

# Orthogonality and Least Squares:

## ②. Scalar (or inner) product:

Definition → Let  $u = (u_1, u_2, \dots, u_n)$  and  $v = (v_1, v_2, \dots, v_n)$  then the scalar product of  $u$  and  $v$  is denoted by  $u \cdot v$  and defined as  $u \cdot v = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$ . This product is also known as dot product.

Note: let,  $u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$  and  $v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$  be two column matrices representing the vectors in  $\mathbb{R}^n$ .

Then, the inner product  $u \cdot v = u \cdot T \cdot v$ .

i.e.,  $u \cdot v = \text{matrix product of } u^T \text{ (transpose of } u) \text{ and } v$ .

## ③. Properties of Inner product:

Let,  $u$  and  $v$  be any two vectors in  $\mathbb{R}^n$ . Then,

i)  $u \cdot v = v \cdot u$  (commutative)

ii)  $(u+v) \cdot w = u \cdot w + v \cdot w$  (distributive).

iii)  $(cu) \cdot v = c \cdot (u \cdot v) = u \cdot (c \cdot v)$

iv)  $u \cdot u \geq 0$  and  $u \cdot u = 0$  if and only if  $u = 0$ .

## Norm of a vector (length of a vector):

The length or norm of a vector  $v$  is a non-negative scalar  $\|v\| = \sqrt{v \cdot v} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$  where,  $v = (v_1, v_2, \dots, v_n)$ .

✓ Note that, this definition implies  $\|v\|^2 = v \cdot v$ .

## Unit vector:

Definition → A vector having length 1, is called a unit vector.

Mathematically, if  $v$  be a vector in  $\mathbb{R}^n$  then its unit vector is,  $\frac{v}{\|v\|}$ .

Example: Find the unit vector along the vector  $v = (-2, 1, 0)$  and verify it.

Solution: Let  $v = (-2, 1, 0)$ .

$$\begin{aligned} \text{Then, } \|v\| &= \sqrt{(-2)^2 + 1^2 + 0^2} \\ &= \sqrt{4 + 1 + 0} \\ &= \sqrt{5}. \end{aligned}$$



Therefore, the unit vector of  $v$  is  $\frac{v}{\|v\|} = \frac{(-2, 1, 0)}{\sqrt{5}} = \left(\frac{-2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0\right)$ .

Verification:

$$\text{let } u = \frac{v}{\|v\|} = \left(\frac{-2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0\right).$$

$$\begin{aligned}\text{Now, the length of } u \text{ is, } \|u\| &= \sqrt{\left(\frac{-2}{\sqrt{5}}\right)^2 + \left(\frac{1}{\sqrt{5}}\right)^2 + (0)^2} \\ &= \sqrt{\frac{4}{5} + \frac{1}{5} + 0} \\ &= \sqrt{\frac{4+1}{5}} \\ &= \sqrt{1} \\ &= 1\end{aligned}$$

Thus,  $\frac{v}{\|v\|} = \left(\frac{-2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0\right)$  be unit vector along the vector  $v$ .

Normalization of a vector:

Definition → let  $v$  be a vector in  $\mathbb{R}^n$ . Set  $u = \frac{v}{\|v\|}$  then process of creating  $u$  is called normalizing  $v$ .

Distance between two vectors:

Definition → let  $u$  and  $v$  are in  $\mathbb{R}^n$ , then the distance between  $u$  and  $v$  is the length between them. It is denoted by  $\text{dis}(u, v)$  and define as,

$$\text{dis}(u, v) = \|u - v\|.$$

Example 1: If  $u = (2, 3)$  and  $v = (3, -1)$  then find the distance between them.

Solution: Given,  $u = (2, 3)$  and  $v = (3, -1)$ .

$$\text{Then, } u - v = (2, 3) - (3, -1) = (-1, 4).$$

Now distance between  $u$  and  $v$  is,

$$\|u - v\| = \sqrt{(-1)^2 + (4)^2} = \sqrt{1+16} = \sqrt{17}$$

Example 2: Find the distance between  $u = \begin{bmatrix} 0 \\ -5 \\ 2 \end{bmatrix}$  and  $z = \begin{bmatrix} -4 \\ -1 \\ 8 \end{bmatrix}$ .

