

## a) The metric

We have a static, isotropic metric. That is, there is no  $t$ -dependence and it is invariant under rotation. Denote our coordinates with  $x^\mu = (t, r, \theta, \phi)$ . We assume 1+3 dimensions, one temporal and three spatial. Isotropic in spatial part, means we have a  $SO(3)$  group (ie. a “sphere”). Thus, the metric must contain

$$g_\Omega = d\theta^2 + \sin^2 \theta d\phi^2.$$

We write our metric as

$$ds^2 = g(r) + \gamma(r)g_\Omega,$$

where there is no  $t$ -dependence due to it being static. Also, the angular dependence is entirely contained in  $g_\Omega$ , to not break isotropy. Thus,  $g$  is on the form

$$g(r) = g_{\mu\nu} dx^\mu dx^\nu, \quad \mu, \nu \in \{t, r\}.$$

Any cross terms between  $dt$  and  $dr$  will break time reversal, as one will get something on the form

$$ds^2 = dt^2 + dt dr + dr^2 = \left(\frac{dt}{dr} + \frac{dt}{dr} + 1\right) dr^2.$$

As the second term is not quadratic in  $dt$ , it changes sign on time reversal, breaking the symmetry. Thus, there can be no cross terms. Our metric is thus

$$ds^2 = A(r)dt^2 - B(r)dr^2 + \gamma(r)(d\theta^2 + \sin^2 \theta d\phi^2).$$

Signs were chosen by convention. As we have no constraints on “r”, we may choose it as we wish. We choose it such that

$$ds^2 = A(r)dt^2 - B(r)dr^2 - r^2(d\theta^2 + \sin^2 \theta d\phi^2).$$

## b) Ricci tensor

We will here use the framework “differentialGeometry3” provided through the course webpage, <http://web.phys.ntnu.no/~mika/QF/software.html>.

```
1 import numpy as np
2 import sympy
3 from differentialGeometry3 import computeGeometry, printGeometry,
  determinantg, ginv
4 from IPython.display import display, Math
5
6 def displayNonZero(T):
7     """Displays the non-zero components of the tensor T
8     Also assumes to be inside iPython or Jupyter, to
9     use the 'display' function"""
10     for index, element in np.ndenumerate(T):
11         if element != 0:
```

```

13         print(index)
14         display(sympy.simplify(element))
15
16 # Define our coordinates
17 t, r, theta, phi = sympy.symbols('t r theta phi')
18 coords = np.array([t, r, theta, phi])
19 A = sympy.Function('A')(r)
20 B = sympy.Function('B')(r)
21
22 # Construct the tensor
23 g_ = np.zeros((4, 4), dtype=object)
24 g_[0,0] = A
25 g_[1,1] = -B
26 g_[2,2] = -r**2
27 g_[3,3] = -r**2 * sympy.sin(theta)**2
28
29 geometry = computeGeometry(g_, coords)
30
31 # Ricci
32 r4i_ = geometry[7]
33
34 # Ricci is diagonal
35 for ele in np.diag(r4i_):
36     display(sympy.simplify(ele))
37     print("—————")

```

Which outputs

$$\begin{aligned}
 & \frac{\frac{d^2}{dr^2}A(r)}{2A(r)} - \frac{\frac{d}{dr}A(r)\frac{d}{dr}B(r)}{4A(r)B(r)} - \frac{\left(\frac{d}{dr}A(r)\right)^2}{4A^2(r)} - \frac{\frac{d}{dr}B(r)}{rB(r)} \\
 & \frac{\frac{d^2}{dr^2}A(r)}{2A(r)} - \frac{\frac{d}{dr}A(r)\frac{d}{dr}B(r)}{4A(r)B(r)} - \frac{\left(\frac{d}{dr}A(r)\right)^2}{4A^2(r)} - \frac{\frac{d}{dr}B(r)}{rB(r)} \\
 & -\frac{r\frac{d}{dr}B(r)}{2B^2(r)} + \frac{r\frac{d}{dr}A(r)}{2A(r)B(r)} - 1 + \frac{1}{B(r)} \\
 & \frac{\left(-rA(r)\frac{d}{dr}B(r) + rB(r)\frac{d}{dr}A(r) - 2(B(r)-1)A(r)B(r)\right)\sin^2(\theta)}{2A(r)B^2(r)}
 \end{aligned}$$

Which as one can see, with a trivial amount of algebra, is exactly what we are supposed to show.

