

Section 1.1Background

$y = y(x)$
 ↑ independent variable
 ↙ dependent variable

$$\frac{dy}{dx}, \frac{d^2y}{dx^2}, \dots$$

$z = z(x, y)$
 ↖ ↗ independent variables
 ↙ dependent variable

$$\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}, \frac{\partial^2 z}{\partial x^2}, \frac{\partial^2 z}{\partial x \partial y}, \frac{\partial^2 z}{\partial y^2}, \dots$$

Definition

An equation involving the derivatives of a dependent variable w.r.t. one or more independent variables is called a differential equation (d.e.).

If only one independent variable occurs it is an ordinary differential equation (o.d.e.), otherwise it is a partial differential equation (p.d.e.).

Definition

The order of a d.e. is the order of the highest derivative it contains.

(2)

Definition

A 1st order o.d.e. is said to be linear if it can be written in the form

$$a_0(x) \frac{dy}{dx} + a_1(x)y = b(x), \quad a_0(x) \neq 0$$

A 2nd order o.d.e. is said to be linear if it can be written in the form

$$a_0(x) \frac{d^2y}{dx^2} + a_1(x) \frac{dy}{dx} + a_2(x)y = b(x), \quad a_0(x) \neq 0$$

3rd order
linear

$$a_0(x) \frac{d^3y}{dx^3} + a_1(x) \frac{d^2y}{dx^2} + a_2(x) \frac{dy}{dx} + a_3(x)y = b(x), \quad a_0(x) \neq 0$$

nth order
linear

$$a_0(x) \frac{d^ny}{dx^n} + a_1(x) \frac{d^{n-1}y}{dx^{n-1}} + a_2(x) \frac{d^{n-2}y}{dx^{n-2}} + \dots$$

$$\dots + a_{n-1}(x) \frac{dy}{dx} + a_n(x)y = b(x), \quad a_0(x) \neq 0$$

Example 1

Describe the following equations :

a) $\frac{d^3y}{dx^3} + x^2 \frac{d^2y}{dx^2} + \ln x \cdot \frac{dy}{dx} + e^x y = 2^x$

ode order = 3 linear

b) $\frac{d^2y}{dx^2} + x^2 \left(\frac{dy}{dx} \right)^4 + 6y = \sin x$

ode order = 2 non-linear

$$c) \frac{d^2 y}{dr^2} + r^4 \cos y = 4e^{-r}$$

ode order = 2 non-linear

$$d) \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$$

pde order = 2 linear

Example 2

Write a differential equation that fits the physical description: The velocity at time t of a particle moving along a straight line is proportional to the fourth power of its position x .

Solution velocity = $\frac{dx}{dt} \propto x^4$

$$\therefore \frac{dx}{dt} = kx^4, \quad k = \text{constant}$$

HW pp. 5 : 1-15 odd