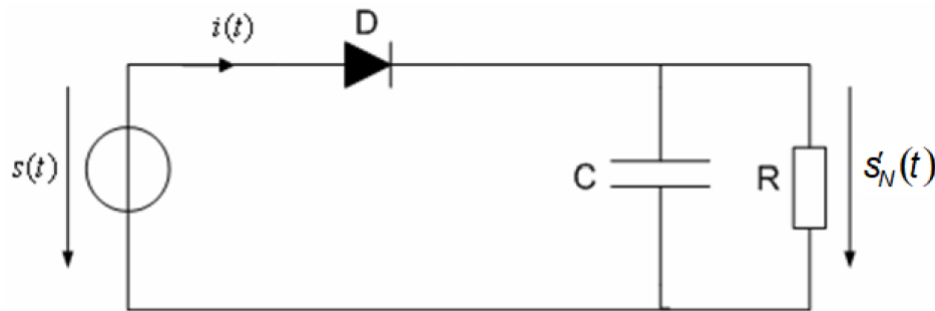


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# 1 Preparation for Experiment.- Northe, Velez, Wörner

## 1.1 6.1 Exercise 1

An AM modulated signal is to be demodulated with an AM demodulator as shown in Fig. 3.3. The modulating signal represents a harmonic oscillation. For the modulation frequency 20 kHz and the modulation depth  $m = 33\%$ , calculate the largest possible time constant  $\tau$  for which distortion-free demodulation is still possible. What is the value of the resistance  $R$  at  $C = 300 \text{ pF}$  under these conditions?



### 1.1.1 Solution: Exercise 1 (AM) — Largest Time Constant for Distortion-Free Demodulation

Given:

- Modulation frequency:  $f_{\max} = 20 \text{ kHz}$
- Modulation depth:  $m = 0.33$
- Capacitance:  $C = 300 \text{ pF} = 300 \times 10^{-12} \text{ F}$

From the lab manual (Eq. 3.6), the time constant  $\tau$  of the envelope detector must satisfy:

$$\frac{1}{\omega_0} \ll \tau < \frac{1}{2\pi m f_{\max}}$$

We use the upper limit:

$$\tau_{\max} = \frac{1}{2\pi m f_{\max}}$$

Substituting values:

$$\tau_{\max} = \frac{1}{2\pi \cdot 0.33 \cdot 20 \times 10^3} = \frac{1}{41,469.576} \approx 24.1 \mu\text{s}$$

To find the corresponding resistance  $R$ :

$$\tau = R \cdot C \quad \Rightarrow \quad R = \frac{\tau}{C}$$

Substituting:

$$R = \frac{24.1 \times 10^{-6}}{300 \times 10^{-12}} = 80,333.33 \Omega \approx \boxed{80.3 \text{ k}\Omega}$$

The following script computes the value and prints the result:

```
[2]: # Given values
f_max = 20e3          # Hz
m = 0.33
C = 300e-12           # Farads

# Compute the maximum time constant tau
import math
tau_max = 1 / (2 * math.pi * m * f_max)

# Compute resistance R
R = tau_max / C

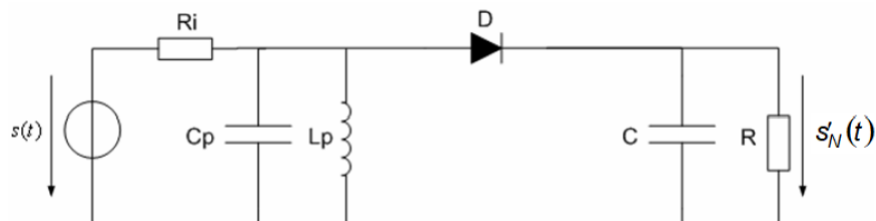
# Display results
print(f"Maximum : {tau_max * 1e6:.2f} μs")
print(f"Required R: {R / 1e3:.1f} kΩ")
```

Maximum : 24.11 μs

Required R: 80.4 kΩ

## 1.2 6.2 Exercise 2

Derive the following equation (representing the transfer function of the circuit used for AM-FM



conversion).