Solution: let  $u = \begin{bmatrix} 0 \\ -5 \\ 2 \end{bmatrix}$  and  $z = \begin{bmatrix} -4 \\ -1 \\ 8 \end{bmatrix}$ .

$$\text{Then, } u - z = \begin{bmatrix} 0 \\ -5 \\ 2 \end{bmatrix} - \begin{bmatrix} -4 \\ -1 \\ 8 \end{bmatrix} = \begin{bmatrix} 4 \\ -4 \\ -6 \end{bmatrix}.$$



$$\text{So, } (u-z) \cdot (u-z) = \begin{bmatrix} 4 \\ -4 \\ -6 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -4 \\ -6 \end{bmatrix} = 16 + 16 + 36 = 72.$$

Now, the distance between  $u$  and  $z$  is

$$\begin{aligned} \text{dis}(u, z) &= \|u - z\| = \sqrt{(u-z) \cdot (u-z)} \\ &= \sqrt{72} \\ &= 6\sqrt{2}. \end{aligned}$$

### \* Orthogonal Vectors:

Two vectors  $u$  and  $v$  in  $\mathbb{R}^n$  are orthogonal to each other if  $u \cdot v = 0$ .

Example: Show that the vectors  $u = (2, -3, 3)$  and  $v = (12, 3, -5)$  are orthogonal.

Solution: Given,  $u = (2, -3, 3)$  and  $v = (12, 3, -5)$

$$\begin{aligned} \text{Now, } u \cdot v &= (2, -3, 3) \cdot (12, 3, -5) \\ &= 24 - 9 - 15 \\ &= 0. \end{aligned}$$

This means  $u$  and  $v$  are orthogonal.

### \* The Pythagorean Theorem:

Statement → Two vectors  $u$  and  $v$  are orthogonal if and only if

$$\|u + v\|^2 = \|u\|^2 + \|v\|^2.$$

Proof

First suppose that  $u$  and  $v$  are orthogonal.

$$\text{Therefore } u \cdot v = 0 \text{ — (P).}$$

$$\text{Since } \|u\|^2 = u \cdot u:$$

$$\begin{aligned} \text{So, } \|u + v\|^2 &= (u + v) \cdot (u + v) \\ &= u \cdot (u + v) + v \cdot (u + v) \\ &= u \cdot u + u \cdot v + v \cdot u + v \cdot v \\ &= \|u\|^2 + 0 + 0 + \|v\|^2 \quad [\text{using (P)}] \\ &= \|u\|^2 + \|v\|^2. \end{aligned}$$

Conversely

$$\begin{aligned} \text{suppose that } \|u + v\|^2 &= \|u\|^2 + \|v\|^2 \\ \Rightarrow (u + v) \cdot (u + v) &= \|u\|^2 + \|v\|^2 \\ \Rightarrow u \cdot u + u \cdot v + v \cdot u + v \cdot v &= \|u\|^2 + \|v\|^2 \\ \Rightarrow \|u\|^2 + u \cdot v + v \cdot u + \|v\|^2 &= \|u\|^2 + \|v\|^2 \\ \Rightarrow u \cdot v + v \cdot u &= 0 \\ \Rightarrow 2u \cdot v &= 0 \\ \Rightarrow u \cdot v &= 0 \end{aligned}$$

This means the vectors  $u$  and  $v$  are orthogonal.



### ⊗. Angles in $\mathbb{R}^2$ (or $\mathbb{R}^3$ ):

If  $u$  and  $v$  are two vectors in  $\mathbb{R}^2$  (or  $\mathbb{R}^3$ ) and if  $\theta$  be the angle between these vectors, then the dot product of  $u$  and  $v$  be defined as,

$$u \cdot v = \|u\| \|v\| \cos \theta$$

$$\Rightarrow \cos \theta = \frac{u \cdot v}{\|u\| \cdot \|v\|}$$

$$\Rightarrow \theta = \cos^{-1} \left( \frac{u \cdot v}{\|u\| \cdot \|v\|} \right)$$

Thus, the angle  $\theta$  between any two vectors  $u$  and  $v$  is defined as,

$$\theta = \cos^{-1} \left( \frac{u \cdot v}{\|u\| \cdot \|v\|} \right).$$

Example, Find the angle between the vectors  $(1, 0, -1)$  and  $(-1, 1, -1)$ .

