

Computer Architecture , project B

Title : Car Parking System

Section : 4C2

Group number : 2

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The project aim :

We want to create a private parking that allows certain people to enter through the gate which has an entrance sensor that is activated by cars approaching the gate, the gate will ask for a password, afterwards if the LED light turns green it indicates that the password was entered correctly so the gate will open. However if the LED light turns red it refers to that the password was entered incorrectly so the gate will refuse to open. After the car enters the exit sensor will detect it and the gate will be locked, At the end the password monitor will reset to its main screen for the next car.

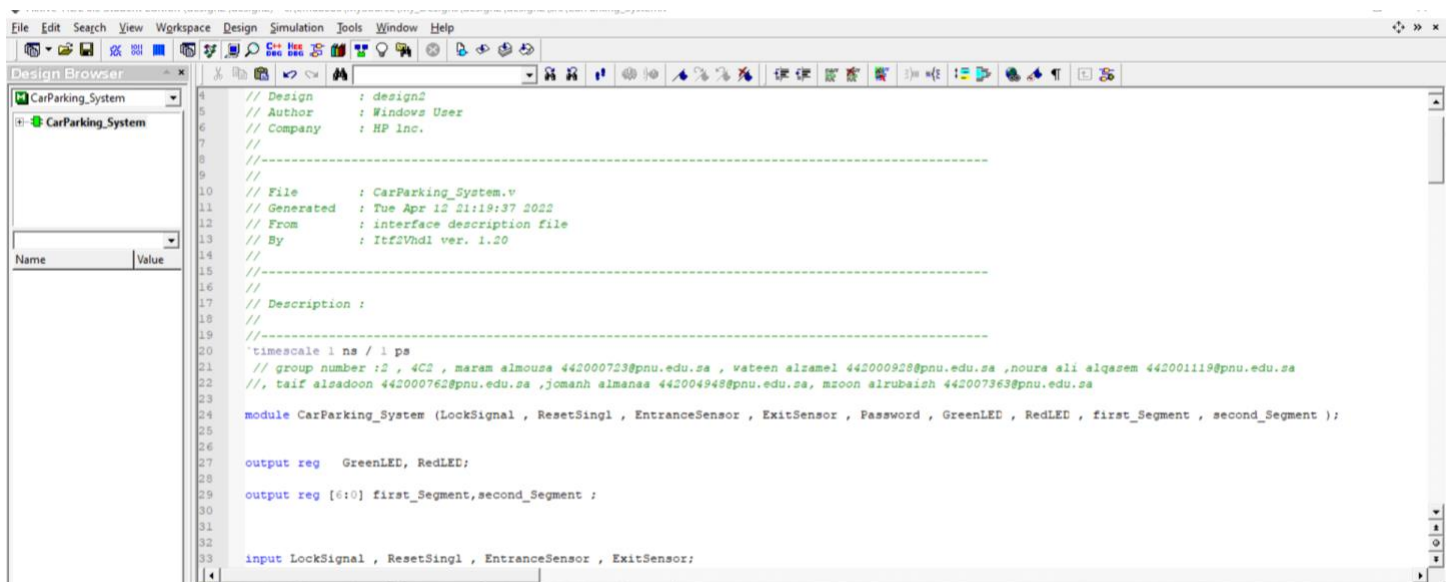
The input:

