# Languages and Algorithms for Artificial Intelligence (Module 2)

Last update: 22 December 2023

# **Contents**

2.1       Syntax         2.2       Semantics         2.3       Substitution         3       Logic programming         3.1       Syntax         3.2       Semantics         3.2.1       State transition system         4       Prolog         4.1       Syntax         4.2       Semantics         4.3       Arithmetic operators         4.4       Lists         4.5       Cut         4.6       Negation         4.7       Meta predicates         4.8       Meta-interpreters	_
1.2.1 Normal forms         1.3 Reasoning         1.3.1 Natural deduction         2 First order logic         2.1 Syntax         2.2 Semantics         2.3 Substitution         3 Logic programming         3.1 Syntax         3.2 Semantics         3.2.1 State transition system         4 Prolog         4.1 Syntax         4.2 Semantics         4.3 Arithmetic operators         4.4 Lists         4.5 Cut         4.6 Negation         4.7 Meta predicates         4.8 Meta-interpreters         5 Constraint programming         5.1 Constraint logic programming (CLP)         5.1.1 Syntax	1
1.3 Reasoning	1
1.3.1 Natural deduction   2 First order logic   2.1 Syntax	
1.3.1 Natural deduction   2 First order logic   2.1 Syntax	
2.1 Syntax 2.2 Semantics 2.3 Substitution  3 Logic programming 3.1 Syntax 3.2 Semantics 3.2.1 State transition system  4 Prolog 4.1 Syntax 4.2 Semantics 4.3 Arithmetic operators 4.4 Lists 4.5 Cut 4.6 Negation 4.7 Meta predicates 4.8 Meta-interpreters  5 Constraint programming 5.1 Constraint logic programming (CLP) 5.1.1 Syntax	
2.2       Semantics         2.3       Substitution         3       Logic programming         3.1       Syntax         3.2       Semantics         3.2.1       State transition system         4       Prolog         4.1       Syntax         4.2       Semantics         4.3       Arithmetic operators         4.4       Lists         4.5       Cut         4.6       Negation         4.7       Meta predicates         4.8       Meta-interpreters         5       Constraint programming         5.1       Constraint logic programming (CLP)         5.1.1       Syntax	Ę
2.3 Substitution  3 Logic programming 3.1 Syntax 3.2 Semantics 3.2.1 State transition system  4 Prolog 4.1 Syntax 4.2 Semantics 4.3 Arithmetic operators 4.4 Lists 4.5 Cut 4.6 Negation 4.7 Meta predicates 4.8 Meta-interpreters  5 Constraint programming 5.1 Constraint logic programming (CLP) 5.1.1 Syntax	
3.1 Syntax	6
3.1 Syntax 3.2 Semantics 3.2.1 State transition system  4 Prolog 4.1 Syntax 4.2 Semantics 4.3 Arithmetic operators 4.4 Lists 4.5 Cut 4.6 Negation 4.7 Meta predicates 4.8 Meta-interpreters  5 Constraint programming 5.1 Constraint logic programming (CLP) 5.1.1 Syntax	6
3.1 Syntax 3.2 Semantics 3.2.1 State transition system  4 Prolog 4.1 Syntax 4.2 Semantics 4.3 Arithmetic operators 4.4 Lists 4.5 Cut 4.6 Negation 4.7 Meta predicates 4.8 Meta-interpreters  5 Constraint programming 5.1 Constraint logic programming (CLP) 5.1.1 Syntax	8
3.2 Semantics 3.2.1 State transition system  4 Prolog 4.1 Syntax 4.2 Semantics 4.3 Arithmetic operators 4.4 Lists 4.5 Cut 4.6 Negation 4.7 Meta predicates 4.8 Meta-interpreters  5 Constraint programming 5.1 Constraint logic programming (CLP) 5.1.1 Syntax	8
4 Prolog 4.1 Syntax	
4.1 Syntax	8
4.1 Syntax	10
4.2 Semantics 4.3 Arithmetic operators 4.4 Lists 4.5 Cut 4.6 Negation 4.7 Meta predicates 4.8 Meta-interpreters  Constraint programming 5.1 Constraint logic programming (CLP) 5.1.1 Syntax	10
4.3 Arithmetic operators  4.4 Lists  4.5 Cut  4.6 Negation  4.7 Meta predicates  4.8 Meta-interpreters  5 Constraint programming  5.1 Constraint logic programming (CLP)  5.1.1 Syntax	
4.4 Lists	
4.5 Cut  4.6 Negation	
4.6 Negation	
4.7 Meta predicates	
4.8 Meta-interpreters	
5.1 Constraint logic programming (CLP)	
5.1 Constraint logic programming (CLP)	18
5.1.1 Syntax	18
· ·	
0.1.4 Semanucs	
5.2 MiniZinc	

## 1 Propositional logic

## 1.1 Syntax

**Syntax** Rules and symbols to define well-formed sentences.

Syntax

The symbols of propositional logic are:

Proposition symbols  $p_0, p_1, \ldots$ 

**Connectives**  $\land \lor \rightarrow \leftrightarrow \neg \bot ()$ 

Well-formed formula The definition of a well-formed formula is recursive:

Well-formed formula

- An atomic proposition is a well-formed formula.
- If S is well-formed,  $\neg S$  is well-formed.
- If  $S_1$  and  $S_2$  are well-formed,  $S_1 \wedge S_2$  is well-formed.
- If  $S_1$  and  $S_2$  are well-formed,  $S_1 \vee S_2$  is well-formed.

