Lab Report of Group 1 (Wörner, Velez, Northe)

The source code and the binaries from the spectrum analyzer from this report can be found in our Github repository.

Our used imports

```
import re
import numpy as np
from numpy.typing import NDArray
from pathlib import Path
import matplotlib.pyplot as plt
from scipy.io.matlab import loadmat
from scipy.constants import Boltzmann
from scipy.stats import linregress
```

Some helper functions to keep the evaluation code short

```
k_B = Boltzmann
                    # Boltzman constant
def dbm_to_mw(dbm):
    return 10**(dbm / 10)
def read_mat(file_path: str | Path, dic_name: str) -> tuple[NDArray, NDArray,
NDArray]:
   0.0.0
   Get the Gain, NF and f vector from the signal analyzer matlab file.
    ws = loadmat(file path)
   ws = ws[dic_name]
    gain = ws['gain'][0, 0].flatten()
    noise = ws['noise'][0, 0].flatten()
    f_steps = ws['f'][0, 0].flatten()
    return gain, noise, f_steps
def read spec csv(file path: Path) -> tuple[list, NDArray, NDArray]:
   Reads the CSV from the Spectrum Analyzer and puts the Metadata in a list,
the freq bins and power
   into Numpy Arrays
   # Read the entire CSV file
   with open(file path, 'r') as f:
```

```
content = f.read()
    # Split content into metadata and data sections using regex to find "DATA"
    parts = re.split(r'\bDATA\b', content)
    # Check if "DATA" section was found
    if len(parts) != 2:
        raise ValueError("No DATA section found in the file.")
    metadata section = parts[0].strip() # Everything before DATA
    data_section = parts[1].strip()  # Everything after DATA
    # Parse the metadata section
    metadata = {}
    for line in metadata_section.splitlines():
       if ',' in line:
            key, value = line.split(',', 1)
            metadata[key.strip()] = value.strip()
    # Parse the data section (split by newline, then split by comma)
    data = []
    for line in data_section.splitlines():
       if ',' in line:
           try:
                x, y = map(float, line.split(','))
                data.append([x, y])
            except ValueError:
                print(f"Skipping invalid line: {line}")
    # Convert data into numpy arrays
    data = np.array(data)
    frequencies = data[:, 0] # First column (Frequency)
    values = data[:, 1]
                           # Second column (Values)
    return metadata, frequencies, values
def scientific_2_str(value: float, unit: str = "\Omega") -> str:
    prefixes = [
        (1e9, 'G'),
        (1e6, 'M'),
        (1e3, 'k'),
        (1, ''),
        (1e-3, 'm'),
        (1e-6, '\mu'),
        (1e-9, 'n'),
       (1e-12, 'p')
   ]
```

```
for factor, prefix in prefixes:
        if abs(value) >= factor:
            formatted = value / factor
            return f"{formatted:.3g} {prefix}{unit}"
    return f"{value:.3g} {unit}" # fallback for very small values
def plot_compare(x1: NDArray, y1: NDArray,
                 x2: NDArray, y2: NDArray,
                 title: str,
                 x_label: str="Resistance [0hm]",
                 y_label: str="Frequency [MHz]",
                 x log: bool=False,
                 y log: bool=False,
                 label1: str="Measurement 1",
                 label2: str="Measurement 2",
                 marker1: str='o',
                 marker2: str='s'):
    Plots two datasets (x1, y1) and (x2, y2) on the same plot.
    This function assumes that x1 and x2 are frequency bins and y1 and y2 are
the corresponding power bins.
    # Align the bins to their corresponding measurements
    plt.figure(figsize=(8, 4))
    # Check if data requires log scaling
    if x_log and y_log:
        plt.loglog(x1, y1, marker=marker1, label=label1)
