## **Lab-1**(Insertion sort, Selection sort)

### **Objective:**

• The objective of this lab is to implement two different type of sorting algorithm.

#### Prog-1

**<u>Title:</u>** A program to implement Insertion Sort.

```
#include<stdio.h>
int main() {
int array[100],n,i,j,key;
printf("Enter the Number of elements: ");
scanf("%d",&n);
printf("\nEnter the Elements:\n");
for(i=1;i<=n;i++)
scanf("%d",&array[i]);
for(j=2;j<=n;j++) {
key=array[j];
i=j-1;
while(i>0&&array[i]>key) {
array[i+1]=array[i];
i=i-1; }
array[i+1]=key; }
printf("Elements sorted in ascending order:\n");
for(i=1;i<=n;i++)
printf(" %d",array[i]);
return 0; }
```

```
Enter the Number of elements: 5

Enter the Elements:
23 1 77 56 92

Elements sorted in ascending order:
1 23 56 77 92
```

#### Prog-2

<u>Title:</u> A program to implement Selection Sort.

```
#include<stdio.h>
int main() {
int A[100], n,i,j,index_min,temp;
printf("Enter number of elements:\n");
scanf("%d", &n);
printf("Enter %d integers:\n", n);
for (i = 0; i < n; i++)
scanf("%d", &A[i]);
for(i=0;i< n-1;i++) {
index_min=i;
for(j=i+1;j< n;j++) {
if(A[j]<A[index_min]) {</pre>
index_min=j; } }
if(index_min!=i) {
temp=A[i];
A[i]=A[index_min];
A[index_min]=temp;} }
printf("Sorted list in ascending order:\n");
```

```
for (i = 0; i < n; i++)

printf("%d\n", A[i]);

return 0; }
```

```
Enter number of elements:

5
Enter 5 integers:

34 2 78 1 93
Sorted list in ascending order:

1
2
34
78
93
```

#### <u>Lab-2(Merge sort)</u>

# **Objective:**

• The objective of this lab is to implement a sorting algorithm.

#### Prog-1

**<u>Title:</u>** A program to implement Merge Sort.

```
#include<stdio.h>
void merge(int AR[],int p,int q,int r){
int n1=q-p+1;
int i,j,k;
int n2=r-q;
int L[n1];
int R[n2];
```

```
for(i=0;i< n1;i++) {
L[i]=AR[p+i];
for(j=0;j< n2;j++){
R[j]=AR[q+j+1];
L[n1]=-9999;
R[n2]=-9999;
i=0;
j=0;
k=p;
while(i<n1 && j<n2) {
if(L[i] \le R[j]) {
AR[k] = L[i];
i++; }
else {
AR[k] = R[j];
j++; }
k++; }
while(i<n1) {
AR[k] = L[i];
i++;
k++; }
while(j < n2) {
AR[k] = R[j];
j++;
k++; } }
void merge_sort(int A[], int p, int r){
int q;
if(p < r){
```

```
q=(p+r)/2;
merge_sort(A,p,q);
merge_sort(A,q+1,r);
merge(A,p,q,r); } }
void printArray(int A[],int n)
{ int i;
printf("Elements sorted in ascending order: \n");
for(i=0;i<n;i++) {
printf("%d\n",A[i]); } }
int main() {
int n,i,A[100];
printf("Enter the Number of elements: ");
scanf("%d",&n);
printf("Enter the elements: \n");
for(i=0;i< n;i++){
scanf("%d",&A[i]); }
merge_sort(A,0,n-1);
printArray(A,n);
return 0; }
Sample Output:
Enter the Number of elements: 5
Enter the elements:
23 14 6 93 4
Elements sorted in ascending order:
6
14
23
```

93

### <u>Lab-3(Quick sort, Heap sort)</u>

#### **Objective:**

• The objective of this lab is to implement two different type of sorting algorithm.