Note that the implication  $S_1 \to S_2$  can be written as  $\neg S_1 \lor S_2$ .

The BNF definition of a formula is:

$$F := \texttt{atomic\_proposition} \, | \, F \wedge F \, | \, F \vee F \, | \, F \rightarrow F \, | \, F \leftrightarrow F \, | \, \neg F \, | \, (F)$$

#### 1.2 Semantics

**Semantics** Rules to associate a meaning to well-formed sentences.

Semantics

**Model theory** What is true.

**Proof theory** What is provable.

**Interpretation** Given a propositional formula F of n atoms  $\{A_1, \ldots, A_n\}$ , an interpretation  $\mathcal{I}$  of F is is a pair (D, I) where:

Interpretation

- D is the domain. Truth values in the case of propositional logic.
- I is the interpretation mapping that assigns to the atoms  $\{A_1, \ldots, A_n\}$  an element of D.

Note: given a formula F of n distinct atoms, there are  $2^n$  district interpretations.

Model **Model** If F is true under the interpretation  $\mathcal{I}$ , we say that  $\mathcal{I}$  is a model of F ( $\mathcal{I} \models F$ ).

Valid formula **Valid formula** A formula F is valid (tautology) iff it is true in all the possible interpretations. It is denoted as  $\models F$ .

**Invalid formula** A formula F is invalid iff it is not valid (:0).

Invalid formula

In other words, there is at least an interpretation where F is false.

**Inconsistent formula** A formula F is inconsistent (unsatisfiable) iff it is false in all the possible interpretations.

Inconsistent formula

Consistent formula A formula F is consistent (satisfiable) iff it is not inconsistent.

Consistent formula

In other words, there is at least an interpretation where F is true.

**Decidability** A logic is decidable if there is a terminating method to decide if a formula is valid.

Decidability

Propositional logic is decidable.

Truth table Useful to define the semantics of connectives.

Truth table

- $\neg S$  is true iff S is false.
- $S_1 \wedge S_2$  is true iff  $S_1$  is true and  $S_2$  is true.
- $S_1 \vee S_2$  is true iff  $S_1$  is true or  $S_2$  is true.
- $S_1 \to S_2$  is true iff  $S_1$  is false or  $S_2$  is true.
- $S_1 \leftrightarrow S_2$  is true iff  $S_1 \to S_2$  is true and  $S_1 \leftarrow S_2$  is true.

 $\textbf{Evaluation} \ \ \text{The connectives of a propositional formula are evaluated in the order:}$ 

Evaluation order

$$\leftrightarrow, \rightarrow, \vee, \wedge, \neg$$

Formulas in parenthesis have higher priority.

**Logical consequence** Let  $\Gamma = \{F_1, \dots, F_n\}$  be a set of formulas (premises) and G a formula (conclusion). G is a logical consequence of  $\Gamma$  ( $\Gamma \models G$ ) if in all the possible interpretations  $\mathcal{I}$ , if  $F_1 \wedge \cdots \wedge F_n$  is true, G is true.

Logical consequence

**Logical equivalence** Two formulas F and G are logically equivalent  $(F \equiv G)$  iff the truth values of F and G are the same under the same interpretation. In other words,  $F \equiv G \iff F \models G \land G \models F$ .

Logical equivalence

Common equivalences are:

Commutativity :  $(P \wedge Q) \equiv (Q \wedge P)$  and  $(P \vee Q) \equiv (Q \vee P)$ 

**Associativity** :  $((P \land Q) \land R) \equiv (P \land (Q \land R))$  and  $((P \lor Q) \lor R) \equiv (P \lor (Q \lor R))$ 

**Double negation elimination** :  $\neg(\neg P) \equiv P$ 

Contraposition :  $(P \rightarrow Q) \equiv (\neg Q \rightarrow \neg P)$ 

Implication elimination :  $(P \to Q) \equiv (\neg P \lor Q)$ 

**Biconditional elimination** :  $(P \leftrightarrow Q) \equiv ((P \rightarrow Q) \land (Q \rightarrow P))$ 

**De Morgan** :  $\neg(P \land Q) \equiv (\neg P \lor \neg Q)$  and  $\neg(P \lor Q) \equiv (\neg P \land \neg Q)$ 

**Distributivity of**  $\wedge$  **over**  $\vee$  :  $(P \wedge (Q \vee R)) \equiv ((P \wedge Q) \vee (P \wedge R))$ 

**Distributivity of**  $\vee$  **over**  $\wedge$  :  $(P \vee (Q \wedge R)) \equiv ((P \vee Q) \wedge (P \vee R))$ 

#### 1.2.1 Normal forms

**Negation normal form (NNF)** A formula is in negation normal form iff negations appear only in front of atoms (i.e. not parenthesis).

Negation normal form

Conjunctive normal form (CNF) A formula F is in conjunctive normal form iff:

Conjunctive normal form

• it is in negation normal form;

• it has the form  $F := F_1 \wedge F_2 \cdots \wedge F_n$ , where each  $F_i$  (clause) is a disjunction of literals

Example.

$$(\neg P \lor Q) \land (\neg P \lor R)$$
 is in CNF.  
 $\neg (P \lor Q) \land (\neg P \lor R)$  is not in CNF (not in NNF).

