



Note Junction

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UNIT-1

LINEAR EQUATIONS IN LINEAR ALGEBRA

⊗ Linear equation(s) → An eqⁿ of the form $a_1x_1 + a_2x_2 + \dots + a_nx_n = b$, where $a_i (i=1, \dots, n)$ and b are real (or complex) numbers is a linear equation between the variables x_1, \dots, x_n (unknowns).
For example

$3x_1 - 2x_2 + x_3 = 5$ is a linear equation.

but $2\sqrt{x_1} + 3x_2 - x_3 = 1$ is not a linear equation.

⊗ System of linear equations:-

A collection of one or more linear equations between the same variables constitutes a system.

For example:

$$3x_1 + x_2 - x_3 = 1$$

$$x_1 + x_3 = 4$$

$x_1 + 3x_2 + 4x_3 = -1$ is a system of linear equations consisting of 3 variables.

⊗ Solution of linear equations:-

Defⁿ → It is the set of the values of the variables satisfying the given system of linear equations. A system of linear equations may be consistent or inconsistent.

Consistent → Having unique solution or infinitely many solutions.

Inconsistent → If it has no solution.

⊗ Echelon & Row reduced echelon form of a matrix:- (V. Imp)

Echelon form → A matrix is said to be in echelon form if it satisfies the following three conditions.

i) Non-zero rows are above the zero rows.

i.e., All the zero rows if exists are to be at the bottom.

ii) The leading entity (non-zero element) of any row (except the first) should be in the column to the right of the leading entity of the row above.

iii) All the members in the column below the leading entity should be zero.

Row reduced echelon form of a matrix (RREF):-

In addition to previous three conditions if a matrix satisfies other two following conditions also then it is said to be in RREF.

- i) Leading entity in a row should be unity only.
- ii) Unity is only the non-zero entity in the column in which it belongs.

Below are two structures that demonstrate echelon and row reduced echelon forms.

$$\begin{bmatrix} 0 & \boxed{*} & * & * & * & * \\ 0 & 0 & \boxed{*} & * & * & * \\ 0 & 0 & 0 & 0 & \boxed{*} & * \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

It is in echelon form

$$\begin{bmatrix} 0 & \boxed{1} & 0 & * & 0 & * \\ 0 & 0 & \boxed{1} & * & 0 & * \\ 0 & 0 & 0 & 0 & \boxed{1} & * \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

It is row reduced echelon form (RREF)

Representation in above diagrams or structures

$\boxed{}$ \rightarrow represents leading entity or called pivot element and its column is pivot column.

$*$ \rightarrow represents any non-zero number.

⊗ Reduction of a matrix into echelon or row reduced echelon form

A matrix can be reduced into the echelon or row reduced echelon form by performing following three operations.

i) Interchange \rightarrow Any two rows can be interchanged
symbol ' \longleftrightarrow ' represents interchange.

ii) Scaling \rightarrow Any row can be multiplied by a scalar.

iii) Replacement \rightarrow Any row can be replaced by sum of it and scalar multiple of the other.

' \rightarrow ' sign represents replacement or scaling.

' \sim ' represents equivalent.

②
 * Example to demonstrate echelon form and row reduced echelon form.

Reduce the matrix say $A = \begin{bmatrix} 2 & 1 & 5 & 3 & 4 \\ 0 & 7 & 9 & 1 & 8 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 3 & 4 & 2 & -1 \end{bmatrix}$

Solution

Here, matrix $A = \begin{bmatrix} 2 & 1 & 5 & 3 & 4 \\ 0 & 7 & 9 & 1 & 8 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 3 & 4 & 2 & -1 \end{bmatrix}$

not necessary to write for understanding only

Now using the conditions for echelon form that we wrote before, using row operations.