        plt.loglog(x2, y2, marker=marker2, label=label2)
    elif x_log:
        plt.semilogx(x1, y1, marker=marker1, label=label1)
        plt.semilogx(x2, y2, marker=marker2, label=label2)
    elif y_log:
        plt.semilogy(x1, y1, marker=marker1, label=label1)
        plt.semilogy(x2, y2, marker=marker2, label=label2)
    else:
        plt.plot(x1, y1, marker=marker1, label=label1)
        plt.plot(x2, y2, marker=marker2, label=label2)
    plt.title(title)
    plt.xlabel(x_label)
    plt.ylabel(y label)
    plt.grid(True)
    plt.legend()
    plt.tight_layout()
    plt.show()
```

```
def plot(x: NDArray,
             y: NDArray,
             title: str,
             x label: str="Resistance [0hm]",
             y_label: str="Frequency [Hz]",
             x log: bool=False,
             y_log: bool=False,
             marker: str='o'):
    plt.figure(figsize=(8, 4))
    if x_log and y_log:
        plt.loglog(x, y, marker=marker)
    elif x_log:
        plt.semilogx(x, y, marker=marker)
    elif y log:
        plt.semilogy(x, y, marker=marker)
    else:
        plt.plot(x, y, marker=marker)
    plt.title(title)
    plt.xlabel(x_label)
    plt.ylabel(y_label)
    plt.grid(True)
    plt.tight_layout()
    plt.show()
def compute and plot cascade with measured(
    f lna: NDArray, gain lna db: NDArray, nf lna db: NDArray,
    f_att: NDArray, gain_att_db: NDArray, nf_att_db: NDArray,
    f_meas: NDArray, gain_meas_db: NDArray, nf_meas_db: NDArray,
    title: str = "5.4 LNA → 6 dB Attenuator: Measured vs Theoretical",
    x_label: str = "$f$ in $[MHz]$", y_label: str = "$P$ in $[dBm]$"
) -> tuple[NDArray, NDArray]:
    Plots measured and theoretical NF and gain for the cascade LNA \rightarrow
Attenuator.
    from scipy.interpolate import interpld
    def db_to_linear(db): return 10**(db / 10)
    def linear_to_db(lin): return 10 * np.log10(lin)
    # Interpolation base: common range across all three datasets
    f_min = max(f_lna.min(), f_att.min(), f_meas.min())
    f \max = \min(f \ln \max(), f \operatorname{att.max}(), f \operatorname{meas.max}())
    f_common = np.linspace(f_min, f_max, num=300)
```

```
# Interpolate all to common frequency base
   G1 = db_to_linear(interpld(f_lna, gain_lna_db, kind='linear',
fill value='extrapolate')(f common))
    F1 = db_to_linear(interpld(f_lna, nf_lna_db, kind='linear',
fill value='extrapolate')(f common))
    G2 = db_to_linear(interpld(f_att, gain_att_db, kind='linear',
fill value='extrapolate')(f common))
    F2 = db_to_linear(interpld(f_att, nf_att_db, kind='linear',
fill_value='extrapolate')(f_common))
    # Compute theoretical cascade using Friis
    G \text{ total} = G1 * G2
    F_{total} = F1 + (F2 - 1) / G1
    # Convert to dB
    gain_theo_db = linear_to_db(G_total)
    nf_theo_db = linear_to_db(F_total)
    # Interpolate measured cascade to f common
    gain_meas_interp = interpld(f_meas, gain_meas_db, kind='linear',
fill_value='extrapolate')(f_common)
    nf meas interp = interpld(f meas, nf meas db, kind='linear',
fill_value='extrapolate')(f_common)
    # Plot all four curves
    plt.figure(figsize=(9, 4))
    plt.plot(f_common, gain_meas_interp, label="Gain (Measured)",
linestyle='-')
    plt.plot(f common, nf meas interp, label="Noise Figure (Measured)",
linestyle='-')
    plt.plot(f_common, gain_theo_db, label="Gain (Theoretical)",
linestyle='--')
    plt.plot(f_common, nf_theo_db, label="Noise Figure (Theoretical)",
linestyle='--')
    plt.title(title)
    plt.xlabel(x_label)
    plt.ylabel(y_label)
    plt.grid(True, alpha=0.3)
    plt.legend()
    plt.tight_layout()
    plt.show()
    return f_common, gain_theo_db, nf_theo_db
```