Solution:

Let  $u = (1, 0, -1)$  and  $v = (-1, 1, -1)$ .

$$\begin{aligned} \text{Now, } \|u\| &= \sqrt{(1, 0, -1) \cdot (1, 0, -1)} \\ &= \sqrt{1+0+1} \\ &= \sqrt{2} \end{aligned}$$

$$\begin{aligned} \|v\| &= \sqrt{(-1, 1, -1) \cdot (-1, 1, -1)} \\ &= \sqrt{(-1)(-1) + 1 \times 1 + (-1) \times (-1)} \\ &= \sqrt{3} \end{aligned}$$

$$\begin{aligned} u \cdot v &= -1 + 0 + 1 \\ &= 0. \end{aligned}$$

$$\therefore \cos \theta = \frac{u \cdot v}{\|u\| \cdot \|v\|}$$

$$\text{or, } \cos \theta = \frac{0}{\sqrt{2} \cdot \sqrt{3}}$$

$$\text{or, } \theta = \cos^{-1}(0)$$

$$\text{or, } \theta = 90^\circ.$$

### ⊗. Orthogonal Sets:

A set of vectors  $\{u_1, u_2, \dots, u_p\}$  in  $\mathbb{R}^n$ , is said to be an orthogonal set if  $u_i \cdot u_j = 0$  for  $i \neq j$  for  $i, j = 1, 2, \dots, p$ .

Example 1: Examine a set of vectors  $\{u_1, u_2, u_3\}$  is an orthogonal set where  $u_1 = (2, -7, -1)$ ,  $u_2 = (-6, -3, 9)$  and  $u_3 = (3, 1, -1)$ ?

Solution:

$$\text{Given, } u_1 = (2, -7, -1), u_2 = (-6, -3, 9), u_3 = (3, 1, -1).$$

$$\text{Now, } u_1 \cdot u_2 = (2, -7, -1) \cdot (-6, -3, 9) = -12 + 21 - 9 = 0.$$

$$u_2 \cdot u_3 = (-6, -3, 9) \cdot (3, 1, -1) = -18 - 3 - 9 = -30 \neq 0$$

$$u_1 \cdot u_3 = (2, -7, -1) \cdot (3, 1, -1) = 6 - 7 + 1 = 0.$$

This shows that the set  $\{u_1, u_2, u_3\}$  is not an orthogonal set.



Example 2: Show that  $\{(3,1,1), (-1,2,1), (-\frac{1}{2}, -2, \frac{7}{2})\}$  is an orthogonal basis for  $\mathbb{R}^3$ . (12)

Solution:

Let,  $u_1 = (3,1,1), u_2 = (-1,2,1), u_3 = (-\frac{1}{2}, -2, \frac{7}{2})$ .

Here,  $u_1 \cdot u_2 = (3,1,1) \cdot (-1,2,1) = -3+2+1=0$ ,

$$u_2 \cdot u_3 = (-1,2,1) \cdot (-\frac{1}{2}, -2, \frac{7}{2}) = \frac{1}{2} - 4 + \frac{7}{2} = 0.$$

$$u_1 \cdot u_3 = (3,1,1) \cdot (-\frac{1}{2}, -2, \frac{7}{2}) = -\frac{3}{2} - 2 + \frac{7}{2} = 0.$$

Therefore,  $\{u_1, u_2, u_3\}$  is an orthogonal set.

Also,  $\|u_1\| = u_1 \cdot u_1 = (3,1,1) \cdot (3,1,1) = 9+1+1 = 11 \neq 0$

$$\|u_2\| = u_2 \cdot u_2 = (-1,2,1) \cdot (-1,2,1) = 1+4+1 = 6 \neq 0.$$

$$\|u_3\| = u_3 \cdot u_3 = (-\frac{1}{2}, -2, \frac{7}{2}) \cdot (-\frac{1}{2}, -2, \frac{7}{2}) = \frac{1}{4} + 4 + \frac{49}{4} = \frac{64}{4} = 16 \neq 0.$$

Since every orthogonal set of non-zero vectors is a basis for the subspace of the space.

