

# Study Plan — Computer Animation (3rd ed.)

## User Story Template & Chapter Cards

### How to Use This Document

Each chapter of Rick Parent’s *Computer Animation, 3rd Edition* is represented as a **user story card**. Cards include the business value, persona, dependencies, acceptance criteria, and a concrete **Tasks** checklist. Duplicate a card when you need variants (e.g., an advanced path using C++/OpenGL instead of Python/Blender). Compile with **pdflatex** (no special packages beyond those in this file).

### Required Data for a Good Story

- **ID & Title** (e.g., CA-03 -- Interpolating Values).
- **Epic/Feature** the story rolls up to (e.g., “Animation Core”).
- **Business Value** stated in stakeholder language.
- **Priority & Estimate** (e.g., Must/Should + story points).
- **Persona** performing the work (e.g., “technical animator”).
- **Dependencies** (tools, rigs, prior chapters).
- **Assumptions/Risks** that might affect scope or timing.
- **Story sentence**: *As a persona, I want capability so that value.*
- **Non-Functional tags** (performance, reliability, security, ...).
- **Acceptance Criteria** in *Given–When–Then* form.
- **Tasks** as a bite-size, checkable list.

### User Story Template (Example)

|  |  |
|--|--|
| <div></div>  |  |
| <b>Epic / Feature</b>  | Production Foundations   |
| <b>Business Value</b>  | Shared understanding of scope and success criteria to reduce rework. |
| <b>Priority / Estimate</b>   | <b>Priority:</b> Must <b>SP:</b> 2                                   |
| <b>Persona</b>   | developer on a new repo  |
| <b>Dependencies</b>  | build tooling, unit test framework                                   |
| <b>Assumptions / Risks</b>   | schedule risk if team lacks a common story format; ambiguity risk    |
| <b>Story</b> <i>As a developer, I want a consistent user story template so that the team can plan and verify work objectively.</i> |  |
| <b>Non-Functional</b>  | <div>PerformanceSecurityReliabilityAccessibilityPrivacyi18n</div>    |

## Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** the repository with this L<sup>A</sup>T<sub>E</sub>X template is available

**When** the author completes the *Tasks* below

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all1y checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Fill in ID/Title, Business Value, Persona, Dependencies, Assumptions/Risks.
- ☐ Draft the story sentence using “As a ... I want ... so that ...”.
- ☐ Write 1–3 *Given–When–Then* acceptance criteria.
- ☐ Break work into 4–7 tasks (each 15–90 minutes).
- ☐ Review with a peer; commit the story card to the project docs.

|                            |   |
|----------------------------|---|
| <b>Epic / Feature</b>      | Orientation & Pipeline  |
| <b>Business Value</b>      | Establish shared understanding of modern CG animation workflow and course outcomes. |
| <b>Priority / Estimate</b> | <b>Priority:</b> Must <b>SP:</b> 2  |
| <b>Persona</b>             | student/TD onboarding to the course plan  |
| <b>Dependencies</b>        | Blender or equivalent DCC; Python 3.x; Git repo for notes/clips                     |
| <b>Assumptions / Risks</b> | time-boxed to one week; risk of tool setup delays                                   |

**Story** *As a learner, I want to map the CG animation pipeline and pick a final-shot concept so that weekly work aligns to a coherent end goal.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** the toolchain installs successfully

**When** the learner produces a brief animatic and a pipeline diagram

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Sketch the pipeline: assets → rig → animation → sim → lighting/render → comp.
- ☐ Create a 10–15s animatic (stepped keys or storyboard with timing).
- ☐ Set up project repo folders for **notes/**, **clips/**, **refs/**.
- ☐ Write risks & constraints for your capstone shot (1 page).

|                            |   |
|----------------------------|---|
| <b>Epic / Feature</b>      | Math & Transforms   |
| <b>Business Value</b>      | Reliable transforms/orientations prevent gimbal issues and rig instability. |
| <b>Priority / Estimate</b> | <b>Priority:</b> Must <b>SP:</b> 3  |
| <b>Persona</b>             | technical animator / TD   |
| <b>Dependencies</b>        | Python notebooks or C++ utility library; test meshes                        |
| <b>Assumptions / Risks</b> | numeric instability if conventions (handedness, units) are inconsistent     |