Overview of Measurement Files

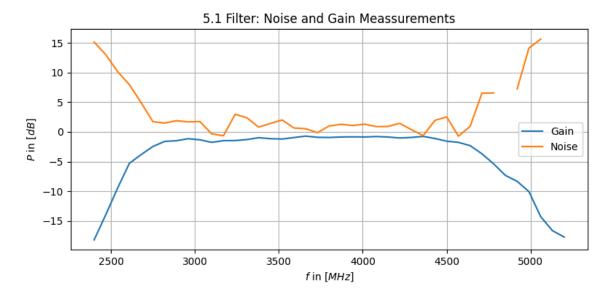
Files can be found under Meassurements/

File Name	Description	
meassurement_5_1.mat	NF measurement of a filter	
meassurement_5_2.mat	NF measurement of an attenuator	
meassurement_5_3.mat	NF measurement of LNA	
meassurement_5_4.mat	NF of LNA \rightarrow Attenuator	
<pre>meassurement_5_4_inverse.mat</pre>	NF of Attenuator \rightarrow LNA	

CSV-File Overview

5.1 Filter

We calculated the results below with some Python code.



```
# search all the indices which are below our 3dB threshold
# and then search for the last and the first one
peak gain = np.max(filter gain)
threshold = peak_gain - 3
crossing_indices = np.where(filter_gain <= threshold)[0]</pre>
if crossing indices.size >= 2:
    peak_index = np.argmax(filter_gain)
    lower_idx = crossing_indices[crossing_indices < peak_index][-1]</pre>
    f1, f2 = filter_f_steps[lower_idx], filter_f_steps[lower_idx + 1]
    g1, g2 = filter_gain[lower_idx], filter_gain[lower_idx + 1]
    f_3db_low = f1 + (threshold - g1) * (f2 - f1) / (g2 - g1)
    upper idx = crossing indices[crossing indices > peak index][0]
    f1, f2 = filter_f_steps[upper_idx - 1], filter_f_steps[upper_idx]
    g1, g2 = filter_gain[upper_idx - 1], filter_gain[upper_idx]
    f 3db high = f1 + (threshold - g1) * (f2 - f1) / (g2 - g1)
    f_center = (f_3db_high - f_3db_low) / 2 + f_3db_low
    print(f"Lower -3 dB frequency: {f_3db_low:.2f} MHz")
    print(f"Upper -3 dB frequency: {f 3db high:.2f} MHz")
    print(f"Estimated center frequency: {f_center:.2f} MHz")
    print("Could not find two -3 dB crossing points.")
```

```
Lower -3 dB frequency: 2686.30 MHz
Upper -3 dB frequency: 4710.45 MHz
Estimated center frequency: 3698.38 MHz
```

```
# we divide as we have steps normed to MHz
f_min = 3e9 / 1e6
f_max = 4.3e9 / 1e6

mask = (filter_f_steps >= f_min) & (filter_f_steps <= f_max)
gain_in_band = filter_gain[mask]

if gain_in_band.size > 0:
    gain_max = np.max(gain_in_band)
    gain_min = np.min(gain_in_band)
    ripple = gain_max - gain_min

print(f"Transmission ripple between 3 GHz and 4.3 GHz: {ripple:.2f} dB")
else:
    print("No data points found in the 3 GHz to 4.3 GHz range.")
```

Transmission ripple between 3 GHz and 4.3 GHz: 1.06 dB

5.2 Attenuator (6 dB)

The frequency response of the 6 dB attenuator is shown in Figure 2. As expected for a passive, linear component, both the gain and the noise figure are nearly constant across the measured frequency range of $200\,\mathrm{MHz}$ to $6\,\mathrm{GHz}$. The measured gain is approximately $-6\,\mathrm{dB}$ throughout, closely matching the nominal attenuation value of the device. Hence:

$$G = -6 \text{ dB}$$

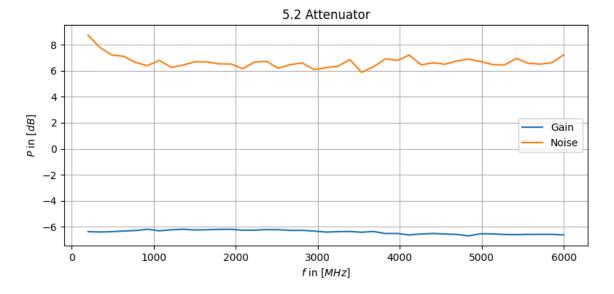
From a theoretical standpoint, for a passive network at ambient temperature $T \approx T_0 = 290 \, \text{K}$, the noise figure is given by:

$$F = 1 + (L - 1)\frac{T}{T_0}$$

where L is the linear loss. At $T=T_0$, this simplifies to F=L, and in dB:

$$F_{\mathrm{dB}} = L_{\mathrm{dB}} = 6\,\mathrm{dB}$$

The experimental results confirm this theoretical expectation. The gain remains consistently around $-6 \, dB$ across the entire frequency sweep, and the noise figure is likewise flat, averaging close to $6 \, dB$. This behavior is characteristic of a broadband, resistive attenuator, which introduces thermal noise equivalent to its loss when matched and operated at room temperature.



