Product Specification

NHD-0420AZ-FL-GBW-33V3

Character Liquid Crystal Display Module

NHD-	Newhaven Display
0420-	4 Lines x 20 Characters
AZ-	Model
F-	Transflective
L-	Edge Yellow/Green LED Backlight
G-	STN (+) Gray
B-	6:00 Optimal View
W-	Wide Temperature
33V3-	3.3VDD, 3.0V Backlight

REACH
Compliant

RoHS
Compliant

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Additional Resources

➢ **Support Forum:** https://support.newhavendisplay.com/hc/en-us/community/topics

➢ **GitHub:** https://github.com/newhavendisplay

➢ **Example Code:** https://support.newhavendisplay.com/hc/en-us/categories/4409527834135-Example-Code/

➢ **Knowledge Center:** https://www.newhavendisplay.com/knowledge_center.html

➢ **Quality Center:** https://www.newhavendisplay.com/quality_center.html

➢ **Precautions for using LCDs/LCMs:** https://www.newhavendisplay.com/specs/precautions.pdf

➢ **Warranty / Terms & Conditions:** https://www.newhavendisplay.com/terms.html

Document Revision History

| Revision	Date	Description	Changed By
-	02/07/2012	3.3V Glass Implemented	SB
1	05/10/2017	Mechanical, Electrical & Optical Characteristics Updated	SB
2	07/01/2025	Updated DDRAM Address Table	KL
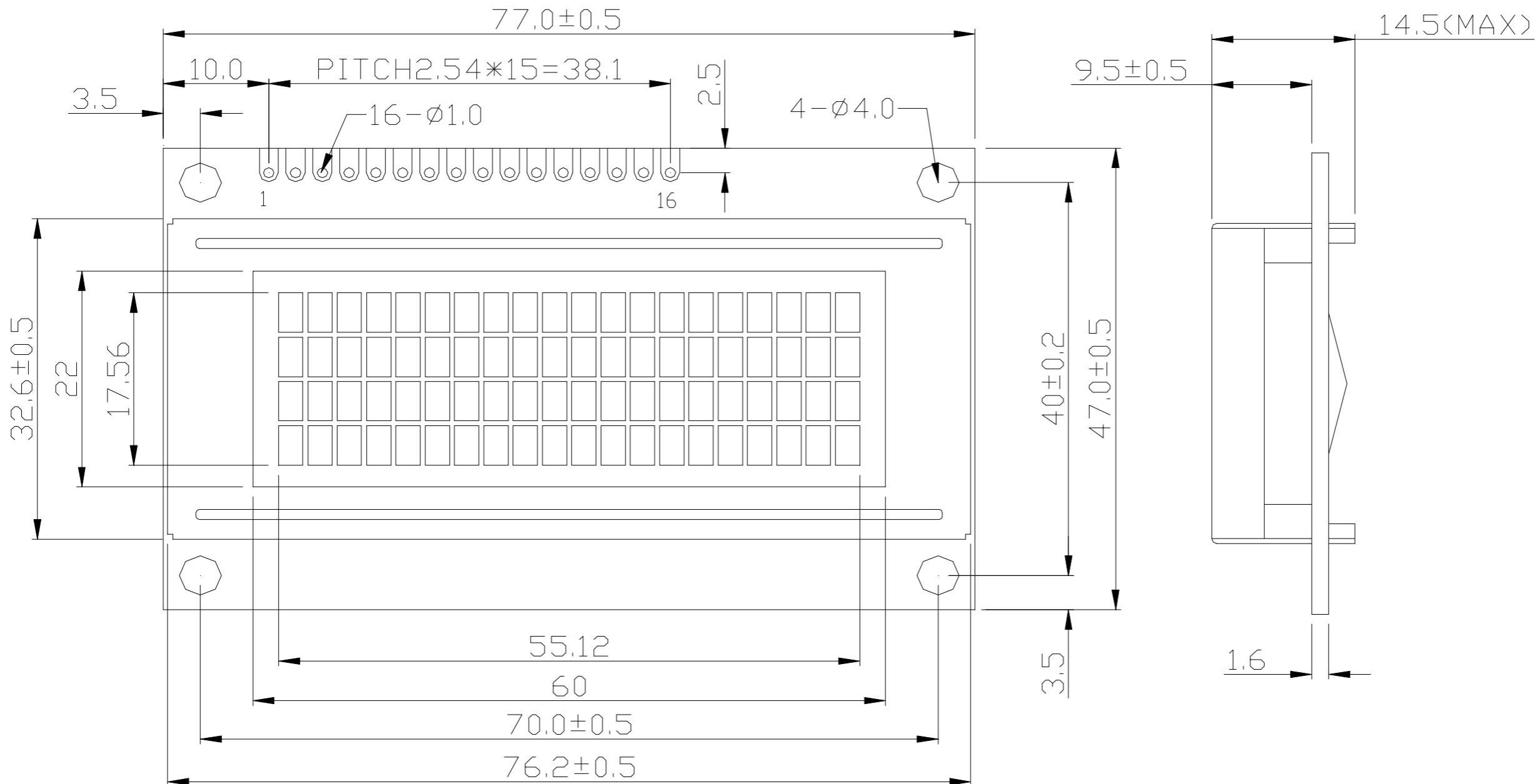
Mechanical Drawing

