```
kindr::WrenchBase<
  Wrench< PrimType_ > >

kindr::VectorBase<
  Vector< PhysicalType
  _, PrimType_, Dimension_ > >

kindr::Vector< PhysicalType
  ::Torque, PrimType_, 3 >

Eigen::Matrix< PrimType
  _, Dimension_, 1 >

kindr::Vector< PhysicalType
  ::Force, PrimType_, 3 >

torque_

force_

kindr::Wrench< PrimType_ >
```