LockSignal , ResetSignal, EntranceSensor, ExitSensor and Password

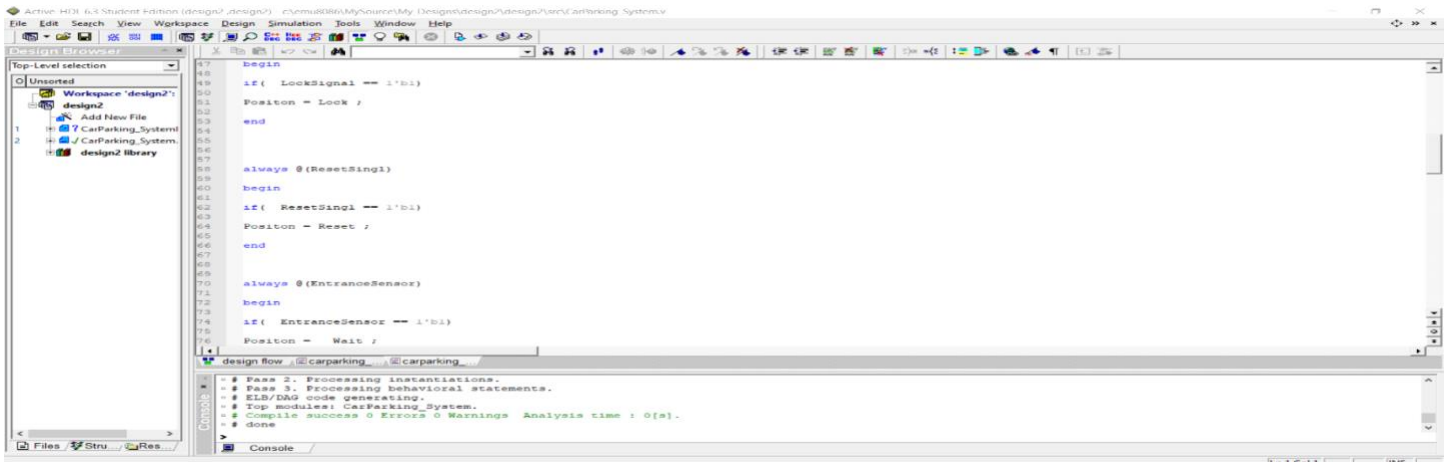
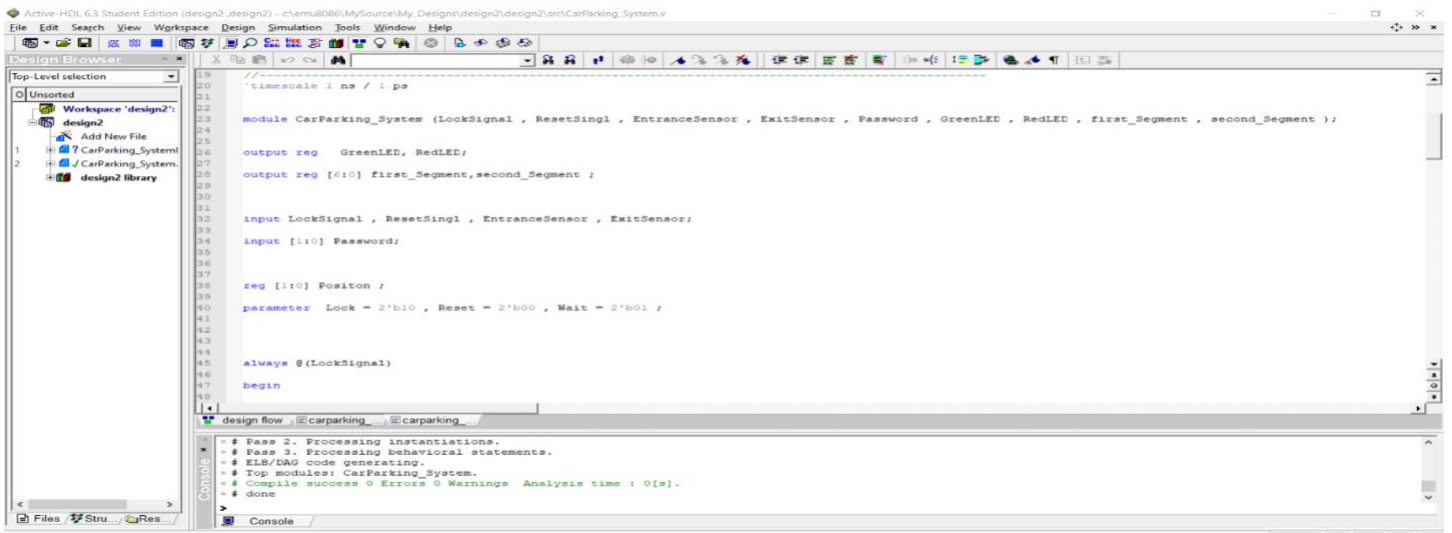
The output:

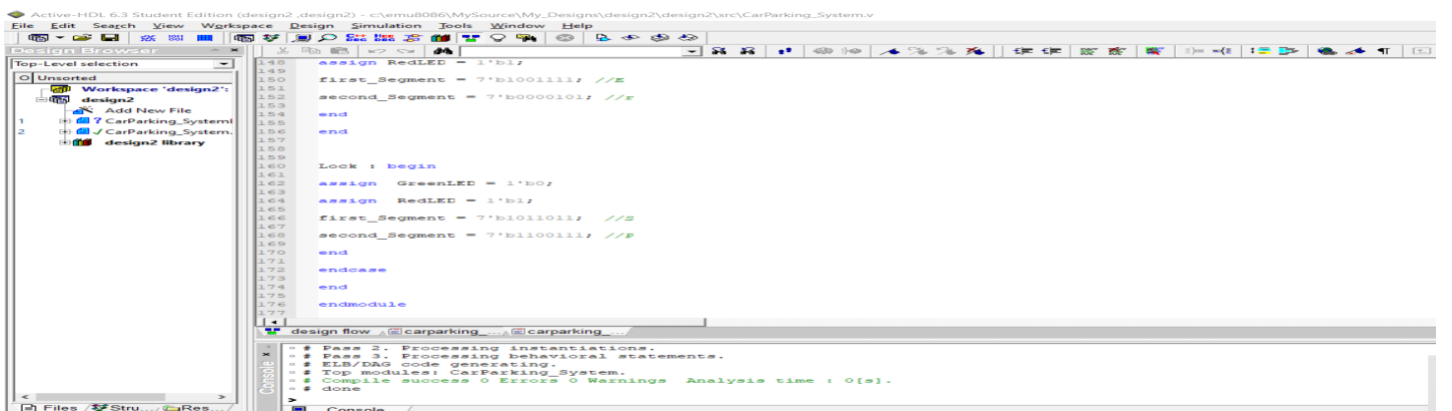
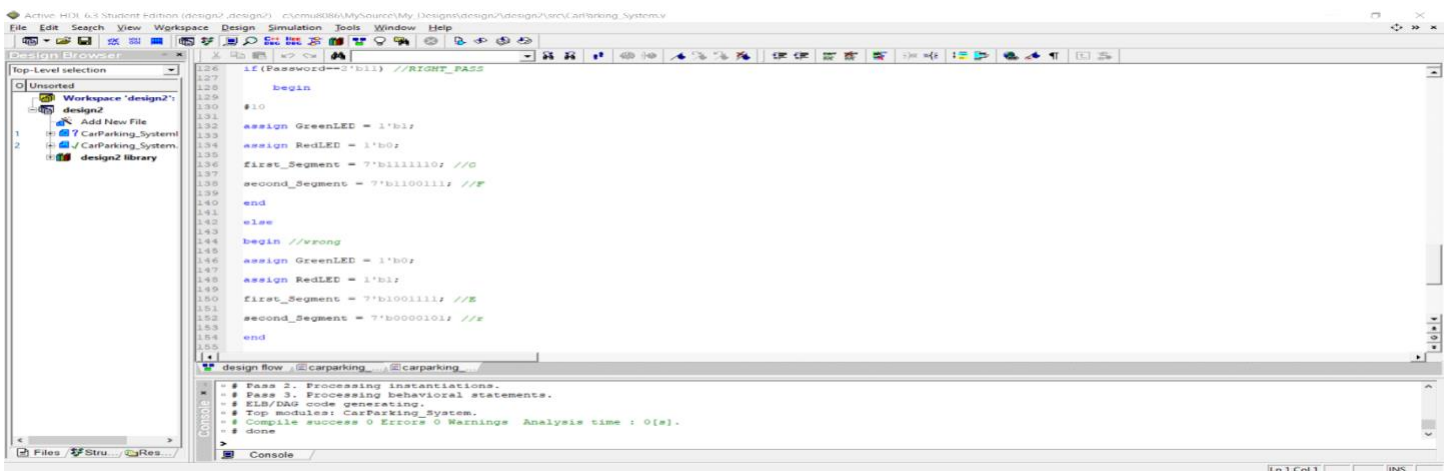
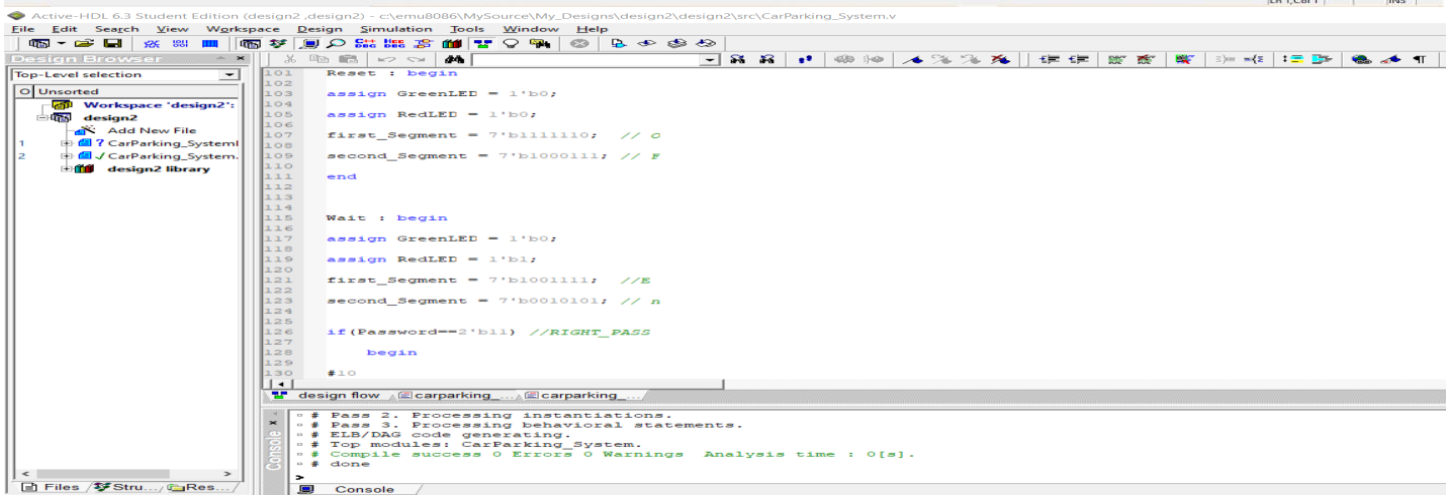
