

Synchronization: Basics

Introduction to Computer Systems
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Instructors:

Class 1: Chen Xiangqun, Sun Guangyu, Liu Xianhua

Class 2: Guan Xuetao

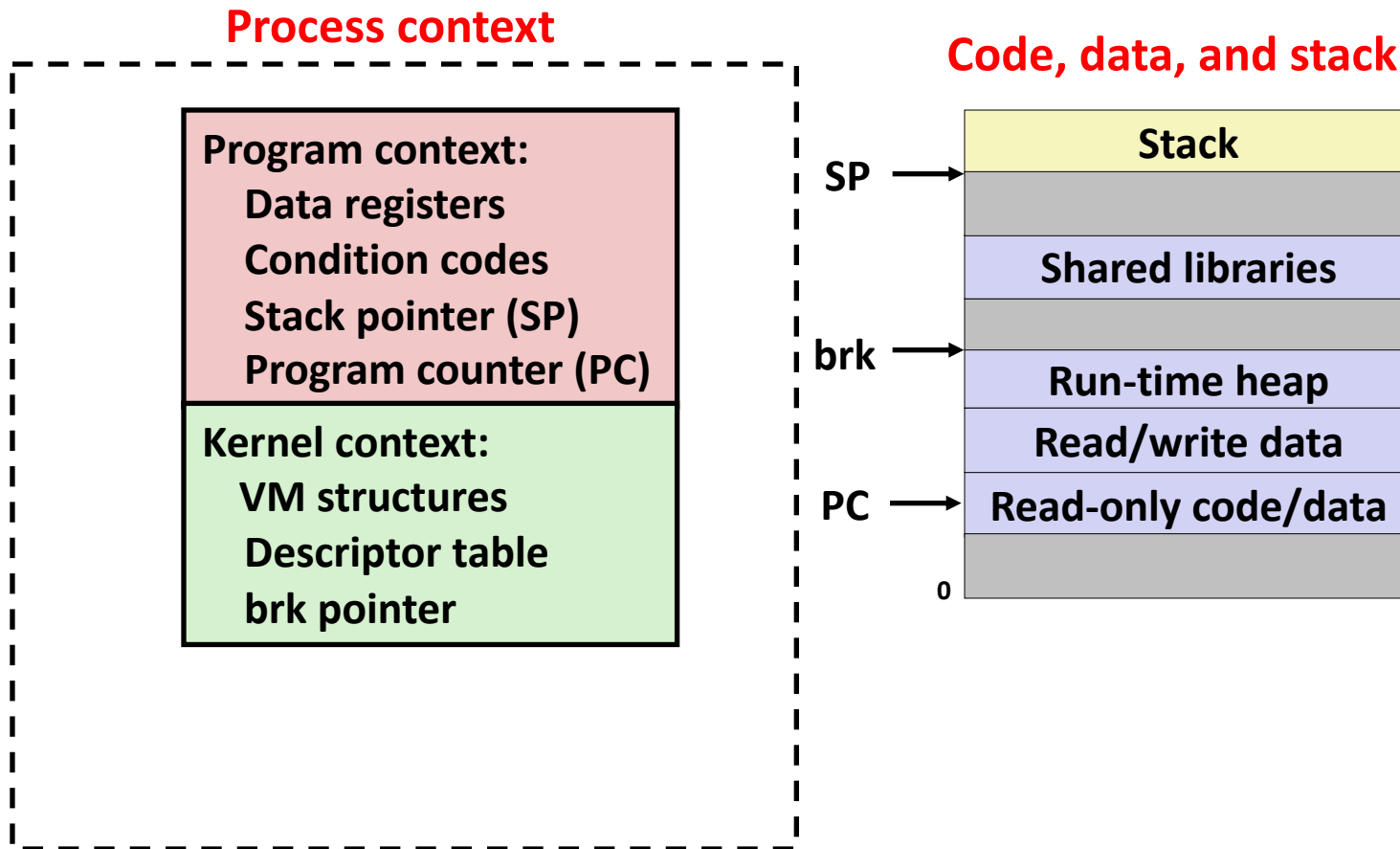
Class 3: Lu Junlin

Today

- **Threads review**
- Sharing
- Mutual exclusion
- Semaphores

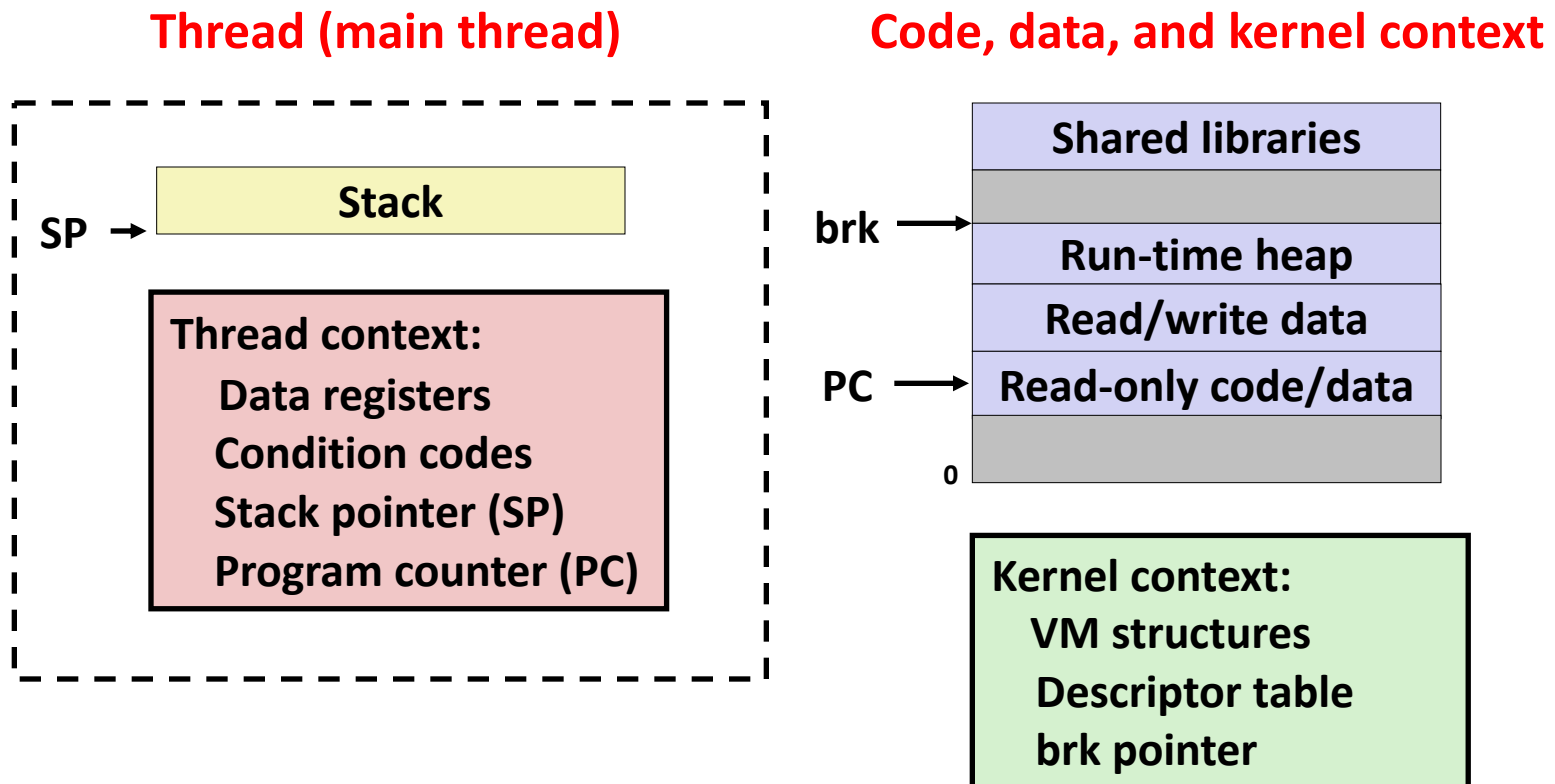
Traditional View of a Process

- Process = process context + code, data, and stack



Alternate View of a Process

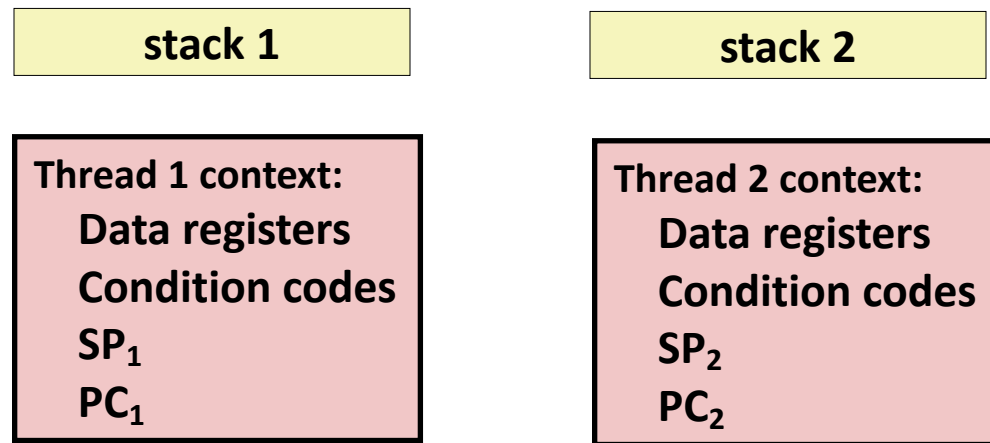
- Process = thread + code, data, and kernel context



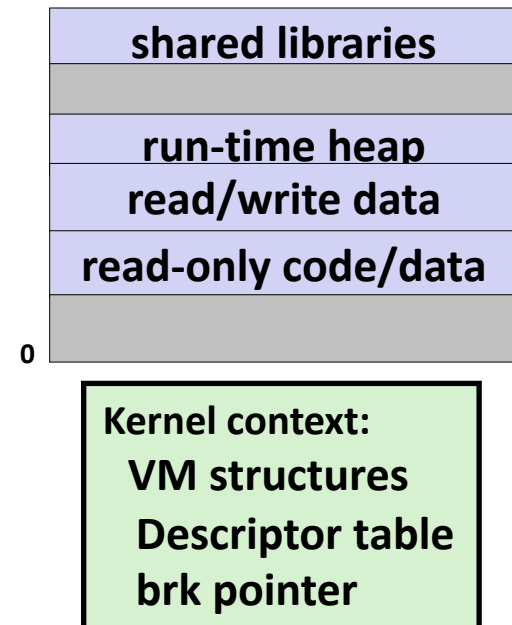
A Process With Multiple Threads

- **Multiple threads can be associated with a process**
 - Each thread has its own logical control flow
 - Each thread shares the same code, data, and kernel context
 - Each thread has its own stack for local variables
 - but not protected from other threads
 - Each thread has its own thread id (TID)

Thread 1 (main thread) Thread 2 (peer thread)



Shared code and data



Don't let picture confuse you!