77.0±0.5

10.0

PITCH2.54*15=38.1

3.5

16−Ø1.0

2.5

4−Ø4.0

14.5(MAX)

9.5±0.5

1

16

32.6±0.5

22

17.56

40±0.2

47.0±0.5

3.5

1.6

55.12

60

70.0±0.5

76.2±0.5
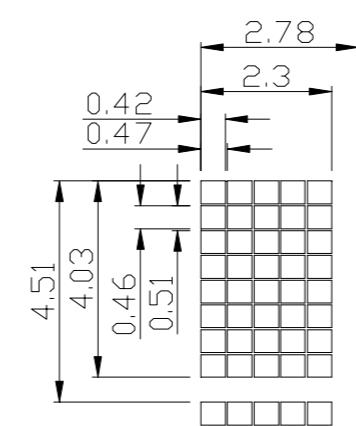
PIN ASSIGNMENT

1	VSS
2	VDD
3	V0
4	RS
5	R/W
6	E
7~14	DB0~DB7
15	LED+
16	LED-

2.78

2.3

0.42

0.47

4.51

4.03

0.46

0.51

Product Description: 4x20 Character LCD

1. Driver IC: ST7066U

2. Driving Mode: 1/16 Duty, 1/5 Bias

3. Interface: 4/8-bit 6800 Parallel

4. Power Requirement: 3.0V LCD, 3.0V/15mA Backlight

5. Optical Features: STN (+) Gray, Transflective, 6:00 View, Edge Yellow/Green Backlight

6. Recommended Pin Header: 1x16pin 2.54 pitch
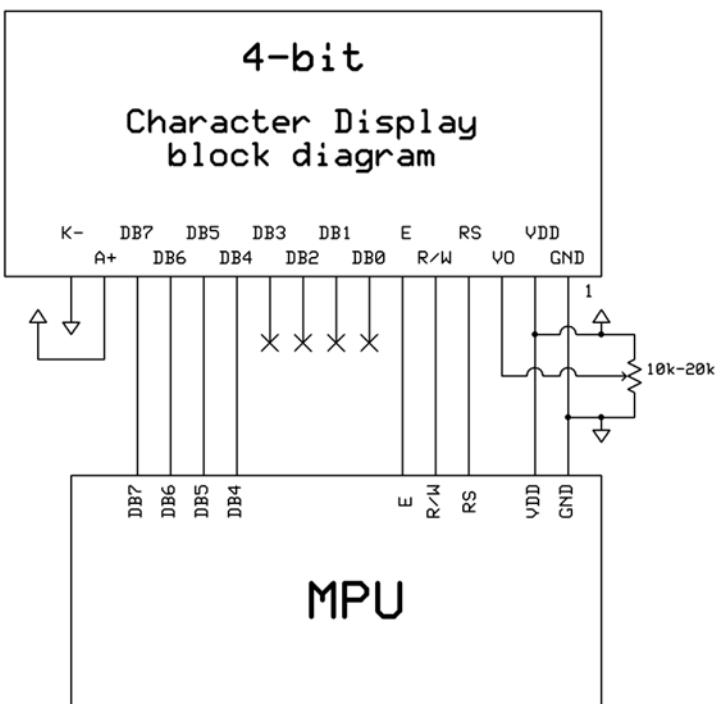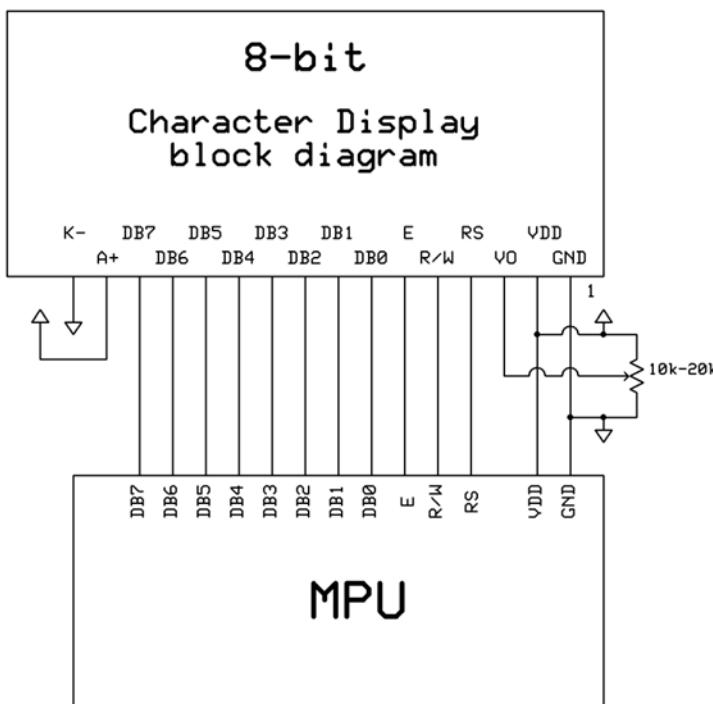
Pin Description

Pin No.	Symbol	External Connection	Function Description
1	V_{SS}	Power Supply	Ground
2	V_{DD}	Power Supply	Supply Voltage for Logic (+3.3V)
3	V_0	Power Supply	Supply Voltage for Contrast (approx. 0V)
4	RS	MPU	Register Select signal. RS=0: Command, RS=1: Data
5	R/W	MPU	Read/Write select signal, R/W=1: Read R/W:=0: Write
