Practical Machine Learning Assignment

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1. Introduction

1.1. Background

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement - a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. More information is available from the website here: http://groupware.les.inf.puc-rio.br/har (http://groupware.les.inf.puc-rio.br/har) (see the section on the Weight Lifting Exercise Dataset).

1.2. Data

The training data for this project are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv (https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv)

The test data are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv (https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv)

The data for this project come from this source: http://groupware.les.inf.puc-rio.br/har (http://groupware.les.inf.puc-rio.br/har). If you use the document you create for this class for any purpose please cite them as they have been very generous in allowing their data to be used for this kind of assignment.

1.3. Task

The goal of your project is to predict the manner in which they did the exercise. This is the "classe" variable in the training set. You may use any of the other variables to predict with. You should create a report describing how you built your model, how you used cross validation, what you think the expected out of sample error is, and why you made the choices you did. You will also use your prediction model to predict 20 different test cases.

2. Data Analysis

I went though the following steps to finish the task:

1. Upload training data and store it in variable training, testing data in testing;

- 2. Randomly divide training data into 2 parts: 75% as sub training data and store it in variable **train**, 25% as sub testing data and store it in **test**;
- 3. Sample training data 3 times more and each time choose 25% as sub testing data;
- 4. Run different models and test the accuracy with 4 sub testing data sets:
- a. Random Forest with Principal Component Analysis
- b. Random Forest without PCA
- c. Classification and Regression Tree with PCA
- d. Classification (default rpart())
- e. Classification (rpart method="class")
- f. Boosted Tree with PCA (Without PCA it would be extremely slow.)
- 5. Compare the accuracy and time to choose a model:
- Accuracy (high to low): b > a > f > e > d > c
- Speed (high to low): c > d > e > a > b > f
- 6. Random Forest has the most accuracy, and the speed is moderate. So I chose it to apply on the testing data.

2.1 Data Uploading and Cleansing

```
set.seed(55555)
library(caret)
library(AppliedPredictiveModeling)
library(randomForest) ## for randomForest()
library(rattle) ## for fancyRpartPlot()
library(rpart) ## for rpart()
library(rpart.plot) ## for rpart.plot()

## Upload data
training = read.csv("D:/R/data/pml-training.csv",
header = TRUE,
stringsAsFactors=FALSE,
na.strings=c("NA", "N/A"))
dim(training) ## 19622 rows, 160 columns
```

```
## [1] 19622 160
```

```
summary(training[,c(2:7, 160)]) ## There are 6 users, 5 classes.
```

```
##
                    raw_timestamp_part_1 raw_timestamp_part_2
   user_name
## Length:19622
                    Min. :1.322e+09 Min. : 294
## Class :character
                    1st Qu.:1.323e+09
                                      1st Qu.:252912
                    Median :1.323e+09 Median :496380
## Mode :character
##
                    Mean :1.323e+09 Mean :500656
                    3rd Qu.:1.323e+09 3rd Qu.:751891
##
##
                    Max. :1.323e+09 Max. :998801
## cvtd_timestamp
                    new_window
                                     num_window
                                                    classe
                    Length:19622
## Length:19622
                                     Min. : 1.0 Length:19622
## Class :character
                    Class :character
                                     1st Qu.:222.0 Class :character
## Mode :character
                                     Median :424.0 Mode :character
                    Mode :character
##
                                     Mean :430.6
##
                                     3rd Qu.:644.0
                                     Max. :864.0
##
```

