| [7:6] | - | 保留不用 | |
|-------|------|--------------------------|---------------------|
| 5 | HDR5 | PF5 输出驱动控制; 1 = 80mA 驱动, | 0 = 12mA 驱动 |
| 4 | HDR4 | PF4 输出驱动控制; 1 = 80mA 驱动, | 0 = 12mA 驱动 |
| 3 | HDR3 | PF2 输出驱动控制; 1 = 80mA 驱动, | 0 = 12mA 驱动 |
| 2 | HDR2 | PF1 输出驱动控制; 1 = 80mA 驱动, | 0 = 12mA 驱动 |
| 1 | HDR1 | PD6 输出驱动控制; 1 = 80mA 驱动, | 0 = 12mA <u></u> 返动 |
| 0 | HDR0 | PD5 输出驱动控制; 1 = 80mA 驱动, | 0 = 12mA 驱动 |

端□复用控制寄存器 0- PMX0

| PMX0 - 端□复用控制寄存器 0 | | | | | | | | | | |
|----------------------|-------|---------------------------------|--|--------------------------|-------|------|------|------|--|--|
| PMX0: 0xEE 默认值: 0x00 | | | | | | | | | | |
| Bit | WCE | C1BF4 | C1AF5 | COBF3 | COACO | SSB1 | TXD6 | RXD5 | | |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | | |
| 位定义 | | | | | | | | | | |
| 7 | WCE | ≒V | PMX0/1 更新使能控制;在更新 PMX0/1 寄存器之前,需要先写 WCE 位为 1,在之后的 6 个系统周期内完成对 PMX0/1 的更新。 | | | | | | | |
| 6 | C1BF4 | 1 = (| 0C1B 辅助输出控制 1 = 0C1B 输出到 PF4 0 = 0C1B 输出到 PB2 | | | | | | | |
| 5 | C1AF5 | 1 = 0 | 0C1A 辅助输出控制 1 = 0C1A 输出到 PF5 0 = 0C1A 输出到 PB1 | | | | | | | |
| 4 | COBF3 | 1 = 0 | OCOB 辅助输出控制 1 = OCOB 输出到 PF3 0 = OCOB 输出到 PD5 | | | | | | | |
| 3 | COACO | 0004 { 000 = 01 = 10 = | 0COA 辅助输出控制 0COA 输出由 COACO 位与 TCCROB 寄存器的 COAS 位共同控制: { COACO, COAS} = 00 = 0COA 输出到 PD6 01 = 0COA 输出到 PE4 10 = 0COA 输出到 PCO 11 = 0COA 同时输出到 PE4 和 PCO | | | | | | | |
| 2 | SSB1 | 1 = 9 | SPSS 辅助输出控制 1 = SPSS 输出到 PB1 0 = SPSS 输出到 PB2 | | | | | | | |
| 1 | TXD6 | | 串□ TXD 辅助输出控制 1 = TXD 输出到 PD6, 0 = TXD 输出到 PD1 | | | | | | | |
| 0 | RXD5 | ' | |)输入控制 k自 PD5 , | | 输入来自 | PD0 | | | |