**Disjunctive normal form (DNF)** A formula F is in disjunctive normal form iff:

Disjunctive normal form

- it is in negation normal form;
- it has the form  $F := F_1 \vee F_2 \cdots \vee F_n$ , where each  $F_i$  is a conjunction of literals.

## 1.3 Reasoning

Reasoning method Systems to work with symbols.

Reasoning method

Given a set of formulas  $\Gamma$ , a formula F and a reasoning method E, we denote with  $\Gamma \vdash^E F$  the fact that F can be deduced from  $\Gamma$  using the reasoning method E.

**Sound** A reasoning method E is sound iff:

Soundness

$$(\Gamma \vdash^E F) \to (\Gamma \models F)$$

**Complete** A reasoning method E is complete iff:

Completeness

$$(\Gamma \models F) \to (\Gamma \vdash^E F)$$

**Deduction theorem** Given a set of formulas  $\{F_1, \ldots, F_n\}$  and a formula G:

Deduction theorem

$$(F_1 \wedge \cdots \wedge F_n) \models G \iff \models (F_1 \wedge \cdots \wedge F_n) \rightarrow G$$

Proof.

 $\rightarrow$  ) By hypothesis  $(F_1 \wedge \cdots \wedge F_n) \models G$ .

So, for each interpretation  $\mathcal{I}$  in which  $(F_1 \wedge \cdots \wedge F_n)$  is true, G is also true. Therefore,  $\mathcal{I} \models (F_1 \wedge \cdots \wedge F_n) \to G$ .

Moreover, for each interpretation  $\mathcal{I}'$  in which  $(F_1 \wedge \cdots \wedge F_n)$  is false,  $(F_1 \wedge \cdots \wedge F_n) \to G$  is true. Therefore,  $\mathcal{I}' \models (F_1 \wedge \cdots \wedge F_n) \to G$ .

In conclusion,  $\models (F_1 \land \cdots \land F_n) \rightarrow G$ .

 $\leftarrow$  ) By hypothesis  $\models (F_1 \land \cdots \land F_n) \rightarrow G$ . Therefore, for each interpretation where  $(F_1 \land \cdots \land F_n)$  is true, G is also true.

In conclusion,  $(F_1 \wedge \cdots \wedge F_n) \models G$ .

**Refutation theorem** Given a set of formulas  $\{F_1, \ldots, F_n\}$  and a formula G:

Refutation theorem

$$(F_1 \wedge \cdots \wedge F_n) \models G \iff F_1 \wedge \cdots \wedge F_n \wedge \neg G$$
 is inconsistent

Note: this theorem is not accepted in intuitionistic logic.

*Proof.* By definition,  $(F_1 \wedge \cdots \wedge F_n) \models G$  iff for every interpretation where  $(F_1 \wedge \cdots \wedge F_n)$  is true, G is also true. This requires that there are no interpretations where  $(F_1 \wedge \cdots \wedge F_n)$  is true and G false. In other words, it requires that  $(F_1 \wedge \cdots \wedge F_n \wedge \neg G)$  is inconsistent.

#### 1.3.1 Natural deduction

- **Proof theory** Set of rules that allows to derive conclusions from premises by exploiting Proof theory syntactic manipulations.
- **Natural deduction** Set of rules to introduce or eliminate connectives. We consider a subset  $\{\land, \rightarrow, \bot\}$  of functionally complete connectives.

Natural deduction for propositional logic

Natural deduction can be represented using a tree like structure:

The conclusion is true when the hypothesis are able to prove the premise. Another tree can be built on top of premises to prove them.

**Introduction** Usually used to prove the conclusion by splitting it.

Introduction rules

$$\frac{\psi \quad \varphi}{\varphi \wedge \psi} \wedge \mathbf{I} \qquad \qquad \vdots \\ \frac{\psi}{\varphi \rightarrow \psi} \rightarrow \mathbf{I}$$

**Elimination** Usually used to exploit hypothesis and derive a conclusion.

Elimination rules

$$\frac{\varphi \wedge \psi}{\varphi} \wedge \mathbf{E} \qquad \frac{\varphi \wedge \psi}{\psi} \wedge \mathbf{E} \qquad \frac{\varphi \qquad \varphi \rightarrow \psi}{\psi} \rightarrow \mathbf{E}$$

**Ex falso sequitur quodlibet** From contradiction, anything follows. This can be used when we have two contradicting hypothesis.

Ex falso sequitur quodlibet

$$\frac{\perp}{\varphi}$$

**Reductio ad absurdum** Assume the opposite and prove a contradiction (not accepted in intuitionistic logic).

Reductio ad absurdum

$$\begin{bmatrix}
\neg \varphi \\
\vdots \\
\frac{\perp}{\varphi} \text{ RAA}$$

## 2 First order logic

## 2.1 Syntax

The symbols of propositional logic are:

Syntax

Constants Known elements of the domain. Do not represent truth values.

Variables Unknown elements of the domain. Do not represent truth values.