6	E	MPU	Operation Enable signal. Falling edge triggered.
7-10	DB0-DB3	MPU	For low order bi-directional three-state data bus lines. These four are not used during 4-bit operation.
11-14	DB4-DB7	MPU	Four high order bi-directional three-state data bus lines.
15	LED+	Power Supply	Backlight Anode (15mA @ 3V)
16	LED-	Power Supply	Backlight Cathode (Ground)

Recommended LCD connector: 2.54mm pitch pins

Backlight connector: ---   **Mates with:** ---

Wiring Diagram

Electrical Characteristics

Item	Symbol	Condition	Min.	Typ.	Max.	Unit
Operating Temperature Range	T_{OP}	Absolute Max	-20	-	+70	ºC
Storage Temperature Range	T_{ST}	Absolute Max	-30	-	+80	ºC
Supply Voltage	V_{DD}	-	3.1	3.3	3.5	V
Supply Current	I_{DD}	V_{DD} = 3.3V	0.5	1.5	3.0	mA
Supply for LCD (contrast)	V_{LCD}	T_{OP} = 25°C	3.1	3.3	3.5	V
"H" Level input	V_{IH}	-	0.7 * V_{DD}	-	V_{DD}	V
"L" Level input	V_{IL}	-	V_{SS}	-	0.6	V
"H" Level output	V_{OH}	-	0.75 * V_{DD}	-	V_{DD}	V
"L" Level output	V_{OL}	-	V_{SS}	-	0.2 * V_{DD}	V
Backlight Supply Current	I_{LED}	-	-	15	20	mA
Backlight Supply Voltage	V_{LED}	I_{LED} = 15mA	2.8	3.0	3.3	V