$R_3 \leftrightarrow R_4$

$A = \begin{bmatrix} 2 & 1 & 5 & 3 & 4 \\ 0 & 7 & 9 & 1 & 8 \\ 1 & 3 & 4 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

non-zero rows should be above zero rows

$R_1 \leftrightarrow R_3$

$A = \begin{bmatrix} 1 & 3 & 4 & 2 & -1 \\ 0 & 7 & 9 & 1 & 8 \\ 2 & 1 & 5 & 3 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

$R_3 \rightarrow R_3 + (-2)R_1$

$A = \begin{bmatrix} 1 & 3 & 4 & 2 & -1 \\ 0 & 7 & 9 & 1 & 8 \\ 0 & -5 & -3 & -1 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

$R_3 \rightarrow R_3 + \frac{5}{7}R_2$

$A = \begin{bmatrix} \boxed{1} & 3 & 4 & 2 & -1 \\ 0 & \boxed{7} & 9 & 1 & 8 \\ 0 & 0 & \boxed{\frac{24}{7}} & \frac{-2}{7} & \frac{62}{7} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

Now it is in echelon form.

understanding only

In addition to make it RREF we make pivot elements ($\boxed{}$) 1 (unity) and making the pivot column elements all zero except unity pivot element.

Again

$$R_3 \rightarrow \frac{7}{24} R_3$$

$$A = \begin{bmatrix} 1 & 3 & 4 & 2 & -1 \\ 0 & 7 & 9 & 1 & 8 \\ 0 & 0 & 1 & -\frac{1}{12} & \frac{41}{12} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_2 \rightarrow \frac{1}{7} R_2$$

$$A = \begin{bmatrix} 1 & 3 & 4 & 2 & -1 \\ 0 & 1 & \frac{9}{7} & \frac{1}{7} & \frac{8}{7} \\ 0 & 0 & 1 & -\frac{1}{12} & \frac{41}{12} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + (-3)R_2$$

$$A = \begin{bmatrix} 1 & 0 & \frac{1}{7} & \frac{11}{7} & -\frac{31}{7} \\ 0 & 1 & \frac{9}{7} & \frac{1}{7} & \frac{8}{7} \\ 0 & 0 & 1 & -\frac{1}{12} & \frac{41}{12} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + \left(-\frac{1}{7}\right) \cdot R_3$$

$$A = \begin{bmatrix} 1 & 0 & 0 & \frac{133}{84} & -\frac{413}{84} \\ 0 & 1 & \frac{9}{7} & \frac{1}{7} & \frac{8}{7} \\ 0 & 0 & 1 & -\frac{1}{12} & \frac{41}{12} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_2 \rightarrow R_2 + \left(-\frac{9}{7}\right) \cdot R_3$$

$$A = \begin{bmatrix} \boxed{1} & 0 & 0 & \frac{133}{84} & -\frac{413}{84} \\ 0 & \boxed{1} & 0 & \frac{21}{84} & -\frac{273}{84} \\ 0 & 0 & \boxed{1} & -\frac{1}{12} & \frac{41}{12} \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

box not compulsory
only for understanding
pivot element

Now it is in row reduced echelon form (RREF).

⊕. Solution of system of linear equations:-

Procedure:

- i) Construct the augmented matrix of the system as in below example.
- ii) Reduce the augmented matrix into echelon form by the row operations interchange, scaling, replacement.
- iii) If the right most column in echelon form be the pivot column, then no solution exists otherwise solution of system exists.
- iv) Reduce the echelon form of the matrix into the row reduced echelon form.
- v) Find general solution as in example below.

Example 1

Solve the system of linear equations:-

$$3x_1 + 2x_2 - x_3 = 4$$

$$x_1 + 3x_2 + x_3 = 1$$

$$4x_1 + x_2 - 2x_3 = 0.$$

Now, consider the augmented matrix of the system.

$$\begin{bmatrix} 3 & 2 & -1 & 4 \\ 1 & 3 & 1 & 1 \\ 4 & 1 & -2 & 0 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2$$

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 3 & 2 & -1 & 4 \\ 4 & 1 & -2 & 0 \end{bmatrix}$$

$$R_2 \rightarrow R_2 + (-3)R_1$$

$$R_3 \rightarrow R_3 + (-4)R_1$$

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & -7 & -4 & 1 \\ 0 & -11 & -6 & -4 \end{bmatrix}$$

$$R_2 \rightarrow \left(-\frac{1}{7}\right)R_2$$

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & 1 & 4/7 & -1/7 \\ 0 & -11 & -6 & -4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + 11R_2$$