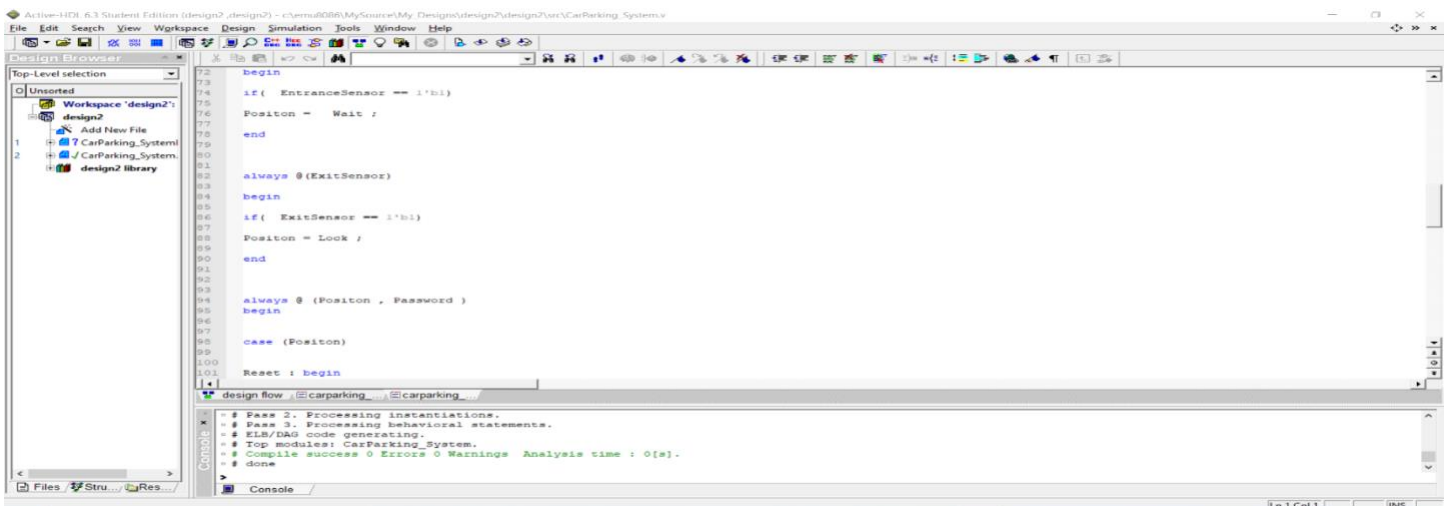
first_Segment, second_Segment , RedLED and GreenLED