*The LED of the backlight is driven by current drain; drive voltage is for reference only. Drive voltage must be selected to ensure backlight current drain is below MAX level stated.

Optical Characteristics

Item		Symbol	Condition	Min.	Typ.	Max.	Unit
Optimal Viewing Angles	Top	φY+	CR ≥ 2	-	40	-	°
	Bottom	φY-		-	60	-	°
	Left	θX-		-	60	-	°
	Right	θX+		-	60	-	°
Contrast Ratio		CR	-	2	5	-	-
Response Time	Rise	T_R	T_{OP} = 25°C	-	150	250	ms
	Fall	T_F		-	200	300	ms

Controller Information

Built-in ST7066U Controller: https://support.newhavendisplay.com/hc/en-us/articles/4414848155159-ST7066U

DDRAM Address

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F	10	11	12	13
40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F	50	51	52	53
14	15	16	17	18	19	1A	1B	1C	1D	1E	1F	20	21	22	23	24	25	26	27
54	55	56	57	58	59	5A	5B	5C	5D	5E	5F	60	61	62	63	64	65	66	67
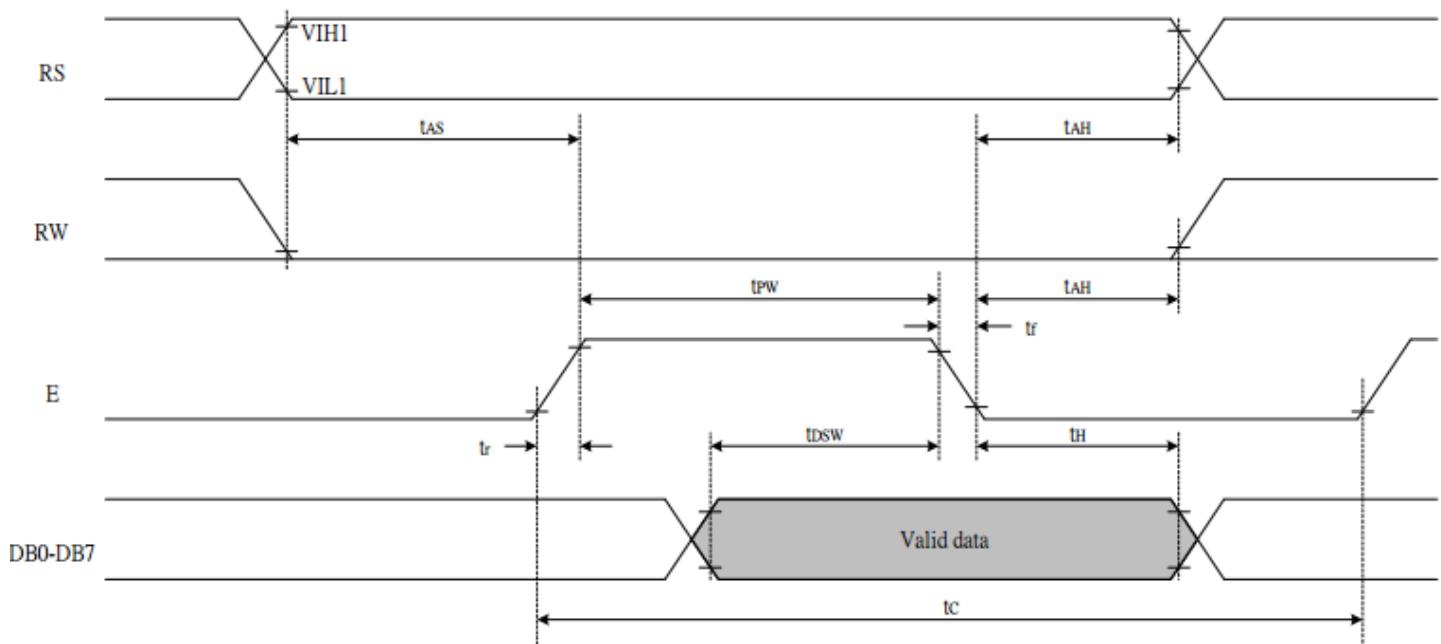
Table of Commands

