A picture containing text

Description automatically generated

**Ain Shams University**

**Faculty of Computer and Information Science**

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**Bioinformatics department**

**Project Title**

**Parallel Median Filter**

**By Team**

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**What is salt and pepper noise?**

Salt-and-pepper noise, also known as impulse noise, is a form of [noise](https://en.wikipedia.org/wiki/Image_noise) sometimes seen on [digital images](https://en.wikipedia.org/wiki/Digital_image). This noise can be caused by sharp and sudden disturbances in the image signal. It presents itself as sparsely occurring white and black [pixels](https://en.wikipedia.org/wiki/Pixel).

An effective [noise reduction](https://en.wikipedia.org/wiki/Noise_reduction) method for this type of noise is the [median filter](https://en.wikipedia.org/wiki/Median_filter)

**Median filter**

The median filter is a non-linear [digital filtering](https://en.wikipedia.org/wiki/Digital_filter) technique, often used to remove [noise](https://en.wikipedia.org/wiki/Signal_noise) from an image or signal. Such [noise reduction](https://en.wikipedia.org/wiki/Noise_reduction) is a typical pre-processing step to improve the results of later processing (for example, [edge detection](https://en.wikipedia.org/wiki/Edge_detection) on an image). Median filtering is very widely used in digital [image processing](https://en.wikipedia.org/wiki/Image_processing) because, under certain conditions, it preserves edges while removing noise (but see the discussion below), also having applications in [signal processing](https://en.wikipedia.org/wiki/Signal_processing).

**A close-up of the front and the back of a coin

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**Enhancements and findings**

* The time complexity of the median filter in sequential code is O(Width\*Height\* filterSize^2). Width \* Height to filter each pixel in the image and filterSize^2 as each pixel is filtered according to its (filterSize^2) neighbors.
* By using MPI (message passing interface), the image was distributed across N number of processors, each executing the code of the median filter, and the results were gathered at a specific core, to reconstruct the filtered image.

**Results**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | N\*N | 2N\*2N | 5N\*5N | 10N\*10N |
| Sequential | 366 | 263 | 1602 |  |
| MPI solution | 216 | 755 | 4611 |  |