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# Release Notes for PNG Decoder on ARM11 ELINUX

ABSTRACT:

Release Notes for PNG Decoder on ARM11 ELINUX

**KEYWORDS:** 

Multimedia codecs, PNG, image

APPROEVD:

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# **Revision History**

VERSION	DATE	AUTHOR	CHANGE DESCRIPTION
1.0	27-Dec-2004	Shailesh R, Sameer PR	Release 1.0 of PNG Decoder on ARM11 RealView Simulator platform
2.0	01-Apr-2005	Shailesh R, Sameer PR	Release 2.0 of PNG Decoder on board with ELINUX
3.0	07-Sep-2005	Puneet Gulati	Build Procedure changes for RVDS2.2
4.0	06-Feb-2006	Lauren Post	Using new format
4.1	09-Mar-2009	Eagle Zhou	Add decode frame api

# **Table of Contents**

Ir	ntroduo	ction	4
11	1.1 1.2 1.3 1.4 1.4.	Purpose Scope Scope Scope Standards Standards References References	4 4 4 4
2	1.4. 1.5 1.6	Definitions, Acronyms, and Abbreviations  Document Location	5 5
<b>∠</b>	2.1 2.2	Assumptions and Known Problems	6
3	3.1 3.2 3.3 3.4 3.5 3.6	Documentation Public Headers Test Application Source Library Source Common Makefiles Test Vectors	7 7 7 7
4	Soft	tware Setup & Tools used	10
5	<b>Bui</b> 5.1 5.2	Id Procedure  Library  Test Application	11
6	Tes 6.1 6.2	Scripts ELINUX	14
-	6.3 6.4	RVDS	14 14
7	Pre	compilation Options	15

### Introduction

### 1.1 Purpose

The purpose of this document is to provide information on the package contents, instructions on building library and test applications and test execution on ARM11 ELINUX, RVDS and Linux x86.

### 1.2 Scope

The scope is restricted to information on the package contents and instructions for building and testing. This document does not provide architecture or details about the APIs provided in the package. Performance data will be provided in another document as detailed in the Requirements Book.

### 1.3 Audience Description

The reader is expected to have basic understanding of PNG decoding.

### 1.4 References

#### 1.4.1 Standards

• PNG Specifications 1.0 (RFC 2083) (<a href="http://www.libpng.org/pub/png/spec">http://www.libpng.org/pub/png/spec</a>)

#### 1.4.2 References

- Compressed Image File formats by John Miano, ACM Press/Addison Wesley Longman.
- Libpng 1.2.7 (http://www.libpng.org/pub/png/libpng.html)
- Zlib 1.2.1(www.zlib.org)
- ZLIB data format v3.3 (RFC 1950)
- 'Deflate' compressed data format Spec v1.3 (RFC 1951)

#### 1.4.3 Freescale Multimedia References

- PNG Decoder Application Programming Interface png\_dec\_api.doc
- PNG Decoder Requirements Book png\_dec\_reqb.doc
- PNG Decoder Test Plan png\_dec\_test\_plan.doc
- PNG Decoder Release notes png\_dec\_release\_notes.doc
- PNG Decoder Test Results png\_dec\_test\_results.doc
- PNG Decoder Performance Results png\_dec\_perf\_results.doc
- PNG Decoder Interface Header png\_dec\_interface.h
- PNG Decoder Application Code png\_test\_wrapper.c

# 1.5 Definitions, Acronyms, and Abbreviations

TERM/ACRONYM	DEFINITION	
API	Application Programming Interface	
ARM	Advanced RISC Machine	
FSL	Freescale	
OS	Operating System	
PNG	Portable Network Graphics	
PNM	Portable aNyMap file. It refers collectively to PBM, PGM, and PPM formats (Portable Bi-level-image Map, Portable Grayscale Map and Portable Pixel Map respectively)	
RGB	Raw pixel data organized in the order of Red, green and blue components. <b>RGB888</b> denotes 8 bits per pixel each for R, G, and B components	
TBD	To Be Determined	
UNIX	Linux PC x/86 C-reference binaries	