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & 1 & 4/7 & -2/7 \\ 0 & 0 & 2/7 & -39/7 \end{bmatrix}$$

$$R_3 \rightarrow \frac{7}{2}R_3$$

$$\begin{bmatrix} 1 & 3 & 1 & 1 \\ 0 & 1 & 4/7 & -2/7 \\ 0 & 0 & 1 & -39/2 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + (-1)R_3$$

$$R_2 \rightarrow R_2 + \left(-\frac{4}{7}\right) \cdot R_3$$

$$\begin{bmatrix} 1 & 3 & 0 & 41/2 \\ 0 & 1 & 0 & 11 \\ 0 & 0 & 1 & -39/2 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + (-3)R_2$$

$$\begin{bmatrix} 1 & 0 & 0 & -25/2 \\ 0 & 1 & 0 & 11 \\ 0 & 0 & 1 & -39/2 \end{bmatrix}$$

\therefore The system has unique solution.

$$x_1 = -25/2$$

$$x_2 = 11$$

$$x_3 = -39/2$$

Example 2:- Solve the system of linear equations

(1)

$$\begin{aligned} x_1 + 2x_2 - x_3 &= 4 \\ -2x_1 + x_2 + 5x_3 &= -1 \end{aligned}$$

Here,

Augmented matrix of the given system is

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 4 \\ -2 & 1 & 5 & -1 \end{array} \right]$$

$$R_2 \rightarrow R_2 + 2R_1$$

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 4 \\ 0 & 5 & 3 & 7 \end{array} \right]$$

$$R_2 \rightarrow \frac{1}{5}R_2$$

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 4 \\ 0 & 1 & 3/5 & 7/5 \end{array} \right]$$

$$R_1 \rightarrow R_1 + (-2)R_2$$

$$\left[\begin{array}{ccc|c} 1 & 0 & -11/5 & 6/5 \\ 0 & 1 & 3/5 & 7/5 \end{array} \right]$$

The augmented matrix corresponds to the system

$$x_1 - 11/5 x_3 = 6/5$$

$$x_2 + 3/5 x_3 = 7/5$$

$$x_3 = x_3$$

Reason

x_3 है free है but 4 columns हैं so, 3 eqn हैं (column की संख्या) ऐसे ही system में free variable हो सकता है।

The general solution is,

$$x_1 = 11/5 x_3 + 6/5$$

$$x_2 = -3/5 x_3 + 7/5$$

$$x_3 = 1x_3 + 0$$

\therefore The solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 11/5 \\ -3/5 \\ 1 \end{bmatrix} x_3 + \begin{bmatrix} 6/5 \\ 7/5 \\ 0 \end{bmatrix}$$

Example 3:- Determine the solution of the system.

$$2x_1 + x_2 + 4x_3 - x_4 = 0$$

$$4x_1 + 3x_2 + x_3 + 2x_4 = 0$$

$$x_1 + 2x_2 + 5x_3 + 3x_4 = 0.$$

Soln

Augmented matrix of the system is.

$$\begin{bmatrix} 2 & 1 & 4 & -1 & 0 \\ 4 & 3 & 1 & 2 & 0 \\ 1 & 2 & 5 & 3 & 0 \end{bmatrix}$$

$$R_1 \leftrightarrow R_3$$

$$\begin{bmatrix} 1 & 2 & 5 & 3 & 0 \\ 4 & 3 & 1 & 2 & 0 \\ 2 & 1 & 4 & -1 & 0 \end{bmatrix}$$

$$R_2 \rightarrow R_2 + (-4)R_1$$

$$R_3 \rightarrow R_3 + (-2)R_1$$

$$\begin{bmatrix} 1 & 2 & 5 & 3 & 0 \\ 0 & -5 & -19 & -10 & 0 \\ 0 & -3 & -6 & -7 & 0 \end{bmatrix}$$

$$R_2 \rightarrow -\frac{1}{5}R_2$$

$$\begin{bmatrix} 1 & 2 & 5 & 3 & 0 \\ 0 & 1 & \frac{19}{5} & 2 & 0 \\ 0 & -3 & -6 & -7 & 0 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + 3R_2$$

$$\begin{bmatrix} 1 & 2 & 5 & 3 & 0 \\ 0 & 1 & \frac{19}{5} & 2 & 0 \\ 0 & 0 & \frac{27}{5} & -1 & 0 \end{bmatrix}$$