Here  $\{u_1, u_2, u_3\}$  is an orthogonal set of vectors, so  $\{u_1, u_2, u_3\}$  is a basis for  $\mathbb{R}^3$  and therefore, is an orthogonal basis for  $\mathbb{R}^3$ .

### ⊛ An Orthogonal Projection:

Example: Find the orthogonal projection of  $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$  onto the line  $\begin{bmatrix} -1 \\ 3 \end{bmatrix}$  and the origin.

Solution,

let.  $y = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, u = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$  for projection onto the line.

Then,

$$y \cdot u = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 3 \end{bmatrix} = (-1)(-1) + (1)(3) = 1+3 = 4$$

$$u \cdot u = \begin{bmatrix} -1 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 3 \end{bmatrix} = (-1)(-1) + (3)(3) = 1+9 = 10.$$

Now, the orthogonal projection  $\hat{y}$  of  $y$  onto  $u$  is,

$$\begin{aligned} \hat{y} &= \left( \frac{y \cdot u}{u \cdot u} \right) \cdot u \\ &= \left( \frac{4}{10} \right) \begin{bmatrix} -1 \\ 3 \end{bmatrix} \\ &= \frac{2}{5} \begin{bmatrix} -1 \\ 3 \end{bmatrix}. \end{aligned}$$

### ⊛ Orthonormal sets:

Orthonormal set  $\rightarrow$  An orthogonal set of unit vectors, is called an orthonormal set.

Orthonormal basis  $\rightarrow$  If every vector of an orthogonal basis of unit vectors then the basis is called orthonormal basis.



✓ Note: An  $m \times n$  matrix  $U$  has orthonormal columns if and only if  $U^T U = I$ .

Example: Let  $U = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{2}{3} \\ \frac{1}{\sqrt{2}} & -\frac{2}{3} \\ 0 & \frac{1}{3} \end{bmatrix}$ . Then show that  $U$  has orthonormal columns if and only if  $U^T U = I$ .

Solution: Let  $U = [u_1 \ u_2]$   
where,  $u_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}$  and  $u_2 = \begin{bmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{bmatrix}$ .

$$\begin{aligned} \text{Then, } U^T U &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{2}{3} \\ \frac{1}{\sqrt{2}} & -\frac{2}{3} \\ 0 & \frac{1}{3} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2} + \frac{1}{2} + 0 & \frac{2}{3\sqrt{2}} - \frac{2}{3\sqrt{2}} + 0 \\ \frac{2}{3\sqrt{2}} - \frac{2}{3\sqrt{2}} + 0 & \frac{4}{9} + \frac{4}{9} + \frac{1}{9} \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\ &= I. \end{aligned}$$

Next,

$$u_1 \cdot u_1 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} = \frac{1}{2} + \frac{1}{2} + 0 = 1$$

$$u_2 \cdot u_2 = \begin{bmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{bmatrix} \cdot \begin{bmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{bmatrix} = \frac{4}{9} + \frac{4}{9} + \frac{1}{9} = 1$$

$$u_1 \cdot u_2 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \cdot \begin{bmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{1}{3} \end{bmatrix} = \frac{2}{3\sqrt{2}} - \frac{2}{3\sqrt{2}} + 0 = 0.$$

and similarly,  $u_2 \cdot u_1 = u_1 \cdot u_2 = 0$ .  
This shows that the columns  $u_1$  and  $u_2$  are orthonormal columns of  $U$ .



## ⊕ The Gram Schmidt Process

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The Gram Schmidt process is a simple process or algorithm to obtain an orthogonal or orthonormal basis for any non-zero subspace of  $\mathbb{R}^n$ .

Example: let  $x_1 = (1, -4, 0, 1)$  and  $x_2 = (7, -7, -4, 1)$ . If  $W = \text{Span}\{x_1, x_2\}$  then construct an orthogonal basis for  $W$  by using Gram-Schmidt process.