Thread 1 (main thread) Thread 2 (peer thread)

stack 1

stack 2

Thread 1 context:
Data registers
Condition codes
 SP_1
 PC_1

Thread 2 context:
Data registers
Condition codes
 SP_2
 PC_2

Shared code and data

shared libraries

run-time heap

read/write data

read-only code/data

0

Kernel context:
VM structures
Descriptor table
brk pointer

Memory is shared between all threads

Threads vs. Processes

■ Threads and processes: similarities

- Each has its own logical control flow
- Each can run concurrently with others
- Each is scheduled and context switched by the kernel

■ Threads and processes: differences

- Threads share code and data, processes (typically) do not
- Threads are less expensive than processes
 - Process control (creating and reaping) is more expensive than thread control
 - Context switches for processes more expensive than for threads

Pros and Cons of Thread-Based Designs

- **+ Easy to share data structures between threads**
 - e.g., logging information, file cache
- **+ Threads are more efficient than processes**
- **– Unintentional sharing can introduce subtle and hard-to-reproduce errors!**

Today

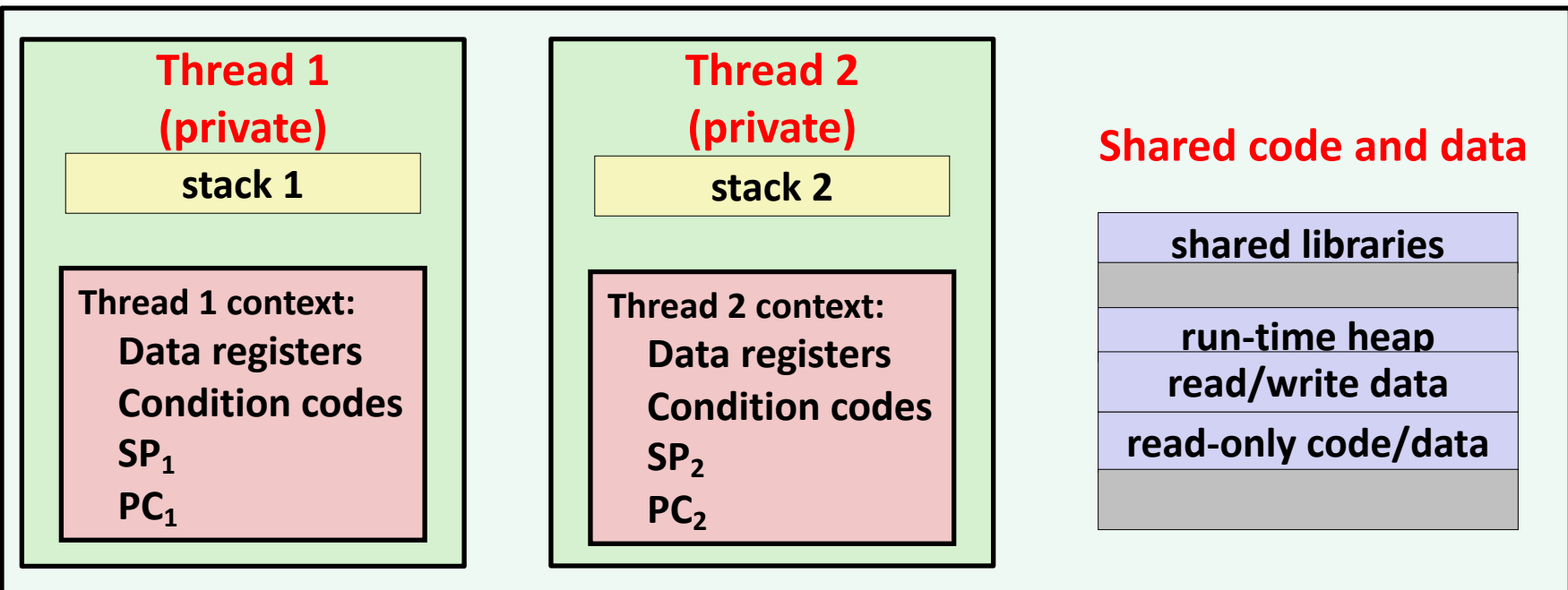
- Threads review
- **Sharing**
- Mutual exclusion
- Semaphores
- Producer-Consumer Synchronization

Shared Variables in Threaded C Programs

- **Question: Which variables in a threaded C program are shared?**
 - The answer is not as simple as “*global variables are shared*” and “*stack variables are private*”
- **Def: A variable x is *shared* if and only if multiple threads reference some instance of x .**
- **Requires answers to the following questions:**
 - What is the memory model for threads?
 - How are instances of variables mapped to memory?
 - How many threads might reference each of these instances?

Threads Memory Model: Conceptual

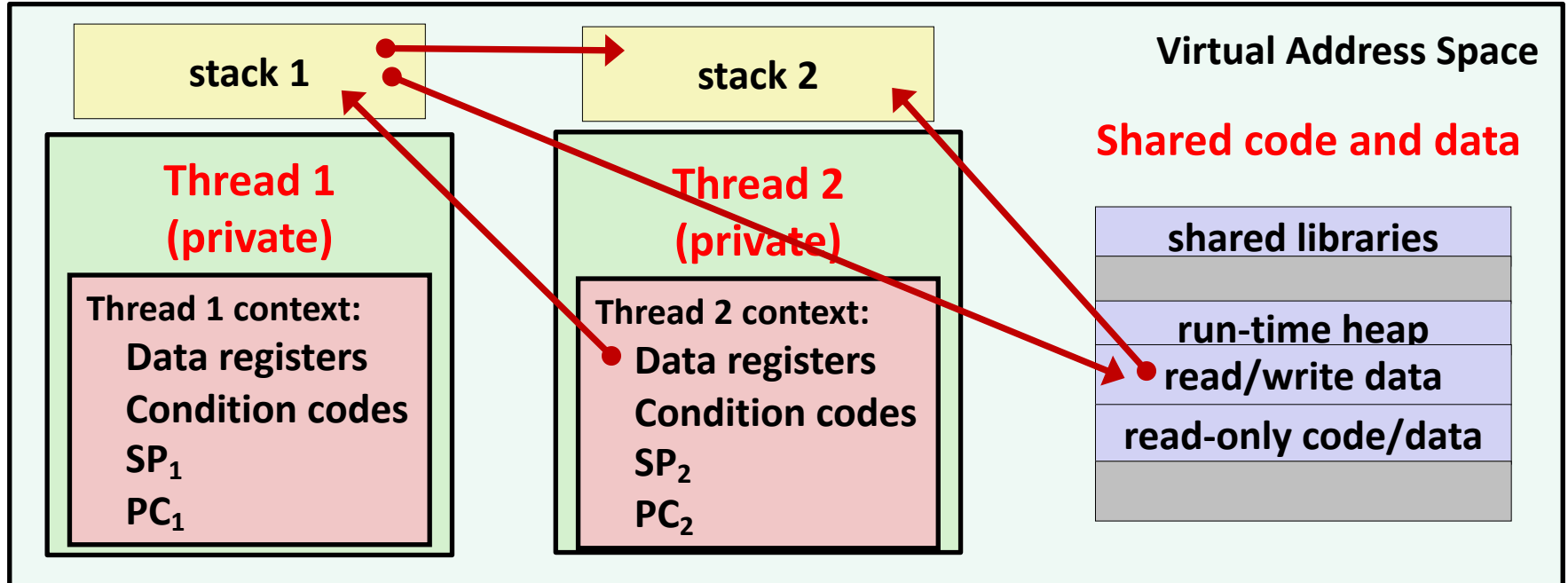
- Multiple threads run within the context of a single process
- Each thread has its own separate thread context
 - Thread ID, stack, stack pointer, PC, condition codes, and GP registers
- All threads share the remaining process context
 - Code, data, heap, and shared library segments of the process virtual address space
 - Open files and installed handlers



Threads Memory Model: Actual

■ Separation of data is not strictly enforced:

- Register values are truly separate and protected, but...
- Any thread can read and write the stack of any other thread



The mismatch between the conceptual and operation model is a source of confusion and errors

Passing an argument to a thread - Pedantic

```
int hist[N] = {0};

int main(int argc, char *argv[]) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++) {
        long* p = Malloc(sizeof(long));
        *p = i;
        Pthread_create(&tids[i],
                       NULL,
                       thread,
                       (void *)p);
    }
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}
```

```
void *thread(void *vargp)
{
    hist[(long *)vargp] += 1;
    Free(vargp);
    return NULL;
}
```

```
void check(void) {
    for (int i=0; i<N; i++) {
        if (hist[i] != 1) {
            printf("Failed at %d\n", i);
            exit(-1);
        }
    }
    printf("OK\n");
}
```

Passing an argument to a thread - Pedantic

```
int hist[N] = {0};

int main(int argc, char *argv[]) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++) {
        long* p = Malloc(sizeof(long));
        *p = i;
        Pthread_create(&tids[i],
                       NULL,
                       thread,
                       (void *)p);
    }
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}
```

```
void *thread(void *vargp)
{
    hist[(long *)vargp] += 1;
    Free(vargp);
    return NULL;
}
```

- Use malloc to create a per thread heap allocated place in memory for the argument
- Remember to free in thread!
- Producer-consumer pattern

Passing an argument to a thread – Also OK!

```
int hist[N] = {0};

int main(int argc, char *argv[]) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++)
        Pthread_create(&tids[i],
                       NULL,
                       thread,
                       (void *)i);
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}
```

```
void *thread(void *vargp)
{
    hist[(long)vargp] += 1;
    return NULL;
}
```

- Ok to Use cast since $\text{sizeof}(\text{long}) \leq \text{sizeof}(\text{void}^*)$
- Cast does NOT change bits

Passing an argument to a thread – **WRONG!**

```
int hist[N] = {0};

int main(int argc, char *argv[]) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++)
        Pthread_create(&tids[i],
                       NULL,
                       thread,
                       (void *) &i);

    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}
```

```
void *thread(void *vargp)
{
    hist[*(long*)vargp] += 1;
    return NULL;
}
```

- **&i** points to same location for all threads!
- **Creates a data race!**

Three Ways to Pass Thread Arg

■ Malloc/free

- Producer malloc's space, passes pointer to pthread_create
- Consumer dereferences pointer

■ Ptr to stack slot

- Producer passes address to producer's stack in pthread_create
- Consumer dereferences pointer

■ Cast of int

- Producer casts an int/long to address in pthread_create
- Consumer casts void* argument back to int/long

Example Program to Illustrate Sharing

```

char **ptr;  /* global var */

int main(int argc, char *argv[])
{
    long i;
    pthread_t tid;
    char *msgs[2] = {
        "Hello from foo",
        "Hello from bar"
    };

    ptr = msgs;
    for (i = 0; i < 2; i++)
        Pthread_create(&tid,
            NULL,
            thread,
            (void *)i);
    Pthread_exit(NULL);
}

```

sharing.c

```

void *thread(void *vargp)
{
    long myid = (long)vargp;
    static int cnt = 0;

    printf("[%ld]:  %s (cnt=%d)\n",
        myid, ptr[myid], ++cnt);
    return NULL;
}