**Function symbols** Function  $f^{(n)}$  applied on n constants to obtain another constant.

**Predicate symbols** Function  $P^{(n)}$  applied on n constants to obtain a truth value.

Connectives 
$$\forall \exists \land \lor \rightarrow \neg \leftrightarrow \top \bot$$
 ( )

Using the basic syntax, the following constructs can be defined:

**Term** Denotes elements of the domain.

$$t := \text{constant} \mid \text{variable} \mid f^{(n)}(t_1, \dots, t_n)$$

**Proposition** Denotes truth values.

$$P := \top |\bot| P \land P | P \lor P | P \to P | P \leftrightarrow P | \neg P | \forall x.P | \exists x.P | (P) | P^{(n)}(t_1, \dots, t_n)$$

**Well-formed formula** The definition of well-formed formula in first order logic extends Well-formed formula the one of propositional logic by adding the following conditions:

- If S is well-formed,  $\exists X.S$  is well-formed. Where X is a variable.
- If S is well-formed,  $\forall X.S$  is well-formed. Where X is a variable.

Free variables The universal and existential quantifiers bind their variable within the scope of the formula. Let  $F_v(F)$  be the set of free variables in a formula F,  $F_v$  is defined as follows:

Free variables

- $F_v(p(t)) = \bigcup vars(t)$
- $F_v(\top) = F_v(\bot) = \varnothing$
- $F_v(\neg F) = F_v(F)$
- $F_v(F_1 \wedge F_2) = F_v(F_1 \vee F_2) = F_v(F_1 \to F_2) = F_v(F_1) \cup F_v(F_2)$
- $F_v(\forall X.F) = F_v(\exists X.F) = F_v(F) \setminus \{X\}$

**Closed formula/Sentence** Proposition without free variables.

Sentence

**Theory** Set of sentences.

Theory

**Ground term/Formula** Proposition without variables.

Formula

### 2.2 Semantics

**Interpretation** An interpretation in first order logic  $\mathcal{I}$  is a pair (D, I):

Interpretation

- *D* is the domain of the terms.
- *I* is the interpretation function such that:
  - $-I(f):D^n\to D$  for every n-ary function symbol.
  - $-I(p)\subseteq D^n$  for every n-ary predicate symbol.

**Variable evaluation** Given an interpretation  $\mathcal{I} = (D, I)$  and a set of variables  $\mathcal{V}$ , a variable variable evaluation is evaluated through  $\eta : \mathcal{V} \to D$ .

**Model** Given an interpretation  $\mathcal{I}$  and a formula F,  $\mathcal{I}$  models F ( $\mathcal{I} \models F$ ) when  $\mathcal{I}, \eta \models F$  Model for every variable evaluation  $\eta$ .

A sentence S is:

**Valid** S is satisfied by every interpretation  $(\forall \mathcal{I} : \mathcal{I} \models S)$ .

**Satisfiable** S is satisfied by some interpretations  $(\exists \mathcal{I} : \mathcal{I} \models S)$ .

**Falsifiable** S is not satisfied by some interpretations  $(\exists \mathcal{I} : \mathcal{I} \not\models S)$ .

**Unsatisfiable** S is not satisfied by any interpretation  $(\forall \mathcal{I} : \mathcal{I} \not\models S)$ .

**Logical consequence** A sentence  $T_1$  is a logical consequence of  $T_2$  ( $T_2 \models T_1$ ) if every Logical consequence model of  $T_2$  is also model of  $T_1$ :

$$\mathcal{I} \models T_2 \rightarrow \mathcal{I} \models T_1$$

**Theorem 2.2.1.** It is undecidable to determine if a first order logic formula is a tautology.

**Equivalence** A sentence  $T_1$  is equivalent to  $T_2$  if  $T_1 \models T_2$  and  $T_2 \models T_1$ .

Equivalence

**Theorem 2.2.2.** The following statements are equivalent:

- 1.  $F_1, \ldots, F_n \models G$ .
- 2.  $(\bigwedge_{i=1}^n F_i) \to G$  is valid.
- 3.  $(\bigwedge_{i=1}^n F_i) \land \neg G$  is unsatisfiable.

#### 2.3 Substitution

**Substitution** A substitution  $\sigma: \mathcal{V} \to \mathcal{T}$  is a mapping from variables to terms. It is written as  $\{X_1 \mapsto t_1, \dots, X_n \mapsto t_n\}$ .

The application of a substitution is the following:

- $p(t_1,\ldots,t_n)\sigma=p(t_1\sigma,\ldots,t_n\sigma)$
- $f(t_1,\ldots,t_n)\sigma = fp(t_1\sigma,\ldots,t_n\sigma)$
- $\perp \sigma = \perp$  and  $\top \sigma = \top$
- $(\neg F)\sigma = (\neg F\sigma)$
- $(F_1 \star F_2)\sigma = (F_1\sigma \star F_2\sigma)$  for  $\star \in \{\land, \lor, \rightarrow\}$

- $(\forall X.F)\sigma = \forall X'(F\sigma[X\mapsto X'])$  where X' is a fresh variable (i.e. does not appear in F).
- $(\exists X.F)\sigma = \exists X'(F\sigma[X\mapsto X'])$  where X' is a fresh variable.