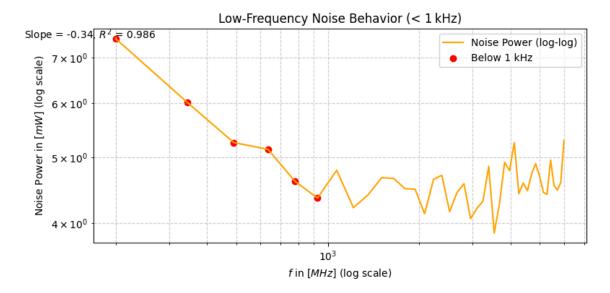
Additional Note: Low-Frequency Noise Behavior

An additional log-log plot of the noise power below 1 kHz reveals a consistent downward trend with a fitted slope of -0.34 and ($R^2 = 0.986$), suggesting a potential frequency dependence. While this behavior resembles 1/f noise in form, the slope is far shallower than the typical value (≈ -1), and since the DUT is a purely passive attenuator, it is unlikely that this is genuine 1/f noise originating from the device.

```
# Convert inputs
freq_hz = np.array(att_f_steps)
noise_dbm = np.array(att_noise)
noise_mw = dbm_to_mw(noise_dbm)

# Filter: keep only frequencies < 1000 Hz
mask = freq_hz < 1000
log_f = np.log10(freq_hz[mask])
log_p = np.log10(noise_mw[mask])</pre>
```

```
# Linear regression on log-log
slope, intercept, r_value, _, _ = linregress(log_f, log_p)
# Plot
plt.figure(figsize=(8, 4))
plt.loglog(freq hz, noise mw, label='Noise Power (log-log)', color='orange')
plt.scatter(freq_hz[mask], noise_mw[mask], color='red', label='Below 1 kHz')
# Annotate slope
plt.text(100, max(noise mw[mask]), f"Slope = {slope:.2f}, $R^2$ =
{r_value**2:.3f}", fontsize=10)
plt.grid(True, which='both', linestyle='--', alpha=0.6)
plt.xlabel('$f$ in $[MHz]$ (log scale)')
plt.ylabel('Noise Power in $[mW]$ (log scale)')
plt.title("Low-Frequency Noise Behavior (< 1 kHz)")</pre>
plt.legend()
plt.tight_layout()
plt.show()
```

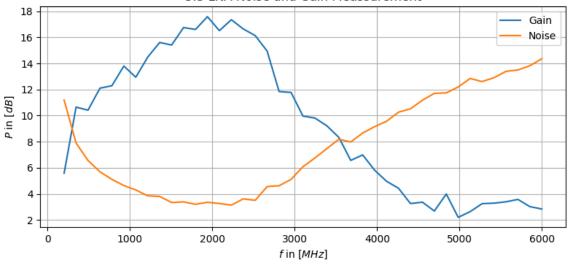


There are multiple possible causes for this: - This could indeed be $\frac{1}{f}$ noise coming from the SNS as it uses a diode to create the noise. This behavior can also be observed in task 5.5. - It could aswell be an artifact from the signal analyzer (averaging, windowing, etc.) But we wouldn't attribute this behavior to the attenuator as it is a passive component and is not the cause for the flicker noise.

5.3 Low noise amplifier (LNA)

Task asks for the frequency at which the LNA produces max gain and at which frequency the NF is minimal. The solution is below the plot.