str(training) ## e.g. column "kurtosis_roll_belt", type chr, contains "NA"

```
## 'data.frame': 19622 obs. of 160 variables:
## $ X
                          : int 1 2 3 4 5 6 7 8 9 10 ...
                          : chr "carlitos" "carlitos" "carlitos" ...
## $ user_name
                        : int 1323084231 1323084231 1323084231 1323084232 1323084232 1
## $ raw timestamp part 1
323084232 1323084232 1323084232 1323084232 ...
## $ raw_timestamp_part_2 : int 788290 808298 820366 120339 196328 304277 368296 440390
484323 484434 ...
## $ cvtd_timestamp
                         : chr
                                "05/12/2011 11:23" "05/12/2011 11:23" "05/12/2011 11:23"
"05/12/2011 11:23" ...
## $ new window
                         : chr
                                "no" "no" "no" "no" ...
## $ num_window
                         : int 11 11 11 12 12 12 12 12 12 12 ...
## $ roll belt
                         : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
## $ pitch_belt
                         : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw_belt
                         : num -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -9
4.4 ...
...
## $ skewness_roll_belt
                         : chr
## $ skewness_roll_belt.1 : chr
## $ skewness_yaw_belt : chr
                                NA NA NA NA NA NA NA NA NA ...
## $ max_roll_belt
                         : num
                         : int
                                NA NA NA NA NA NA NA NA NA ...
## $ max_picth_belt
                                ...
## $ max_yaw_belt
                         : chr
## $ min roll belt
                         : num
                                NA NA NA NA NA NA NA NA NA ...
                                NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_belt
                        : int
                                ... ... ...
## $ min_yaw_belt
                         : chr
## $ amplitude_roll_belt : num
                                NA NA NA NA NA NA NA NA NA ...
                                NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt
                         : int
                                ...
## $ amplitude_yaw_belt
                         : chr
## $ var_total_accel_belt
                         : num
                                NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_belt
                                NA NA NA NA NA NA NA NA NA ...
                          : num
                                NA ...
## $ stddev_roll_belt
                         : num
## $ var_roll_belt
                                NA NA NA NA NA NA NA NA NA ...
                          : num
## $ avg_pitch_belt
                          : num
                                NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_belt
                                NA NA NA NA NA NA NA NA NA ...
                         : num
                                NA NA NA NA NA NA NA NA NA ...
## $ var pitch belt
                          : num
                                NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt
                         : num
## $ stddev_yaw_belt
                                NA NA NA NA NA NA NA NA NA ...
                         : num
## $ var_yaw_belt
                         : num
                                NA NA NA NA NA NA NA NA NA ...
                                ## $ gyros belt x
                          : num
## $ gyros belt y
                          : num
                                0 0 0 0 0.02 0 0 0 0 0 ...
## $ gyros_belt_z
                         : num
                                -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0
                         : int -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel belt x
## $ accel_belt_y
                         : int 4453243424...
## $ accel belt z
                          : int 22 22 23 21 24 21 21 21 24 22 ...
## $ magnet_belt_x
                         : int -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
                         : int 599 608 600 604 600 603 599 603 602 609 ...
## $ magnet belt y
## $ magnet_belt_z
                         : int -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
## $ roll arm
                         ## $ pitch arm
                          : num 22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
## $ yaw_arm
                         ## $ total accel arm
                         : int 34 34 34 34 34 34 34 34 34 ...
                         : num NA ...
## $ var_accel_arm
## $ avg_roll_arm
                          : num NA NA NA NA NA NA NA NA NA ...
```

```
##
   $ stddev_roll_arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
   $ var_roll_arm
                                    NA NA NA NA NA NA NA NA NA ...
##
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ avg_pitch_arm
                             : num
##
   $ stddev_pitch_arm
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ var_pitch_arm
                             : num
   $ avg_yaw_arm
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ stddev_yaw_arm
                             : num
##
   $ var_yaw_arm
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
                             : num
                                    ##
   $ gyros_arm_x
##
   $ gyros_arm_y
                                    0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03
                             : num
. . .
                                    -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
##
   $ gyros_arm_z
                             : num
##
   $ accel_arm_x
                             : int
                                    -288 -290 -289 -289 -289 -289 -289 -288 -288 ...
   $ accel_arm_y
                             : int
                                    109 110 110 111 111 111 111 111 109 110 ...
##
##
   $ accel_arm_z
                             : int
                                    -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
                                    -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
##
   $ magnet arm x
                             : int
##
   $ magnet_arm_y
                             : int
                                    337 337 344 344 337 342 336 338 341 334 ...
                             : int
                                    516 513 513 512 506 513 509 510 518 516 ...
##
   $ magnet_arm_z
                                    ... ... ... ...
##
   $ kurtosis_roll_arm
                             : chr
                                    ##
   $ kurtosis_picth_arm
                             : chr
##
   $ kurtosis_yaw_arm
                             : chr
##
   $ skewness_roll_arm
                             : chr
##
   $ skewness_pitch_arm
                             : chr
   $ skewness_yaw_arm
##
                             : chr
##
   $ max_roll_arm
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ max_picth_arm
                             : num
   $ max_yaw_arm
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
##
##
   $ min roll arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
                                    NA NA NA NA NA NA NA NA NA ...
   $ min_pitch_arm
##
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ min_yaw_arm
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ amplitude_roll_arm
                             : num
   $ amplitude_pitch_arm
                                    NA NA NA NA NA NA NA NA NA ...
##
                             : num
##
   $ amplitude_yaw_arm
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
   $ roll_dumbbell
                                    13.1 13.1 12.9 13.4 13.4 ...
##
                             : num
   $ pitch_dumbbell
                                    -70.5 -70.6 -70.3 -70.4 -70.4 ...
##
                             : num
##
   $ yaw_dumbbell
                                    -84.9 -84.7 -85.1 -84.9 -84.9 ...
                             : num
   $ kurtosis roll dumbbell
                             : chr
##
   $ kurtosis picth dumbbell : chr
##
   $ kurtosis_yaw_dumbbell
                             : chr
##
                                    ... ... ... ...
   $ skewness_roll_dumbbell : chr
                                    .. .. .. ..
   $ skewness_pitch_dumbbell : chr
##
                                    ... ... ... ...
##
   $ skewness_yaw_dumbbell
                             : chr
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ max roll dumbbell
                             : num
##
   $ max_picth_dumbbell
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
                                    ... ... ... ...
##
   $ max yaw dumbbell
                             : chr
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ min_roll_dumbbell
##
   $ min_pitch_dumbbell
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
                                    ... ... ... ...
   $ min_yaw_dumbbell
                             : chr
##
   $ amplitude roll dumbbell : num
                                    NA NA NA NA NA NA NA NA NA ...
##
     [list output truncated]
```

```
## Clean covariants
df <- training[,-c(1:7, 160)] ## drop the first 7 and the last columns
df <- suppressWarnings(data.frame(apply(df, 2, as.numeric))) ## convert all columns to numeri
c
df[is.na(df)] <- 0; sum(is.na(df)) ## replace <NA> with 0
```

```
## [1] 0
```

```
df <- df[vapply(df, function(x) length(unique(x)) > 1, logical(1L))] ## remove same value col
umns
dim(df) ## 19622 rows, 143 columns
```

```
## [1] 19622 143
```

```
training <- data.frame(classe=training$classe, df); rm(df)
training$classe <- as.factor(training$classe)</pre>
```