#### Prog-1

**<u>Title:</u>** A program to implement Quick Sort.

```
#include<stdio.h>
void swap(int* a, int* b) {
int t = *a;
*a = *b;
*b = t;  }
int partition (int A[], int low, int high) {
int pivot = A[high];
int i = (low - 1);
for (int j = low; j \le high-1; j++) {
if (A[j] < pivot) {
i++;
swap(&A[i], &A[j]); } }
swap(&A[i + 1], &A[high]);
return (i + 1);
void quickSort(int A[], int low, int high) {
if (low < high) {
int pi = partition(A, low, high);
quickSort(A, low, pi - 1);
quickSort(A, pi + 1, high); } }
void printArray(int A[], int size) {
int i;
```

```
for (i=0; i < size; i++)
printf("%d ", A[i]);
printf("\n"); }
int main() {
int A[] = {10, 7, 8, 9, 1, 5};
int n = sizeof(A)/sizeof(A[0]);
quickSort(A, 0, n-1);
printf("Sorted Aay: \n");
printArray(A, n);
return 0; }</pre>
```

```
Sorted Aay:
1 5 7 8 9 10
```

#### Prog-2

<u>Title:</u> A program to implement Heap Sort.

```
#include<istream>
using namespace std;
void max_heapify(int A[], int n, int i) {
int temp=0;
int largest = i;
int l = 2*i + 1;
int r = 2*i + 2;
if (l < n && A[l] > A[largest])
largest = l;
```

```
if (r < n \&\& A[r] > A[largest])
largest = r;
if (largest != i) {
temp=A[i];
A[i]=A[largest];
A[largest]=temp;
max_heapify(A, n, largest); } }
void heapSort(int A[], int n) {
for (int i = n / 2 - 1; i >= 0; i--)
max_heapify(A, n, i);
for (int i=n-1; i>=0; i--)
\{ swap(A[0], A[i]); \}
max_heapify(A, i, 0); } }
void printArray(int A[], int n) {
for (int i=0; i<n; ++i)
printf("\%d\n",A[i]); 
int main() {
int A[100],n,i;
printf("Enter the number of Elements: \n");
scanf("%d",&n);
printf("Enter the Numbers to be sorted: \n");
for(i=0;i< n;i++)
scanf("%d",&A[i]);
heapSort(A, n);
printf("Sorted array in ascending order:\n");
printArray(A, n); }
```

```
Enter the number of Elements:

Enter the Numbers to be sorted:

34 28 9 33 1

Sorted array in ascending order:

1

9

28

33

34
```

#### Lab-4 (BFS,DFS)

#### **Objective:**

• The objective of this lab is to implement two different type of searching algorithm.

#### Prog-1

<u>Title:</u> A program to implement Breadth First Search (BFS) algorithm.

```
#include<stdio.h>
int a[20][20], q[20], visited[20], n, i, j, f = 0, r = -1;
void bfs(int v) {
  for(i = 1; i <= n; i++)
  if(a[v][i] && !visited[i])
  q[++r] = i;
  if(f <= r) {
    visited[q[f]] = 1;
    bfs(q[f++]); }}
int main() {
  int v;</pre>
```

```
printf("Enter the number of vertices:");
scanf("%d", &n);
for(i=1; i \le n; i++) {
q[i] = 0;
visited[i] = 0; }
printf("Enter graph data in matrix form:\n");
for(i=1; i<=n; i++) {
for(j=1;j<=n;j++) {
scanf("%d", &a[i][j]); } }
printf("Enter the starting vertex:");
scanf("%d", &v);
bfs(v);
printf("The node which are reachable are:\n");
for(i=1; i \le n; i++) 
if(visited[i])
printf("%d\t", i);
else {
printf("Bfs is not possible. Not all nodes are reachable");
break; } } }
Sample Output:
Enter the number of vertices:3
Enter graph data in matrix form:
2 5 3
5 3 1
7 3 5
Enter the starting vertex:2
The node which are reachable are:
1
            2
                         3
```

<u>Title:</u> A program to implement Depth First Search(DFS) algorithm.

```
#include<stdio.h>
#include<conio.h>
int a[20][20],reach[20],n;
void dfs(int v) {
int i;
reach[v]=1;
for (i=1;i<=n;i++)
if(a[v][i] && !reach[i]) {
printf("\n \%d->\%d",v,i);
dfs(i); } }
int main() {
int i,j,count=0;
printf("Enter number of vertices:");
scanf("%d",&n);
for (i=1;i<=n;i++) {
reach[i]=0;
for (j=1;j<=n;j++)
a[i][j]=0;
printf("Enter the adjacency matrix:\n");
for (i=1;i<=n;i++)
for (j=1;j<=n;j++)
scanf("%d",&a[i][j]);
dfs(1);
printf("\n");
for (i=1;i<=n;i++) {
```

```
if(reach[i])
count++; }
if(count==n)
printf("Graph is connected"); else
printf("Graph is not connected");
return 0; }
```

```
Enter number of vertices:4
Enter the adjacency matrix:
2 5 2 5
6 1 2 0
4 2 5 3
5 1 9 2

1->2
2->3
3->4
Graph is connected
```