**Unifier** A substitution  $\sigma$  is a unifier for  $e_1, \ldots, e_n$  if  $e_1 \sigma = \cdots = e_n \sigma$ .

Unifier

**Most general unifier** A unifier  $\sigma$  is the most general unifier (MGU) for  $\bar{e} = e_1, \ldots, e_n$  if every unifier  $\tau$  for  $\bar{e}$  is an instance of  $\sigma$  ( $\tau = \sigma \rho$  for some substitution  $\rho$ ). In other words,  $\sigma$  is the smallest substitution to unify  $\bar{e}$ .

Most general unifier

## 3 Logic programming

## 3.1 Syntax

A logic program has the following components (defined using BNF):

**Atom**  $A := p(t_1, \ldots, t_n)$  for  $n \ge 0$ 

Atom

**Goal**  $G := \top \mid \bot \mid A \mid G_1 \wedge G_2$ 

Goal

**Horn clause** A clause with at most one positive literal.

Horn clause

$$K := A \leftarrow G$$

In other words, A and all the literals in G are positive as  $A \leftarrow G = A \vee \neg G$ .

**Program**  $P := K_1 \dots K_m$  for  $m \ge 0$ 

Program

### 3.2 Semantics

#### 3.2.1 State transition system

**State** Pair  $\langle G, \theta \rangle$  where G is a goal and  $\theta$  is a substitution.

State

Intial state  $\langle G, \varepsilon \rangle$ 

Successful final state  $\langle \top, \theta \rangle$ 

Failed final state  $\langle \perp, \varepsilon \rangle$ 

**Derivation** A sequence of states. A derivation can be:

Derivation

**Successful** If the final state is successful.

**Failed** If the final state is failed.

**Infinite** If there is an infinite sequence of states.

Given a derivation, a goal G can be:

**Successful** There is a successful derivation starting from  $\langle G, \varepsilon \rangle$ .

**Finitely failed** All the derivations starting from  $\langle G, \varepsilon \rangle$  are failed.

**Computed answer substitution** Given a goal G and a program P, if there exists a successful derivation  $\langle G, \varepsilon \rangle \mapsto *\langle \top, \theta \rangle$ , then the substitution  $\theta$  is the computed answer substitution of G.

Computed answer substitution

**Transition** Starting from the state  $\langle A \wedge G, \theta \rangle$  of a program P, a transition on the atom A can result in:

Transition

**Unfold** If there exists a clause  $(B \leftarrow H)$  in P and a (most general) unifier  $\beta$  for  $A\theta$  and B, then we have a transition:  $\langle A \wedge G, \theta \rangle \mapsto \langle H \wedge G, \theta \beta \rangle$ .

In other words, we want to prove that  $A\theta$  holds. To do this, we search for a clause that has as conclusion  $A\theta$  and add its premise to the things to prove. If a unification is needed to match  $A\theta$ , we add it to the substitutions of the state.

**Failure** If there are no clauses  $(B \leftarrow H)$  in P with a unifier for  $A\theta$  and B, then we have a transition:  $\langle A \wedge G, \theta \rangle \mapsto \langle \bot, \varepsilon \rangle$ .

Non-determinism A transition has two types of non-determinism:

**Don't-care** Any atom in  $(A \wedge G)$  can be chosen to determine the next state. This affects the length of the derivation (infinite in the worst case).

**Don't-know** Any clause  $(B \to H)$  in P with an unifier for  $A\theta$  and B can be Don't-know chosen. This determines the output of the derivation.

**Selective linear definite resolution** Approach to avoid non-determinism when constructing a derivation.

SLD resolution

Don't-care

**Selection rule** Method to select the atom in the goal to unfold (eliminates don't-care non-determinism).

Selection rule

**SLD tree** Search tree constructed using all the possible clauses according to a selection rule and visited following a search strategy (eliminates don't know non-determinism).

SLD tree

**Theorem 3.2.1** (Soundness). Given a program P, a goal G and a substitution  $\theta$ , if  $\theta$  is a computed answer substitution, then  $P \models G\theta$ .

**Theorem 3.2.2** (Completeness). Given a program P, a goal G and a substitution  $\theta$ , if  $P \models G\theta$ , then it exists a computed answer substitution  $\sigma$  such that  $G\theta = G\sigma\beta$ .

**Theorem 3.2.3.** If a computed answer substitution can be obtained using a selection rule r, it can be obtained also using a different selection rule r'.

Prolog SLD

**Selection rule** Select the leftmost atom.

Tree search strategy Search following the order of definition of the clauses.

This results in a left-to-right, depth-first search of the SLD tree. Note that this may end up in a loop.

## 4 Prolog

It may be useful to first have a look at the "Logic programming" section of Languages and Algorithms for AI (module 2).

## 4.1 Syntax

**Term** Following the first-order logic definition, a term can be a:

Term

- Constant (lowerCase).
- Variable (UpperCase).
- Function symbol (f(t1, ..., tn) with t1, ..., tn terms).

**Atomic formula** An atomic formula has form:

Atomic formula

where p is a predicate symbol and t1, ..., tn are terms.

Note: there are no syntactic distinctions between constants, functions and predicates.

**Clause** A Prolog program is a set of horn clauses:

Horn clause

Fact A.

Rule A :- B1, ..., Bn. (A is the head and B1, ..., Bn the body)

where:

- A, B1, ..., Bn are atomic formulas.
- , represents the conjunction  $(\land)$ .
- :- represents the logical implication  $(\Leftarrow)$ .