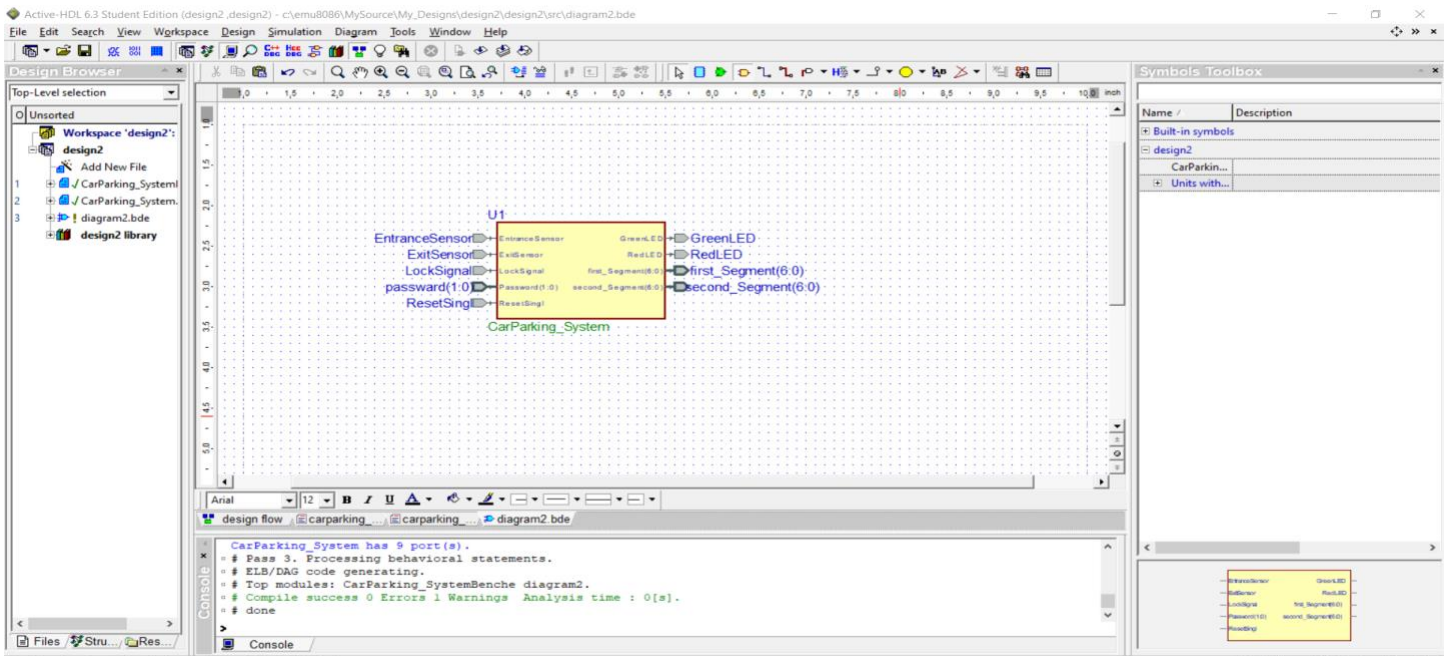
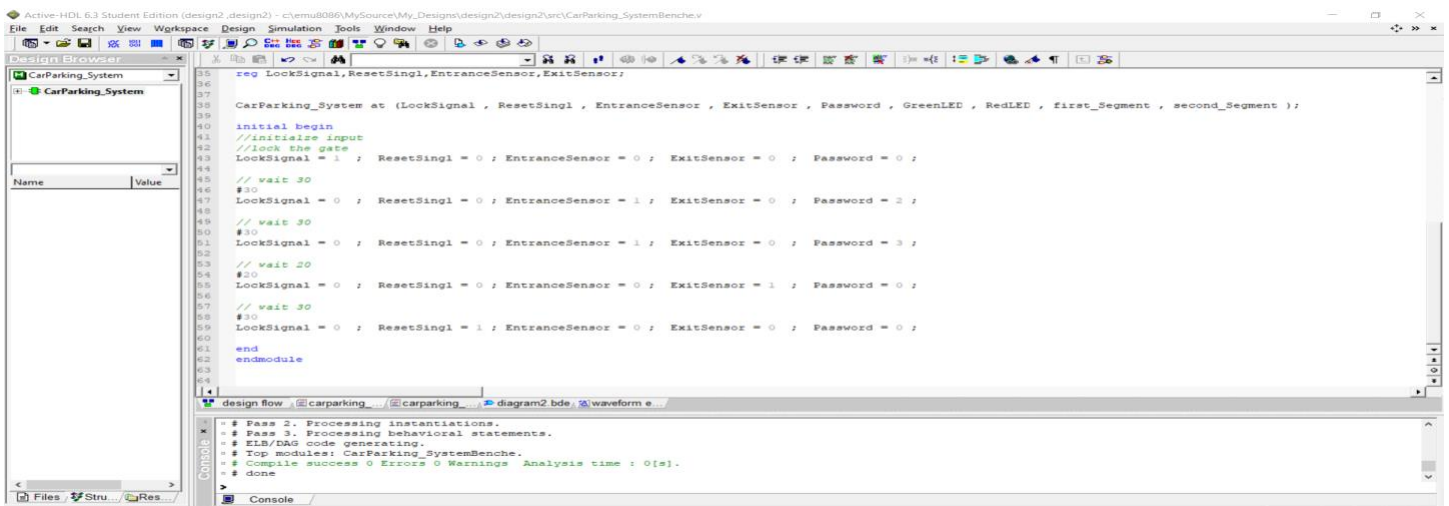
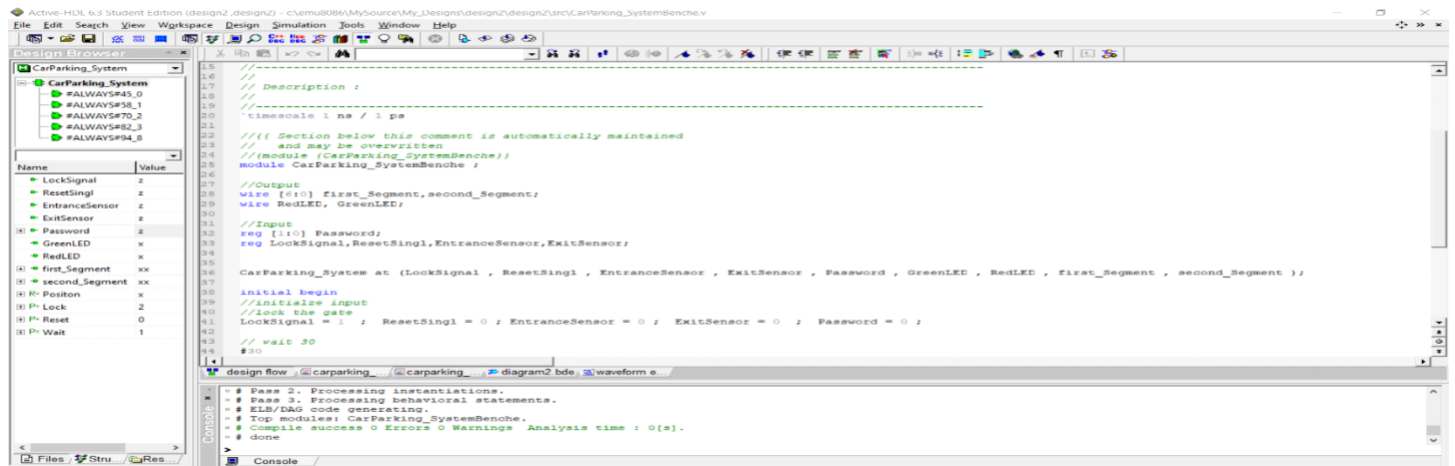
The problem solution :