```

Peer threads reference main thread's stack indirectly through global ptr variable

A common, but inelegant way to pass a single argument to a thread routine

Mapping Variable Instances to Memory

■ Global variables

- *Def*: Variable declared outside of a function
- **Virtual memory contains exactly one instance of any global variable**

■ Local variables

- *Def*: Variable declared inside function without `static` attribute
- **Each thread stack contains one instance of each local variable**

■ Local static variables

- *Def*: Variable declared inside function with the `static` attribute
- **Virtual memory contains exactly one instance of any local static variable.**

Mapping Variable Instances to Memory

Global var: 1 instance (ptr [data])

Local vars: 1 instance (i.m, msgs.m)

```
char **ptr; /* global var */

int main(int main, char *argv[])
{
    long i;
    pthread_t tid;
    char *msgs[2] = {
        "Hello from foo",
        "Hello from bar"
    };

    ptr = msgs;
    for (i = 0; i < 2; i++)
        Pthread_create(&tid,
            NULL,
            thread,
            (void *)i);
    Pthread_exit(NULL);
}
```

sharing.c

Local var: 2 instances (
myid.p0 [peer thread 0's stack],
myid.p1 [peer thread 1's stack]
)

```
void *thread(void *vargp)
{
    long myid = (long)vargp;
    static int cnt = 0;

    printf("[%ld]: %s (cnt=%d)\n",
        myid, ptr[myid], ++cnt);
    return NULL;
}
```

Local static var: 1 instance (cnt [data])

Shared Variable Analysis

■ Which variables are shared?

| <i>Variable instance</i> | <i>Referenced by main thread?</i> | <i>Referenced by peer thread 0?</i> | <i>Referenced by peer thread 1?</i> |
|------------------------------|---------------------------------------|---|---|
| ptr | yes | yes | yes |
| cnt | no | yes | yes |
| i.m | yes | no | no |
| msgs.m | yes | yes | yes |
| myid.p0 | no | yes | no |
| myid.p1 | no | no | yes |

```

char **ptr; /* global var */
int main(int main, char *argv[]) {
    long i; pthread_t tid;
    char *msgs[2] = {"Hello from foo",
                     "Hello from bar" };

    ptr = msgs;
    for (i = 0; i < 2; i++)
        Pthread_create(&tid,
                       NULL, thread, (void *)i);
    Pthread_exit(NULL);
}

```

```

void *thread(void *vargp)
{
    long myid = (long)vargp;
    static int cnt = 0;

    printf("[%ld]: %s (cnt=%d)\n",
           myid, ptr[myid], ++cnt);
    return NULL;
}

```

Shared Variable Analysis

■ Which variables are shared?

| <i>Variable instance</i> | <i>Referenced by main thread?</i> | <i>Referenced by peer thread 0?</i> | <i>Referenced by peer thread 1?</i> |
|--------------------------|-----------------------------------|-------------------------------------|-------------------------------------|
| <code>ptr</code> | yes | yes | yes |
| <code>cnt</code> | no | yes | yes |
| <code>i.m</code> | yes | no | no |
| <code>msgs.m</code> | yes | yes | yes |
| <code>myid.p0</code> | no | yes | no |
| <code>myid.p1</code> | no | no | yes |

■ Answer: A variable `x` is shared iff multiple threads reference at least one instance of `x`. Thus:

- `ptr`, `cnt`, and `msgs` are shared
- `i` and `myid` are *not* shared

Today

- Threads review
- Sharing
- **Mutual exclusion**
- Semaphores
- Producer-Consumer Synchronization

Synchronizing Threads

- Shared variables are handy...
- ...but introduce the possibility of nasty *synchronization* errors.

badcnt.c: Improper Synchronization

```

/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                  thread, &niters);
    Pthread_create(&tid2, NULL,
                  thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}

```

badcnt.c

```

/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}

```

```

linux> ./badcnt 10000
OK cnt=20000
linux> ./badcnt 10000
BOOM! cnt=13051
linux>

```

cnt should equal 20,000.

What went wrong?

Assembly Code for Counter Loop

C code for counter loop in thread i

```
for (i = 0; i < niters; i++)
    cnt++;
```

Asm code for thread i

| | |
|--|---|
| <pre> movq (%rdi), %rcx testq %rcx,%rcx jle .L2 movl \$0, %eax </pre> | <pre> } H_i : Head </pre> |
| <pre> .L3: movq cnt(%rip), %rdx addq \$1, %rdx movq %rdx, cnt(%rip) </pre> | <pre> } L_i : Load cnt U_i : Update cnt S_i : Store cnt </pre> |
| <pre> addq \$1, %rax cmpq %rcx, %rax jne .L3 .L2: </pre> | <pre> } T_i : Tail </pre> |

Concurrent Execution

- **Key idea:** In general, any sequentially consistent interleaving is possible, but some give an unexpected result!
 - I_i denotes that thread i executes instruction I
 - $\%rdx_i$ is the content of $\%rdx$ in thread i 's context

| i (thread) | $instr_i$ | $\%rdx_1$ | $\%rdx_2$ | cnt |
|--------------|-----------|-----------|-----------|-----|
| 1 | H_1 | - | - | 0 |
| 1 | L_1 | 0 | - | 0 |
| 1 | U_1 | 1 | - | 0 |
| 1 | S_1 | 1 | - | 1 |
| 2 | H_2 | - | - | 1 |
| 2 | L_2 | - | 1 | 1 |
| 2 | U_2 | - | 2 | 1 |
| 2 | S_2 | - | 2 | 2 |
| 2 | T_2 | - | 2 | 2 |
| 1 | T_1 | 1 | - | 2 |

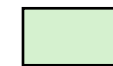
OK

Concurrent Execution

- **Key idea:** In general, any sequentially consistent interleaving is possible, but some give an unexpected result!

- I_i denotes that thread i executes instruction I
- $\%rdx_i$ is the content of $\%rdx$ in thread i 's context

| i (thread) | $instr_i$ | $\%rdx_1$ | $\%rdx_2$ | cnt |
|--------------|-----------|-----------|-----------|-----|
| 1 | H_1 | - | - | 0 |
| 1 | L_1 | 0 | - | 0 |
| 1 | U_1 | 1 | - | 0 |
| 1 | S_1 | 1 | - | 1 |
| 2 | H_2 | - | - | 1 |
| 2 | L_2 | - | 1 | 1 |
| 2 | U_2 | - | 2 | 1 |
| 2 | S_2 | - | 2 | 2 |
| 2 | T_2 | - | 2 | 2 |
| 1 | T_1 | 1 | - | 2 |



Thread 1
critical section



Thread 2
critical section

OK

Concurrent Execution (cont)

- Incorrect ordering: two threads increment the counter, but the result is 1 instead of 2

| i (thread) | instr _i | %rdx ₁ | %rdx ₂ | cnt |
|------------|--------------------|-------------------|-------------------|-----|
| 1 | H ₁ | - | - | 0 |
| 1 | L ₁ | 0 | - | 0 |
| 1 | U ₁ | 1 | - | 0 |
| 2 | H ₂ | - | - | 0 |
| 2 | L ₂ | - | 0 | 0 |
| 1 | S ₁ | 1 | - | 1 |
| 1 | T ₁ | 1 | - | 1 |
| 2 | U ₂ | - | 1 | 1 |
| 2 | S ₂ | - | 1 | 1 |
| 2 | T ₂ | - | 1 | 1 |

Oops!

Concurrent Execution (cont)

■ How about this ordering?

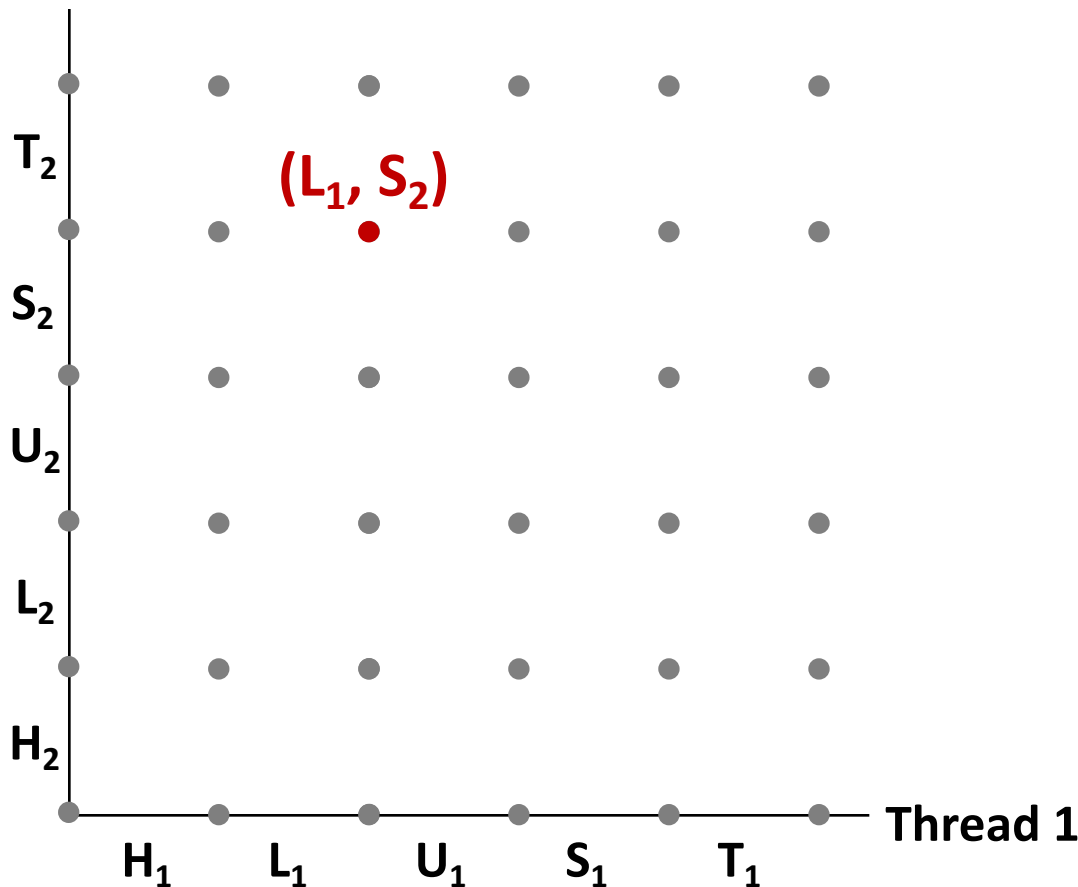
| i (thread) | instr _i | %rdx ₁ | %rdx ₂ | cnt |
|------------|--------------------|-------------------|-------------------|-----|
| 1 | H ₁ | | | 0 |
| 1 | L ₁ | 0 | | |
| 2 | H ₂ | | | |
| 2 | L ₂ | | 0 | |
| 2 | U ₂ | | 1 | |
| 2 | S ₂ | | 1 | 1 |
| 1 | U ₁ | 1 | | |
| 1 | S ₁ | 1 | | 1 |
| 1 | T ₁ | | | 1 |
| 2 | T ₂ | | | 1 |

Oops!