### 1.2.1 Solution: Exercise 2 (FM) — Derivation of Equation (3.15)

We analyze the FM demodulator circuit **before the diode**, which consists of a series resistor ( $R_i$ ) and a parallel LC tank ( $L_p$   $C_p$ ).

We aim to compute the transfer function:

$$G(\omega) = \frac{V_{\text{out}}}{V_{\text{in}}}$$

where: - ( $V_{\text{in}}$ ): FM input signal - ( $V_{\text{out}}$ ): voltage across the LC tank

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### 1.2.2 Step 1: Impedance of the LC Tank

The parallel combination is:

$$Z_{LC} = \left( \frac{1}{j\omega C_p} \parallel j\omega L_p \right) = \frac{\left( \frac{1}{j\omega C_p} \right) \cdot (j\omega L_p)}{\frac{1}{j\omega C_p} + j\omega L_p}$$

**Numerator:**

$$\frac{1}{j\omega C_p} \cdot j\omega L_p = \frac{L_p}{C_p}$$

**Denominator:**

$$\frac{1}{j\omega C_p} + j\omega L_p = \frac{1 - \omega^2 L_p C_p}{j\omega C_p}$$

**Therefore:**

$$Z_{LC} = \frac{L_p/C_p}{(1 - \omega^2 L_p C_p)/(j\omega C_p)} = \frac{j\omega L_p}{1 - \omega^2 L_p C_p}$$

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### 1.2.3 Step 2: Total Series Impedance

The total impedance from input to ground is:

$$Z_{\text{total}} = R_i + Z_{LC} = R_i + \frac{j\omega L_p}{1 - \omega^2 L_p C_p}$$

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### 1.2.4 Step 3: Voltage Divider

Using voltage division:

$$G(\omega) = \frac{V_{\text{out}}}{V_{\text{in}}} = \frac{Z_{LC}}{R_i + Z_{LC}} = \frac{\frac{j\omega L_p}{1 - \omega^2 L_p C_p}}{R_i + \frac{j\omega L_p}{1 - \omega^2 L_p C_p}}$$

Multiply numerator and denominator by  $(1 - \omega^2 L_p C_p)$ :

$$G(\omega) = \frac{j\omega L_p}{j\omega L_p + R_i(1 - \omega^2 L_p C_p)}$$


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### 1.2.5 Final Result

$$G(\omega) = \frac{j\omega L_p}{j\omega L_p + R_i(1 - \omega^2 L_p C_p)}$$

This transfer function describes how the **slope detector** converts **frequency variations (FM)** into **amplitude variations (AM)**, which can then be demodulated by the envelope detector.

## 1.3 6.3 Exercise 3 IQ

$$\begin{aligned} f_c &= 1 \text{ MHz} \\ s(t) &= 2 \left[ 1 + 0.5 \cos \left( 4\pi \times 10^3 \text{ Hz} \cdot t + \frac{\pi}{4} \right) \right] \cos \left( 2\pi \times 10^6 \text{ Hz} \cdot t - \sin \left( 6\pi \times 10^3 \text{ Hz} \cdot t - \frac{\pi}{4} \right) \right) \\ 0 &\leq t \leq 1.5 \text{ ms} \end{aligned}$$

### 1.3.1 6.3.1 Formulas of I and Q signals after LPF

Introducing some signs:

$$\begin{aligned} \omega_0 &= 2\pi \times 10^6 \text{ Hz} \\ \omega_{f1} &= 2\pi \times 2 \cdot 10^3 \text{ Hz} \\ \omega_{f2} &= 2\pi \times 3 \cdot 10^3 \text{ Hz} \\ a(t) &= 2 \left[ 1 + 0.5 \cos \left( 4\pi \times 10^3 \text{ Hz} \cdot t + \frac{\pi}{4} \right) \right] \\ \phi(t) &= \sin \left( \omega_{f2} \cdot t - \frac{\pi}{4} \right) \end{aligned}$$

Apply cosine subtraction identity:

$$s(t) = a(t) \cos(\omega_0 \cdot t - \phi(t)) = a(t) [\cos(\omega_0 \cdot t) \cos(\phi(t)) + \sin(\omega_0 \cdot t) \sin(\phi(t))]$$

