT<br>DoPE_KEY_UP<br>DoPE_KEY_DOWN<br>DoPE_KEY_UP_FAST<br>DoPE_KEY_DOWN_FAST<br>DoPE_KEY_ON<br>DoPE_KEY_F3<br>DoPE_KEY_OFF<br>DoPE_KEY_F3+DoPE_KEY_DPOTI<br>DoPE_KEY_DPOTI_CONTROL<br>DoPE_KEY_HIGH_PRESSURE<br>DoPE_KEY_LOW_PRESSURE | Activate Position Control (or Open Loop mode)<br>Activate Load Control<br>Activate Extension Control<br>Apply SHalt (or Control Off in Open Loop mode)<br>Move crosshead UP with slow speed<br>Move crosshead DOWN with slow speed<br>Move crosshead UP with fast speed<br>Move crosshead DOWN with slow speed<br>Turn on drive<br>Turn on drive<br>Turn off drive<br>Turn off drive<br>Move crosshead UP/DOWN with DigiPoti in position mode<br>Enable High Pressure mode<br>Enable Low Pressure mode     |
| <b>Supported LED's</b><br><br>DoPE_LED_CTRL_POS<br>DoPE_LED_CTRL_LOAD<br>DoPE_LED_CTRL_EXTENSION<br>DoPE_LED_HALT<br>DoPE_LED_UP<br>DoPE_LED_DOWN<br>DoPE_LED_UP+ DoPE_LED_DOWN<br>DoPE_LED_UP_FAST<br>DoPE_LED_DOWN_FAST<br>DoPE_LED_OFF<br>DoPE_LED_ON<br>DoPE_LED_DPOTI_CONTROL<br>DoPE_LED_HIGH_PRESSURE<br>DoPE_LED_LOW_PRESSURE                | Position Control (or Open Loop mode) active<br>Load Control active<br>Extension Control active<br>Crosshead is halted<br>Crosshead is moving UP with slow or fast speed<br>Crosshead is moving DOWN with slow or fast speed<br>DigiPoti position mode active (or fast cycles)<br>Crosshead is moving UP with fast speed<br>Crosshead is moving DOWN with fast speed<br>Drive is turned off<br>Drive is turned on<br>DigiPoti position mode active<br>High Pressure mode active<br>Low Pressure mode active |

## 1.2 DoPERmcReDefine

Redefine the PushMode and RmcDPoti settings for the remote control default handling.  
After an initialization with DoPESelSetup or DoPEInitialize the PushMode and RmcDPoti settings are copied from the setup. This command redefines the PushMode and RmcDPoti settings.  
(This command must be used if the EDC setup doesn't support RmcDPoti information)

| Function declaration  | Description  |
|---|--|
| extern unsigned DoPERmcReDefin(<br>DoPE_HANDLE DoPEHdl[]<br>WORD PushMode<br>DoPERmcDPoti RmcDPoti[MAX_CTRL]) | Function returns Error constant (DoPERR_XXXX)<br>DoPE link handle array (terminated by NULL).<br>!=0 enables, 0 disables the push mode for Up/Down keys<br>RMC DigiPoti definition |

### 1.3 DoPERmcKeys

Set / reset / toggle keys for the remote control default handling.

The three key patterns will be processed in the following sequence (important with conflicting data):

- 1.) Flashing bits. (lowest priority)
- 2.) Resetting of the bits.
- 3.) Setting of the bits. (highest priority)

| Function declaration  | Description   |
|---|---|
| extern unsigned DoPERmcKeys (<br>DoPE_HANDLE     DoPEHdl[]<br>unsigned __int64   SetKeys<br>unsigned __int64   ResKeys<br>unsigned __int64   ToggleKeys | Function returns Error constant (DoPERR_xxxx)<br>DoPE link handle array (terminated by NULL).<br>RMC emulation keys to set<br>RMC emulation keys to clear<br>RMC emulation keys to toggle |

### 1.4 DoPERmcState

Get keys and LED's state of the remote control default handling.

This command supplies any change of RMC default handler key input and LED output since the last call.

| Function declaration   | Description  |
|--|--|
| extern unsigned DoPERmcState (<br>DoPE_HANDLE     DoPEHdl[]<br>DoPEOnRmcEvent   *pRmcEvent | Function returns Error constant (DoPERR_xxxx)<br>DoPE link handle array (terminated by NULL).<br>Pointer to RMC event structure (refere to OnRmcEvent handler) |

### 1.5 DoPESetOnRmcEventHdlr

The OnRmcEvent Handler supplies any change of RMC default handler key input and LED output.

| Function declaration  | Description  |
|---|--|
| extern unsigned DLLAPI     DoPESetOnRmcEventHdlr<br>DoPE_HANDLE     DoPEHdl<br>DoPEOnRmcEventHdlr   Hdlr<br>LPVOID           lpParameter  | Function returns Error constant (DoPERR_xxxx)<br>DoPE link handle<br>User function to be called after every RMC default handler key and LED changes.<br>User specific pointer. |
| <b>User function for the OnRmcEvent event:</b>  |  |
| unsigned CALLBACK OnRmcEvent<br>DoPE_HANDLE     DoPEHdl<br>DoPEOnRmcEvent   *pRmcEvent<br>LPVOID           lpParameter  | Function should return 0 (reserved for future versions)<br>DoPE link handle<br>Pointer to received RMC event structure<br>User specific pointer set with DoPESetOnRmcEventHdlr |
| typedef struct<br>{<br>unsigned           __int64   Keys<br>unsigned           __int64   NewKeys<br>unsigned           __int64   GoneKeys<br>unsigned           __int64   Leds<br>unsigned           __int64   NewLeds<br>unsigned           __int64   GoneLeds<br>} DoPEOnRmcEvent | Current key state<br>New keys<br>Gone keys<br>Current LED state<br>New LED's<br>Gone LED's   |