■ We can analyze the behavior using a *progress graph*

Progress Graphs

Thread 2



A **progress graph** depicts the discrete **execution state space** of concurrent threads.

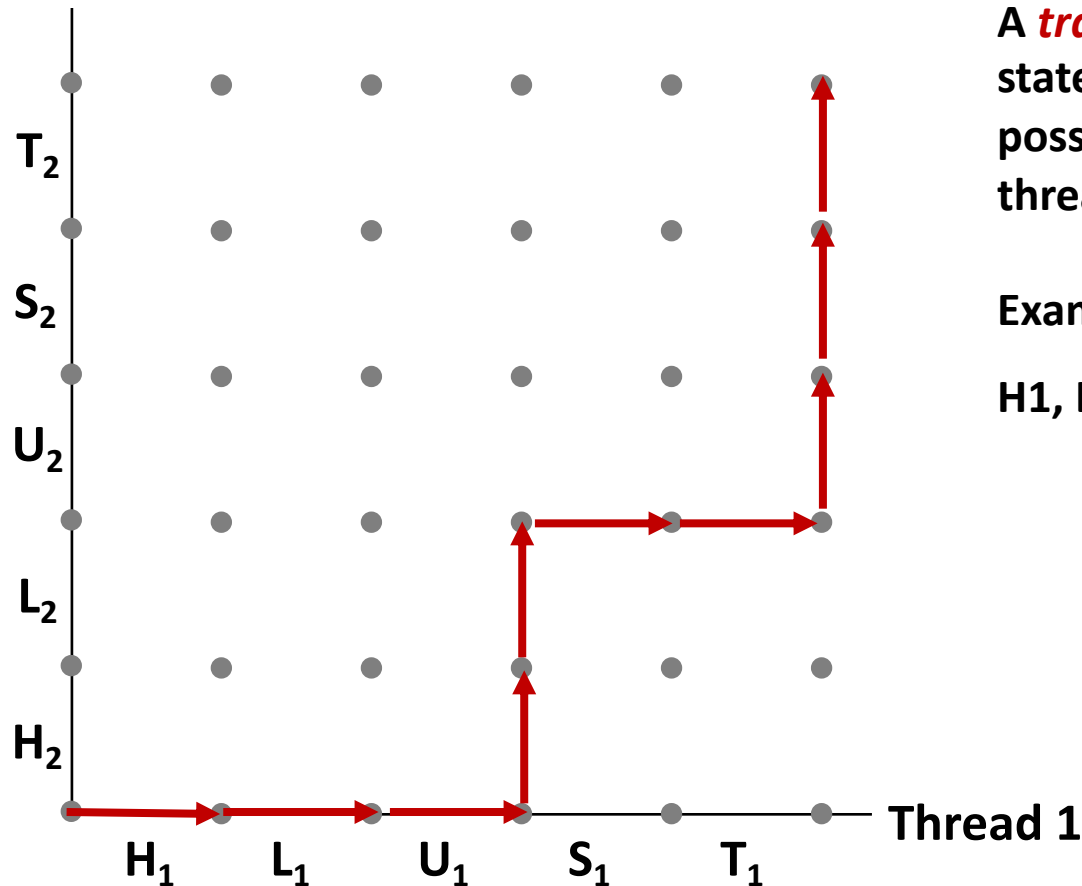
Each axis corresponds to the sequential order of instructions in a thread.

Each point corresponds to a possible **execution state** ($\text{Inst}_1, \text{Inst}_2$).

E.g., (L_1, S_2) denotes state where thread 1 has completed L_1 and thread 2 has completed S_2 .