Instruction	Instruction code										Description	Execution time (fosc= 270 KHZ
	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0		
Clear Display	0	0	0	0	0	0	0	0	0	1	Write "20H" to DDRAM and set DDRAM address to "00H" from AC	1.52ms
Return Home	0	0	0	0	0	0	0	0	1	-	Set DDRAM Address to "00H" from AC and return cursor to its original position if shifted. The contents of DDRAM are not changed.	1.52ms
Entry mode Set	0	0	0	0	0	0	0	1	I/D	SH	Sets cursor move direction and specifies display shift. These parameters are performed during data write and read.	37µs
Display ON/ OFF control	0	0	0	0	0	0	1	D	C	B	D=1: Entire display on C=1: Cursor on B=1: Blinking cursor on	37µs
Cursor or Display shift	0	0	0	0	0	1	S/C	R/L	-	-	Sets cursor moving and display shift control bit, and the direction without changing DDRAM data.	37µs
Function set	0	0	0	0	1	DL	N	F	-	-	DL: Interface data is 8/4 bits N: Number of lines is 2/1 F: Font size is 5x11/5x8	37µs
Set CGRAM Address	0	0	0	1	AC5	AC4	AC3	AC2	AC1	AC0	Set CGRAM address in address counter	37µs
Set DDRAM Address	0	0	1	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Set DDRAM address in address counter.	37µs
Read busy Flag and Address	0	1	BF	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Whether during internal operation or not can be known by reading BF. The contents of address counter can also be read.	0s
Write data To Address	1	0	D7	D6	D5	D4	D3	D2	D1	D0	Write data into internal RAM (DDRAM/CGRAM).	37µs
Read data From RAM	1	1	D7	D6	D5	D4	D3	D2	D1	D0	Read data from internal RAM (DDRAM/CGRAM).	37µs
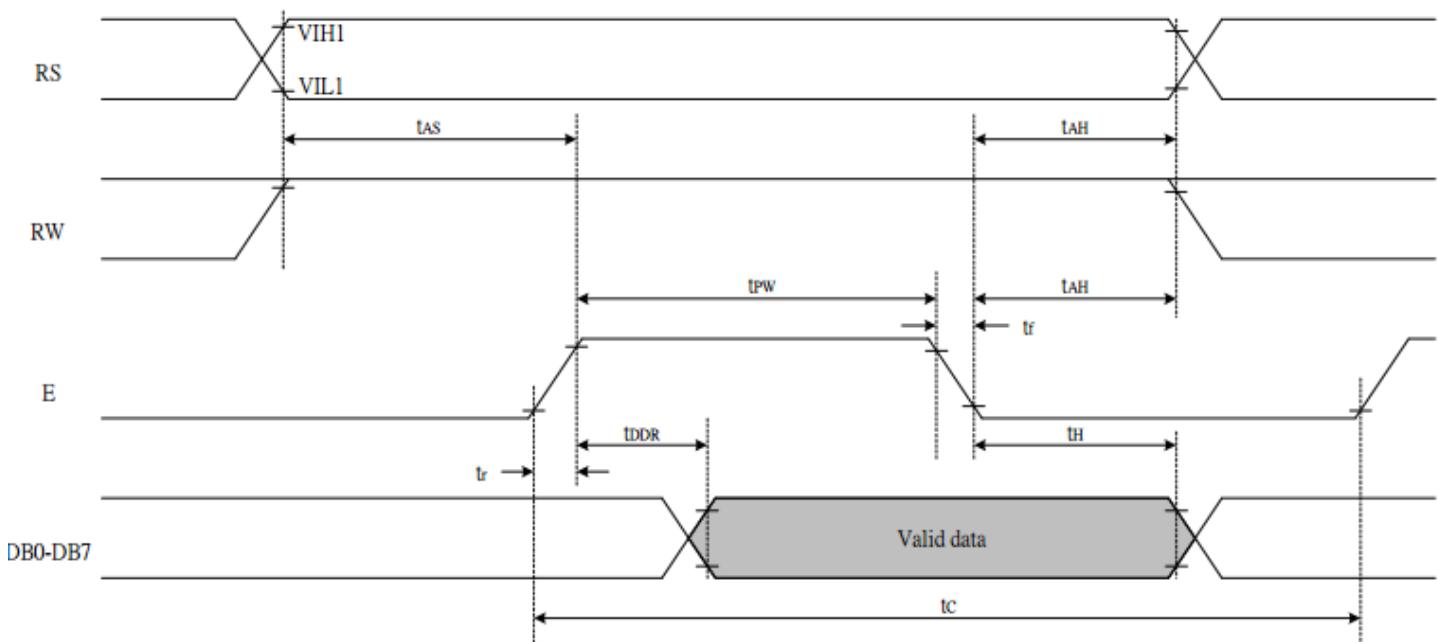
Timing Characteristics

