

Question 4, Assignment 5: CS 754, Spring 2024-25

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1. Consider that you learned a dictionary \mathbf{D} to sparsely represent a certain class \mathcal{S} of images - say handwritten alphabet or digit images. How will you convert \mathbf{D} to another dictionary which will sparsely represent the following classes of images? Note that you are not allowed to learn the dictionary all over again, as it is time-consuming.
 - (a) Class \mathcal{S}_1 which consists of images obtained by applying a known affine transform \mathbf{A}_1 to a subset of the images in class \mathcal{S} , and by applying another known affine transform \mathbf{A}_2 to the other subset. Assume that the images in \mathcal{S} consisted of a foreground against a constant 0-valued background, and that the affine transformations $\mathbf{A}_1, \mathbf{A}_2$ do not cause the foreground to go outside the image canvas.
 - (b) Class \mathcal{S}_2 which consists of images obtained by applying an intensity transformation $I_{new}^i(x, y) = \alpha(I_{old}^i(x, y))^2 + \beta(I_{old}^i(x, y)) + \gamma$ to the images in \mathcal{S} , where α, β, γ are known.
 - (c) Class \mathcal{S}_4 which consists of images obtained by downsampling the images in \mathcal{S} by a factor of k in both X and Y directions.
 - (d) Class \mathcal{S}_5 which consists of images obtained by applying a blur kernel which is known to be a linear combination of blur kernels belonging to a known set \mathcal{B} , to the images in \mathcal{S} .
 - (e) Class \mathcal{S}_6 which consists of 1D signals obtained by applying a Radon transform in a known angle θ to the images in \mathcal{S} . [4 x 5 = 20 points]

(a) Let \mathbf{A}_1 and \mathbf{A}_2 be the known affine transformation operators. Since affine transforms are linear, they can be applied to each atom in the dictionary. Let D_{A_1} and D_{A_2} be the transformed dictionaries obtained by applying \mathbf{A}_1 and \mathbf{A}_2 respectively to every reshaped atom of \mathbf{D} . Then,

$$\mathbf{D}' = [D_{A_1} \mid D_{A_2}]$$

This new dictionary \mathbf{D}' will be able to sparsely represent both subsets of images, as follows:

$$f' = \mathbf{D}' \begin{bmatrix} \theta_f \\ 0 \end{bmatrix} \quad \text{if } f' \text{ came from } A_1(f), \quad \text{and} \quad f' = \mathbf{D}' \begin{bmatrix} 0 \\ \theta_f \end{bmatrix} \quad \text{if } f' \text{ came from } A_2(f)$$

where $f = D\theta_f$ and θ_f is k -sparse.

(b) For an image $f = D\theta$, consider the intensity transformation:

$$f' = \alpha(f \odot f) + \beta f + \gamma \mathbf{1}$$

where \odot denotes point-wise multiplication and $\mathbf{1}$ is a vector of all ones. Expanding:

$$f' = \alpha(D\theta \odot D\theta) + \beta D\theta + \gamma \mathbf{1}$$

Let \tilde{D} be a matrix formed by element-wise products of all pairs of dictionary atoms:

$$\tilde{D}_{(i,j)} = D_i \odot D_j \quad \forall i, j$$

and $\tilde{\theta} = \text{vec}(\theta\theta^T)$, then:

$$f' = [\mathbf{1} \mid D \mid \tilde{D}] \begin{bmatrix} \gamma \\ \beta\theta \\ \alpha\tilde{\theta} \end{bmatrix}$$

So, the new dictionary is:

$$D' = [\mathbf{1} \mid D \mid \tilde{D}]$$

which contains the constant vector, the original dictionary atoms, and all pairwise element-wise products of atoms.

(c) Downsampling by a factor k is a linear operation that reduces spatial resolution. Let S_k be the downsampling operator that maps an image of size (h, w) to $(h/k, w/k)$. Then, applying this to each atom in D (after reshaping) gives:

$$D'_i = \text{vec}(S_k(\text{reshape}(D_i))) \quad \forall i$$

So the new dictionary is:

$$D' = [D'_1 \ D'_2 \ \dots \ D'_K]$$

where each D'_i is a downsampled version of D_i .

(d) Suppose the blur kernel b is given by $b = \sum_{j=1}^n \beta_j b_j$ for known $\{b_j\} \in \mathcal{B}$. Since convolution is linear:

$$f' = b * \text{reshape}(f) = \left(\sum_j \beta_j b_j \right) * \left(\sum_i D_i \theta_i \right) = \sum_{i,j} \beta_j (b_j * \text{reshape}(D_i)) \theta_i$$

Define $D^{(j)}$ as the dictionary obtained by convolving each atom D_i (reshaped) with b_j :

$$D_i^{(j)} = \text{vec}(b_j * \text{reshape}(D_i)) \quad \Rightarrow \quad D' = \sum_j \beta_j D^{(j)}$$

So D' is the linear combination of the blurred versions of the original dictionary atoms.

(e) Let R_θ denote the Radon transform at angle θ . Since it's a linear operation:

$$f' = R_\theta(\text{reshape}(f)) = R_\theta \left(\sum_i \text{reshape}(D_i) \theta_i \right) = \sum_i R_\theta(\text{reshape}(D_i)) \theta_i$$

Let $D'_i = R_\theta(\text{reshape}(D_i))$, vectorised. Then:

$$D' = [D'_1 \ D'_2 \ \dots \ D'_K]$$

is the new dictionary, where each atom is transformed by the Radon operator.