

## 26.7 2-wire Serial Interface Characteristics

Table 26-6 describes the requirements for devices connected to the 2-wire Serial Bus. The ATmega48P/88P/168P/328P 2-wire Serial Interface meets or exceeds these requirements under the noted conditions.

Timing symbols refer to Figure 26-7.

**Table 26-6.** 2-wire Serial Bus Requirements

| Symbol          | Parameter  | Condition   | Min                                | Max                         | Units         |
|-----------------|--|---|------------------------------------|-----------------------------|---------------|
| $V_{IL}$        | Input Low-voltage                                |   | -0.5                               | $0.3 V_{CC}$                | V             |
| $V_{IH}$        | Input High-voltage                               |   | $0.7 V_{CC}$                       | $V_{CC} + 0.5$              | V             |
| $V_{hys}^{(1)}$ | Hysteresis of Schmitt Trigger Inputs             |   | $0.05 V_{CC}^{(2)}$                | –                           | V             |
| $V_{OL}^{(1)}$  | Output Low-voltage                               | 3 mA sink current                                     | 0                                  | 0.4                         | V             |
| $t_r^{(1)}$     | Rise Time for both SDA and SCL                   |   | $20 + 0.1C_b^{(3)(2)}$             | 300                         | ns            |
| $t_{of}^{(1)}$  | Output Fall Time from $V_{IHmin}$ to $V_{ILmax}$ | $10 \text{ pF} < C_b < 400 \text{ pF}^{(3)}$          | $20 + 0.1C_b^{(3)(2)}$             | 250                         | ns            |
| $t_{SP}^{(1)}$  | Spikes Suppressed by Input Filter                |   | 0                                  | $50^{(2)}$                  | ns            |
| $I_i$           | Input Current each I/O Pin                       | $0.1V_{CC} < V_i < 0.9V_{CC}$                         | -10                                | 10                          | $\mu\text{A}$ |
| $C_i^{(1)}$     | Capacitance for each I/O Pin                     |   | –                                  | 10                          | pF            |
| $f_{SCL}$       | SCL Clock Frequency                              | $f_{CK}^{(4)} > \max(16f_{SCL}, 250\text{kHz})^{(5)}$ | 0                                  | 400                         | kHz           |
| Rp              | Value of Pull-up resistor                        | $f_{SCL} \leq 100 \text{ kHz}$                        | $\frac{V_{CC} - 0.4V}{3\text{mA}}$ | $\frac{1000\text{ns}}{C_b}$ | $\Omega$      |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | $\frac{V_{CC} - 0.4V}{3\text{mA}}$ | $\frac{300\text{ns}}{C_b}$  | $\Omega$      |
| $t_{HD;STA}$    | Hold Time (repeated) START Condition             | $f_{SCL} \leq 100 \text{ kHz}$                        | 4.0                                | –                           | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 0.6                                | –                           | $\mu\text{s}$ |
| $t_{LOW}$       | Low Period of the SCL Clock                      | $f_{SCL} \leq 100 \text{ kHz}$                        | 4.7                                | –                           | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 1.3                                | –                           | $\mu\text{s}$ |
| $t_{HIGH}$      | High period of the SCL clock                     | $f_{SCL} \leq 100 \text{ kHz}$                        | 4.0                                | –                           | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 0.6                                | –                           | $\mu\text{s}$ |
| $t_{SU;STA}$    | Set-up time for a repeated START condition       | $f_{SCL} \leq 100 \text{ kHz}$                        | 4.7                                | –                           | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 0.6                                | –                           | $\mu\text{s}$ |
| $t_{HD;DAT}$    | Data hold time                                   | $f_{SCL} \leq 100 \text{ kHz}$                        | 0                                  | 3.45                        | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 0                                  | 0.9                         | $\mu\text{s}$ |
| $t_{SU;DAT}$    | Data setup time                                  | $f_{SCL} \leq 100 \text{ kHz}$                        | 250                                | –                           | ns            |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 100                                | –                           | ns            |
| $t_{SU;STO}$    | Setup time for STOP condition                    | $f_{SCL} \leq 100 \text{ kHz}$                        | 4.0                                | –                           | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 0.6                                | –                           | $\mu\text{s}$ |
| $t_{BUF}$       | Bus free time between a STOP and START condition | $f_{SCL} \leq 100 \text{ kHz}$                        | 4.7                                | –                           | $\mu\text{s}$ |
|                 |  | $f_{SCL} > 100 \text{ kHz}$                           | 1.3                                | –                           | $\mu\text{s}$ |

Notes: 1. In ATmega48P/88P/168P/328P, this parameter is characterized and not 100% tested.  
2. Required only for  $f_{SCL} > 100 \text{ kHz}$ .