

# BITM 2313 HUMAN COMPUTER INTERACTION

## LAB 8:TRANSFORMING THEORY INTO PRACTICE

BITM 2313 SEMESTER 2 SESI 2020/2021

#### 1.0 OBJECTIVE

To analyze the advantages and disadvantages of Human Robot Social Interaction

### 2.0 INTRODUCTION

Human computer interaction is basically a study of how humans interacts with computer and what needs to be done to make the fundamental interaction of a computer with a human being more successful and use-full.

Now a days this topic has become very popular for research purposes. Human-Robot Social Interaction became one of active research fields in which researchers from different areas propose solutions and directives leading robots to improve their interactions with humans. Human robot interaction and human computer interaction can benefit from each other progress, even robots in human robot interaction are often designed to be mobile and autonomous which differ from computers.

### 3.0 FROM HCI TO HUMAN ROBOT SOCIAL INTERACTION

We consider that the human robot fundamental interaction and human computer fundamental interaction can profit from each other progress, even robots in human robot interaction are often configured to be motorized and self-governing which differ from computers.

#### 4.0 LAB ACTIVITY

In a group of three students, choose <u>one</u> of the Human Robot Social Interaction. **Identify** what are the benefits and current limitations of this robot. Could social robots facilitate children with autism spectrum disorders?

## Related video:

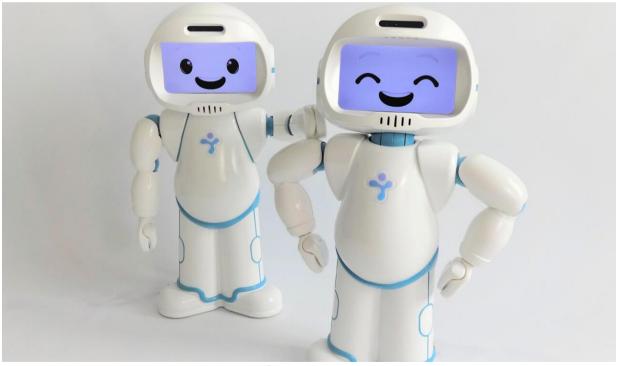
https://www.youtube.com/watch?v=BJZcGJSK1Z0&feature=youtu.be https://www.youtube.com/watch?v=2017kmkEukE&feature=youtu.be https://www.youtube.com/watch?v=pgxWbldQVkE

# Related Information:

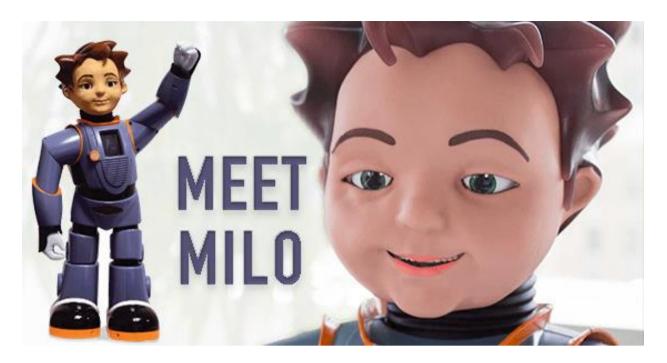
https://spectrum.ieee.org/the-human-os/biomedical/devices/robot-therapy-for-autism https://dot.la/autism-robot-moxie-ai-2645867544.html https://www.edutopia.org/article/can-robot-help-autistic-children-connect



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