Quantification

Quantification

**Facts** Variables appearing in a fact are quantified universally.

$$A(X) . \equiv \forall X : A(X)$$

**Rules** Variables appearing the the body only are quantified existentially. Variables appearing in both the head and the body are quantified universally.

$$A(X) :- B(X, Y) . \equiv \forall X, \exists Y : A(X) \Leftarrow B(X, Y)$$

**Goals** Variables are quantified existentially.

$$:- B(Y). \equiv \exists Y : B(Y)$$

#### 4.2 Semantics

**Execution of a program** A computation in Prolog attempts to prove the goal. Given a program P and a goal :-  $p(t1, \ldots, tn)$ , the objective is to find a substitution  $\sigma$  such that:

$$P \models [p(t1, \ldots, tn)]\sigma$$

In practice, it uses two stacks:

**Execution stack** Contains the predicates the interpreter is trying to prove.

Backtracking stack Contains the choice points (clauses) the interpreter can try.

**SLD resolution** Prolog uses SLD resolution with the following choices:

SLD

**Left-most** Always proves the left-most literal first.

**Depth-first** Applies the predicates following the order of definition.

Note that the depth-first approach can be efficiently implemented (tail recursion) but the termination of a Prolog program on a provable goal is not guaranteed as it may loop depending on the ordering of the clauses.

**Disjunction operator** The operator; can be seen as a disjunction and makes the Prolog interpreter explore the remaining SLD tree looking for alternative solutions.

## 4.3 Arithmetic operators

In Prolog:

Arithmetic operators

- Integers and floating points are built-in atoms.
- Math operators are built-in function symbols.

Therefore, mathematical expressions are terms.

is **predicate** The predicate is is used to evaluate and unify expressions:

where T is a numerical atom or a variable and Expr is an expression without free variables. After evaluation, the result of Expr is unified with T.

Example.

Note: a term representing an expression is evaluated only with the predicate **is** (otherwise it remains as is).

Relational operators (>, <, >=, =<, ==, =/=) are built-in.

#### 4.4 Lists

A list is defined recursively as:

Lists

#### Empty list []

**List constructor** . (T, L) where T is a term and L is a list.

Note that a list always ends with an empty list.

As the formal definition is impractical, some syntactic sugar has been defined:

**List definition** [t1, ..., tn] can be used to define a list.

**Head and tail** [H | T] where H is the head (term) and T the tail (list) can be useful for recursive calls.

#### 4.5 Cut

The cut operator (!) allows to control the exploration of the SLD tree.

Cut

A cut in a clause:

$$p := q1, ..., qi, !, qj, ..., qn.$$

makes the interpreter consider only the first choice points for q1, ..., qi, dropping all the other possibilities. Therefore, if qj, ..., qn fails, there won't be backtracking and p fails.

Example.

In the second case, the cut drops the choice point q(2) and only considers q(1).

**Mutual exclusion** A cut can be useful to achieve mutual exclusion. In other words, to represent a conditional branching:

a cut can be used as follows:

$$p(X) := a(X), !, b.$$
  
 $p(X) := c.$ 

If a(X) succeeds, other choice points for p will be dropped and only b will be evaluated. If a(X) fails, the second clause will be considered, therefore evaluating c.

### 4.6 Negation

**Closed-world assumption** Only what is stated in a program P is true, everything else is false:

Closed-world assumption

$$\mathtt{CWA}(P) = P \cup \{ \neg A \mid A \text{ is a ground atomic formula and } P \not\models A \}$$

**Non-monotonic inference rule** Adding new axioms to the program may change the set of valid theorems.

As first-order logic in undecidable, closed-world assumption cannot be directly applied in practice.

**Negation as failure** A negated atom  $\neg A$  is considered true iff A fails in finite time:

Negation as failure

$$NF(P) = P \cup \{ \neg A \mid A \in FF(P) \}$$

where  $FF(P) = \{B \mid P \not\models B \text{ in finite time}\}\$  is the set of atoms for which the proof fails in finite time. Note that not all atoms B such that  $P \not\models B$  are in FF(P).

**SLDNF** SLD resolution with NF to solve negative atoms.

SLDNF

Given a goal of literals :-  $L_1$ , ...,  $L_m$ , SLDNF does the following:

- 1. Select a positive or ground negative literal  $L_i$ :
  - If  $L_i$  is positive, apply the normal SLD resolution.
  - If  $L_i = \neg A$ , prove that A fails in finite time. If it succeeds,  $L_i$  fails.
- 2. Solve the goal :-  $L_1$ , ...,  $L_{i-1}$ ,  $L_{i+1}$ , ... $L_m$ .

**Theorem 4.6.1.** If only positive or ground negative literal are selected during resolution, SLDNF is correct and complete.

**Prolog SLDNF** Prolog uses an incorrect implementation of SLDNF where the selection rule always chooses the left-most literal. This potentially causes incorrect deductions.