2.2 Data Partition

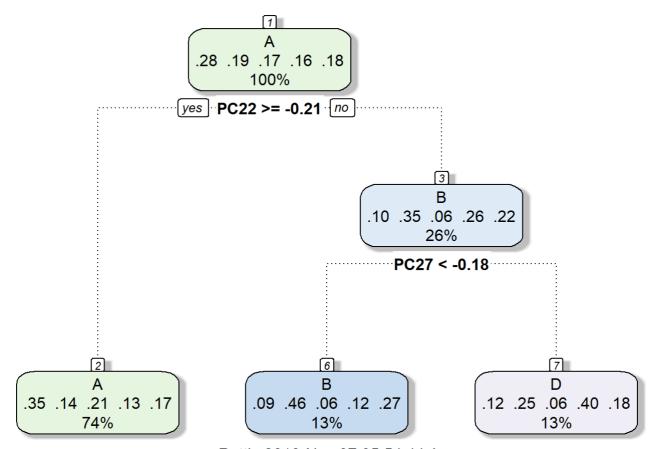
```
## Data partition
trainIndex = createDataPartition(training$classe, p = 3/4, list=FALSE)
train = training[trainIndex,]
library(rlist)
testIndices<- list(-trainIndex)
for (i in 2:4) {
testIndices <- list.append(testIndices, createDataPartition(training$classe, p = 1/4, list=FALSE))
}</pre>
```