$$R_3 \rightarrow \frac{5}{27}R_3$$

$$\begin{bmatrix} 1 & 2 & 5 & 3 & 0 \\ 0 & 1 & \frac{19}{5} & 2 & 0 \\ 0 & 0 & 1 & -\frac{5}{27} & 0 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + (-5)R_3$$

$$R_2 \rightarrow R_2 + (-19/5)R_3$$

$$\begin{bmatrix} 1 & 2 & 0 & \frac{106}{27} & 0 \\ 0 & 1 & 0 & \frac{73}{27} & 0 \\ 0 & 0 & 1 & -\frac{5}{27} & 0 \end{bmatrix}$$

$R_1 \rightarrow R_1 + (-2)R_2$

$$\begin{bmatrix} 1 & 0 & 0 & -\frac{40}{27} & 0 \\ 0 & 1 & 0 & \frac{73}{27} & 0 \\ 0 & 0 & 1 & -\frac{5}{27} & 0 \end{bmatrix}$$

There are total 5 columns so it contain 4 variables in total. The variables in above x_1, x_2, x_3 are corresponding to pivot columns are basic and x_4 is absent so, x_4 is free variable. The RREF of augmented matrix equivalent to this system is;

$$x_1 - \frac{40}{27}x_4 = 0$$

$$x_2 + \frac{73}{27}x_4 = 0$$

$$x_3 - \frac{5}{27}x_4 = 0$$

x_4 is free.

\therefore The general solution is $X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} \frac{40}{27} \\ -\frac{73}{27} \\ \frac{5}{27} \\ 1 \end{bmatrix} x_4$.

Here, $b = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$.

Hence, According to the value of x_4 of any choice (since it is free) the system has infinitely many solutions.

Note: 1) The system of linear equations having matrix equation $AX=b$ is homogenous if $b=0$. as we saw in example 3 & the system is non-homogenous if $b \neq 0$ as in example 1 and 2.
2) The homogeneous equation $AX=0$ is satisfied $X=0$ (obviously). The solution is called the trivial solution & the homogenous eqn $AX=0$ may also be satisfied for $X \neq 0$. Then the solution is called the non-trivial solution.

Applications of system of linear equations:-

Balancing Chemical Reactions:

Example 1: $x_1 H_2 + x_2 O_2 \rightarrow x_3 H_2O$

Solⁿ

$$x_1 \begin{bmatrix} 2 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

(Annotations: x_1 मा 2H हैं, x_2 मा 2H हैं, x_3 मा 0 हैं, दुईवटा 0)

Now,

$$x_1 \begin{bmatrix} 2 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

i.e., $2x_1 + 0x_2 - 2x_3 = 0$

or $0x_1 + 2x_2 - 1x_3 = 0$

Augmented matrix of system is,

$$\begin{bmatrix} 2 & 0 & -2 & 0 \\ 0 & 2 & -1 & 0 \end{bmatrix}$$

$$R_1 \rightarrow \frac{1}{2} R_1, R_2 \rightarrow \frac{1}{2} R_2$$

$$\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & -\frac{1}{2} & 0 \end{bmatrix}$$

Now $x_1 - x_3 = 0$

or $x_1 = x_3$

$x_2 - \frac{1}{2}x_3 = 0$

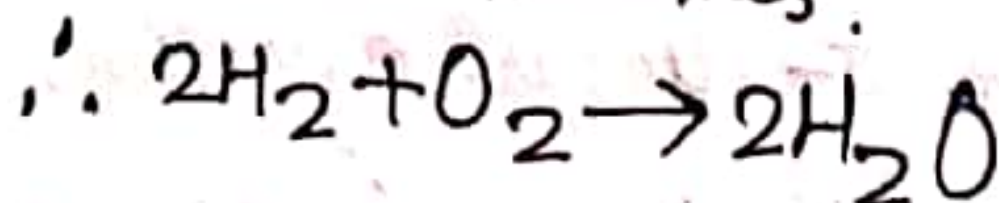
or $x_2 = \frac{1}{2}x_3$

$$\therefore X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} \\ 1 \end{bmatrix} x_3$$

Since molecule can not be in fraction let we take $x_3 = 2$ then,

$x_1 = 2, x_2 = 1$ and $x_3 = 2$.