Solution:

Given  $x_1 = (1, -4, 0, 1)$  and  $x_2 = (7, -7, -4, 1)$ . Also let  $W = \text{Span}\{x_1, x_2\}$ . Then  $W$  is a subspace of  $\mathbb{R}^4$ . Let  $v_1 = x_1$ . By Gram-Schmidt process we construct vectors  $v_2$  so that  $\{v_1, v_2\}$  is an orthogonal basis for  $W$ .

$$\text{Take } v_1 = x_1 = (1, -4, 0, 1)$$

$$\text{and } v_2 = x_2 - \left( \frac{x_2 \cdot v_1}{v_1 \cdot v_1} \right) \cdot v_1$$

$$= x_2 - \left( \frac{x_2 \cdot x_1}{x_1 \cdot x_1} \right) x_1 \quad [\because v_1 = x_1]$$

$$= x_2 - \frac{(7, -7, -4, 1) \cdot (1, -4, 0, 1)}{(1, -4, 0, 1) \cdot (1, -4, 0, 1)} x_1$$

$$= x_2 - \frac{7 + 28 + 0 + 1}{1 + 16 + 0 + 1} x_1$$

$$= (7, -7, -4, 1) - \frac{36}{18} \cdot (1, -4, 0, 1)$$

$$= (5, 1, -4, -1).$$

This,  $\{v_1, v_2\}$  is an orthogonal set of non-zero vectors in  $W$ . Since  $W$  is defined by a basis of two vectors. So, the set  $\{v_1, v_2\}$  is an orthogonal basis for  $W$ .

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Remember that: ✓

$$v_1 = x_1$$

$$v_2 = x_2 - \left( \frac{x_2 \cdot v_1}{v_1 \cdot v_1} \right) \cdot v_1$$

$$v_3 = x_3 - \frac{x_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_3 \cdot v_2}{v_2 \cdot v_2} v_2$$

so on to  $v_p$

Then  $\{v_1, \dots, v_p\}$  is an orthogonal basis for  $W$



### ⑧. The QR-factorization Algorithm:

If  $A$  is an  $m \times n$  matrix with linearly independent columns then  $A$  can be factored as  $A = QR$  where  $Q$  is an  $m \times n$  matrix whose columns form an orthonormal basis for  $\text{col } A$  and  $R$  is an  $n \times n$  upper triangular invertible matrix with positive entries on its diagonal.

Example. Find QR-factorization of a matrix  $A$  where.

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

Solution:

Let the columns of  $A$  are  $x_1, x_2, x_3$ .

So,  $x_1 = (1, 1, 1, 1), x_2 = (0, 1, 1, 1), x_3 = (0, 0, 1, 1)$ .

Let  $v_1 = x_1 = (1, 1, 1, 1)$

Take  $v_2 = x_2 - \frac{x_2 \cdot v_1}{v_1 \cdot v_1} \cdot v_1$

$$= (0, 1, 1, 1) - \frac{(0, 1, 1, 1) \cdot (1, 1, 1, 1)}{(1, 1, 1, 1) \cdot (1, 1, 1, 1)} (1, 1, 1, 1)$$

$$= (0, 1, 1, 1) - \frac{3}{4} (1, 1, 1, 1)$$

$$= \frac{1}{4} (-3, 1, 1, 1)$$

Set  $v_2' = (-3, 1, 1, 1)$ .

$$\text{Also, } v_3 = x_3 - \frac{x_3 \cdot v_1}{v_1 \cdot v_1} \cdot v_1 - \frac{x_3 \cdot v_2'}{v_2' \cdot v_2'} \cdot v_2'$$

$$= (0, 0, 1, 1) - \frac{2}{4} (1, 1, 1, 1) - \frac{2}{12} (-3, 1, 1, 1)$$

$$= \frac{1}{3} (0, -2, 1, 1)$$

Set  $v_3' = (0, -2, 1, 1)$ .