5.3 LNA Noise and Gain Meassurement



```
max_gain = np.max(lna_gain)
f_max_gain = lna_f_steps[np.argmax(lna_gain)]
print(f"LNA gain is max @ {f_max_gain} MHz with {max_gain:.2f} dB")

min_noise = np.min(lna_noise)
f_min_noise = lna_f_steps[np.argmin(lna_noise)]
print(f"LNA noise is min @ {f_min_noise} MHz with {min_noise:.2f} dB")
```

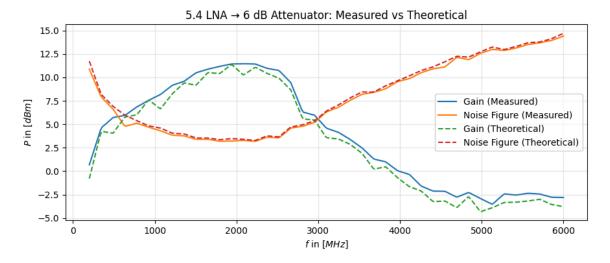
```
LNA gain is max @ 1940 MHz with 17.59 dB
LNA noise is min @ 2230 MHz with 3.13 dB
```

5.4 LNA with subsequent 6 dB attenuator

LNA Followed by Attenuator

```
title_lna_att = "5.4 LNA -> $6$dB Attenuator"
lna_att_gain, lna_att_noise, lna_att_f_steps = read_mat('Meassurements/
meassurement_5_4.mat', 'messung_5_4_LNA_Att')

# Compute and plot all (We parse the signals of LNA and att in the way defined for the function)
f_plot, gain_theo, nf_theo = compute_and_plot_cascade_with_measured(
    f_lna=lna_f_steps, gain_lna_db=lna_gain, nf_lna_db=lna_noise,
    f_att=att_f_steps, gain_att_db=att_gain, nf_att_db=att_noise,
    f_meas=lna_att_f_steps, gain_meas_db=lna_att_gain,
nf_meas_db=lna_att_noise
)
```



In this configuration, the low-noise amplifier (LNA) is followed by a 6 dB attenuator. The measured gain is consistent with theoretical expectations: compared to the standalone LNA (Section 5.3), the gain curve is approximately 6 dB lower, as expected from adding a fixed attenuator after the amplifier.

To estimate the theoretical noise figure of the cascade, we apply the **Friis formula** for two components:

$$F_{\text{total}} = F_1 + \frac{F_2 - 1}{G_1}$$

Where: - F_1 : noise factor of the LNA (converted from NF in dB) - F_2 : noise factor of the attenuator - G_1 : gain of the LNA (linear) —

This is automatically handled by the snippet that generates the comparison plot. The following points about the gain and noise figure are worth mentioning:

Gain

- The measured gain closely resembles the theoretical prediction, with a small deviation of approximately 0.5 to 1 dB at higher frequencies.
- This minor difference could be attributed to:
 - Connector losses
 - Cable losses
- The overall gain shape and roll-off behavior are well preserved, demonstrating that the theoretical cascade model correctly reflects the behavior of the actual system.

Noise Figure

- The **noise figure** shows very good agreement between the measured and calculated curves throughout most of the frequency range.
- Both curves confirm that the NF remains low and stable (~4–6 dB) in the mid-band, where the LNA operates with maximum effectiveness.
- Slight divergence at the higher-frequency end may be caused by:
 - ▶ Temperature variations
 - Measurement uncertainty
 - ► Random behavior of noise

Attenuator Followed by LNA

In contrast, when the attenuator is placed before the LNA, the overall system gain remains roughly the same, but the noise figure is significantly higher, especially at higher frequencies.

This behavior is predicted by the Friis formula:

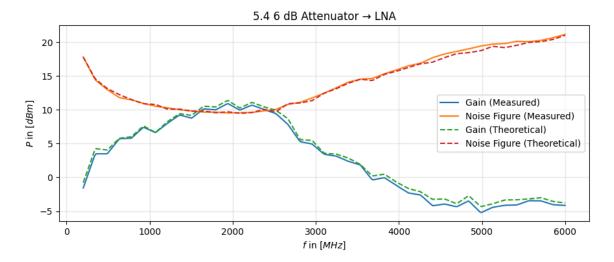
$$F_{\text{swapped}} = F_2 + \frac{F_1 - 1}{G_2}$$