### **1.6 Document Location**

docs/png\_dec

# 2 Release History

RELEASE NUMBER	DELIVERABLES	FEATURES
1.0		Engineering Release
2.1	<ul> <li>Documentation</li> <li>Application Interface header file</li> <li>ELINUX and RVDS libraries and test applications</li> <li>UNIX/Linux x/86 Reference library and test application</li> <li>Makefiles and Source code for library and test application</li> <li>Test vectors</li> </ul>	<ul> <li>Shared library support</li> <li>Upgrade to RVDS 2.2</li> </ul>
2.2	Same	<ul> <li>API changes to fix name collisions with other codecs</li> </ul>
2.3	Same	Add decode frame api

Table 1. Details of the release

# 2.1 Assumptions and Known Problems

None

### 2.2 Contacts

Please report any problems to the following email address: <a href="mmsw@freescale.com">mmsw@freescale.com</a>

### 3 List of Deliverables

### 3.1 Documentation

**Base directory:** /ARM11/

Subdirectory	Files
docs/png_dec	png_dec_api.doc
	png_dec_reqb.doc
	png_dec_test_plan.doc
	png_dec_test_results.doc
	png_dec_perf_results.doc
	png_dec _release_notes.doc

### 3.2 Public Headers

**Base directory:** /ARM11/

Subdirectory	Files
API_include	png_interface.h

### 3.3 Test Application Source

**Base directory:** /ARM11/src/image/png dec

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Subdirectory	Files	
test/	"Makefile" makefile for building RVDS, UNIX and ELINUX	
	board executables.	
test/c_source	*.c, application code.	
test/test_util/scripts	Batch files to be run on the board	

# 3.4 Library Source

Base directory: /ARM11/src/image/png dec

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Subdirectory	Files	
library	Makefile "Makefile" for building RVDS, UNIX, and ELINUX	
	libraries.	
	libpng_dec_arm11_RVDS.a – Special options for simulator	
testing		
	libpng_dec_arm11_ELINUX.a - static library for board	
libpng_dec_arm11_ELINUX.so – shared library for box		
	libpng_dec_UNIX.a – library for Linux x/86 – c reference	
	code	
library/c_source	*.c, PNG decoder source code	
library/include	*.h, PNG decoder library header files	

# 3.5 Common Makefiles

Base Directory: /ARM11/common

Makefile	Description	
common.mk	This is a common makefile included in the codec library makefile for building the libraries. This file includes common options used by all codecs. Following flags can be overwritten or added to in the codec library makefile  1. Path to toolchain tools (TC_ROOT)	
	<ol> <li>GNU header file path (HEADER_PATHS)</li> <li>GNU library path (LIB_PATHS)</li> <li>GNU Compiler/Assembler Options         (GNU_CFLAGS, GNU_AFLAGS)     </li> </ol>	
	<ul> <li>5. Endian Flags</li> <li>6. Optimization Flags(OPTIM_LEVEL, OPTIM_TYPE)</li> <li>7. Common options for RVDS,UNIX and ELINUX (CFLAGS,AFLAGS)</li> </ul>	
	<ol> <li>8. Build specific flags</li> <li>9. Source directory of 'C' code</li> <li>10. Source directory of 'assembly(.s)' code</li> <li>11. Object directory for .o files</li> <li>12. RVDS Compilation Tools</li> <li>13. Codec header path</li> <li>14. Arguments for librarian for UNIX builds</li> <li>15. SHARED_ELINUX builds for libraries that must be linked using the toolchain because of external library includes.</li> </ol>	
common_testapp.mk	This is the common makefile included in the codec test makefile for building the test application. This file includes the common options used by the all the codecs. Following flags can be overwritten or added to in the codec test makefile	
	<ol> <li>Toolchain path depending on the build option</li> <li>Compiler Flags</li> <li>Linker flags</li> <li>Paths for c_source, exe and object directories</li> <li>Codec header files' INCLUDES path</li> <li>Endian Flags</li> <li>CODEC_LIB generation</li> </ol>	

### 3.6 Test Vectors

Base Directory: multimedia\_vectors/test\_vectors

The test vectors are provided in another location from the library and test source.