2.3 Train Models

```
## Principal Component Analysis
preProc <- preProcess(train[,-1], method=c("center", "scale", "pca"), thresh=0.8); preProc</pre>
```

```
## Created from 14718 samples and 143 variables
##
## Pre-processing:
## - centered (143)
## - ignored (0)
## - principal component signal extraction (143)
## - scaled (143)
##
## PCA needed 28 components to capture 80 percent of the variance
```

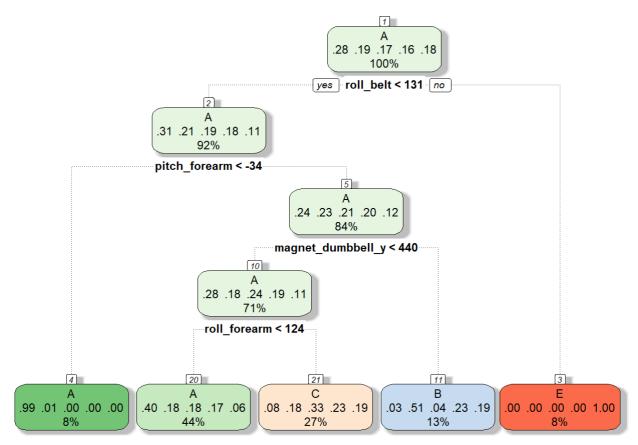
```
trainPC <- predict(preProc, train)</pre>
## Random Forest
## RF + PCA
modFit <- randomForest(classe~., data=trainPC, method="class")</pre>
## Cross validation
accRF <- matrix(0, nrow=4, ncol=1)</pre>
for (i in 1:4) {
test = training[testIndices[[i]],]
testPC <- predict(preProc, test)</pre>
pred <- predict(modFit, testPC)</pre>
accRF[i,1] <- confusionMatrix(test$classe, pred)$overall["Accuracy"]</pre>
}; rm(modFit, test, testPC, pred)
## RF without PCA
accRF1 <- matrix(0, nrow=4, ncol=1)</pre>
modFit <- randomForest(classe~., data=train, method="class")</pre>
for (i in 1:4) {
test = training[testIndices[[i]],]
pred <- predict(modFit, test)</pre>
accRF1[i,1] <- confusionMatrix(test$classe, pred)$overall["Accuracy"]</pre>
}; rm(modFit, test, pred)
## Classification and Regression Trees
## rpart + PCA
modFit <- train(classe~., data=trainPC, method="rpart")</pre>
fancyRpartPlot(modFit$finalModel)
```



Rattle 2018-Nov-07 05:54:44 Arwen

```
accRP <- matrix(0, nrow=4, ncol=1)
for (i in 1:4) {
  test = training[testIndices[[i]],]
  testPC <- predict(preProc, test)
  pred <- predict(modFit, testPC)
  accRP[i,1] <- confusionMatrix(test$classe, pred)$overall["Accuracy"]
}; rm(modFit, test, testPC, pred)

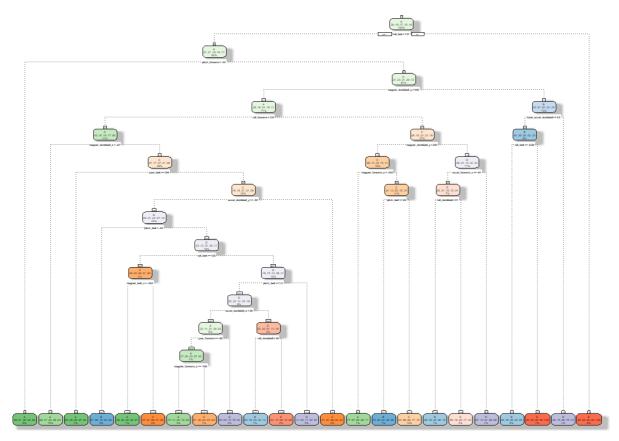
## rpart(default)
modFit <- train(classe~., data=train, method="rpart")
fancyRpartPlot(modFit$finalModel)</pre>
```