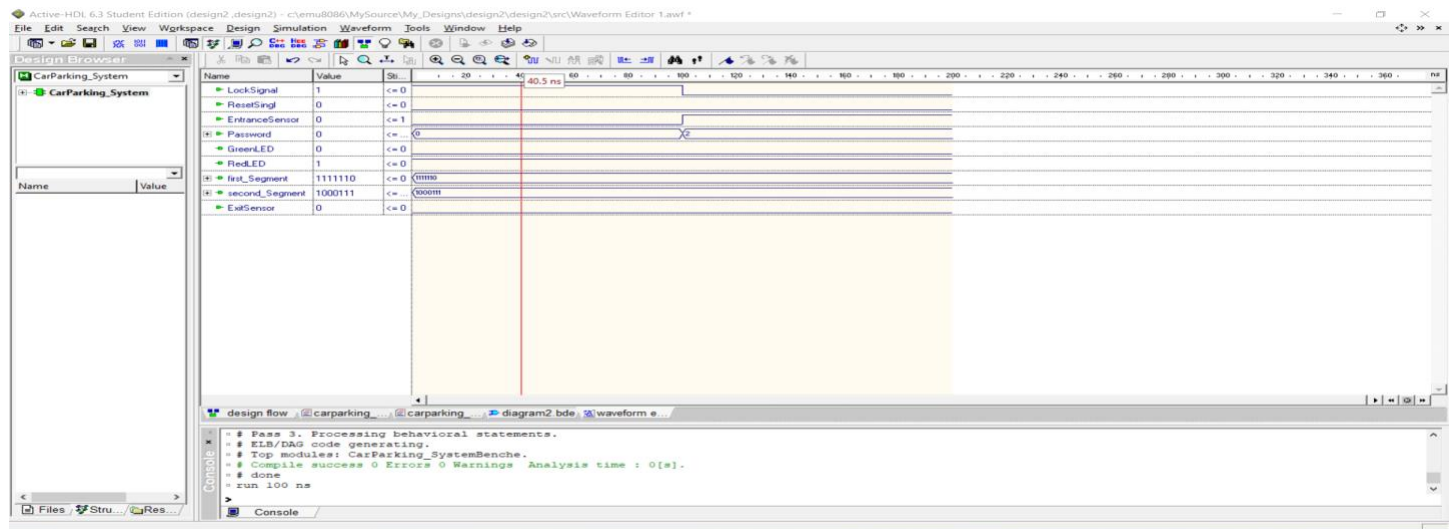
```
File Edit Search View Workspace Design Simulation Tools Window Help
Design Browser
CarParking_System
CarParking_System
Name Value
// Design : design2
// Author : Windows User
// Company : HP Inc.
//
//
// File : CarParking_System.v
// Generated : Tue Apr 12 21:19:37 2022
// From : interface description file
// By : Itf2Vhdl ver. 1.20
//
//
// Description :
//
//
timescale 1 ns / 1 ps
// group number :2 , 4C2 , maram almoussa 442000723@pnu.edu.sa , vateen alzamel 442000928@pnu.edu.sa ,noura ali alqasem 442001119@pnu.edu.sa
//, talf alsadoon 442000762@pnu.edu.sa ,jomanh almanaa 442004948@pnu.edu.sa, mzoon alrubaish 442007363@pnu.edu.sa
module CarParking_System (LockSignal , ResetSingl , EntranceSensor , ExitSensor , Password , GreenLED , RedLED , first_Segment , second_Segment );
output reg GreenLED, RedLED;
output reg [6:0] first_Segment, second_Segment ;
input LockSignal , ResetSingl , EntranceSensor , ExitSensor;
```