Subdirectory	Files	
png_dec/input/sample_test_cases	*. png – input files to decoder, in the form of png code- stream	
png_dec/ref/sample_test_cases	Reference outputs for the *.png files in the sample test cases – the reference vectors are the decoded output in the form of ppm files <sup>1</sup>	
png_dec/ref/sample_test_cases /big_end_ref_565_555	Reference vectors for 16-bit output format in the specific case of big-endian organization of data	

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<sup>&</sup>lt;sup>1</sup> The raw decoded output is formatted in the ppm format and can be viewed using a tool like IrfanView (www.irfanview.com)

# 4 Software Setup & Tools used

- ARM RVDS 2.2 (build 503) should be installed in the PC.
- Freescale Linux OS Release L26.1.15 must be running on the evaluation board.
- Intel based Red Hat Linux Machine must have the Montavista toolchain installed on it.
  - o MontaVista 3.4.3-25.0.36.0501313 2005-08-21
- 'Cygwin' **Version** CYGWIN\_NT-5.1, a freely downloadable linux emulator is installed in PC **http://www.cygwin.com/**.
- 'make' utility available for targeted platforms

### **5 Build Procedure**

All the required makefiles are provided under individual directories. The library can be built for windows / target processor (ARM1136J-S). The details for the build procedure are described below.

### 5.1 Library

To build the library, run 'make' on 'Makefile' from library directory. The makefile shall create the required directory to hold the object files. The makefile can be used if you want to build the library only. The same makefile can used to build libraries for both board, Unix/Linux and RVDS with different build options. The following options are available to build the library.

#### **Options**

- a) **BUILD options**:
  - BUILD= ELINUX: This is the default option and builds both static library 'libpng\_dec\_arm11\_ELINUX.a' and shared library 'libpng\_dec\_arm11\_ELINUX.so', for testing on the board.
  - BUILD=RVDS: This option builds the static library 'libpng\_dec\_arm11\_RVDS.a', for testing on RVDS (Armulator).
  - BUILD=UNIX: This option builds the static library 'libpng\_dec\_UNIX.a', for testing on UNIX/Linux machine.

Eg: make BUILD= ELINUX make BUILD=RVDS make BUILD=UNIX

#### b) ENDIAN options for RVDS:

- TARGET\_ENDIAN=LITTLE: This is the default option and sets the endian-ness to 'little'
- o TARGET\_ENDIAN=BIG: This option sets the endian-ness to big Eg: make BUILD=RVDS TARGET\_ENDIAN=BIG

#### c) clean options:

- o **clean\_RVDS**: Deletes all the object files and the RVDS library 'libpng\_dec\_arm11\_RVDS.a'.
- o **clean\_ELINUX**: Deletes all the object file and the ELINUX libraries libpng\_dec\_arm11\_ELINUX.a and libpng\_dec\_arm11\_ELINUX.so.
- o clean\_UNIX: Deletes all the object files and the UNIX library 'libpng\_dec\_UNIX.a'.
- o clean: Deletes all the object files and RVDS, UNIX and ELINUX libraries.

**Note**: Make appropriate changes in file 'common.mk' at directory 'ARM11/common' for the location of toolchains.

The library that is built is saved as libpng\_dec\_arm11\_RVDS.a for RVDS build, and libpng\_dec\_arm11\_ELINUX.a and libpng\_dec\_arm11\_ELINUX.so for board build. These libraries are saved in the current directory (the same directory in which the source and assembly directories are listed).

