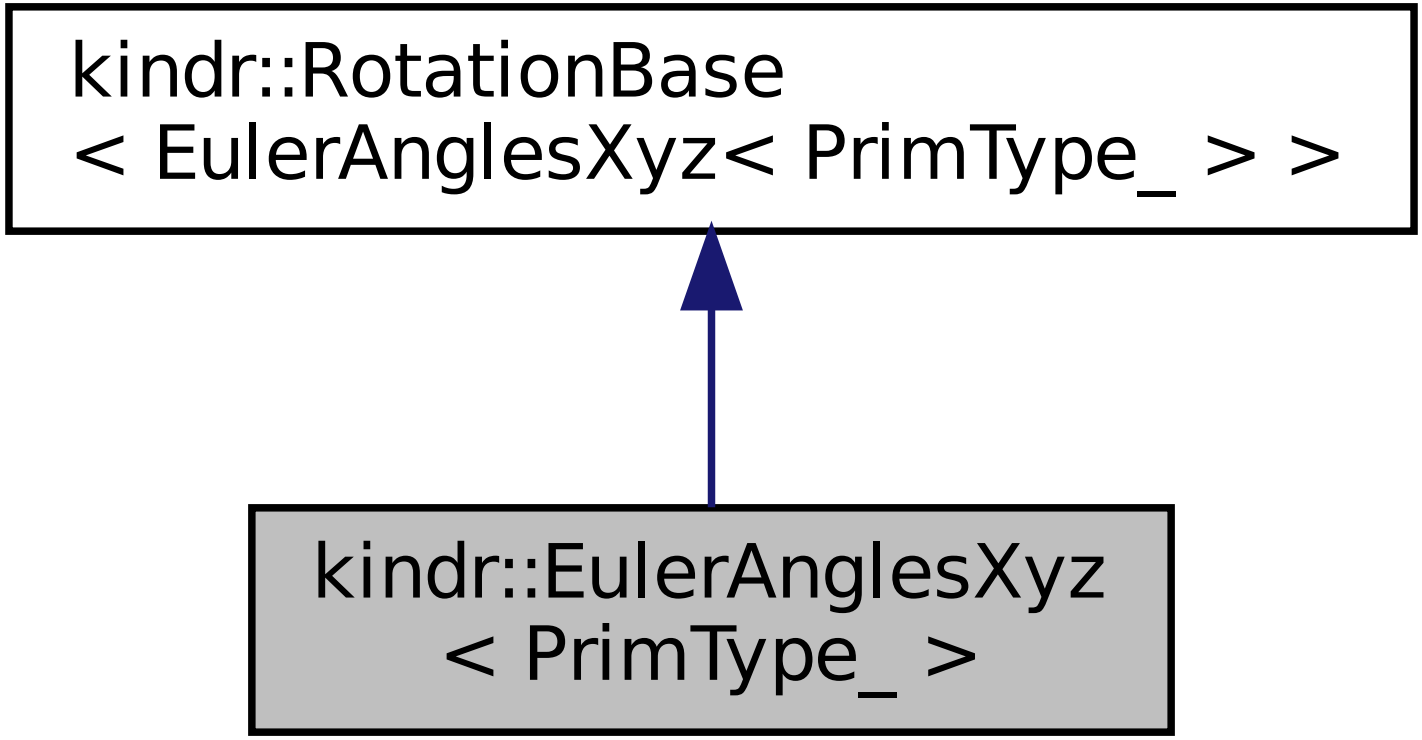
kindr::RotationBase
< EulerAnglesXyz< PrimType_ > >
kindr::EulerAnglesXyz
< PrimType_ >