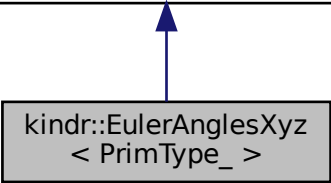


```
kindr::RotationBase  
< EulerAnglesXyz< PrimType_ > >
```



A diagram illustrating a relationship between two C++-like type definitions. A light gray box at the bottom contains the text 'kindr::EulerAnglesXyz < PrimType_ >'. A blue arrow points vertically upwards from this box to a white box at the top. The white box contains the text 'kindr::RotationBase < EulerAnglesXyz< PrimType_ > >'. This represents that EulerAnglesXyz inherits from or is a specialization of RotationBase.

```
kindr::EulerAnglesXyz  
< PrimType_ >
```