Here, F_2 is now the dominant term (bein the attenuator's noise figure), since it comes first. The LNA still amplifies the signal and noise, but the attenuator has already degraded the SNR by introducing thermal noise and reducing signal power. The result is a higher system noise figure, as seen in the plot, particularly because the first component in the chain dominates the overall noise performance. This is observed when plotting the following:

```
title_att_lna = "5.4 6 dB Attenuator → LNA"
att_lna_gain, att_lna_noise , att_lna_f_steps = read_mat(
    'Meassurements/meassurement_5_4_inverse.mat',
    'messung_5_4_LNA_Att_reverse'
)

# Compute and plot theoretical + measured for: Attenuator → LNA (We switch the order of parsing the combined parameters)
f_plot_rev, gain_theo_rev, nf_theo_rev = compute_and_plot_cascade_with_measured(
```

```
f_lna=att_f_steps, gain_lna_db=att_gain, nf_lna_db=att_noise,
  f_att=lna_f_steps, gain_att_db=lna_gain, nf_att_db=lna_noise,
  f_meas=att_lna_f_steps, gain_meas_db=att_lna_gain,
nf_meas_db=att_lna_noise,
  title=title_att_lna
)
```



Analogous to the previous case, it is worth mentioning:

Gain

- The measured gain closely matches the theoretical prediction, validating the cascade model.
- In this configuration, overall gain is the same as for the previous case where the LNA was placed before the attenuator.

Noise Figure

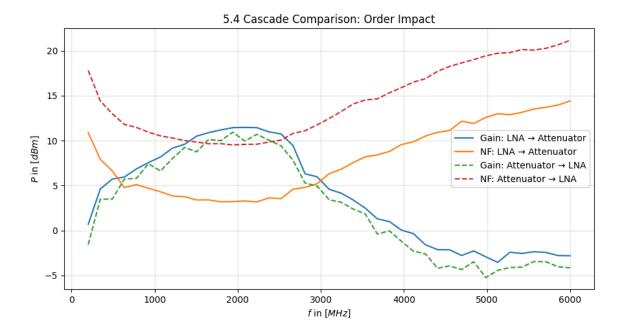
- The noise figure is significantly worse than in the LNA \rightarrow Attenuator configuration.
- Both theoretical and measured NF increase sharply with frequency, reaching values above 20dB.
- This behavior confirms the theoretical expectation from the Friis formula: placing the component with the higher noise figure at the front of the chain amplifies its negative effect on the overall noise performance.

Comparison: Impact of component ordering

The following plot compares the total **gain** and **noise figure** of two cascaded configurations:

- LNA \rightarrow Attenuator
- Attenuator \rightarrow LNA

```
def plot cascade comparison(
   f1: NDArray, gain1: NDArray, nf1: NDArray,
    f2: NDArray, gain2: NDArray, nf2: NDArray,
    label_gain1: str = "Gain: LNA → Attenuator",
    label_nf1: str = "NF: LNA → Attenuator",
    label_gain2: str = "Gain: Attenuator → LNA",
    label_nf2: str = "NF: Attenuator → LNA",
    title: str = "5.4 Cascade Comparison: Order Impact",
    x_{abel}: str = "$f$ in $[MHz]$", <math>y_{abel}: str = "$P$ in $[dBm]$",
   linestyle1: str = '-', linestyle2: str = '--'
):
    plt.figure(figsize=(9, 5))
    # Plot LNA → Attenuator
    plt.plot(f1, gain1, linestyle=linestyle1, label=label_gain1)
    plt.plot(f1, nf1, linestyle=linestyle1, label=label nf1)
    # Plot Attenuator → LNA
    plt.plot(f2, gain2, linestyle=linestyle2, label=label_gain2)
    plt.plot(f2, nf2, linestyle=linestyle2, label=label_nf2)
    plt.title(title)
    plt.xlabel(x label)
    plt.ylabel(y_label)
    plt.grid(True, alpha=0.3)
    plt.legend()
    plt.tight_layout()
    plt.show()
plot_cascade_comparison(
    f1=lna_att_f_steps, gain1=lna_att_gain, nf1=lna_att_noise,
    f2=att_lna_f_steps, gain2=att_lna_gain, nf2=att_lna_noise,
   linestyle1='-', linestyle2='--'
)
```



Gain Behavior

- When the LNA is placed before the attenuator, the signal is amplified first, then attenuated.
- In the Attenuator → LNA configuration, the signal is attenuated before amplification. Overall
 the gain from both measurements yield approximatelly the same gain value as observed above,
 since this operation equals adding the dB value of the two gains the result is not altered by the
 components order.

