Isn't it true that if I subdivide the global element edge into P+1 pieces, do a first order flux reconstruction on each of those pieces to get each sub-face value, then re-assemble the pieces to compose each edge node flux value that I have a P-th order reconstruction?

The only information needed for this approach is what I have: the interior node on either side of the piece of the global edge for each sub-face - I have that from the sub-element triangulation. The global edges are formed using Gauss points on the linear edges, so I have the weights needed to do a high order integration. I don't need the node values on the global element vertices or on the shared faces, because that's not needed for the first order flux (or WENO) reconstruction in FV methods. I would like to use the existing interior node locations, which are not equispaced, etc. For a first order or WENO flux reconstruction, how would I normally proceed with a FV based approach, given the following: - The single interior nodes opposing the sub-element face; one from the neighbor element interior and one from the current element interior - For WENO, other information from interior nodes to each global element, as needed.

1. First-Order (Godunov-Type) Flux Reconstruction

Step 1: Identify the Two Opposing Interior Nodes for Each Sub-Face

For each sub-face of the global edge, determine:

- $U_L o$ Value from the interior node of the current element (left state).
- $U_R o$ Value from the interior node of the neighboring element (right state).

These values form the left and right states needed for a Riemann solver.

Why This Works:

This follows the finite-volume (FV) method's structure, where fluxes are computed at element interfaces.

Each sub-face naturally forms a FV interface, with two opposing interior states.

Step 2: Compute the Numerical Flux at the Sub-Face

Once U_L and U_R are defined, compute the numerical flux at the sub-face center using any approximate Riemann solver, such as:

$$F_{\text{sub-face}} = F(U_L, U_R)$$

Common Riemann Solvers Used in FV Methods:

- Roe Flux → Linearized Riemann solver, accurate but requires entropy fix.
- HLL/HLLC Flux → Simple and robust, especially for compressible flows.
- Lax-Friedrichs Flux → Diffusive but stable (can be used in early tests).

Result:

A first-order accurate FV flux at each sub-face of the global edge.

Ready for high-order integration using Gauss weights to form a P-th order flux reconstruction at the global edge node.

2. WENO-Based Flux Reconstruction (Higher-Order)

For higher-order WENO flux reconstruction, we need to improve the accuracy of U_L and U_R before computing the numerical flux.

Step 1: Form WENO Candidate Reconstructions for U_L and U_R

Instead of using just one interior node per element, WENO flux reconstruction uses multiple interior nodes from each element to form a stencil.

For each sub-face of the global edge:

- Define three or more interior nodes from the current element as candidate left states.
- Define three or more interior nodes from the neighboring element as candidate right states.
- Compute smoothness indicators to choose the most accurate state for flux computation.

How WENO Selects the Best Reconstruction:

- 1. Compute multiple candidate reconstructions $U_{L,i}$ and $U_{R,i}$ from different interior nodes.
- 2. Compute smoothness indicators \$ S_i \$ for each candidate state:

$$S_i = \sum_m \left(rac{d^m U_i}{dx^m}
ight)^2$$

3. Compute WENO weights:

$$lpha_i = rac{d_i}{(\epsilon + S_i)^p} \ \omega_i = rac{lpha_i}{\sum_j lpha_j}$$

where:

- o (d_i) are optimal high-order weights.
- (\epsilon) is a small regularization constant.
- o (p) controls how aggressively WENO favors smooth stencils.
- 4. Compute the final reconstructed values:

$$U_L = \sum_i \omega_i U_{L,i}, \quad U_R = \sum_i \omega_i U_{R,i}$$



☑ Shock-free, high-order accurate flux reconstruction at each sub-face of the global edge.

Ensures no spurious oscillations near discontinuities.

Step 2: Compute the Numerical Flux at the Sub-Face

Now that we have higher-order reconstructed values U_L, U_R from WENO, compute the numerical flux as before:

$$F_{
m sub ext{-}face} = F(U_L, U_R)$$

where (F(U_L, U_R)) is evaluated using the same Riemann solver.



WENO-reconstructed flux, which is much more accurate than the first-order case.

3. Final Step: High-Order Edge Flux Reconstruction

For each **global edge node**, integrate the sub-face fluxes using Gauss quadrature:

$$F_{ ext{edge-node}} = \sum_{i=1}^{P+1} w_i F_{ ext{sub-face},i}$$

- ★ Why This Works:
- Recovers full P-th order accuracy at the edge node using high-order integration.
- Maintains robustness near shocks using WENO.

Summary of First-Order vs. WENO Reconstruction

| Approach | Accuracy | Stability | Computational Cost | Best Used For |
|---------------------------------------|----------------------|---------------------------|-----------------------|---------------------------------------|
| First-Order FV Flux Reconstruction | 1st-order | Very robust | Low | Initial tests, smooth solutions |
| WENO Flux Reconstruction | High-order (P-th) | Handles shocks well | Moderate | Shock tubes, discontinuities |

*Your method naturally extends from first-order to high-order WENO, following classical FV techniques.