# **Home work (three sorting algorithm)**

#### Prog-1

<u>Title:</u> A program to implement Radix Sort algorithm.

```
#include<stdio.h>
int A[100];
int POCKET[10][9];
int N;
```

```
void RADIX(void);
int main() {
int i,j;
for(i=0;i<10;i++)
for(j=0;j<9;j++)
POCKET[i][j]=-9999;
printf("Enter the Number of elements to be sorted: ");
scanf("%d",&N);
printf("\nEnter the Elements: \n");
for(i=0;i< N;i++){
scanf("%d",&A[i]); }
RADIX();
printf("Here are your elements sorted in ascending order: \n");
for(i=N-1;i>=0;i--) {
printf("%d\n",A[i]); } }
void RADIX(void){
int a,b,c,temp,l,x=1;
int k=3;
for(k=1;k<=3;k++){
for(l=0;l< N;l++){}
temp=(A[1]/x)\% 10;
POCKET[temp][l]=A[l]; }
x=x*10;
c=0;
for(a=9;a>=0;a--){
for(b=0;b<9;b++){
if(POCKET[a][b]!=-9999){
```

```
A[c]=POCKET[a][b];

c=c+1; } } 
for(a=0;a<10;a++)

for(b=0;b<9;b++)

POCKET[a][b]=-9999; } }

Sample Output:

Enter the Number of elements to be sorted: 5

Enter the Elements:
33 2 53 89 1

Here are your elements sorted in ascending order:
1
2
33
53
89
```

<u>Title:</u> A program to implement Counting Sort algorithm.

```
#include <stdio.h>
void countingSort(int array[], int size) {
int output[10];
int max = array[0];
for (int i = 1; i < size; i++) {
  if (array[i] > max)
  max = array[i]; }
  int count[10];
  for (int i = 0; i <= max; ++i) {</pre>
```

```
count[i] = 0;}
for (int i = 0; i < size; i++) {
count[array[i]]++; }
for (int i = 1; i \le max; i++) {
count[i] += count[i - 1]; }
for (int i = size - 1; i >= 0; i--) {
output[count[array[i]] - 1] = array[i];
count[array[i]]--; }
for (int i = 0; i < size; i++) {
array[i] = output[i]; } }
void printArray(int array[], int size) {
for (int i = 0; i < size; ++i) {
printf("%d ", array[i]); }
printf("\n"); }
int main() {
int array[] = \{4, 2, 2, 8, 3, 3, 1\};
int n = sizeof(array) / sizeof(array[0]);
countingSort(array, n);
printArray(array, n); }
```

1 2 2 3 3 4 8

<u>Title:</u> A program to implement Bucket Sort algorithm.

#### **Source Code:**

```
#include <iostream>
#include <algorithm>
#include <vector>
using namespace std;
void bucketSort(float arr[], int n) {
vector<float> b[n];
for (int i=0; i< n; i++) {
int bi = n*arr[i]; // Index in bucket
b[bi].push_back(arr[i]); }
for (int i=0; i<n; i++)
sort(b[i].begin(), b[i].end()); int index = 0;
for (int i = 0; i < n; i++)
for (int j = 0; j < b[i].size(); j++)
arr[index++] = b[i][j];
int main() { float arr[] = \{0.897, 0.565, 0.656, 0.1234, 0.665, 0.3434\};
int n = sizeof(arr)/sizeof(arr[0]);
bucketSort(arr, n);
cout << "Sorted array is \n";
for (int i=0; i< n; i++)
cout << arr[i] << " ";
return 0; }
```

#### **Sample Output:**

#### Lab-5 (Activity Selection problem, 0-1 knapsack)

#### **Objective:**

• The objective of this lab is to implement two different type of problem of greedy algorithm.

#### Prog-1

<u>Title:</u> A program to implement activity selection problem.