Noise Figure Behavior

- With the LNA first, the noise figure remains relatively low, with a minimum of almost 4dB at 2000 MHz, especially across the central bandwidth. This reflects the LNA's role in preserving the signal-to-noise ratio (SNR) early in the chain.
- Conversely, in the Attenuator followed by the LNA case, the system exhibits a much higher
 noise figure, particularly at higher frequencies. The attenuator introduces thermal noise and
 reduces the signal before the LNA can amplify it, which causes significant degradation in SNR.
 The noise figure climbs to over 15 dB in some regions.

5.5 Noise figure measurement of the LNA with Y-Factor method

The following cell should load in the CSV file from the meassuring device. The evaluation is below the code and plots.

```
meta_data_cold_cal, f_steps_n1, N_1 = read_spec_csv("Meassurements/
SNS_Cold_Cal.csv")
meta_data_hot_cal, f_steps_n2, N_2 = read_spec_csv("Meassurements/")
```

```
SNS_Hot_Cal.csv")
meta_data_cold, f_steps_nl_dut, N_1_DUT = read_spec_csv("Meassurements/
SNS_Cold.csv")
meta_data_cold, f_steps_n2_dut, N_2_DUT = read_spec_csv("Meassurements/
SNS_Hot.csv")
f_steps = f_steps_n1
```

```
ENR: float = 15.0  # [dB]
ENR_lin = 10 ** (ENR / 10)
```

Calculation for $G_1(f)$ and NF(f)

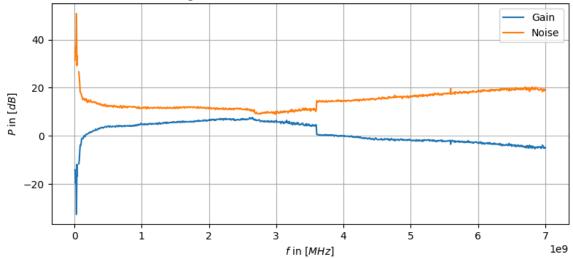
```
\# eq 2.21 + eq 2.23
y_sns = np.divide(N_2, N_1)
y_dut = np.divide(N_2_DUT, N_1_DUT)
f 2 = np.divide(ENR lin, np.subtract(y sns, 1))
f_sys = np.divide(ENR_lin, np.subtract(y_dut, 1))
# according to equation 2.26 we get for each freq-bin a G value
delta meas = np.subtract(N 2, N 1)
delta_dut = np.subtract(N_2_DUT, N_1_DUT)
g1 = np.divide(delta dut, delta meas)
G1 = 10 * np.log10(g1)
# eq 2.25
f_1 = np.subtract(f_sys, np.divide(np.subtract(f_2, 1), g1))
NF 1 = 10 * np.log10(f 1)
print(f"Max gain {np.nanmax(G1):.2f} dB @
{scientific_2_str(f_steps_n1[np.nanargmax(G1)], 'Hz')}")
print(f"Min NF {np.nanmin(NF 1):.2f} dB @
{scientific_2_str(f_steps_n1[np.nanargmin(NF_1)], 'Hz')}")
```

```
[0.03891201 0.01090236 0.01702255 ... 0.3378907 0.30726848 0.31905599]
Max gain 7.64 dB @ 2.65 GHz
Min NF 9.07 dB @ 2.98 GHz
```

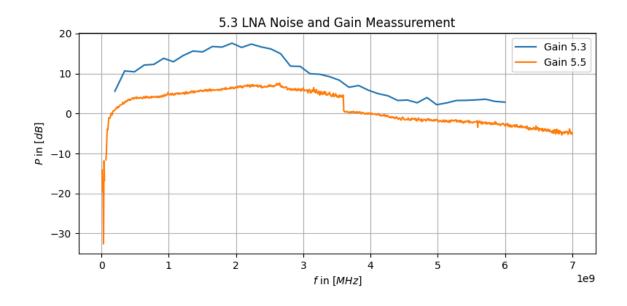
```
/tmp/ipykernel_112133/2509546734.py:13: RuntimeWarning: invalid value
encountered in log10
  G1 = 10 * np.log10(g1)
/tmp/ipykernel_112133/2509546734.py:17: RuntimeWarning: invalid value
```