### c) Maxwell equation

From the program mentioned above, we have  $|g| = -r^4 AB \sin^2 \theta$ . The inhomogeneous Maxwell equation is

$$\nabla_\mu F^{\mu\nu} = \frac{1}{\sqrt{|g|}} \partial_\mu \left( \sqrt{|g|} F^{\mu\nu} \right) = j^\nu.$$

We have that  $F_{\mu\nu} = -E_\mu$ , and from the isometric property  $E_\theta = E_\phi = 0$  (which actually follows from the hairy ball theorem).  $j^0 = \rho$ , where  $\rho$  is the charge density, which is zero everywhere except at the point charge. Thus

$$\partial_\mu \left( \sqrt{|g|} F^{\mu 0} \right) = 0.$$

Given that  $E_r$  is the only non-zero component of  $E$ , and the relation between  $F$  and  $E$ , we get

$$\partial_r \left( i r^2 \sin \theta \sqrt{AB} F^{r0} \right) = 0.$$

Which we may write more conveniently as

$$\partial_r \left( r^2 \sqrt{AB} F^{r0} \right) = 0,$$

so that

$$r^2 \sqrt{AB} F^{r0} = C$$

where  $C$  is some constant. Using

$$F^{r0} = g^{rr} F_{r0} g^{00} = -\frac{F_{r0}}{AB} = \frac{E_r}{AB},$$

where we used that  $g$  is diagonal, we conclude that

$$r^2 \sqrt{AB} F^{r0} = C \Rightarrow E_r = \frac{C \sqrt{AB}}{r^2}.$$

Lastly remains determining  $C$ . As we move to  $r \rightarrow \infty$ , we must approach Minkowski space, that is  $A = B = 1$ . Thus, applying Gauss's law at large  $r$ , we simply get

$$\int dS E(r) = Q,$$

and we identify that  $E = \frac{Q}{4\pi r^2}$ . Comparing with our expression for  $E$ , we see that  $C = \frac{Q}{4\pi}$ .

## d) Electromagnetic stress tensor and Einstein equations

Again, we make use of the aforementioned framework. The stress tensor is defined as

$$T^{\mu\nu} = -F^{\mu\alpha} F_\alpha^\nu + \frac{1}{4} g^{\mu\nu} F_{\alpha\beta} F^{\alpha\beta}.$$

We implement it in Python

```

1 def stressTensor(F, g-):
2     """Compute stress tensor T from EM-field F"""
3     g = ginv(g-)
4     d = g-[:,0].size
5     T = np.zeros((d,d), dtype=object)
6     for mu in range(d):
7         for nu in range(d):
8             T[mu, nu] = F[mu, :] @ (g- @ F)[:, nu] - sympy.Rational
9             (1, 4) * g[mu, nu] * np.tensordot(g- @ F @ g-, F)
10
11         return T
12
13 def lower(T):
14     """Lowers the indices of the (upper) tensor T"""
15     return g- @ T @ g-

```

Here, we also defined the function lower because we need the stress tensor with lower indices. Using our knowledge about  $E$ , and that there is no  $B$ -field, we construct  $F$ .

$$F_{\mu\nu} = \begin{bmatrix} 0 & E_r & 0 & 0 \\ -E_r & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Or, in Python code,

```

1 F = np.zeros(g-.shape, dtype=object)
2 Q = sympy.symbols('Q')
3 E = sympy.sqrt(A * B) * Q / (4*sympy.pi*r**2)
4
5 F[1, 0] = - E / (A * B)
6 F[0, 1] = -F[1, 0]
7
8 T = stressTensor(F, g-)
9 T_ = lower(T)
10 displayNonZero(T_)

```

Which outputs

(0,0)

$$-\frac{3Q^2 A(r)}{32\pi^2 r^4}$$

(1,1)

$$\frac{3Q^2 B(r)}{32\pi^2 r^4}$$

(2,2)

$$\frac{Q^2}{32\pi^2 r^2}$$

(3,3)

$$\frac{Q^2 \sin^2(\theta)}{32\pi^2 r^2}$$

Now, to show that the Einstein equation

$$G_{\mu\nu} = -\kappa T_{\mu\nu}$$

reduces to

$$R_{\mu\nu} = -\kappa T_{\mu\nu}$$

we must employ a trick. Firstly, note

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu}.$$

Consider

$$G^\nu_\mu = R^\nu_\mu - \frac{1}{2} R g^\nu_\mu = -\kappa T^\nu_\mu.$$

If we take the trace on both sides, and denote by only the letter of the tensor its trace, we get

$$R - 2R = -\kappa T = 0.$$

We here used that the trace of  $g$  is 4 ( $g^\nu_\mu = \delta^\nu_\mu$ ), and that the electromagnetic stress tensor is traceless. Thus,  $R = 0$ , and the Einstein equation reduces as we wanted to show. Using our framework, we may find the explicit form of the (non-trivial) Einstein equations.

```

k = sympy.Symbol("k")
for i in range(4):
    print(f'({i}, {i})')
    display(sympy.Eq(ricci_[i, i], -k * T_[i, i]))

