

TRAN Hoang Tung

The Discretetime Fourier Transform (DTFT)

DTFT Properties

Frequency Presentation of LT Systems

Sampling & Reconstruction

Discrete-time Fourier Analysis

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The Discrete-time Fourier Transform (DTFT)

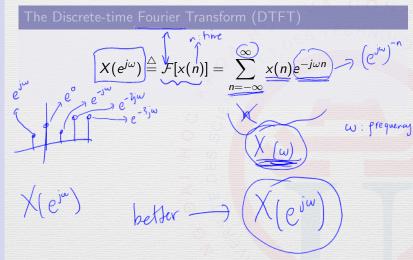
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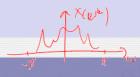
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Two Properties



Periodicity

$$X(e^{j\omega}) \stackrel{?}{=} X(e^{j[\omega+2\pi]})$$

Implication: We need only one period of $X(e^{j\omega})$

$$X(e^{j\omega}) = \sum_{k=0}^{k+0} x(k) \cdot e^{-jn\omega}$$

$$X(e^{j[\omega+in]}) = \sum_{-\infty}^{\infty}$$

Two Properties

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Periodicity

$$X(e^{j\omega}) = X(e^{j[\omega+2\pi]})$$

Implication: We need only one period of $X(e^{j\omega})$



Symmetry

For real-valued x(n)

 $X(e^{-j\omega}) = X^*(e^{j\omega})^{\tau} = e^{-j\omega}$

Implication: We now need to consider only a half period of $X(e^{j\omega})$





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Linearity

$$\mathcal{F}[\underline{a_1x_1(n) + a_2x_2(n)}] = \underline{\underline{a_1}}\mathcal{F}[x_1(n)] + \underline{a_2}\mathcal{F}[x_2(n)]$$

$$(e^{j\omega}) = a_1 \times (e^{j\omega}) + a_2 \times (e^{j\omega})$$

$$= \left[\chi(n-5)\right] = \chi(e^{j\omega})$$

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Linearity

$$\mathcal{F}[a_1x_1(n) + a_2x_2(n)] = a_1\mathcal{F}[x_1(n)] + a_2\mathcal{F}[x_2(n)]$$

Time-shifting

$$\mathcal{F}[x(n-k)] = X(e^{j\omega})e^{-j\omega k}$$

Properties (1)

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Linearity

$$\mathcal{F}[a_1x_1(n) + a_2x_2(n)] = a_1\mathcal{F}[x_1(n)] + a_2\mathcal{F}[x_2(n)]$$

Time-shifting

$$\mathcal{F}[x(n-k)] = X(e^{j\omega})e^{-j\omega k}$$

Frequency-shifting

$$\mathcal{F}[x(n)e^{j\omega_0n}] = X(e^{j(\omega-\omega_0)})$$

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Conjugation

$$\mathcal{F}[x^*(n)] = X^*(e^{-j\omega})$$

$$(a+b)^* = a^* + b^*$$

$$(a+b)^* = a^$$

Properties (2)

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Conjugation

$$\mathcal{F}[x^*(n)] = X^*(e^{-j\omega})$$

Folding

$$\mathcal{F}[x(-n)] = X(e^{-j\omega})$$

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Conjugation

$$\mathcal{F}[x^*(n)] = X^*(e^{-j\omega})$$

Folding

$$\mathcal{F}[x(-n)] = X(e^{-j\omega})$$

Convolution

$$\mathcal{F}[x_1(n) * x_2(n)] = \mathcal{F}[x_1(n)]\mathcal{F}[x_2(n)] = X_1(e^{j\omega})X_2(e^{j\omega})$$



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Frequency Response

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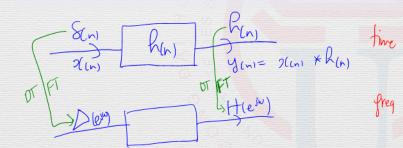
Frequency Presentation of LTI Systems

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Definition

The <u>DTFT</u> of an impulse response is called the frequency response (or transfer function) of an LTI system

$$H(e^{j\omega}) \stackrel{\triangle}{=} \mathcal{F}[h(n)] = \sum_{n=-\infty}^{\infty} h(n)e^{-j\omega n}$$



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Response to a Complex Exponential $e^{j\omega_0 n}$

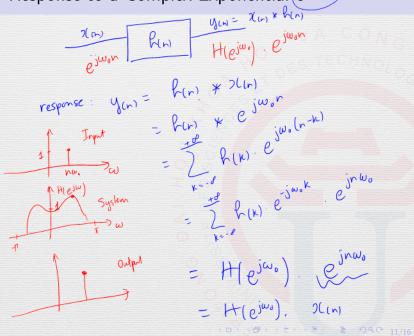
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Response to a Complex Exponential $e^{j\omega_0 n}$

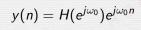
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Response to Sinusoidal $x(n) = A\cos(\omega_0 n\theta_0)$

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Response to Sinusoidal $x(n) = A\cos(\omega_0 n\theta_0)$

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$$y(n) = A|H(e^{j\omega_0})|\cos(\omega_0 n + \theta_0 + \angle H(e^{j\omega_0}))$$

This response is called the steady-state response, denoted by $y_{ss}(n)$.



Frequency Response from Difference Equations

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Frequency Presentation of LTI **Systems**

Given an LTI system

$$y(n) + \sum_{l=1}^{N} a_{l}y(n-l) = \sum_{m=0}^{M} b_{m}x(n-m)$$

$$y(n) - 4y(n-3) + 3y(n-1) = 2(1)$$

$$y(n) + \sum_{l=1}^{N} a_{l}y(n-l) = \sum_{m=0}^{M} b_{m}x(n-m)$$

$$y(n) + \sum_{l=1}^{N} a_{l}y(n-l) = \sum_{l=1}^{M} b_{m}x(n-m)$$

$$y(n)$$

Frequency Response from Difference Equations

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Given an LTI system

$$y(n) + \sum_{l=1}^{N} a_l y(n-l) = \sum_{m=0}^{M} b_m x(n-m)$$

its frequency response is

$$H(e^{j\omega}) = \frac{\sum_{m=0}^{M} b_m e^{-j\omega m}}{1 + \sum_{l=1}^{N} a_l e^{-j\omega l}}$$



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Sampling

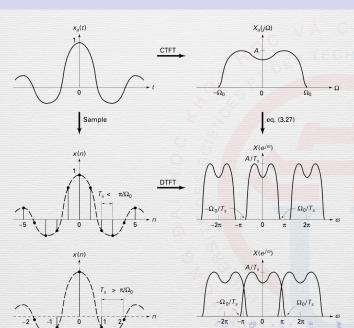
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