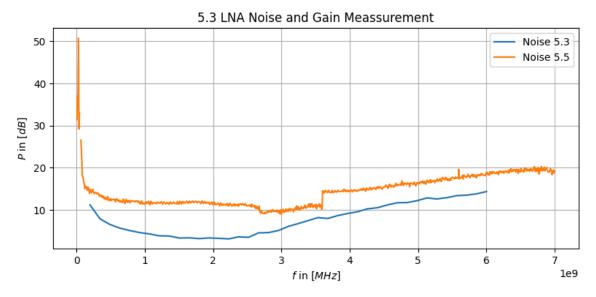
```
encountered in log10
NF_1 = 10 * np.log10(f_1)
```

5.5 Noise figure measurement of the LNA with Y-Factor method



Comparison with Task 5.3





Evaluation As we can see in the results, the measured G_1 and NF is much lower than the internal G+NF measurement method. While the gain plot atleast has the same shape albeit being at a significant lower level. For the NF measurement we can see that the graph follows the same form, but with a larger offset of up to $\sim 8dB$, between 500Hz up to 2.75GHz. For higher frequencies the difference fluctuates around $\sim 6dB$. Also it seems that there is $\frac{1}{f}$ noise visible in the NF graph at lower frequencies as already discussed in the measurement with the attenuator.

Reasons for deviations: - ENR is frequency dependent and we are using on fixed value across the whole frequency range. This is accommodate for in the internal measurement method. - As described in the last section of the theoretical part of the PDF, if NF>10dB the measuring system can mask the noise from the DUT and therefore is not accurate. But because the NF is at

max. 15dB and our ENR = 15dB, this shouldnt have affected our measurements, as it has to be much greater than the ENR.

5.6 Conclusion (Theoretical-Expectation)

Assuming typical values we can compute the expected noise for both scenarios:

```
def db to lin(db): return 10 ** (db / 10)
def lin_to_db(lin): return 10 * np.log10(lin)
# Component specs (fixed values)
F_lna = db_to_lin(3) # LNA NF
G_att = db_to_lin(-6)  # Attenuator gain (loss)
F_att = db_to_lin(6)  # Attenuator NF
G_mpa = db_to_lin(13)  # MPA gain
F_mpa = db_to_lin(6)  # MPA NF
# --- Case 1: LNA → Attenuator → MPA
F case1 = F lna + (F att - 1)/G lna + (F mpa - 1)/(G lna * G att)
NF_casel_db = lin_to_db(F_casel)
# --- Case 2: Attenuator → LNA → MPA
F_{case2} = F_{att} + (F_{lna} - 1)/G_{att} + (F_{mpa} - 1)/(G_{att} * G_{lna})
NF_{case2_db} = lin_{to_db}(F_{case2})
print(f"Case 1 NF (LNA → Att → MPA): {NF case1 db:.2f} dB")
print(f"Case 2 NF (Att → LNA → MPA): {NF_case2_db:.2f} dB")
NF dB sub = 9.3
NF_dB_opt = 4.1
noise_ratio = 10 ** ((NF_dB_sub - NF_dB_opt) / 10)
print(f"Suboptimal config is {noise_ratio:.2f} x more noisy")
```

```
Case 1 NF (LNA \rightarrow Att \rightarrow MPA): 4.13 dB
Case 2 NF (Att \rightarrow LNA \rightarrow MPA): 9.25 dB
Suboptimal config is 3.31× more noisy
```

5.6 Conclusion (Theoretical Expectation)

Based on theoretical calculations using the Friis formula for cascaded noise figure, we expect the following system behavior depending on the order of components:

Configuration	Total Gain (dB)	Noise Fig- ure (dB)	Comments
$LNA \rightarrow Attenuator \rightarrow MPA$	≈ 21 dB	4.1 dB	Optimal SNR preservation; LNA amplifies before any signal degradation.
Attenuator \rightarrow LNA \rightarrow MPA	≈ 21 dB	9.3 dB	Suboptimal: signal degraded before amplification.

This confirms the importance of placing low-noise amplifiers at the front of the chain to minimize overall system noise. Hence an appropriate choice of placing the LNA as the first component results in a noise power 3.3 times lower w.r.t. the suboptimal case.