Reguleringsteknik 1

J. Christian Andersen

Kursusuge 6

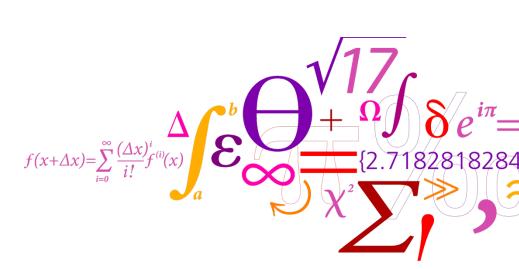
Plan

- Stabilitetsmargin
 - Begreber (igen)
 - Nyquist plot
- PID design ud fra frekvensanalyse
 - P- regulator
 - PI regulator
 - P-Lead regulator
- Grupperegningsopgaver
 - PI-Lead
 - Multiple choice

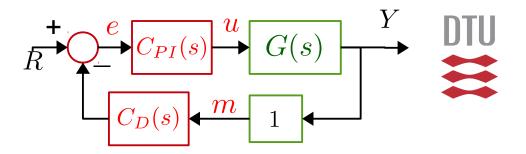
DTU Electrical Engineering

Department of Electrical Engineering





Grupperegning Lektion 6



1. Design en PI-Lead regulator til et system G1

$$G_1 = \frac{9000}{(100s+1)(s^2+60s+900)}$$

a) Design en PI-Lead regulator, når der vælges:

$$N_i = 2, \ \alpha = 0.1 \text{ og } \gamma_M = 70^o$$

2. Multible choice opgaver på campusnet