*Proof.* When proving :- \+capital(X)., the intended meaning is:

$$\exists X : \neg capital(X)$$

In SLDNF, to prove :- \+capital(X)., the algorithm proves :- capital(X)., which results in:

$$\exists X : capital(X)$$

and then negates the result, which corresponds to:

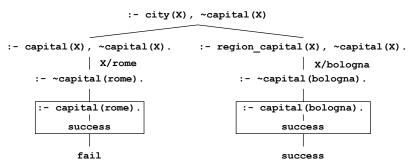
$$\neg(\exists X : capital(X)) \iff \forall X : (\neg capital(X))$$

**Example** (Correct SLDNF resolution). Given the program:

```
capital(rome).
region_capital(bologna).
city(X) :- capital(X).
city(X) :- region_capital(X).
?- city(X), \+capital(X).
```

13

its resolution succeeds with X=bologna as \+capital(X) is ground by the unification of city(X).



**Example** (Incorrect SLDNF resolution). Given the program:

```
capital(rome).
region_capital(bologna).
city(X) :- capital(X).
city(X) :- region_capital(X).
?- \+capital(X), city(X).
:- capital(x), city(X)
| x/rome
success
| fail
```

its resolution fails as \+capital(X) is a free variable and the proof of capital(X) is ground with X=rome and succeeds, therefore failing \+capital(X). Note that bologna is not tried as it does not appear in the axioms of capital.

## 4.7 Meta predicates

call/1 Given a term T, call(T) considers T as a predicate and evaluates it. At the time of evaluation, T must be a non-numeric term.

#### Example.

```
p(X) :- call(X).
q(a).
?- p(q(Y)).
    yes Y=a
```

fail/0 The evaluation of fail always fails, forcing the interpreter to backtrack.

fail/0

**Example** (Implementation of negation as failure).

```
not(P) := call(P), !, fail.
not(P).
```

Note that the cut followed by fail (!, fail) is useful to force a global failure.

#### bagof/3 and setof/3

bagof/3 The predicate bagof(X, P, L) unifies L with a list of the instances of X bagof/3 that satisfy P. Fails if none exists.

sefof/3 The predicate setof(X, P, S) unifies S with a set of the instances of X sefof/3 that satisfy P. Fails if none exists.

In practice, for computational reasons, a list (with repetitions) might be computed.

#### Example.

```
p(1).
p(2).
p(1).

?- setof(X, p(X), S).
    yes S=[1, 2] X=X

?- bagof(X, p(X), S).
    yes S=[1, 2, 1] X=X
```

Quantification When solving a goal, the interpreter unifies free variables with a value. This may cause unwanted behaviors when using bagof or setof. The X^ tells the interpreter to not (permanently) bind the variable X.

#### Example.

#### Example.

```
father(giovanni, mario).
father(giovanni, giuseppe).
father(mario, paola).

?- findall(X, father(X, Y), S).
    yes S=[giovanni, mario] X=X Y=Y
```

var/1 The predicate var(T) is true if T is a variable.

var/1

nonvar/1 The predicate nonvar(T) is true if T is not a free variable.

nonvar/1

number/1 The predicate number(T) is true if T is a number.

number/1

ground/1 The predicate ground(T) is true if T does not have free variables.

ground/1

=../2 The operator T =... L unifies L with a list where its head is the head of T and the tail contains the remaining arguments of T (i.e. puts all the components of a predicate into a list). Only one between T and L may be a variable.

#### Example.

clause/2 The predicate clause(Head, Body) is true if it can unify Head and Body with an existing clause. Head must be initialized to a non-numeric term. Body can be a variable or a term.

Example.

```
p(1).
q(X, a) :- p(X), r(a).
q(2, Y) :- d(Y).

?- clause(p(1), B).
    yes B=true

?- clause(p(X), true).
    yes X=1

?- clause(q(X, Y), B).
    yes X=_1 Y=a B=p(_1), r(a);
    X=2 Y=_2 B=d(_2)
```

assert/1 The predicate assert(T) adds T in an unspecified position of the clauses assert/1 database of Prolog. In other words, it allows to dynamically add clauses.

asserta/1 As assert(T), with insertion at the beginning of the database.

assertz/1 As assert(T), with insertion at the end of the database.

assertz/1

Note that :- assert((p(X))) quantifies X existentially as it is a query. If it is not ground and added to the database as is, is becomes a clause and therefore quantified universally:  $\forall X : p(X)$ .

Example (Lemma generation).

generate\_lemma/1 allows to add to the clauses database all the intermediate steps to compute the Fibonacci sequence (similar concept to dynamic programming).

retract/1 The predicate retract(T) removes from the database the first clause that retract/1 unifies with T.

abolish/2 The predicate abolish(T, n) removes from the database all the occurrences abolish/2 of T with arity n.

## 4.8 Meta-interpreters

**Meta-interpreter** Interpreter for a language  $L_1$  written in another language  $L_2$ .

Meta-interpreter

**Prolog vanilla meta-interpreter** The Prolog vanilla meta-interpreter is defined as follows:

Vanilla meta-interpreter

```
solve(true) :- !.
solve((A, B)) :- !, solve(A), solve(B).
solve(A) :- clause(A, B), solve(B).
```

In other words, the clauses state the following:

- 1. A tautology is a success.
- 2. To prove a conjunction, we have to prove both atoms.
- 3. To prove an atom A, we look for a clause A :- B that has A as conclusion and prove its premise B.

