

```
kindr::RotationDiffBase  
< EulerAnglesZyxDiff<  
  PrimType_ > >
```



A diagram illustrating a relationship between two C++-like type definitions. A light gray box at the bottom contains the text 'kindr::EulerAnglesZyxDiff < PrimType\_ >'. A blue arrow points upwards from this box to a white box at the top. The white box contains the text 'kindr::RotationDiffBase < EulerAnglesZyxDiff< PrimType\_ > >'. This indicates that 'kindr::RotationDiffBase' is a specialization or derived type of 'kindr::EulerAnglesZyxDiff'.

```
kindr::EulerAnglesZyxDiff  
< PrimType_ >
```