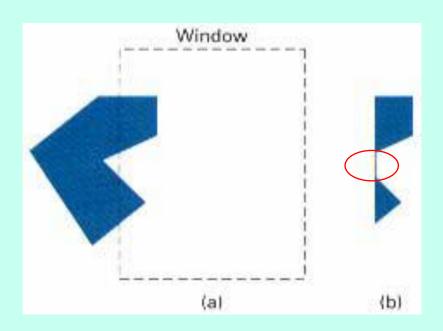
# **Polygon Clipping**

**Weiler-Atherton Polygon Clipping** 

Convex polygons are correctly clipped by the Sutherland
 -Hodgeman algorithm, but concave polygons may be dis
 played with extra areas (area inside the red circle), as de
 monstrated in the following figure.



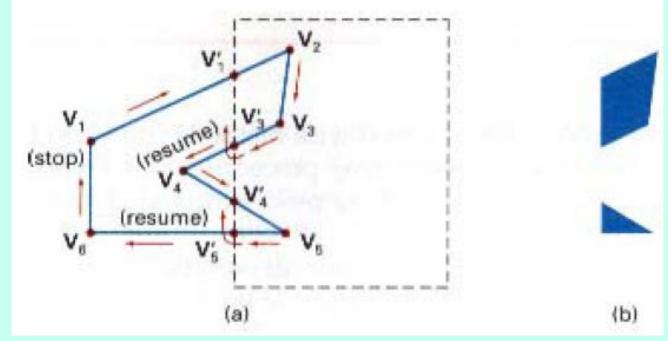
- •This algorithm was developed for identifying visible surfaces, and can be used to clip a fill area that is either a convex polygon or a concave polygon.
- •The basic idea of this algorithm is that instead of proceeding around the polygon edges as vertices are processed, we will follow the window boundaries.
- •The path we follow depends on:
- polygon-processing direction (clockwise or counterclockwise)
- The pair of polygon vertices outside-to-inside or an inside-to-outside.

For clockwise processing of polygon vertices, we use the following rules:

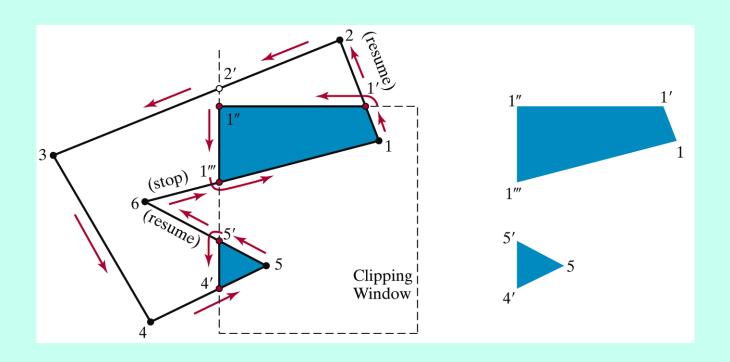
- For an outside-to-inside pair of vertices, follow polygon boundaries.
- For an inside-to-outside pair of vertices, follow window boundaries in a clockwise direction.

→ Example

• In the following figure, the processing direction in the W eiler-Atherton algorithm and the resulting clipped polyg on is shown for a rectangular clipping window.



- For an outside-to-inside pair of vertices, follow the polygon boundary
- → For an inside-to-outside pair of vertices, follow the window boundary in a clockwise direction



- → Process the edges of the polygon in a counterclockwise order until an inside-outside pair of vertices is encounter ed
- → Follow the window boundaries in a counterclockwise dir ection from the exit-intersection point to another intersection point with the polygon
- Repeat until at a previously processed vertex
- → Return to the exit-intersection point and continue proces sing the polygon edges in a counterclockwise order