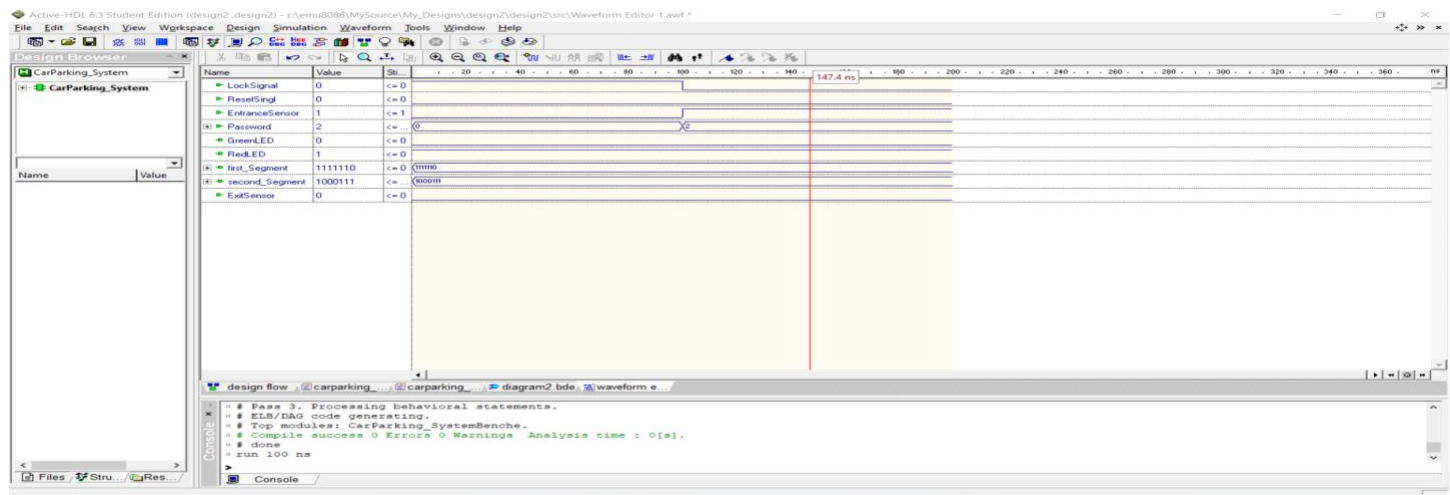


The first scenario:



When the Lock_Signal equals one then the GreenLED will equal zero and the RedLED will equal one and the first segment will equal 1111110 and the second segment will equal 1000111

The second scenario :



When the Lock_Signal equals zero then the GreenLED will equal zero and the RedLED will equal one and the first segment will equal 1111110 and the second segment will equal 1000111

Solution code :

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```
module CarParking_System (LockSignal , ResetSingl , EntranceSensor , ExitSensor , Password , GreenLED , RedLED , first_Segment , second_Segment );
```

```
output reg  GreenLED, RedLED;
```

```
output reg [6:0] first_Segment,second_Segment ;
```

```
input LockSignal , ResetSingl , EntranceSensor , ExitSensor;
```

```
input [1:0] Password;
```

```
reg [1:0] Positon ;
```

```
parameter Lock = 2'b10 , Reset = 2'b00 , Wait = 2'b01 ;
```

```
always @(LockSignal)
```

```
begin
```

```
if( LockSignal == 1'b1)
```

```
    Positon = Lock ;
```

```
end
```

```
always @(ResetSingl)
```

```
begin
```

```
if( ResetSingl == 1'b1)
```

```
    Positon = Reset ;
```

```
end
```

```
always @(EntranceSensor)
```

```
begin
```

```
if( EntranceSensor == 1'b1)
```

```
    Positon = Wait ;
```

```
end
```

```
always @(ExitSensor)
```

```
begin
```

```
if( ExitSensor == 1'b1)
```

```
    Positon = Lock ;
```

```
end
```

```
always @ (Positon , Password )
```

```
begin
```



```

case (Positon)

Reset : begin

assign GreenLED = 1'b0;

assign RedLED = 1'b0;

first_Segment = 7'b1111110; // O

second_Segment = 7'b1000111; // F

end

Wait : begin

assign GreenLED = 1'b0;

assign RedLED = 1'b1;

first_Segment = 7'b1001111; //E

second_Segment = 7'b0010101; // n

if(Password==2'b11) //RIGHT_PASS      begin      #10

assign GreenLED = 1'b1;

assign RedLED = 1'b0;

first_Segment = 7'b1111110; //O

second_Segment = 7'b1100111; //F

end

else

begin //wrong

assign GreenLED = 1'b0;

assign RedLED = 1'b1;

first_Segment = 7'b1001111;      //E

second_Segment = 7'b0000101; //r

end

end

Lock : begin

assign  GreenLED = 1'b0;

assign RedLED = 1'b1;

first_Segment = 7'b1011011;      //S

second_Segment = 7'b1100111; //P

end

endcase      end

endmodule

```

the testbenches code :

```
module CarParking_SystemBenche

//Output
wire [6:0] first_Segment,second_Segment;

wire RedLED, GreenLED;

//Input
reg [1:0] Password;

reg LockSignal,ResetSingl,EntranceSensor,ExitSensor;

CarParking_System at (LockSignal , ResetSingl , EntranceSensor , ExitSensor , Password , GreenLED , RedLED , first_Segment ,
second_Segment );

initial begin

//initialize input

//lock the gate

LockSignal = 1 ; ResetSingl = 0 ; EntranceSensor = 0 ; ExitSensor = 0 ; Password = 0 ;


// wait 30

#30

LockSignal = 0 ; ResetSingl = 0 ; EntranceSensor = 1 ; ExitSensor = 0 ; Password = 2 ;


// wait 30

#30

LockSignal = 0 ; ResetSingl = 0 ; EntranceSensor = 1 ; ExitSensor = 0 ; Password = 3 ;


// wait 20

#20

LockSignal = 0 ; ResetSingl = 0 ; EntranceSensor = 0 ; ExitSensor = 1 ; Password = 0 ;


// wait 30

#30

LockSignal = 0 ; ResetSingl = 1 ; EntranceSensor = 0 ; ExitSensor = 0 ; Password = 0 ;


end

endmodule
```

References :

The fifth edition of computer organization and design

Computer Organization and Architecture

<https://verificationguide.com/systemverilog/systemverilog-program-block/>