

Comprehensive Technical Report

Automated Material Stream Identification System

Github Repo URL: <https://github.com/NourEldeenM/material-stream-identification-system/tree/main>

1. Summary

This report presents a comprehensive summary of an Automated Material Stream Identification (MSI) system designed to classify waste materials into six categories: Glass, Paper, Cardboard, Plastic, Metal, and Trash. The system achieves **95.33% accuracy** using DL-based feature extraction (ResNet50) combined with Support Vector Machine (SVM) classification.

Key Points:

- Implemented data augmentation increasing dataset size (1,960 → 3,000 image)
- Feature Extraction using ResNet50 CNN
- KNN and SVM classifiers
- Developed real-time classification system with web-based interface

2. Feature Extraction Methods

ResNet50 Convolutional Neural Network

ResNet50 is a pre-trained DL model with 50 layers.

Overview:

- **Depth:** 50 layers
- **Pre-training:** ImageNet dataset
- **Feature Extraction:** Average Pooling
- **Output dimensions:** 2,048 features

Implementation :

```
ResNet50(weights='imagenet', include_top=False, pooling='avg')
```

- Remove final classification layer (include_top=False)
- Apply average pooling
- Extract 2,048-dimensional features
- Input image size: 224×224×3

Results:

- Training Accuracy: 100%

- Testing Accuracy: **95.33%** on SVM classifier and **93.17%** on KNN classifier

Advantages:

1. **Semantic features**
 2. **Transfer learning**
 3. **Reduced dimensionality**
 4. **Better generalization**
 5. **Robust to variations**
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3. Classifiers Comparison

3.1 k-Nearest Neighbors (k-NN)

Algorithm Overview

k-NN is a non-parametric, instance-based learning algorithm that classifies samples based on the majority vote of their k nearest neighbors.

Classification Decision:

```
For a new sample:  
1. Calculate distance to all training samples  
2. Select k nearest neighbors  
3. Majority vote determines class
```

Implementation Details

Hyperparameters:

- **k (neighbors):** 3 (optimized via GridSearchCV)
- **Distance metric:** Manhattan (optimized via GridSearchCV)
- **Weighting:** Distance-weighted (closer neighbors have more influence) (optimized via GridSearchCV)
- **Rejection threshold:** 0.6 (confidence-based unknown detection)

Distance Metrics Evaluated:

- **Euclidean:** $\sqrt{(\sum(x_i - y_i)^2)}$
- **Manhattan:** $\sum|x_i - y_i|$
- **Minkowski:** $(\sum|x_i - y_i|^p)^{(1/p)}$

Feature Preprocessing

StandardScaler Normalization:

```
X_scaled = (X - mean) / std_deviation
```

Hyperparameter Tuning

Grid Search:

```
param_grid = {
    'n_neighbors': [3, 5, 7, 9, 11, 15],
    'weights': ['uniform', 'distance'],
    'metric': ['euclidean', 'manhattan', 'minkowski']
}
```

Cross-Validation:

- 5-fold stratified cross-validation

Optimal Parameters Found:

- k = 3
- weights = 'distance'
- metric = 'euclidean'

Rejection Mechanism

Confidence-Based Unknown Detection:

```
if max_probability < rejection_threshold:
    prediction = 'Unknown'
else:
    prediction = argmax(probabilities)
```

Performance Results

Metric	Value
Training Accuracy	100%
Testing Accuracy	93.17%
Best k	3
Best Metric	Euclidean
Feature Dimensions	2,048
Training Samples	2,400
Testing Samples	600

3.2 Support Vector Machine (SVM)

Algorithm Overview

SVM finds the optimal hyperplane that maximizes the margin between classes in high-dimensional space.

Objective: Maximize margin while minimizing classification error

Implementation Details

Multi-class Strategy: One-vs-Rest (OvR):

- Train 6 binary classifiers (one per class)
- Each classifier: "class i" vs. "all other classes"
- Final prediction: class with the highest confidence

Probability:

```
probability=True
```

Converts SVM decision scores to probabilities for confidence estimation.

Performance Results

Metric	Value
Training Accuracy	100%
Testing Accuracy	95.33%
Kernel	rbf
C	3
Gamma	scale

4. Data Augmentation

Initial Dataset:

- Total: 1,960 images
- 95 Corrupt images

Target:

- Minimum 30% increase
- Balanced classes
- Final: 3,000 images

Augmentation Techniques

1. Rotation ($\pm 30^\circ$)

2. **Horizontal Flip**
3. **Vertical Flip**
4. **Brightness Up (1.1-1.3×)**
5. **Brightness Down (0.7-0.9×)**
6. **Scale Up (1.1-1.2×)**
7. **Scale Down (0.8-0.9×)**

Implementation Strategy

- Skipped 95 corrupt images
 - Validated all augmented images
 - Maintained original test set separate (to prevent data leakage)
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5. System Architecture

Overview

```
Camera → Image Capture → Preprocessing → Feature Extraction → Classification →  
Display  
(224x224 RGB)     (Normalize)     (ResNet50)     (SVM/KNN)     (UI)
```

Tech Stack

Backend:

- FastAPI (REST API)
- Python
- TensorFlow/Keras (ResNet50)
- scikit-learn (KNN/SVM)
- OpenCV

Frontend:

- React.js
 - Vite build tool
 - Webcam component
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Models Configuration Details

k-NN Classifier Configuration

```
KNeighborsClassifier(  
    n_neighbors=3,  
    weights='distance',  
    metric='manhattan',
```

```
n_jobs=-1  
)
```

SVM Classifier Configuration

```
SVC(  
    kernel='rbf',  
    C=30,  
    gamma='scale',  
    rejection_threshold=0.4  
)
```

ResNet50 Feature Extractor Configuration

```
ResNet50(  
    weights='imagenet',  
    include_top=False,  
    pooling='avg'  
)
```