Target	Compilation	<b>Build Options</b>	Library Name
	Environment		
Board	PC (Using Cygwin)	BUILD= ELINUX	libpng_dec_arm11_ELINUX.a,
			libpng_dec_arm11_ELINUX.so
RVDS	PC (Using Cygwin)	BUILD=RVDS	libpng_dec_arm11_RVDS.a
		TARGET_ENDIAN=	
		BIG/LITTLE	
Unix/	Linux/Unix machine	BUILD=UNIX	libpng_dec_UNIX.a
Linux		TARGET_ENDIAN=	
		BIG/LITTLE	

### 5.2 Test Application

To build the test application, run 'make' on 'Makefile' from the test directory. This makefile can create executables for testing on Linux x86, the ARM11board and RVDS for ARM11. The executables png\_dec\_arm11\_RVDS' for RVDS, png\_dec\_arm11\_ELINUX for board and png\_dec\_UNIX for UNIX are stored under test/exe directory. The makefile shall create the required directory structure to hold the object files and executables. The following commands should be invoked so as to build the executables.

#### **Options**

#### 1) **BUILD options**:

- o **BUILD=ELINUX**: This is the default option and builds the executable 'png\_dec\_arm11\_ELINUX', for the board.
- o **BUILD=RVDS**: This option builds the executable 'png\_dec\_arm11\_RVDS' for the RVDS (Armulator).
- o **BUILD=UNIX**: This option builds the executable 'png\_dec\_UNIX' for the Unix/Linux machine.

Eg: make BUILD=ELINUX (for board)
make BUILD=RVDS (for Armulator)

make BUILD=UNIX (for Unix/Linux machine)

#### 2) ENDIAN options for RVDS:

o **TARGET\_ENDIAN=LITTLE**: This is the default option and sets the endian-ness to 'little'

• TARGET\_ENDIAN=BIG: This option sets the endian-ness to big Eg: make BUILD=RVDS TARGET\_ENDIAN=BIG

#### 3) LIBRARY options:

o **LIB= STATIC**: This option builds the ELINUX test application linked with the ELINUX static library 'libpng\_dec\_arm11\_ELINUX.a'.If nothing is specified ,the executable links with shared library 'libpng\_dec\_arm11\_ELINUX.so'

**Eg:** make LIB=STATIC

#### 4) clean options:

- o **clean\_RVDS**: Deletes all the object files and the RVDS executable 'png\_dec\_arm11\_RVDS'.
- o **clean\_ELINUX**: Deletes all the object file and the ELINUX 'png\_dec\_arm11\_ELINUX'.
- o **clean\_UNIX**: Deletes all the object files and the Unix/Linux executable 'png\_dec\_UNIX'.
- o **clean**: Deletes all the object files and RVDS,UNIX ELINUX executables.

#### Note:

In 'common\_testapp.mk' at directory 'ARM11/common', the paths for the compiling and linking tools are hard coded for the current set-up. These paths may not be the same in the user's directory set up. Hence, the 'common\_testapp.mk' should be modified to point to the directories where the linking and compilation tools are present before building the application for board.

The following table summarises the build options,

Target	Compilation	<b>Build Options</b>	Executable Name
	Environment		
Board	Redhat Linux	BUILD=ELINUX	png_dec_arm11_ELINUX
	Machine	LIB= STATIC	
RVDS	PC (Using	BUILD=RVDS	png_dec_arm11_RVDS
	Cygwin)	TARGET_ENDIAN=LITTLE/BIG	
UNIX/	Unix/Linux	BUILD=UNIX	png_dec_UNIX
Linux	machine	TARGET_ENDIAN=LITTLE/BIG	

# **6 Test Application Execution**

### 6.1 Scripts

In the test\test\_util\scripts directory, a script file exists for doing batch processing on several vectors. The script can be modified or parameters set to specify the binaries to use.

### 6.2 ELINUX

png\_dec\_arm11\_ELINUX <input file> <output file> <output format> <output-width> <output-height> <scaling mode> <raw format>

### **6.3 RVDS**

Please refer ARM documentation regarding loading the image and configuring the RVDS debugger for ARM1136J-S

• RVDS:
Once the image is loaded press "F5" or select the pull down menu option "Debug -> Execution Control" to run the loaded image.

### **6.4 UNIX Reference**

To execute on Linux x/86 type:

png\_dec\_UNIX <input vector> <output vector>

# **7 Pre compilation Options**

The following C options need to be set

C Defines	Description	Remarks
LOG_TIMING	To log performance	
	timing results	