# **Source Code:**

```
#include <stdio.h>
void ActivitySelection(int start[], int finish[], int n){
 printf("The following activities are selected:\n");
 int j = 0;
 printf("%d ", j);
 int i;
 for (i = 1; i < n; i++  {
 if (start[i] >= finish[j] {
printf("%d", i);
j = i; \} \}
int main() {
int start[] = \{1, 3, 2, 0, 5, 8, 11\};
int finish[] = \{3, 4, 5, 7, 9, 10, 12\};
int n = sizeof(start) / sizeof(start[0]);
ActivitySelection(start, finish, n);
return 0; }
```

#### **Sample Output:**

Following activities are selected:1 3 7 10

**<u>Title:</u>** A program to implement 0-1 knapsack problem.

## **Source Code:**

```
#include<stdio.h>
int max(int a, int b) {
if(a>b) {return a;}
else {return b;}}
int knapsack (int W, int wt[], int val[], int n) {
int i, w; int knap[n+1] [W+1];
for (i = 0; i \le n; i++) {
for (w = 0; w \le W; w++) {
if (i==0 || w==0)
knap[i][w] = 0;
else if (wt[i-1] \le w)
knap[i][w] = max(val[i-1] + knap[i-1][w-wt[i-1]], knap[i-1][w]);
else knap[i][w] = knap[i-1][w]; }
return knap[n][W]; }
int main() {
int val[] = \{20, 25, 40\};
int wt[] = \{25, 20, 30\};
int W = 50;
int n = \text{sizeof(val)/sizeof(val[0])};
printf("The solution is : %d", knapsack(W, wt, val, n));
return 0; }
```

#### **Sample Output:**

The solution is: 65

## Lab-6 (Prim's algorithm, Kruskals algorithm)

#### **Objective:**

• The objective of this lab is to implement two different type of algorithms to find the shortest path from a graph using MST(Minimum Spanning Tree)

#### Prog-1

**<u>Title:</u>** A program to implement Prim's algorithm.

```
#include<stdio.h>
#include<conio.h>
#include<stdlib.h>
int i,j,k,a,b,u,v,n,ne=1;
int min,mincost=0,cost[9][9],parent[9];
int find(int);
int uni(int,int);
void main() {
printf("\n\tImplementation of Kruskal's algorithm\n");
printf("\nEnter the no. of vertices:");
scanf("%d",&n);
printf("\nEnter the cost adjacency matrix:\n");
for(i=1;i \le n;i++) {
for(j=1;j<=n;j++) {
scanf("%d",&cost[i][j]);
if(cost[i][j]==0)
cost[i][j]=999; } }
printf("The edges of Minimum Cost Spanning Tree are\n");
while (ne < n) {
for(i=1,min=999;i<=n;i++) {
```

```
for(j=1;j \le n;j++) {
if(cost[i][j] < min) {
min=cost[i][j];
a=u=i;
b=v=j; } } }
u=find(u); v=find(v);
if(uni(u,v)) {
printf("%d edge (%d,%d) =%d\n",ne++,a,b,min);
mincost +=min; }
cost[a][b]=cost[b][a]=999; }
printf("\n\tMinimum cost = %d\n",mincost);
getch(); } int find(int i) {
while(parent[i])
i=parent[i];
return i; }
int uni(int i,int j) { if(i!=j) {
parent[j]=i;
return 1; } return 0; }
```

```
Implementation of Kruskal's algorithm

Enter the no. of vertices:3

Enter the cost adjacency matrix:
0 8 9
3 0 3
0 3 0

The edges of Minimum Cost Spanning Tree are
1 edge (2,1) =3
2 edge (2,3) =3
```