Thus,  $\{v_1, v_2', v_3'\}$  be an orthogonal basis. Then let  $\{u_1, u_2, u_3\}$  be normalize of the orthogonal basis.

$$\text{So, } u_1 = \frac{v_1}{\|v_1\|} = \frac{(1, 1, 1, 1)}{2}$$

$$u_2 = \frac{v_2'}{\|v_2'\|} = \frac{(-3, 1, 1, 1)}{\sqrt{12}}$$

$$u_3 = \frac{v_3'}{\|v_3'\|} = \frac{(0, -2, 1, 1)}{\sqrt{6}}$$



Let  $Q$  be the matrix whose columns are  $u_1, u_2, u_3$ . Then

$$Q = \begin{bmatrix} 1/2 & -3/\sqrt{12} & 0 \\ 1/2 & 1/\sqrt{12} & -2/\sqrt{6} \\ 1/2 & 2/\sqrt{12} & 1/\sqrt{6} \\ 1/2 & 1/\sqrt{12} & 1/\sqrt{6} \end{bmatrix}$$

Since we have  $A = QR$ , by QR-factorization theorem. Then,  
 $Q^T A = Q^T (QR) = Q^T Q R = I R = R$ .

Now,

$$R = Q^T A$$

$$\Rightarrow R = \begin{bmatrix} 1/2 & 1/2 & 1/2 & 1/2 \\ -3/\sqrt{12} & 1/\sqrt{12} & 1/\sqrt{12} & 1/\sqrt{12} \\ 0 & -2/\sqrt{6} & 1/\sqrt{6} & 1/\sqrt{6} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 3/2 & 1 \\ 0 & 3/\sqrt{12} & 2/\sqrt{12} \\ 0 & 0 & 2/\sqrt{6} \end{bmatrix}$$

### ⊛. Least Squares Problems:

If  $A$  is  $m \times n$  matrix and  $b$  is in  $\mathbb{R}^m$  then a least square solution of  $Ax = b$  is an  $\hat{x}$  in  $\mathbb{R}^n$  such that  
 $\|b - A\hat{x}\| \leq \|b - Ax\|$  for all  $x$  in  $\mathbb{R}^n$ .

Note: The least-squares solution of  $Ax = b$  satisfies the equation

The matrix eqn  $A^T A x = A^T b$  — (1).  
 represents a system of equations called the normal equations for  $Ax = b$ . A solution of (1) is often denoted by  $\hat{x}$ .

Example 1: Find the least-squares solution of the inconsistent system  $Ax = b$  for  $A = \begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix}$ ,  $b = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$ .

Solution:-

$$\text{Here, } A^T A = \begin{bmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{bmatrix} \begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 17 & 1 \\ 1 & 5 \end{bmatrix}.$$

Since the least-squares solution of  $Ax = b$  satisfies the equation  $A^T A x = A^T b$ .

$$\text{Therefore } \hat{x} = (A^T A)^{-1} (A^T b) \text{ — (2)}$$



Here,  $|A^T A| = \begin{vmatrix} 17 & 1 \\ 1 & 5 \end{vmatrix} = 84 \neq 0.$

Then,  $(A^T A)^{-1} = \frac{1}{84} \begin{bmatrix} 5 & -1 \\ -1 & 17 \end{bmatrix}$

Therefore ① becomes,

$$\begin{aligned} \hat{x} &= \frac{1}{84} \begin{bmatrix} 5 & -1 \\ -1 & 17 \end{bmatrix} \begin{bmatrix} 19 \\ 11 \end{bmatrix} \\ &= \frac{1}{84} \begin{bmatrix} 84 \\ 168 \end{bmatrix} \\ &= \begin{bmatrix} 1 \\ 2 \end{bmatrix} \end{aligned}$$

Example 2: Determine the least-square error in the least-squares solution of  $Ax=b$  where  $A$  and  $b$  are  $\begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix}$  and  $\begin{bmatrix} 2 \\ 0 \\ 11 \end{bmatrix}$ .

Solution:-

$A$  &  $b$  use in this are same as in example 1

From previous example we have  $\hat{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ .

Then,  $A\hat{x} = \begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 3 \end{bmatrix}.$

So,  $b - A\hat{x} = \begin{bmatrix} 2 \\ 0 \\ 11 \end{bmatrix} - \begin{bmatrix} 4 \\ 4 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ -4 \\ 8 \end{bmatrix}$

and  $\|b - A\hat{x}\| = \sqrt{(-2)^2 + (-4)^2 + (8)^2} = \sqrt{84}.$

Thus, the least square error is  $\sqrt{84}$ .

Note:-  $\|Av\| < \|Au\|$  shows  $v$  is the least square solution of  $Ax=b$ .