Now mix/multiply the bandpass signal with the signal from the LO:

$$s_I(t) = \frac{1}{2} s(t) \cdot \cos(\omega_0 t)$$

$$s_Q(t) = \frac{1}{2}s(t) \cdot \sin(\omega_0 t)$$

With the following identities:

$$\cos^2(\omega_0 t) = \frac{1 + \cos(2\omega_0 t)}{2}$$

$$\sin(\omega_0 t) \cos(\omega_0 t) = \frac{1}{2} \sin(2\omega_0 t)$$

We get this equation for one branch. We just show the I-part as it is the same for the Q-part:

$$\begin{aligned} s_I(t) &= \frac{1}{2}a(t) [\cos(\omega_0 t) \cos(\phi(t)) + \sin(\omega_0 t) \sin(\phi(t))] \cdot \cos(\omega_0 t) \\ &= \frac{1}{2}a(t) [\cos(\phi(t)) \cos^2(\omega_0 t) + \sin(\phi(t)) \sin(\omega_0 t) \cos(\omega_0 t)] \\ &= \frac{1}{2}a(t) \left[ \cos(\phi(t)) \cdot \frac{1 + \cos(2\omega_0 t)}{2} + \sin(\phi(t)) \cdot \frac{1}{2} \sin(2\omega_0 t) \right] \end{aligned}$$

Now we want to get rid of the  $2\omega_0$  parts, so we have to use a LPF.

$$s_I(t) = \frac{1}{2}a(t) [\cos(\phi(t))]$$

$$s_Q(t) = \frac{1}{2}a(t) [\sin(\phi(t))]$$

Resubstitute  $\phi$  and  $\omega$  terms:

$$s_I(t) = \left[ 1 + 0.5 \cos \left( 2\pi \times 2 \cdot 10^3 \text{ Hz} \cdot t + \frac{\pi}{4} \right) \right] \cdot \left[ \cos \left( \sin \left( 2\pi \times 3 \cdot 10^3 \text{ Hz} \cdot t - \frac{\pi}{4} \right) \right) \right]$$

$$s_Q(t) = \left[ 1 + 0.5 \cos \left( 2\pi \times 2 \cdot 10^3 \text{ Hz} \cdot t + \frac{\pi}{4} \right) \right] \cdot \left[ \sin \left( \sin \left( 2\pi \times 3 \cdot 10^3 \text{ Hz} \cdot t - \frac{\pi}{4} \right) \right) \right]$$

### 1.3.2 6.3.2 Determine for the signal $s(t)$ :

- Mean carrier amplitude  $A_T$
- Modulation depth  $m$
- AM modulation frequency  $f_{N,Am}$
- Peak phase deviation  $\Delta\phi$
- Modulation index  $\eta$
- Peak frequency deviation  $\Delta f$
- FM modulation frequency  $f_{N,FM}$

$$s(t) = \underbrace{2 \left[ 1 + 0.5 \cos \left( 2\pi \cdot 2 \cdot 10^3 \cdot t + \frac{\pi}{4} \right) \right]}_{\text{AM envelope}} \cdot \cos \left( \underbrace{2\pi \cdot 10^6 \cdot t}_{\text{Carrier}} - \underbrace{\sin \left( 2\pi \cdot 3 \cdot 10^3 \cdot t - \frac{\pi}{4} \right)}_{\text{PM phase deviation}} \right)$$

Swing:  $a_{\max} = 2 * (1 + 0.5) = 3$  and  $a_{\min} = 2 * (1 - 0.5) = 1 \rightarrow \Delta a = 2$

$$A_T = 2$$

$$m = \frac{a_n}{A_T} = \frac{1}{2} = 0.5$$

$$f_{N,AM} = 2kHz$$

As an amplitude swing from  $-1$  to  $1$  equates to  $1$  rad by converting  $A = -1$

$$\Delta\phi = 1rad$$

The modulation index:

$$\eta = \frac{\Delta\omega}{\omega} = \frac{2\pi \cdot 3kHz}{2\pi \cdot 3kHz} = 1$$

Therefore

$$\Delta f = 3kHz$$

$$f_{N,FM} = 3kHz$$