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# Human Follower Robot

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Department of Computer Science and Engineering  
Bangladesh University of Engineering and Technology

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# Motivation

Human  
Follower  
Robot

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- Average Human carrying capacity is near 40 kg (1 ton)

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- But scientists suggest humans carry no more than 25kg for a healthy lifestyle
- Carrying items are especially hard when they are distributed into small parts, e.g. 20 small boxes of paper

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- Average Human carrying capacity is near 40 kg (1 ton)
- But scientists suggest humans carry no more than 25kg for a healthy lifestyle
- Carrying items are especially hard when they are distributed into small parts, e.g. 20 small boxes of paper
- Even harder if one wants to carry way above his capacity!  
human labor is must

# Our Proposal

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And human labor is costly, time consuming and  
inefficient!  
**Solutions???**



# Our Proposal

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## Meet Our project proposal - RFID Based Human Follower Carrier

# Description

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**Our micro-controller based project is basically a carrying cart. But it does so much more than carrying!**



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- The user basically carries a **small card** which comes with a particular cart, and the cart detects & follows him, carrying the things he puts in it

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- The cart can also avoid basic obstacles on its path

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- The user basically carries a **small card** which comes with a particular cart, and the cart detects & follows him, carrying the things he puts in it
- The cart can also avoid basic obstacles on its path
- The user can also feed basic commands to the cart like **parking** in a place, **summoning** it again if in the cart's range

# Useful Scenarios

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**There can be many uses to this cheap but user-friendly technology. Some are as follows:**

- Shopping mall cart
- Airport luggage carrier
- OT Table
- Machinery Workbench
- Construction items carrier

...and much more!

# Components : Processing Unit

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## Components needed to build this project (tentative):

- ATmega32
- Motor Driver Processor

# Components : Sensors

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## **Components needed to build this project (tentative):**

- Ultrasonic sensor (more range), or
- Infrared sensor (more precise)

\*subject to implementation

# Components : Actuators

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## Components needed to build this project (tentative):

- TT Gear Motor
- Servo Motor

# Components : RFID Comm.

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## Components needed to build this project (tentative):

- RF Nano, or
- NRF24LO1+RF Module



# Components : Others

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## **Components needed to build this project (tentative):**

- Wheels
- 18650 Li-on Battery
- 18650 Battery Holder
- Male and Female Jumper wire
- Base materials
- DC Power Switch etc.

# Cost Effectiveness

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Let, average price for making a prototype cart = **3-4k BDT.**

Imagine a warehouse scenario with 10 human workers.

Each worker is paid =  
10k/month

So, total cost =  
 $10 \times 10k = 1lac/month$

Each cart costs = 4k

So, total cost  
=  $10 \times 4k$   
= 40k for lifetime

**So automating this warehouse with our cart cuts cost and increases productivity!**

# Conclusion

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Since this is a really **cheap** setup, it could be used with any carrier that carries items in any scenario and make the process much easier, cost effective and user friendly.

**Why carry things, when you can have your smartcart to carry it for you?**

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## Thank You!

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