Writing data from MPU to ST7066U

		Write Mode (Writing data from MPU to ST7066U)					
T_C	Enable Cycle Time	Pin E	1200	-	-	ns
T_{PW}	Enable Pulse Width	Pin E	460	-	-	ns
T_R, T_F	Enable Rise/Fall Time	Pin E	-	-	25	ns
T_{AS}	Address Setup Time	Pins: RS,RW,E	0	-	-	ns
T_{AH}	Address Hold Time	Pins: RS,RW,E	10	-	-	ns
T_{DSW}	Data Setup Time	Pins: DB0 - DB7	80	-	-	ns
T_H	Data Hold Time	Pins: DB0 - DB7	10	-	-	ns

Reading data from ST7066U to MPU

Read Mode (Reading Data from ST7066U to MPU)						
T_C	Enable Cycle Time	Pin E	1200	-	-	ns
T_{PW}	Enable Pulse Width	Pin E	480	-	-	ns
T_R, T_F	Enable Rise/Fall Time	Pin E	-	-	25	ns
T_{AS}	Address Setup Time	Pins: RS,RW,E	0	-	-	ns
T_{AH}	Address Hold Time	Pins: RS,RW,E	10	-	-	ns
T_{DDR}	Data Setup Time	Pins: DB0 - DB7	-	-	320	ns
T_H	Data Hold Time	Pins: DB0 - DB7	10	-	-	ns

Built-in Font Table

Example Initialization Program

```
8-bit Initialization:
/*******************************************************/
void command(char i)
{
        P1 = i;                         //put data on output Port
        D_I =0;                         //D/I=LOW : send instruction
        R_W =0;                         //R/W=LOW : Write
        E  = 1;
        Delay(1);                       //enable pulse width  >= 300ns
        E  = 0;                         //Clock enable: falling edge
}
/*******************************************************/
void write(char i)
{
        P1 = i;                         //put data on output Port
        D_I =1;                         //D/I=HIGH : send data
        R_W =0;                         //R/W=LOW : Write
        E  = 1;
        Delay(1);                       //enable pulse width  >= 300ns
        E  = 0;                         //Clock enable: falling edge
}
/*******************************************************/
void init()
{
        E = 0;
        Delay(100);                     //Wait >40 msec after power is applied
        command(0x30);                  //command 0x30 = Wake up
        Delay(30);                      //must wait 5ms, busy flag not available
        command(0x30);                  //command 0x30 = Wake up #2
        Delay(10);                      //must wait 160us, busy flag not available
        command(0x30);                  //command 0x30 = Wake up #3
        Delay(10);                      //must wait 160us, busy flag not available
        command(0x38);                  //Function set: 8-bit/2-line
        command(0x10);                  //Set cursor
        command(0x0c);                  //Display ON; Cursor ON
        command(0x06);                  //Entry mode set
}
/*******************************************************/
```