<u>Title:</u> A program to implement Prim's algorithm.

```
#include<stdio.h>
#include<conio.h>
int a,b,u,v,n,i,j,ne=1;
int visited[10]= {0},min,mincost=0,cost[10][10];
void main() {
printf("\nEnter the number of nodes:")
scanf("%d",&n);
printf("\nEnter the adjacency matrix:\n");
for(i=1; i<=n; i++)
for(j=1; j<=n; j++) {
scanf("%d",&cost[i][j]);
if(cost[i][j]==0)
cost[i][j]=999; }
visited[1]=1;
printf("\n");
while (ne < n) {
for (i=1,min=999; i<=n; i++)
for (j=1; j<=n; j++)
if(cost[i][j]< min)
if(visited[i]!=0)
{ min=cost[i][j];
a=u=i; b=v=j;
if(visited[u]==0 \parallel visited[v]==0) {
printf("\n Edge %d:(%d %d) cost:%d",ne++,a,b,min);
mincost+=min;
```

```
visited[b]=1; }
cost[a][b]=cost[b][a]=999; }
printf("\n Minimun cost=%d",mincost);
getch(); }
```

```
Enter the adjacency matrix:
        00080
   0
     0
 0
   8 0
        000
              11
0
 8
   07
        04002
0
 0
   70
        9 14 0 0 0
0
   09
        0 10 0 0 0
 0 4 14 10 0
0
              2 0
0
 9 9 9 9
          20
8 11 0 0 0 0 1 0 7
0 0 2 0 0 0 6 7 0
 Edge 1:(1 2)
              cost:4
 Edge 2:(1
           8)
              cost:8
 Edge 3:(8 7)
              cost:1
 Edge 4:(7
          6)
              cost:2
 Edge 5:(6 3)
              cost:4
 Edge 6:(3 9)
              cost:2
 Edge 7:(3 4)
              cost:7
 Edge 8:(4 5)
              cost:9
Minimun cost=37
```

#### Lab-7 (Dijkstra's algorithm, Bellman Ford algorithm)

#### **Objective:**

• The objective of this lab is to implement two different type of algorithms to find the single shortest path from a graph.

<u>Title:</u> A program to implement Dijkstra's algorithm.

```
#include <stdio.h>
#include inits.h>
#define V 5
int minDistance(int dist[],bool sptSet[]) {
int min = INT_MAX, min_index;
for (int v = 0; v < V; v++)
if (sptSet[v] == false \&\&
dist[v] \ll min
min = dist[v], min\_index = v;
return min_index; }
void printPath(int parent[], int j) {
if (parent[j] == -1) return;
printPath(parent, parent[j]);
printf("%d", j); }
int printSolution(int dist[], int n,
int parent[]) { int src = 0;
printf("Vertex\t
                     Distance\t
                                    Path");
for (int i = 1; i < V; i++) {
printf("\n\%d -> \%d \t\ \%d\t\ \%d\ ",
src, i, dist[i], src);
printPath(parent, i); } }
void dijkstra(int graph[V][V], int src) {
int dist[V]; int parent[V];
for (int i = 0; i < V; i++) { parent[0] = -1;
dist[i] = INT\_MAX;
```

```
sptSet[i] = false; }
dist[src] = 0;
for (int count = 0; count < V - 1; count++) {
int u = minDistance(dist, sptSet);
sptSet[u] = true;
for (int v = 0; v < V; v++)
if (!sptSet[v] && graph[u][v] &&
dist[u] + graph[u][v] < dist[v]) \{parent[v] = u;
dist[v] = dist[u] + graph[u][v]; \}
printSolution(dist, V, parent); }
int main() {
int graph[V][V] = { \{0, 10, 3, 9, 5\},
\{0, 0, 1, 2, 3\},\
\{0, 4, 0, 6, 2\},\
\{0, 0, 0, 0, 7\},\
\{0, 0, 0, 9, 0\}, \};
dijkstra(graph, 0);
return 0; }
```