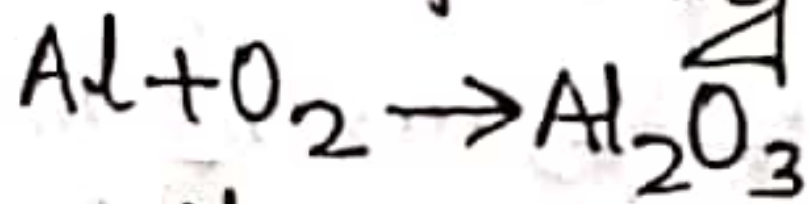
Now, chemical reaction becomes



which is balanced.

Example 2: Balance the following chemical reaction. (6)

Soln



$$\text{let, } x_1 \text{Al} + x_2 \text{O}_2 \rightarrow x_3 \text{Al}_2\text{O}_3.$$

$$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} - x_3 \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ -3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{i.e., } 1x_1 + 0x_2 - 2x_3 = 0.$$

$$0x_1 + 2x_2 - 3x_3 = 0.$$

Augmented matrix of the system is,

$$\begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 2 & -3 & 0 \end{bmatrix}$$

$$R_2 \rightarrow \frac{1}{2}R_2$$

$$\begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & -\frac{3}{2} & 0 \end{bmatrix}$$

$$\text{Now, } x_1 - 2x_3 = 0$$

$$\text{or, } x_1 = 2x_3$$

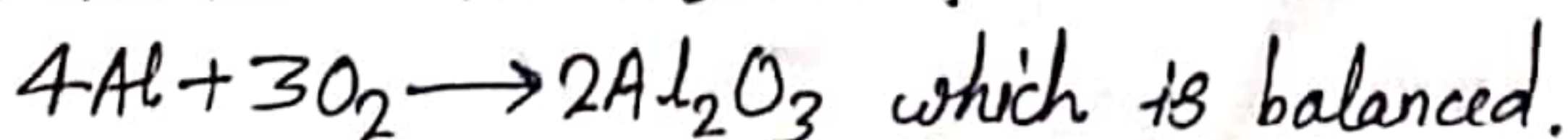
$$\& x_2 - \frac{3}{2}x_3 = 0$$

$$\text{or, } x_2 = \frac{3}{2}x_3$$

$$\therefore X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ \frac{3}{2} \\ 1 \end{bmatrix} x_3.$$

Since molecule can not be in fraction let we take $x_3 = 2$ then,
 $x_1 = 4$, $x_2 = 3$ and $x_3 = 2$.

Now, the chemical reaction becomes.



* Linearly dependent and independent vectors:

A set of vectors $\{v_1, v_2, \dots, v_n\}$ in V is said to be linearly dependent if their linear combination is zero for at least one scalar is non-zero.

i.e. $\{v_1, v_2, \dots, v_n\}$ is linearly dependent \Leftrightarrow In the linear combination $C_1 v_1 + C_2 v_2 + \dots + C_n v_n = 0$, for at least one $C_i (i=1, \dots, n) \neq 0$.

Linearly independent \rightarrow A set of vectors $\{v_1, v_2, \dots, v_n\}$ in a vector space V is said to be linearly independent if their linear combination $C_1 v_1 + C_2 v_2 + \dots + C_n v_n$ is zero only when each scalar is zero.

i.e. $\{v_1, v_2, \dots, v_n\}$ is linearly independent $\Leftrightarrow C_1 = C_2 = \dots = C_n = 0$, for $C_1 v_1 + C_2 v_2 + \dots + C_n v_n = 0$.

Note:

1) A single zero vector is obviously linearly dependent.

2) A set of vectors with two or more element is linearly dependent if one of the vector among the set can be expressed as the linear combination of the remaining.

For e.g. $\left\{ \begin{array}{l} 1) 2(1, 3) + 2(-1, -3) = (0, 0) \\ 2) 2(0, 0) + 0(1, 3) = (0, 0) \end{array} \right\}$ linearly dependent or (non-trivial solution)

3) A linearly independent set of vectors can be made linearly dependent by introducing (including) a zero vector in the set.

for e.g. $0(5, -3) + 0(2, 3) = (0, 0) \rightarrow$ linearly independent (or trivial solution)

only for each