```

Giving

(0,0)

$$-\frac{\frac{d^2}{dr^2}A(r)}{2B(r)} + \frac{\frac{d}{dr}A(r)\frac{d}{dr}B(r)}{4B^2(r)} + \frac{\left(\frac{d}{dr}A(r)\right)^2}{4A(r)B(r)} - \frac{\frac{d}{dr}A(r)}{rB(r)} = \frac{3Q^2kA(r)}{32\pi^2r^4}$$

(1,1)

$$\frac{\frac{d^2}{dr^2}A(r)}{2A(r)} - \frac{\frac{d}{dr}A(r)\frac{d}{dr}B(r)}{4A(r)B(r)} - \frac{\left(\frac{d}{dr}A(r)\right)^2}{4A^2(r)} - \frac{\frac{d}{dr}B(r)}{rB(r)} = -\frac{3Q^2kB(r)}{32\pi^2r^4}$$

(2,2)

$$-\frac{r\frac{d}{dr}B(r)}{2B^2(r)} + \frac{r\frac{d}{dr}A(r)}{2A(r)B(r)} - 1 + \frac{1}{B(r)} = -\frac{Q^2k}{32\pi^2r^2}$$

(3,3)

$$-\frac{r\sin^2(\theta)\frac{d}{dr}B(r)}{2B^2(r)} + \frac{r\sin^2(\theta)\frac{d}{dr}A(r)}{2A(r)B(r)} - \frac{(B(r)-1)\sin^2(\theta)}{B(r)} = -\frac{Q^2k\sin^2(\theta)}{32\pi^2r^2}$$

### e) Finding the relation $AB$

We notice that taking

$$BR_{00} + AR_{11} = -\kappa(BT_{00} + AT_{11})$$

vastly simplifies our expression, as the right hand side is zero. Thus, after computing the LHS

$$-\frac{A(r)\frac{d}{dr}B(r)}{rB(r)} - \frac{\frac{d}{dr}A(r)}{r} = 0.$$

Multiplying away  $r$  and raising the  $B$ , we recognize this as simply

$$\frac{d}{dr}(AB) = 0.$$

As we may rescale our  $t$  as we want, we get

$$AB = \text{const} = 1.$$

### f) Determining $A$ and $B$

We have

$$R_{22} = \frac{1}{B} - 1 + \frac{r}{2B}\left(\frac{A'}{A} - \frac{B'}{B}\right) = -\kappa T_{22}.$$

Inserting  $A = \frac{1}{B}$  and solving using our framework, we get

$$B(r) = \frac{32\pi^2 r^2}{C_1 r + Q^2 k + 32\pi^2 r^2}$$

$$A(r) = \frac{C_1}{32\pi^2 r} + \frac{Q^2 k}{32\pi^2 r^2} + 1$$

We expect to regain the Schwarzschild solution as  $Q \rightarrow 0$ , so we have

$$\lim_{Q \rightarrow 0} A(r) = \frac{C_1}{32\pi^2 r} + 1 = 1 - \frac{2GM}{r}.$$

We here inserted  $g_{00}$  for the Schwarzschild metric. Thus,  $C_1 = -2GM \cdot 32\pi^2 = -64GM\pi^2$ . And we get, after inserting  $\kappa = 8\pi G$ ,

$$A(r) = 1 - \frac{2GM}{r} + \frac{GQ^2}{4\pi r^2}$$

$$B(r) = \left(1 - \frac{2GM}{r} + \frac{GQ^2}{4\pi r^2}\right)^{-1}$$

## g) Singularities

Similarly to Schwarzschild, we get a singularity at  $r = 0$  from  $g_{tt}$  and one in  $g_{rr}$  from the denominator going to zero. Let us consider the second one, which comes from  $B$ . Since  $B = A^{-1}$ , we need to find the zeros of  $A$ . Simply solving using our framework, and with the help of sympy, we get that the zero points of  $A$  are

$$r = GM \left( 1 \pm \sqrt{1 - \frac{Q^2}{4\pi GM^2}} \right).$$

We are happy to see that for  $Q \rightarrow 0$ , this reduces to  $r = 0$  and  $r = 2GM$ , which is as expected.