## **Constraint programming**

#### Class of problems

Constraint satisfaction problem (CSP) Defined by:

Constraint satisfaction problem

- A finite set of variables  $X_1, \ldots, X_n$ .
- A domain for each variable  $D(X_1), \ldots, D(X_n)$ .
- A set of constraints  $\{C_1, \ldots, C_m\}$

A solution is an assignment to all the variables while satisfying the constraints.

Constraint optimization problem (COP) Extension of a constraint satisfaction problem with an objective function with domain D:

$$f: D(X_1) \times \cdots \times D(X_n) \to D$$

A solution is a CSP solution that optimizes f.

#### Class of languages

Constraint logic programming (CLP) Add constraints and solvers to logic programming. Generally more efficient than plain logic programming.

Constraint logic programming

optimization

problem

**Imperative languages** Add constraints and solvers to imperative languages.

Imperative languages

## 5.1 Constraint logic programming (CLP)

#### **5.1.1** Syntax

**Atom**  $A := p(t_1, \ldots, t_n)$ , for  $n \ge 0$ . p is a predicate.

Atom

**Constraint**  $C := c(t_1, \ldots, t_n) \mid C_1 \wedge C_2$ , for  $n \geq 0$ . c is an atomic constraint.

Constraint

**Goal**  $G := \top \mid \bot \mid A \mid C \mid G_1 \wedge G_2$ 

Goal

Constraint logic clause  $K := A \leftarrow G$ 

Constraint logic

clause

Constraint logic program  $P := K_1 \dots K_m$ , for  $m \ge 0$ 

Constraint logic program

#### 5.1.2 Semantics

#### **Transition system**

Transition system

**State** Pair  $\langle G, C \rangle$  where G is a goal and C is a constraint.

Initial state  $\langle G, \top \rangle$ 

**Successful final state**  $\langle \top, C \rangle$  with  $C \neq \bot$ 

Failed final state  $\langle G, \bot \rangle$ 

**Transition** Starting from the state  $\langle A \wedge G, C \rangle$  of a program P, a transition on the atom A can result in:

**Unfold** If there exists a clause  $(B \leftarrow H)$  in P and an assignment  $(B \doteq A)$  such that  $((B \doteq A) \land C)$  is still valid, then we have a transition  $\langle A \land G, C \rangle \mapsto \langle H \land G, (B \doteq A) \land C \rangle$ .

In other words, we want to develop an atom A and the current constraints are denoted as C. We look for a clause whose head equals A, applying an assignment if needed. If this is possible, we transit from solving A to solving the body of the clause and add the assignment to the set of active constraints.

**Failure** If there are no clauses  $(B \leftarrow H)$  with a valid assignment  $((B \doteq A) \land C)$ , Failure then we have a transition  $(A \land G, C) \mapsto (\bot, \bot)$ .

Moreover, starting from the state  $\langle C \wedge G, D_1 \rangle$  of a program P, a transition on the constraint C can result in:

**Solve** If  $(C \wedge D_1) \iff D_2$  holds, then we have a transition  $\langle C \wedge G, D_1 \rangle \mapsto Solve \langle G, D_2 \rangle$ .

In other words, we want to develop a constraint C and the current constraints are denoted as  $D_1$ . If  $(C \wedge D_1)$  is valid, we call it  $D_2$  and continue solving the rest of the goal constrained to  $D_2$ .

**Non-determinism** As in logic programming, there is don't-care and don't-know non-determinism. A SLD search tree is also used.

#### **Derivation strategies**

**Generate-and-test** Strategy adopted by logic programs. Every possible assignment to the variables are generated and tested.

The workflow is the following:

- 1. Determine domain.
- 2. Make an assignment to each variable.
- 3. Test the constraints.

**Constrain-and-generate** Strategy adopted by constraint logic programs. Exploit Constrain-and-generate facts to reduce the search space.

The workflow is the following:

- 1. Determine domain.
- 2. Restrict the domain following the constraints.
- 3. Make an assignment to each variable.

#### 5.2 MiniZinc

Declarative language for constraint programming.

Built-in types bool, int, float, string

Built-in types

Unfold

Logical operators

Parameter User-inputted value passed to the solver before execution.

Parameter

<domain>: <name>

```
Example. int: size;
                                                                                 Variable
Variable Value computed by the solver.
                               var <domain>: <name>
     Example. var bool: flag;
                                                                                 Set
Set For defining ranges.
                             set of <domain>: <name>
     Example. set of int: top10 = 1..10;
Array Array of parameters or variables.
                                                                                 Array
                    array[<index range>] of <domain>:
                                                         <name>
     Example. array[1..5] of var int: vars;
Aggregation functions sum, product, min, max.
                                                                                 Aggregation
                                                                                 functions
     Forall
         forall(<iterators> in <domain>)(<conditions>)
         forall(<iterators> in <domain> where <conditions>)(<conditions>)
         Example. forall(i, j in 1..3 where i < j)(arr[i] != arr[j]);
     Exists
         exists(<iterators> in <domain>)(<conditions>)
         exists(<iterators> in <domain> where <conditions>)(<conditions>)
Constraints
                                                                                 Constraints
                             constraint <expression>
     Multiple constraints are seen as conjunctions.
     Example. constraint X >= 5 / X != 10;
     Global constraints all_different(...), all_equal(...)
Solver
                                                                                 Solver
     Satisfiability problem
                                     solve satisfy;
     Optimization problem
                              solve minimize <variable>;
```

<end of course>