**Story** *As a TD, I want robust transform/orientation utilities so that rigs and cameras behave predictably.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

#### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** reference tests are available

**When** matrix/quaternion conversions and parent/child transforms pass unit tests

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

#### Tasks

- ☐ Implement 4x4 homogeneous transforms; verify inverse and composition.
- ☐ Implement quaternion  $\leftrightarrow$  matrix / axis-angle; add unit tests.
- ☐ Build a demo rig (2-bone chain) to visualize local vs world transforms.
- ☐ Document conventions (axes, degrees/radians, units).

**Epic / Feature** Curves & Timing

**Business Value** Smooth, controllable motion and camera paths with consistent speed profiling.

**Priority / Estimate** **Priority:** Must **SP:** 3

**Persona** animator / tools engineer

**Dependencies** curve evaluation utilities; plotting

**Assumptions / Risks** time slippage from arc-length reparametrization if not cached

**Story** *As an animator, I want spline and orientation interpolation so that paths and rotations are smooth and predictable.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

**Acceptance Criteria (BDD)**

**Scenario** Happy path

**Given** test paths and keyframes exist

**When** constant-speed motion along a spline and correct SLERP orientation

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all1y checks; Docs updated; Delivered/flagged.

**Tasks**

- ☐ Implement Cubic Hermite, Catmull–Rom, and B-spline evaluation.
- ☐ Implement SLERP; compare with normalized LERP (error plot).
- ☐ Reparametrize a path by arc length; demonstrate constant-speed fly-through.
- ☐ Render a 5s camera move before/after reparam (side-by-side).

**Epic / Feature**

Keyframing & Shape Interp

**Business Value**

Artist-friendly controls for timing and deformations.

**Priority / Estimate**

**Priority:** Should    **SP:** 3

**Persona**

animator

**Dependencies**

blendshape targets; keyframe editor

**Assumptions / Risks**

topology mismatch breaks shape interpolation

**Story** *As an animator, I want a keyframe editor and blendshape mixer so that I can sculpt timing and shape changes.*

**Non-Functional**

Performance

Security

Reliability

Accessibility

Privacy

i18n

**Acceptance Criteria (BDD)**

**Scenario** Happy path

**Given** targets and rig are available

**When** morph and keyed timing match the reference beat sheet

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set.

All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

• *Definition of Done:*

#### Tasks

- ☐ Build a mini keyframe editor (stepped/linear/bezier tangents).
- ☐ Create 3–5 blendshape targets; implement normalized weight mixing.
- ☐ Animate a 10s morph sequence with clean in-betweens.
- ☐ Export a turntable clip of neutral vs extreme shapes.

**Epic / Feature**  
**Business Value**

FK/IK Rigs  
Fast posing with constraints to reduce foot sliding and joint breakage.

**Priority / Estimate**

**Priority:** Must    **SP:** 4

**Persona**

rigger / animator

**Dependencies**

test character; solver utilities

**Assumptions / Risks**

solver divergence near singularities

**Story** *As a rigger, I want stable FK/IK with joint limits so that animators can reach targets without artifacts.*

**Non-Functional**

Performance

Security

Reliability

Accessibility

Privacy

i18n

**Acceptance Criteria (BDD)**

**Scenario** Happy path

**Given** rig joint limits are set

**When** IK solver reaches target within tolerance and without popping

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set.

All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

• *Definition of Done:*

#### Tasks

- ☐ Implement CCD and Jacobian-transpose IK; log iteration counts.
- ☐ Add joint limits, pole vector, preferred angles.
- ☐ Animate a 5–10s reach-and-grasp on a moving object.
- ☐ Plot end-effector error over time; ensure monotonic convergence.