Trajectories in Progress Graphs

Thread 2

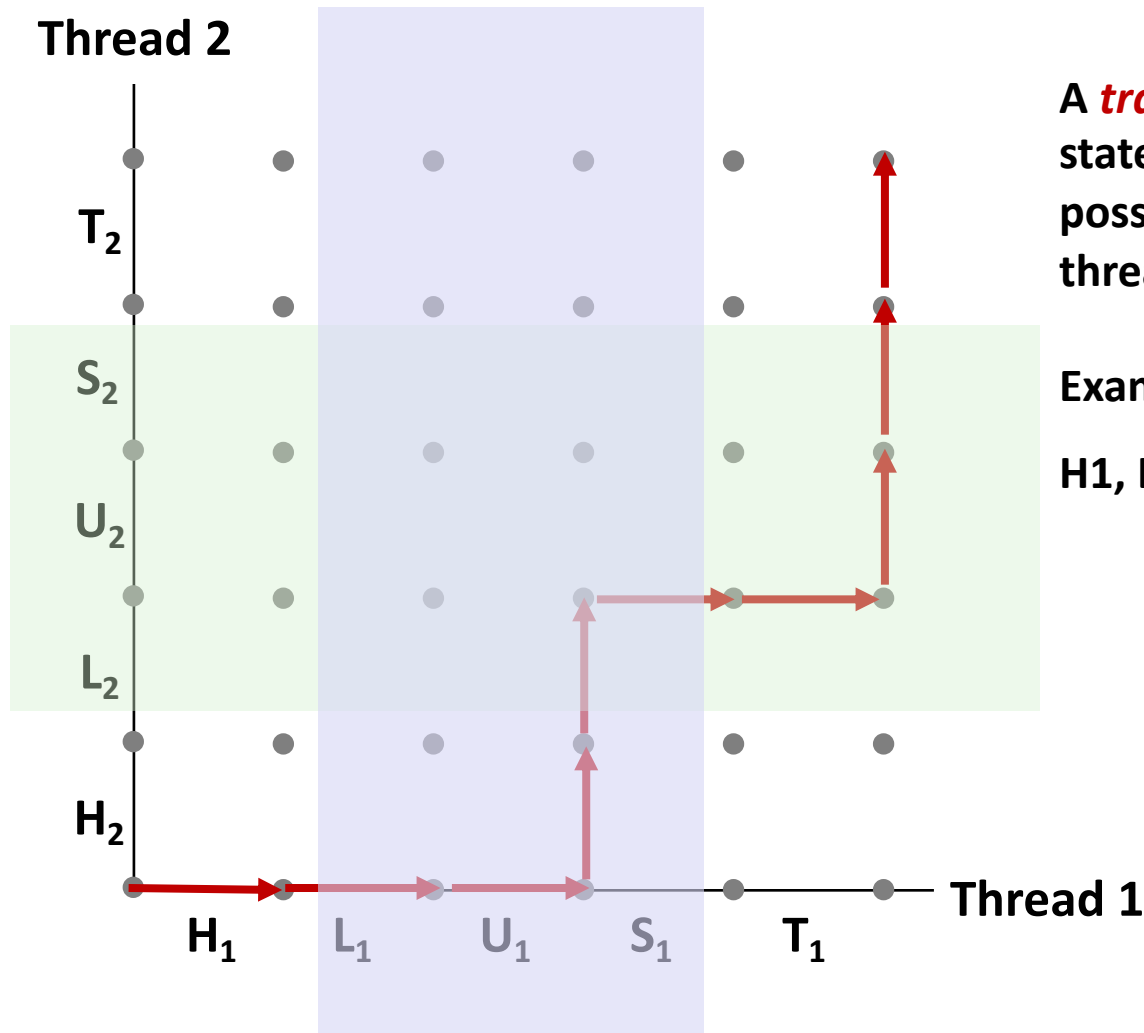


A **trajectory** is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

$H_1, L_1, U_1, H_2, L_2, S_1, T_1, U_2, S_2, T_2$

Trajectories in Progress Graphs

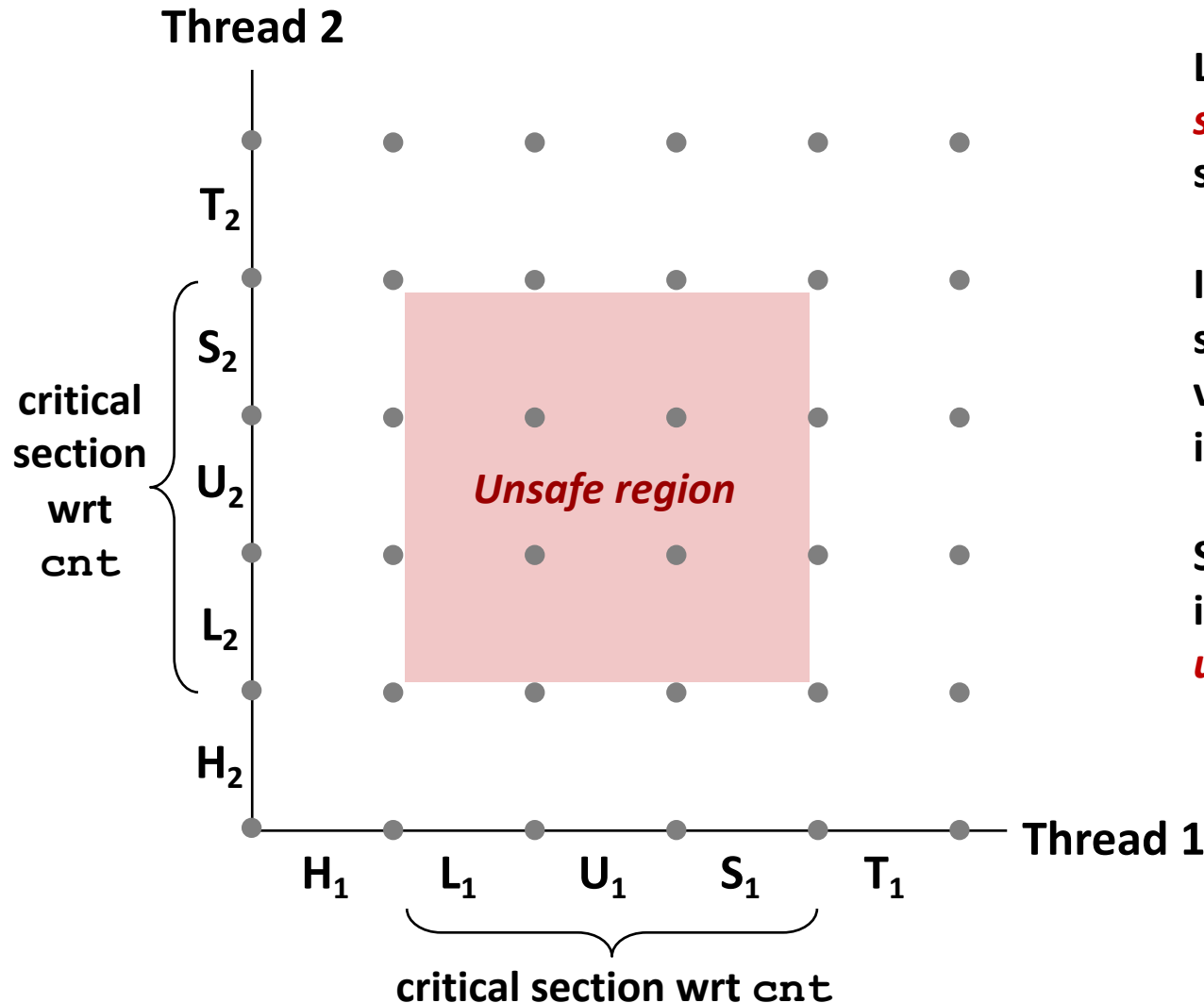


A **trajectory** is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

$H_1, L_1, U_1, H_2, L_2, S_1, T_1, U_2, S_2, T_2$

Critical Sections and Unsafe Regions

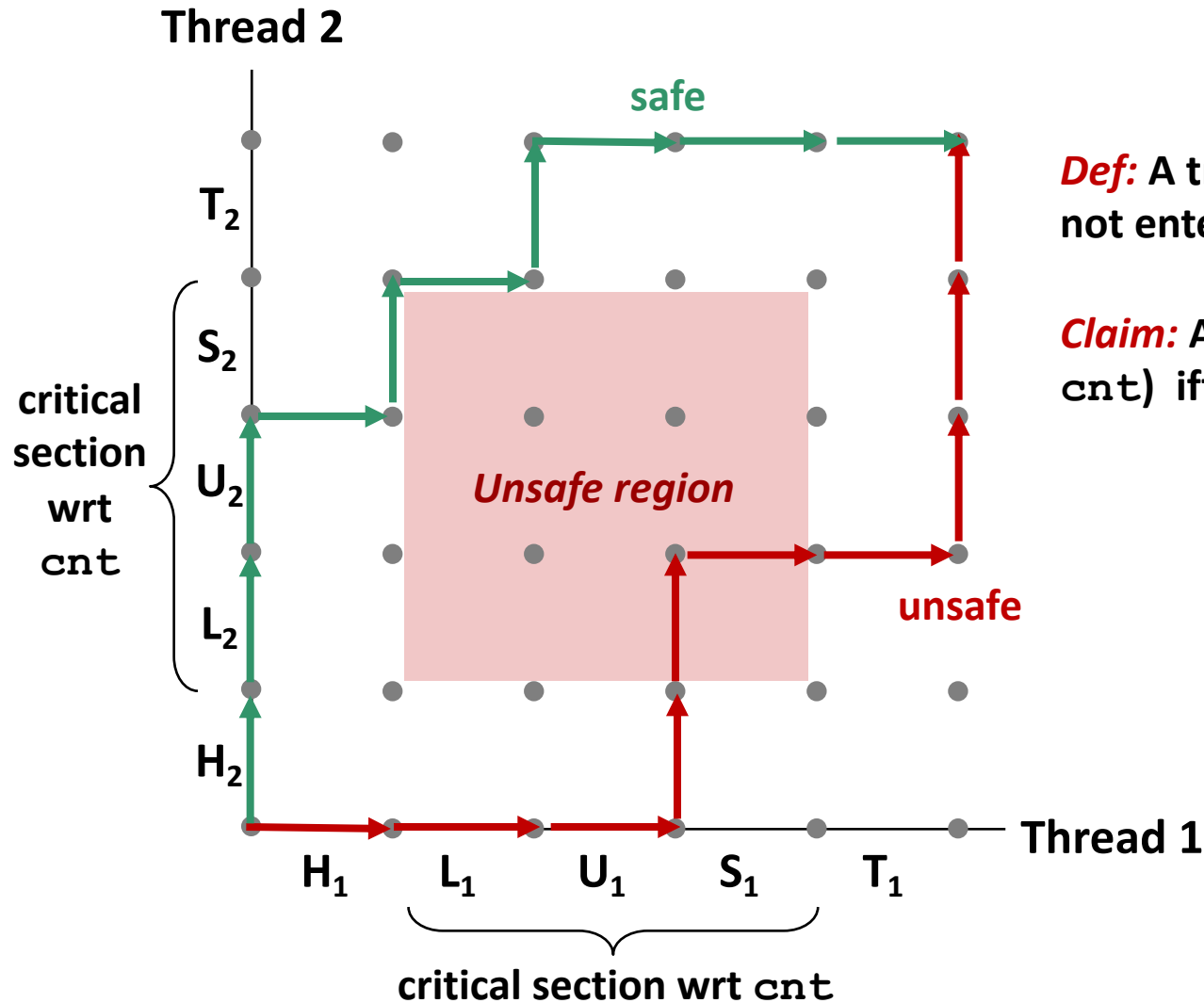


L , U , and S form a **critical section** with respect to the shared variable `cnt`

Instructions in critical sections (wrt some shared variable) should not be interleaved

Sets of states where such interleaving occurs form **unsafe regions**

Critical Sections and Unsafe Regions



Def: A trajectory is *safe* iff it does not enter any unsafe region

Claim: A trajectory is correct (wrt cnt) iff it is safe

badcnt.c: Improper Synchronization

```

/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                  thread, &niters);
    Pthread_create(&tid2, NULL,
                  thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}

```

badcnt.c

```

/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}

```

| Variable | main | thread1 | thread2 |
|----------|------|---------|---------|
| cnt | yes* | yes | yes |
| niters.m | yes | no | no |
| tid1.m | yes | no | no |
| i.1 | no | yes | no |
| i.2 | no | no | yes |
| niters.1 | no | yes | no |
| niters.2 | no | no | yes |

Enforcing Mutual Exclusion

- **Question:** How can we guarantee a safe trajectory?
- **Answer:** We must *synchronize* the execution of the threads so that they can never have an unsafe trajectory.
 - i.e., need to guarantee *mutually exclusive access* for each critical section.
- **Classic solution:**
 - Semaphores (Edsger Dijkstra)

Today

- Threads review
- Sharing
- Mutual exclusion
- **Semaphores**
- Producer-Consumer Synchronization

Semaphores

- ***Semaphore***: non-negative global integer synchronization variable. Manipulated by *P* and *V* operations.
- ***P(s)***
 - If *s* is nonzero, then decrement *s* by 1 and return immediately.
 - Test and decrement operations occur atomically (indivisibly)
 - If *s* is zero, then suspend thread until *s* becomes nonzero and the thread is restarted by a *V* operation.
 - After restarting, the *P* operation decrements *s* and returns control to the caller.
- ***V(s)***:
 - Increment *s* by 1.
 - Increment operation occurs atomically
 - If there are any threads blocked in a *P* operation waiting for *s* to become non-zero, then restart exactly one of those threads, which then completes its *P* operation by decrementing *s*.
- **Semaphore invariant: ($s \geq 0$)**

Semaphores

- ***Semaphore***: non-negative global integer synchronization variable
- **Manipulated by P and V operations:**
 - $P(s)$: [**while** ($s == 0$) **wait()**; $s--$;]
 - Dutch for “Proberen” (test)
 - $V(s)$: [$s++$;]
 - Dutch for “Verhogen” (increment)
- **OS kernel guarantees that operations between brackets [] are executed indivisibly**
 - Only one P or V operation at a time can modify s .
 - When **while** loop in P terminates, only that P can decrement s
- **Semaphore invariant: ($s \geq 0$)**

C Semaphore Operations

Pthreads functions:

```
#include <semaphore.h>

int sem_init(sem_t *s, 0, unsigned int val); /* s = val */

int sem_wait(sem_t *s); /* P(s) */
int sem_post(sem_t *s); /* V(s) */
```

CS:APP wrapper functions:

```
#include "csapp.h"

void P(sem_t *s); /* Wrapper function for sem_wait */
void V(sem_t *s); /* Wrapper function for sem_post */
```

badcnt.c: Improper Synchronization

```

/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                  thread, &niters);
    Pthread_create(&tid2, NULL,
                  thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}

```

badcnt.c

```

/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}

```

How can we fix this using semaphores?

Using Semaphores for Mutual Exclusion

■ Basic idea:

- Associate a unique semaphore *mutex*, initially 1, with each shared variable (or related set of shared variables).
- Surround corresponding critical sections with $P(mutex)$ and $V(mutex)$ operations.

■ Terminology:

- *Binary semaphore*: semaphore whose value is always 0 or 1
- *Mutex*: binary semaphore used for mutual exclusion
 - P operation: “locking” the mutex
 - V operation: “unlocking” or “releasing” the mutex
 - “Holding” a mutex: locked and not yet unlocked.
- *Counting semaphore*: used as a counter for set of available resources.

goodcnt.c: Proper Synchronization

- Define and initialize a mutex for the shared variable `cnt`:

```
volatile long cnt = 0; /* Counter */
sem_t mutex;          /* Semaphore that protects cnt */

sem_init(&mutex, 0, 1); /* mutex = 1 */
```

- Surround critical section with *P* and *V*:

```
for (i = 0; i < niters; i++) {
    P(&mutex);
    cnt++;
    V(&mutex);
}
```

goodcnt.c

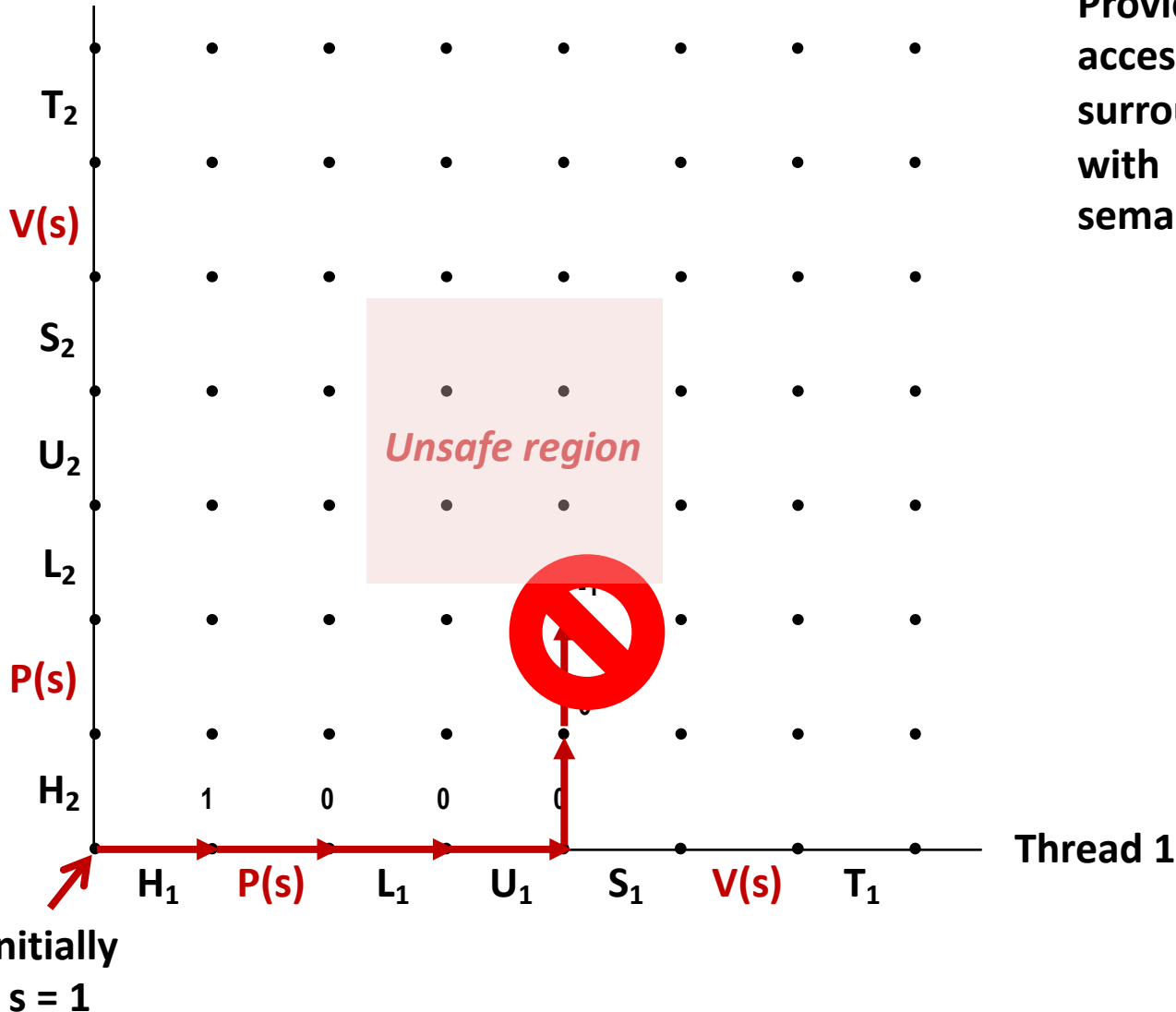
```
linux> ./goodcnt 10000
OK cnt=20000
linux> ./goodcnt 10000
OK cnt=20000
linux>
```