4-bit Initialization:
/**/
```c
void command(char i)
{
        P1 = i;                         //put data on output Port
        D_I =0;                         //D/I=LOW : send instruction
        R_W =0;                         //R/W=LOW : Write
        Nybble();                       //Send lower 4 bits
        i = i<<4;                       //Shift over by 4 bits
        P1 = i;                         //put data on output Port
        Nybble();                       //Send upper 4 bits
}
/**********************************************************/
void write(char i)
{
        P1 = i;                         //put data on output Port
        D_I =1;                         //D/I=HIGH : send data
        R_W =0;                         //R/W=LOW : Write
        Nybble();                       //Clock lower 4 bits
        i = i<<4;                       //Shift over by 4 bits
        P1 = i;                         //put data on output Port
        Nybble();                       //Clock upper 4 bits
}
/**********************************************************/
void Nybble()
{
        E = 1;
        Delay(1);                       //enable pulse width  >= 300ns
        E = 0;                          //Clock enable: falling edge
}
/**********************************************************/
void init()
{
        P1 = 0;
        P3 = 0;
        Delay(100);                     //Wait >40 msec after power is applied
        P1 = 0x30;                      //put 0x30 on the output port
        Delay(30);                      //must wait 5ms, busy flag not available
        Nybble();                       //command 0x30 = Wake up
        Delay(10);                      //must wait 160us, busy flag not available
        Nybble();                       //command 0x30 = Wake up #2
        Delay(10);                      //must wait 160us, busy flag not available
        Nybble();                       //command 0x30 = Wake up #3
        Delay(10);                      //can check busy flag now instead of delay
        P1= 0x20;                       //put 0x20 on the output port
        Nybble();                       //Function set: 4-bit interface
        command(0x28);                  //Function set: 4-bit/2-line
        command(0x10);                  //Set cursor
        command(0x0F);                  //Display ON; Blinking cursor
        command(0x06);                  //Entry Mode set
}
/**********************************************************/
```

Quality Information

Test Item	Content of Test	Test Condition	Note
High Temperature storage	Endurance test applying the high storage temperature for a long time.	+80°C , 48hrs	2
Low Temperature storage	Endurance test applying the low storage temperature for a long time.	-30°C , 48hrs	1,2
High Temperature Operation	Endurance test applying the electric stress (voltage & current) and the high thermal stress for a long time.	+70°C 48hrs	2
Low Temperature Operation	Endurance test applying the electric stress (voltage & current) and the low thermal stress for a long time.	-20°C , 48hrs	1,2
High Temperature / Humidity Operation	Endurance test applying the electric stress (voltage & current) and the high thermal with high humidity stress for a long time.	+40°C , 90% RH , 48hrs	1,2
Thermal Shock resistance	Endurance test applying the electric stress (voltage & current) during a cycle of low and high thermal stress.	0°C,30min -> 25°C,5min -> 50°C,30min = 1 cycle 10 cycles	
Vibration test	Endurance test applying vibration to simulate transportation and use.	10-55Hz , 15mm amplitude. 60 sec in each of 3 directions X,Y,Z For 15 minutes	3
Static electricity test	Endurance test applying electric static discharge.	VS=800V, RS=1.5kΩ, CS=100pF One time	

Note 1: No condensation to be observed.
Note 2: Conducted after 4 hours of storage at 25°C, 0%RH.
Note 3: Test performed on product itself, not inside a container.