Rattle 2018-Nov-07 05:55:08 Arwen

```
accRP1 <- matrix(0, nrow=4, ncol=1)
for (i in 1:4) {
  test = training[testIndices[[i]],]
  pred <- predict(modFit, test)
  accRP1[i,1] <- confusionMatrix(test$classe, pred)$overall["Accuracy"]
}; rm(modFit, test, pred)

## rpart(class)
modFit <- rpart(classe~., data=train, method="class")
fancyRpartPlot(modFit)</pre>
```



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```
## Caution: Need to suppress output explicitly
modFit <- train(classe~., method="gbm", data=trainPC)</pre>
```

```
accGBM <- matrix(0, nrow=4, ncol=1)
for (i in 1:4) {
  test = training[testIndices[[i]],]
  testPC <- predict(preProc, test)
  pred <- predict(modFit, testPC)
  accGBM[i,1] <- confusionMatrix(test$classe, pred)$overall["Accuracy"]
}; rm(modFit, test, testPC, pred, i)</pre>
```

2.4 Compare Accuracy

```
## Compare Accuracy
acc <- data.frame(accRF, accRF1, accRP, accRP1, accRP2, accGBM)
names(acc) <- c("RF+PCA", "RF", "rpart+PCA", "rpart(default)", "rpart(class)", "gbm+PCA"); acc</pre>
```

```
## RF+PCA RF rpart+PCA rpart(default) rpart(class) gbm+PCA
## 1 0.9524878 0.9928630 0.3621533 0.4957178 0.7349103 0.7555057
## 2 0.9902181 0.9973507 0.3641736 0.4870593 0.7413899 0.7915223
## 3 0.9881802 0.9989810 0.3664153 0.4974526 0.7491339 0.7845934
## 4 0.9904218 0.9977583 0.3664153 0.4917465 0.7428164 0.7929488
```

colMeans(acc)

```
## RF+PCA RF rpart+PCA rpart(default) rpart(class)
## 0.9803270 0.9967383 0.3647894 0.4929940 0.7420626
## gbm+PCA
## 0.7811426
```

2.5 Predict

```
rm(training, trainIndex, testIndices, trainPC, preProc)

## Upload then clean testing data
testing = read.csv("D:/R/data/pml-testing.csv",
header = TRUE,
stringsAsFactors=FALSE,
na.strings=c("NA", "N/A"))
dim(testing) ## 20 rows, 160 columns
```

```
## [1] 20 160
```

tail(names(testing)) ## The last column is "problem_id".

```
## [1] "accel_forearm_y" "accel_forearm_z" "magnet_forearm_x"
## [4] "magnet_forearm_y" "magnet_forearm_z" "problem_id"
```

```
df <- testing[,-c(1:7, 160)] ## drop the first 7 and the last columns
df <- suppressWarnings(data.frame(apply(df, 2, as.numeric))) ## convert all columns to numeri
c
df[is.na(df)] <- 0; ## replace <NA> with 0
testing <- data.frame(classe="", df); rm(df)

## Predict
modFit <- randomForest(classe~. , data=train, method="class")
pred <- predict(modFit, testing); pred</pre>
```

```
## 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20
## B A B A A E D B A A B C B A E E A B B B
## Levels: A B C D E
```