**Epic / Feature** MoCap Pipeline

**Business Value** High-fidelity base motion retargeted to house rigs with minimal cleanup.

**Priority / Estimate** **Priority:** Should **SP:** 4

**Persona** motion TD

**Dependencies** BVH/FBX clips; OpenCV; retarget tool

**Assumptions / Risks** foot drift and scale mismatches require cleanup

**Story** *As a motion TD, I want to retarget and blend MoCap so that I can quickly block complex performances.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** calibration data and clips exist

**When** retargeted animation passes foot-contact checks and timing constraints

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Calibrate camera(s) and reconstruct a simple 3D point set.
- ☐ Retarget BVH to course rig; fix contacts with constraints.
- ☐ Blend two clips; add time-warp to match beats.
- ☐ Produce an 8–12s walk-to-reach composite before/after cleanup.



|                            |  |
|----------------------------|--|
| <b>Epic / Feature</b>      | Particles, Rigid, Cloth                                |
| <b>Business Value</b>      | Realistic secondary motion increases production value. |
| <b>Priority / Estimate</b> | <b>Priority:</b> Must <b>SP:</b> 5                     |
| <b>Persona</b>             | VFX TD   |
| <b>Dependencies</b>        | physics integrators; collision library                 |
| <b>Assumptions / Risks</b> | instability with large time steps; tuning time         |

**Story** *As a VFX TD, I want stable particle/rigid/cloth sims so that shots look physically plausible.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** collision proxies exist

**When** sims run without explosion and meet timing budgets

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set.    •    *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Implement particle forces and emitters; add lifetime and randomness.
- ☐ Build mass-spring cloth; compare explicit vs semi-implicit integration.
- ☐ Add rigid bodies with impulse collisions (restitution, friction).
- ☐ Render a 10s composite: ball hits boxes; cloth banner reacts.

**Epic / Feature** Fluid Effects  
**Business Value** Believable smoke/water interactions for hero shots.  
**Priority / Estimate** **Priority:** Should **SP:** 5  
**Persona** FX artist / TD  
**Dependencies** grid solver (2D); SPH prototype; render volumes  
**Assumptions / Risks** cost constraints on resolution/time; coupling to colliders

**Story** *As an FX TD, I want smoke and liquid sims so that I can art-direct turbulent motion efficiently.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** domain and sources are set

**When** smoke shows vorticity confinement and liquid shows plausible splashes

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Implement a 2D stable fluids grid (advection, diffuse, project).
- ☐ Prototype SPH for splashes; tune kernel radius/viscosity.
- ☐ Add collider coupling; emitters for smoke and pour.
- ☐ Render an 8–10s flipbook comparing parameter sweeps.

**Epic / Feature** Virtual Humans  
**Business Value** Solid deformations and locomotion for character shots.  
**Priority / Estimate** **Priority:** Must **SP:** 5  
**Persona** character TD  
**Dependencies** skinned mesh; skin weights; terrain asset  
**Assumptions / Risks** skinning artifacts at joints; foot sliding on uneven terrain  
**Story** *As a character TD, I want robust skinning and a walk cycle so that human motion reads believably.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** weights and controls are defined

**When** walk cycle maintains COM over support polygon; no interpenetration

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Paint skin weights; test extreme poses; fix elbow/shoulder artifacts.
- ☐ Animate a gait cycle with contact and passing phases.
- ☐ Add simple garment (shirt/skirt) interacting with body.
- ☐ Render a 10s walk over uneven terrain; measure stride and cadence.

|                            |  |
|----------------------------|--|
| <b>Epic / Feature</b>      | Face Rig & Lip-Sync  |
| <b>Business Value</b>      | Expressive dialogue and emotions for storytelling.                   |
| <b>Priority / Estimate</b> | <b>Priority:</b> Should <b>SP:</b> 4                                 |
| <b>Persona</b>             | facial rigger / animator   |
| <b>Dependencies</b>        | blendshapes or FACS AUs; audio clip                                  |
| <b>Assumptions / Risks</b> | coarticulation timing; uncanny valley risk if eyes/eyelids misbehave |

**Story** *As a facial animator, I want a viseme-driven rig so that lip-sync and expressions feel natural.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** audio and transcript exist

**When** lip closures on labials are correct; eye focus is consistent; no popping

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set.    •    *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Build facial controls (brows, lids, lips, jaw); map visemes to shapes.
- ☐ Time-align phonemes; add coarticulation smoothing.
- ☐ Animate 10–15s dialogue with micro-motions (eye saccades, blinks).
- ☐ Export with audio waveform overlay for review.