Warning: It's orders of magnitude slower than `badcnt.c`.

| Function | badcnt | goodcnt |
|------------------------------|--------|---------|
| Time (ms) niters = 10^6 | 12 | 450 |
| Slowdown | 1.0 | 37.5 |

Why Mutexes Work

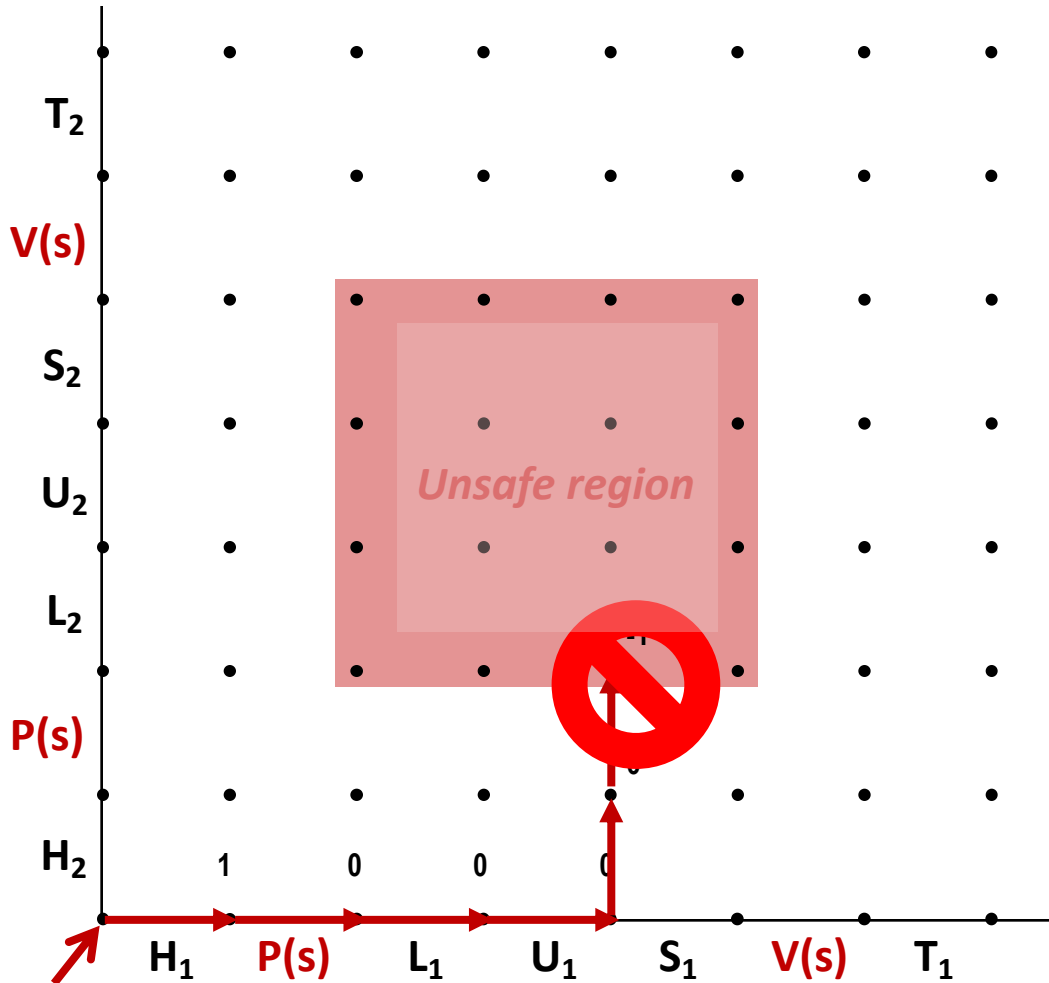
Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Why Mutexes Work

Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

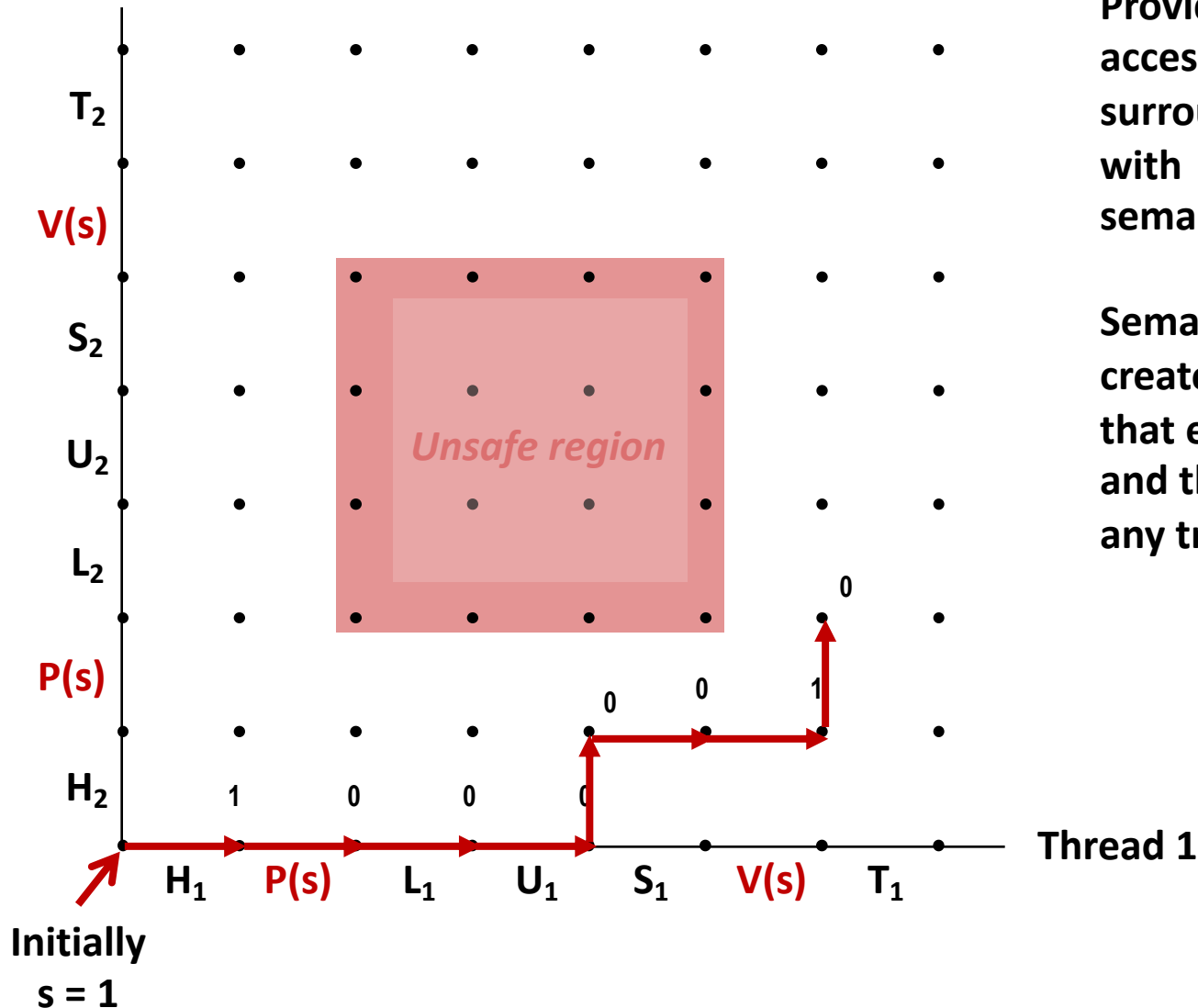
Semaphore invariant creates a *forbidden region* that encloses unsafe region and that cannot be entered by any trajectory.

