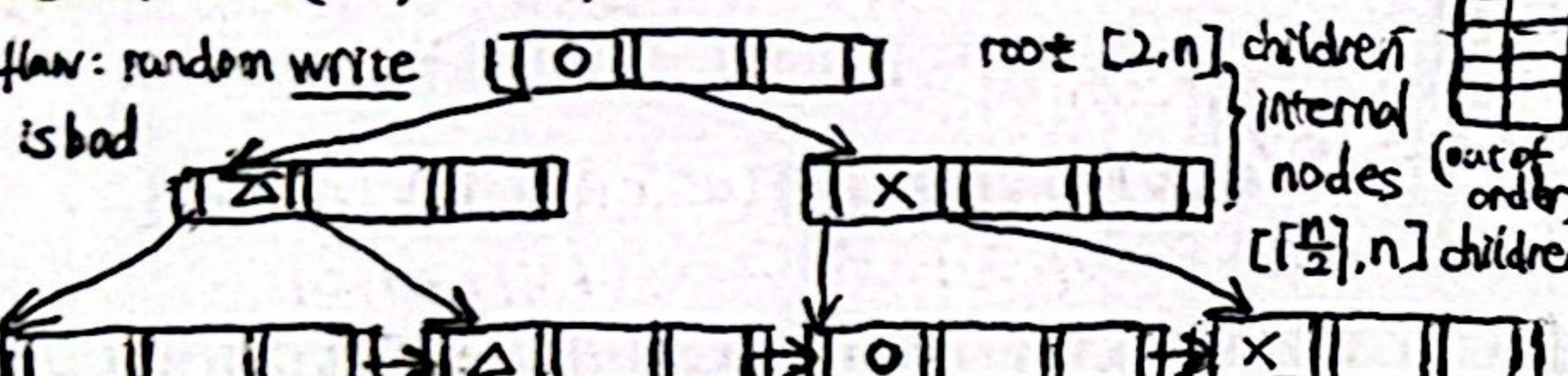


7. Indexing

search key
clustering/primary index: 检索键顺序 = 文件内顺序
nonclustering/secondary index: 不同
dense v.s. sparse: 是否每个 search key 都有 index
multilevel index → binary search
nonunique search key

B+ Tree: $(n-1)sk + n \text{ ptr}$

flaw: random write
is bad



range search: $\text{findRange}(lb, ub) \geq \lceil \frac{n-1}{2} \rceil$ values leaf nodes (in order)

update = delete old + insert new

find → delete underflow

merge with sibling overflow

redistribute overflow

Complexity (height of tree, N entries)

best (all-full): $H_{\text{min}} = 1 + \log_2 \lceil \frac{N}{n-1} \rceil$

worst (half-full): $H_{\text{max}} = 2 + \log_2 \lceil \frac{N}{(n-1)/2} \rceil$

B+ Tree 文件插入: 本真表插入

bulk loading: 一次插入多个项 (有序)

Hashing

search keys

hash function buckets

of B = $\frac{Nr}{B} \cdot (1+d)$

$h(K)=B$

B

桶的个数

LSM Trees

Memory

insert

others

Disk

projection → duplicate

sort

sk

of L = k · # of L

internal node

插入: 不到 leaf, 先到 buffer, buffer 里

no yes

再到叶下缓冲区, 可以 leaf

Bitmap Indices

Transformation: $(O_1, O_2, E_1, E_2) \equiv (O_1, E) \wedge O_2(E_2)$

of bits = # of records

equivalence rules (partial): $E_1 \Delta E_2 \equiv E_2 \Delta E_1$ → assume evenly distribute

连接有交集 符合律

cost estimation: $t_r, br, tr, fr, V(A, r)$

selection: N_r

join: $r \times s \rightarrow n_r \times n_s$ tuples, $(n_r + s)$ bytes

join: $R \times S \Rightarrow R \times S$

join: $R \times S \Rightarrow R \times S$