**Epic / Feature** Agents & Crowds  
**Business Value** Scalable background motion and intelligent navigation.  
**Priority / Estimate** **Priority:** Could **SP:** 4  
**Persona** gameplay/AI engineer  
**Dependencies** navmesh; pathfinding; steering behaviors  
**Assumptions / Risks** congestion at bottlenecks; performance drops with agent count  
**Story** *As an AI engineer, I want steering and pathfinding so that crowds navigate scenes convincingly.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** map and obstacles are defined

**When** agents reach goals with low collision rate and stable frame time

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Implement seek/arrive/wander and obstacle avoidance; blend behaviors.
- ☐ Build a navmesh; pathfind with A\*; add local avoidance.
- ☐ Simulate 50–200 agents through a choke point; measure throughput.
- ☐ Render a 15s crowd flow; record collision metrics.

|                            |   |
|----------------------------|---|
| <b>Epic / Feature</b>      | Procedural Models   |
| <b>Business Value</b>      | Quickly generate complex detail (plants, blobs, smooth surfaces). |
| <b>Priority / Estimate</b> | <b>Priority:</b> Could <b>SP:</b> 4                               |
| <b>Persona</b>             | look-dev / TD   |
| <b>Dependencies</b>        | metaball/implicit surface tools; L-system module                  |
| <b>Assumptions / Risks</b> | temporal coherence during deformation; performance                |

**Story** *As a look-dev TD, I want implicit surfaces and plant growth so that I can generate rich motion without manual modeling.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** procedural modules are wired

**When** garden growth is temporally coherent and controllable

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Implement metaballs and preview via marching cubes/squares.
- ☐ Build an L-system with stochastic rules; add wind sway.
- ☐ Apply subdivision (Catmull–Clark/Loop) with crease control.
- ☐ Render a 10s procedural garden pullback (wireframe + shaded passes).

**Epic / Feature**

Rendering & Delivery

**Business Value**

Predictable render times and delivery-ready media.

**Priority / Estimate**

**Priority:** Must **SP:** 2

**Persona**

lighting/compositing TD

**Dependencies**

render farm or local batch; FFmpeg

**Assumptions / Risks**

render time vs quality trade-offs

**Story** *As a lighting TD, I want sampling/motion-blur controls so that finals balance quality and cost.*

**Non-Functional**

Performance

Security

Reliability

Accessibility

Privacy

i18n

**Acceptance Criteria (BDD)**

**Scenario** Happy path

**Given** scenes are renderable

**When** finals and preview renders differ only in controlled quality parameters

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:*

All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

#### Tasks

- ☐ Compare sample counts and reconstruction filters; enable motion blur.
- ☐ Batch-render best shots at “preview” and “final” settings; log timings.
- ☐ Package output with correct color space and bitrate using FFmpeg.

|                            |   |
|----------------------------|---|
| <b>Epic / Feature</b>      | Math Companion  |
| <b>Business Value</b>      | Faster debugging and verifiable numerics across chapters. |
| <b>Priority / Estimate</b> | <b>Priority:</b> Should <b>SP:</b> 2                      |
| <b>Persona</b>             | TD / engineer   |
| <b>Dependencies</b>        | Jupyter or C++ test harness                               |
| <b>Assumptions / Risks</b> | overfitting tests to specific scenes                      |

**Story** *As a TD, I want a math/test companion so that I can validate formulas and catch regressions quickly.*

**Non-Functional** Performance Security Reliability Accessibility Privacy i18n

### Acceptance Criteria (BDD)

**Scenario** Happy path

**Given** reference equations are captured

**When** unit tests for each formula pass and are linked to chapter cards

**Then** the stated Outcomes/Deliverables for this chapter are produced and verifiable.

*Definition of Ready:* Persona clear; AC drafted; Dependencies known; Estimate set. • *Definition of Done:* All ACs pass; Tests green; Security/all checks; Docs updated; Delivered/flagged.

### Tasks

- ☐ Create a notebook per chapter; derive and validate key equations.
- ☐ Add finite-difference checks for Jacobians and gradients.
- ☐ Track assumptions (units, handedness, conventions) alongside tests.