Initially
 $s = 1$

Thread 1

Why Mutexes Work

Thread 2

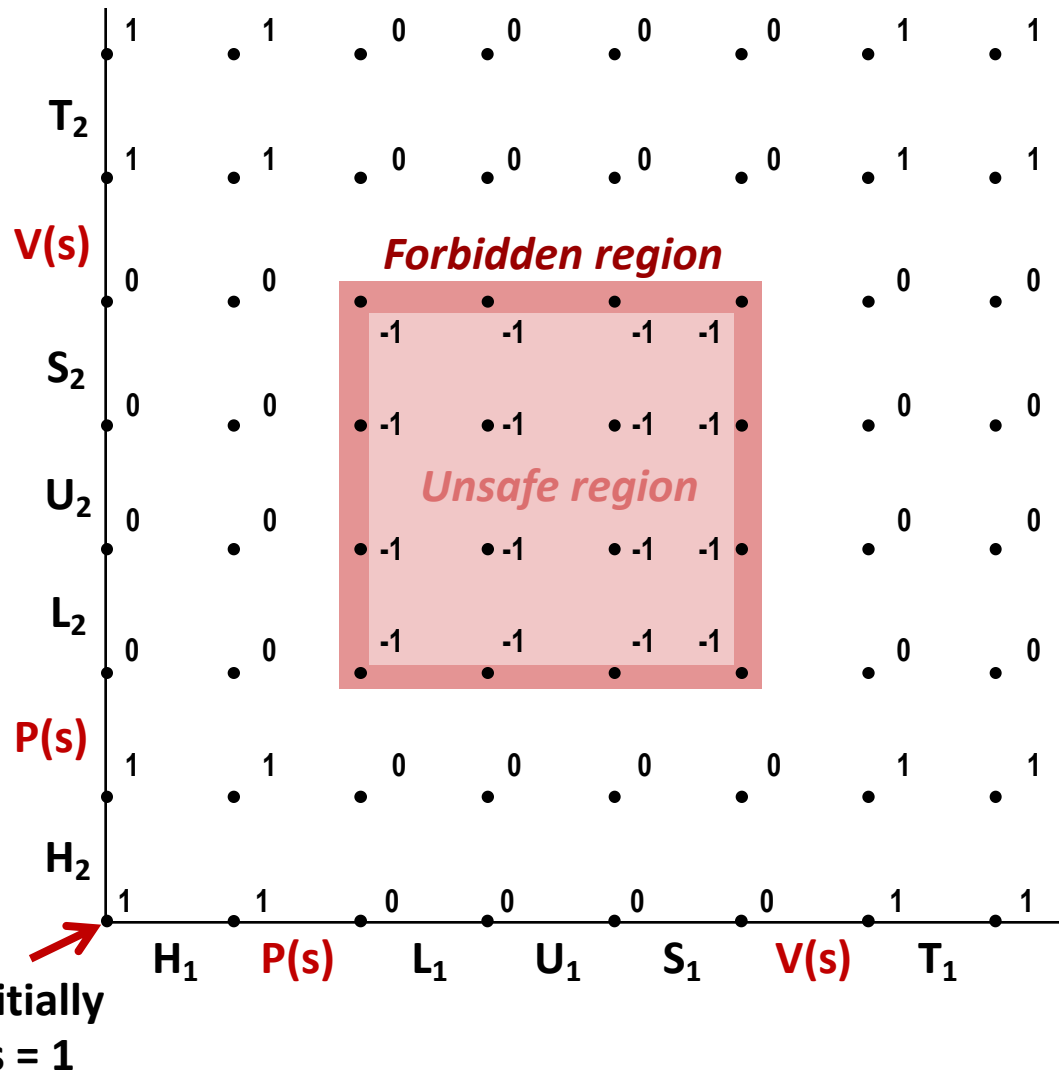


Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Semaphore invariant
creates a *forbidden region*
that encloses unsafe region
and that cannot be entered by
any trajectory.

Why Mutexes Work

Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Semaphore invariant creates a **forbidden region** that encloses unsafe region and that cannot be entered by any trajectory.

Enforcing Mutual Exclusion

- **Mutex is special case of semaphore**
 - Value either 0 or 1
- **Pthreads provides `pthread_mutex_t`**
 - Operations: lock, unlock
- **Recommended over general semaphores when appropriate**

goodmcent.c: Mutex Synchronization

- Define and initialize a mutex for the shared variable `cnt`:

```
volatile long cnt = 0; /* Counter */
pthread_mutex_t mutex;
pthread_mutex_init(&mutex, NULL); // No special attributes
```

- Surround critical section with *lock* and *unlock*:

```
for (i = 0; i < niters; i++) {
    pthread_mutex_lock(&mutex);
    cnt++;
    pthread_mutex_unlock(&mutex);
}
```

goodcnt.c

```
linux> ./goodmcent 10000
OK cnt=20000
linux> ./goodmcent 10000
OK cnt=20000
linux>
```

| Function | badcnt | goodcnt | goodmcent |
|------------------------------|--------|---------|-----------|
| Time (ms) niters = 10^6 | 12 | 450 | 214 |
| Slowdown | 1.0 | 37.5 | 17.8 |

Today

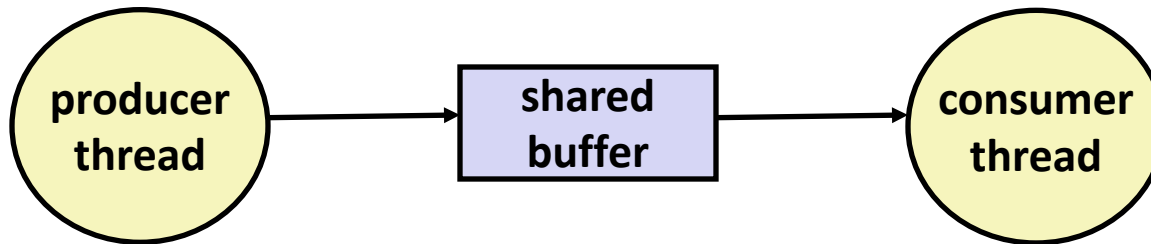
- Threads review
- Sharing
- Mutual exclusion
- Semaphores
- **Producer-Consumer Synchronization**

Using Semaphores to Coordinate Access to Shared Resources

- **Basic idea: Thread uses a semaphore operation to notify another thread that some condition has become true**
 - Use counting semaphores to keep track of resource state.
 - Use binary semaphores to notify other threads.

- **The Producer-Consumer Problem**
 - Mediating interactions between processes that generate information and that then make use of that information

Producer-Consumer Problem



■ Common synchronization pattern:

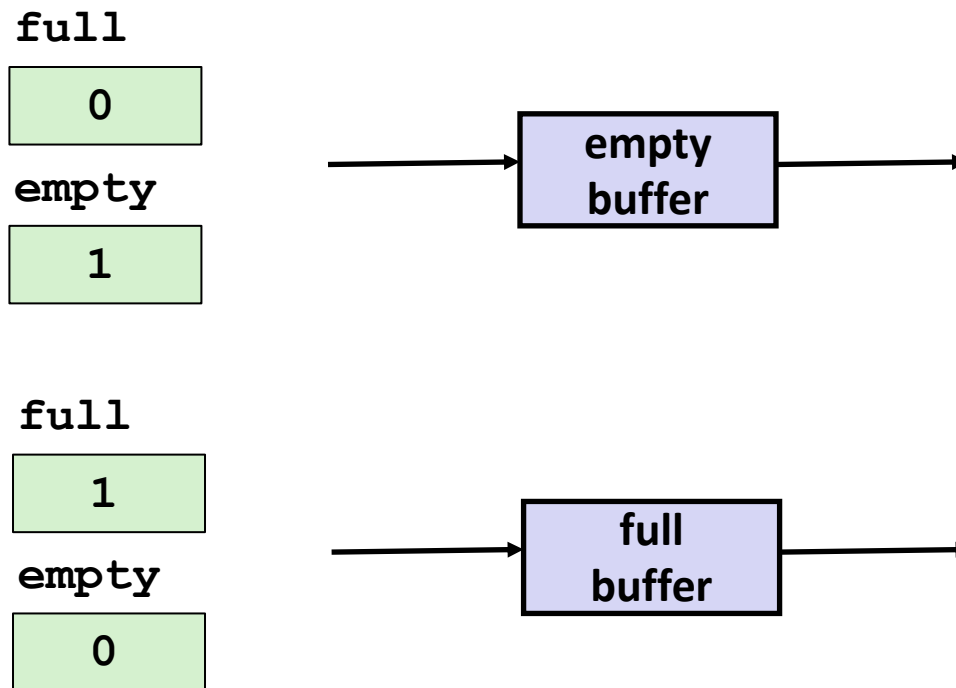
- Producer waits for empty *slot*, inserts item in buffer, and notifies consumer
- Consumer waits for *item*, removes it from buffer, and notifies producer

■ Examples

- Multimedia processing:
 - Producer creates video frames, consumer renders them
- Event-driven graphical user interfaces
 - Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in buffer
 - Consumer retrieves events from buffer and paints the display

Producer-Consumer on 1-element Buffer

- Maintain two semaphores: `full` + `empty`



Producer-Consumer on 1-element Buffer

```
#include "csapp.h"

#define NITERS 5

void *producer(void *arg);
void *consumer(void *arg);

struct {
    int buf; /* shared var */
    sem_t full; /* sems */
    sem_t empty;
} shared;
```

```
int main(int argc, char** argv) {
    pthread_t tid_producer;
    pthread_t tid_consumer;

    /* Initialize the semaphores */
    Sem_init(&shared.empty, 0, 1);
    Sem_init(&shared.full, 0, 0);

    /* Create threads and wait */
    Pthread_create(&tid_producer, NULL,
                  producer, NULL);
    Pthread_create(&tid_consumer, NULL,
                  consumer, NULL);

    Pthread_join(tid_producer, NULL);
    Pthread_join(tid_consumer, NULL);

    return 0;
}
```

Producer-Consumer on 1-element Buffer

Initially: `empty==1, full==0`

Producer Thread

```
void *producer(void *arg) {
    int i, item;

    for (i=0; i<NITERS; i++) {
        /* Produce item */
        item = i;
        printf("produced %d\n",
              item);

        /* Write item to buf */
        P(&shared.empty);
        shared.buf = item;
        V(&shared.full);
    }
    return NULL;
}
```

Consumer Thread

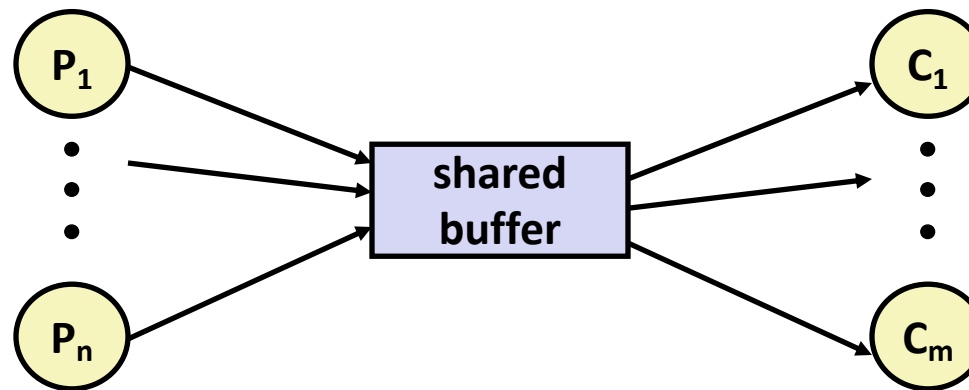
```
void *consumer(void *arg) {
    int i, item;

    for (i=0; i<NITERS; i++) {
        /* Read item from buf */
        P(&shared.full);
        item = shared.buf;
        V(&shared.empty);

        /* Consume item */
        printf("consumed %d\n", item);
    }
    return NULL;
}
```


Why 2 Semaphores for 1-Entry Buffer?

- Consider multiple producers & multiple consumers



- Producers will contend with each to get **empty**
- Consumers will contend with each other to get **full**

Producers

```
P(&shared.empty);
shared.buf = item;
V(&shared.full);
```

empty



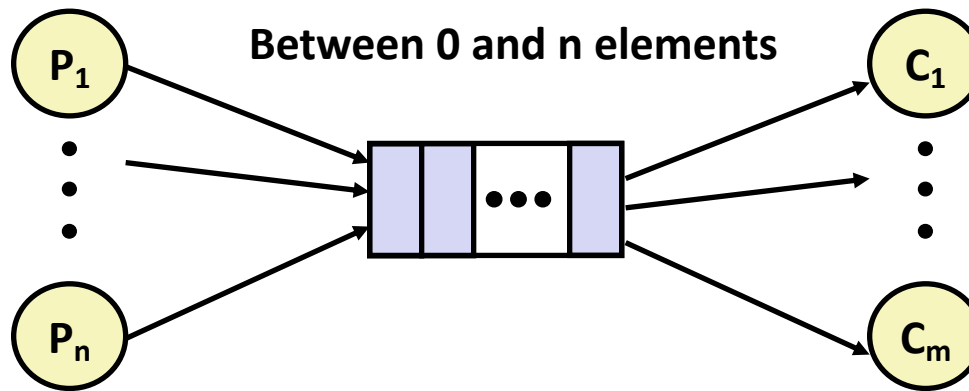
full



Consumers

```
P(&shared.full);
item = shared.buf;
V(&shared.empty);
```

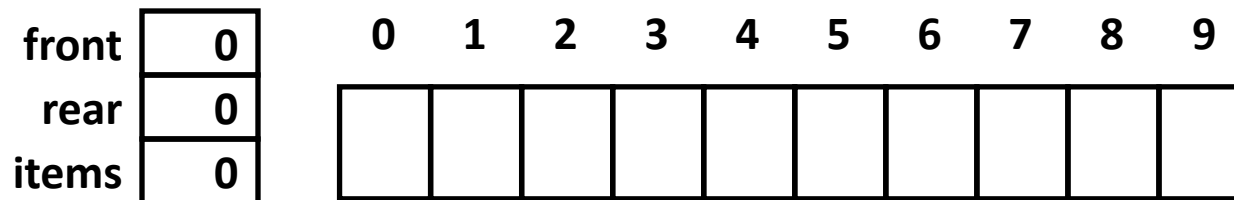
Producer-Consumer on an n -element Buffer



- Implemented using a shared buffer package called `sbuf`.

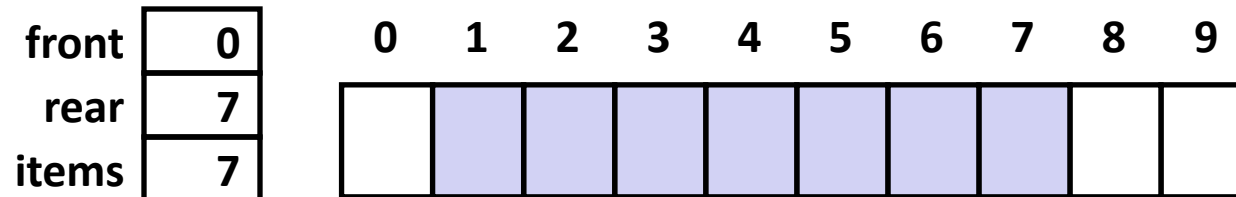
Circular Buffer (n = 10)

- Store elements in array of size n
- items: number of elements in buffer
- Empty buffer:
 - front = rear
- Nonempty buffer
 - rear: index of most recently inserted element
 - front: (index of next element to remove – 1) mod n
- Initially:

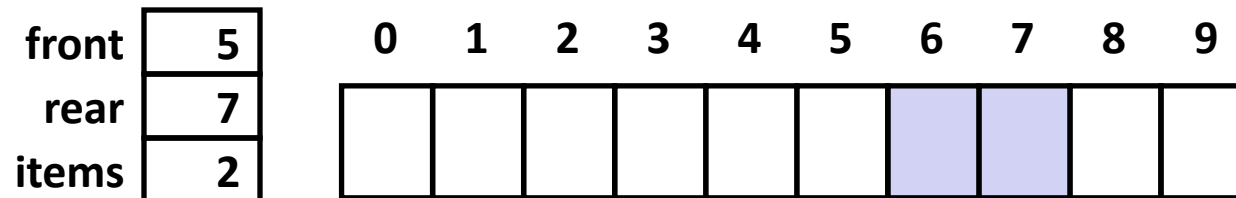


Circular Buffer Operation (n = 10)

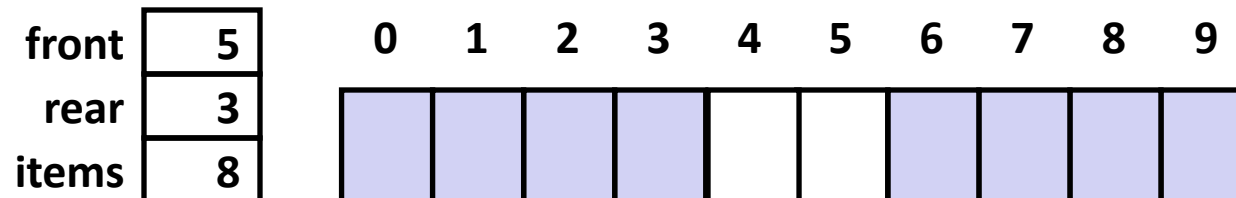
■ Insert 7 elements



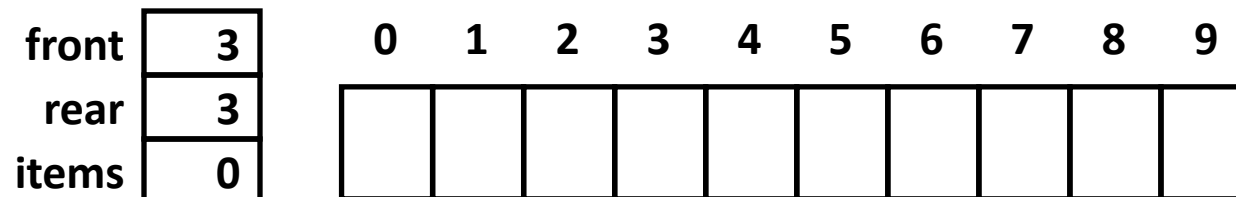
■ Remove 5 elements



■ Insert 6 elements



■ Remove 8 elements



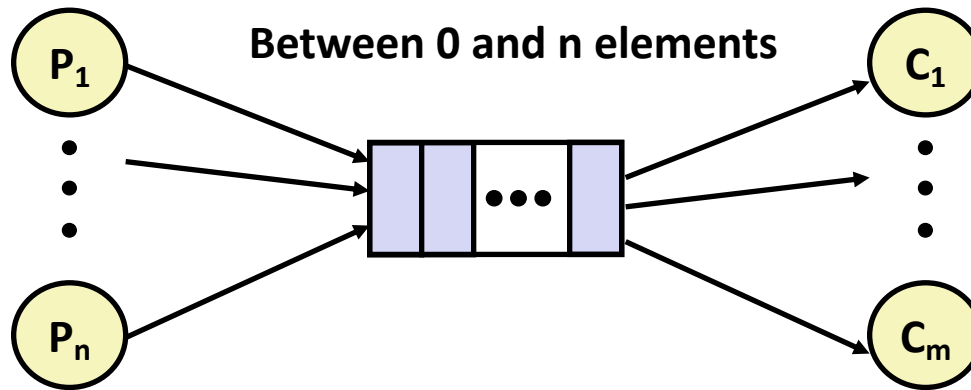
Sequential Circular Buffer Code

```
init(int v)
{
    items = front = rear = 0;
}
```

```
insert(int v)
{
    if (items >= n)
        error();
    if (++rear >= n) rear = 0;
    buf[rear] = v;
    items++;
}
```

```
int remove()
{
    if (items == 0)
        error();
    if (++front >= n) front = 0;
    int v = buf[front];
    items--;
    return v;
}
```

Producer-Consumer on an n -element Buffer



- **Requires a mutex and two counting semaphores:**
 - `mutex`: enforces mutually exclusive access to the buffer and counters
 - `slots`: counts the available slots in the buffer
 - `items`: counts the available items in the buffer
- **Makes use of general semaphores**
 - Will range in value from 0 to n

sbuf Package - Declarations

```
#include "csapp.h"

typedef struct {
    int *buf;          /* Buffer array */
    int n;             /* Maximum number of slots */
    int front;         /* buf[front+1 (mod n)] is first item */
    int rear;          /* buf[rear] is last item */
    sem_t mutex;       /* Protects accesses to buf */
    sem_t slots;       /* Counts available slots */
    sem_t items;       /* Counts available items */
} sbuf_t;

void sbuf_init(sbuf_t *sp, int n);
void sbuf_deinit(sbuf_t *sp);
void sbuf_insert(sbuf_t *sp, int item);
int sbuf_remove(sbuf_t *sp);
```

sbuf.h

sbuf Package - Implementation

Initializing and deinitializing a shared buffer:

```
/* Create an empty, bounded, shared FIFO buffer with n slots */
void sbuf_init(sbuf_t *sp, int n)
{
    sp->buf = Calloc(n, sizeof(int));
    sp->n = n; /* Buffer holds max of n items */
    sp->front = sp->rear = 0; /* Empty buffer iff front == rear */
    Sem_init(&sp->mux, 0, 1); /* Binary semaphore for locking */
    Sem_init(&sp->slots, 0, n); /* Initially, buf has n empty slots */
    Sem_init(&sp->items, 0, 0); /* Initially, buf has zero items */
}

/* Clean up buffer sp */
void sbuf_deinit(sbuf_t *sp)
{
    Free(sp->buf);
}
```


sbuf Package - Implementation

Inserting an item into a shared buffer:

```
/* Insert item onto the rear of shared buffer sp */
void sbuf_insert(sbuf_t *sp, int item)
{
    P(&sp->slots);          /* Wait for available slot */
    P(&sp->mutex);           /* Lock the buffer          */
    if (++sp->rear >= sp->n) /* Increment index (mod n) */
        sp->rear = 0;
    sp->buf[sp->rear] = item; /* Insert the item          */
    V(&sp->mutex);           /* Unlock the buffer        */
    V(&sp->items);           /* Announce available item */
}
```

sbuf.c

sbuf Package - Implementation

Removing an item from a shared buffer:

```
/* Remove and return the first item from buffer sp */
int sbuf_remove(sbuf_t *sp)
{
    int item;
    P(&sp->items);          /* Wait for available item */
    P(&sp->mutex);           /* Lock the buffer */
    if (++sp->front >= sp->n) /* Increment index (mod n) */
        sp->front = 0;
    item = sp->buf[sp->front]; /* Remove the item */
    V(&sp->mutex);           /* Unlock the buffer */
    V(&sp->slots);           /* Announce available slot */
    return item;
}
```

sbuf.c

Demonstration

- **See program produce-consume.c in code directory**
- **10-entry shared circular buffer**
- **5 producers**
 - Agent i generates numbers from $20*i$ to $20*i - 1$.
 - Puts them in buffer
- **5 consumers**
 - Each retrieves 20 elements from buffer
- **Main program**
 - Makes sure each value between 0 and 99 retrieved once

Summary

- **Programmers need a clear model of how variables are shared by threads.**
- **Variables shared by multiple threads must be protected to ensure mutually exclusive access.**
- **Semaphores are a fundamental mechanism for enforcing mutual exclusion**
 - And can also support producer-consumer synchronization