Vertex	Distance	Path
0 -> 1	7	0 2 1
0 -> 2	3	0 2
0 -> 3	9	0 3
0 -> 4	5	0 4

<u>Title:</u> A program to implement Bellman Ford algorithm.

```
#include <stdio.h>
#include <stdlib.h>
int Bellman_Ford(int G[20][20], int V, int E, int edge[20][2])
{ int i,u,v,k,distance[20],parent[20],S,flag=1;
for(i=0;i<V;i++)
distance[i] = 1000, parent[i] = -1;
printf("Enter source: ");
scanf("%d",&S);
distance[S-1]=0;
for(i=0;i< V-1;i++) {
for(k=0;k<E;k++) {
u = edge[k][0], v = edge[k][1];
if(distance[u]+G[u][v] < distance[v])
distance[v] = distance[u] + G[u][v], parent[v]=u; \}
for(k=0;k<E;k++) {
u = edge[k][0], v = edge[k][1];
if(distance[u]+G[u][v] < distance[v])
flag = 0; }
if(flag)
for(i=0;i< V;i++)
printf("Vertex %d -> cost = %d parent = %d\n",i+1,distance[i],parent[i]+1);
return flag; }
int main() {
int V,edge[20][2],G[20][20],i,j,k=0;
printf("BELLMAN FORD\n");
```

```
printf("Enter no. of vertices: ");
scanf("%d",&V);
printf("Enter graph in matrix form:\n");
for(i=0;i<V;i++)
for(j=0;j<V;j++) {
    scanf("%d",&G[i][j]);
    if(G[i][j]!=0)
    edge[k][0]=i,edge[k++][1]=j; }
    if(Bellman_Ford(G,V,k,edge))
    printf("\nNo negative weight cycle\n");
    else printf("\nNegative weight cycle exists\n");
    return 0; }</pre>
```

```
BELLMAN FORD
Enter no. of vertices: 5
Enter graph in matrix form:
0 10 11 5 14
0 0 1 2 5
11 21 0 16 4
9 3 9 0 2
7 17 -6 -3 0
Enter source: 1
Negative weight cycle exists
```

#### **Lab-8 (Floyd Warshall algorithm)**

#### **Objective:**

• The objective of this lab is to implement two different type of algorithms to find the shortest path from a graph using MST (Minimum Spanning Tree)

#### Prog-1

**<u>Title:</u>** A program to implement Floyd Warshall algorithm.

```
#include<iostream>
#include<iomanip>
#define NODE 4
#define INF 999
using namespace std;
int costMat[NODE][NODE] = {
{0, 8, INF, 1},
{INF, 0, 1, INF},
{4, INF, 0, INF},
{INF, 2, 9, 0}, };
void floydWarshal() {
int cost[NODE][NODE];
for(int i = 0; i < NODE; i++)
for(int j = 0; j < NODE; j++)
cost[i][j] = costMat[i][j];
for(int k = 0; k < NODE; k++) {
for(int i = 0; i < NODE; i++)
for(int j = 0; j < NODE; j++)
if(cost[i][k]+cost[k][j] < cost[i][j])
cost[i][j] = cost[i][k] + cost[k][j];
```

```
\label{eq:cout} \begin{split} & \text{cout} << \text{"The matrix:"} << \text{endl;} \\ & \text{for(int } i=0; \text{i} < \text{NODE; } i++) \; \{ \\ & \text{for(int } j=0; \text{j} < \text{NODE; } j++) \\ & \text{cout} << \text{setw(3)} << \text{cost[i][j];} \\ & \text{cout} << \text{endl; } \} \; \} \\ & \text{int main()} \; \{ \\ & \text{floydWarshal(); } \} \end{split}
```

```
The matrix:

0 3 4 1
5 0 1 6
4 7 0 5
7 2 3 0
```

# **Lab-9** (Rod cutting problem)

# **Objective:**

• The objective of this lab is to implement a dynamic problem.

### Prog-1

<u>Title:</u> A program to implement Rod Cutting problem.

```
#include<iostream>
#include<climits>
using namespace std;
int rodCutting(int n, int value[])
{ int i,j;
int result[n+1];
```

```
result[0]=0;
for(i=1; i<=n; i++) {
result[i]=INT_MIN;
for(j=0; j< i; j++) {
result[i]=max(result[i],value[j]+result[i-(j+1)]); } }
return result[n]; }
int main() { int n;
cout<<"Enter the length of the rod:"<<endl;</pre>
cin>>n;
int value[n];
cout<<"Enter the values of pieces of rod of all size:"<<endl;
for(int i=0; i<n; i++)
cin>>value[i];
cout<<"Maximum obtainable value by cutting up the rod in many pieces are:"<<endl;
cout<<rodCutting(n,value);</pre>
cout<<endl;
return 0; }
```

```
Enter the length of the rod:
1 5 8 9 10 17 17 20 24 30
Enter the values of pieces of rod of all size:
Maximum obtainable value by cutting up the rod in many pieces are:
5
```

# **Index:**

# **List of Implemented Algorithms**

# **Sorting:**

1. Insertion sort	1-2
2. Selection sort	2-3
3. Merge sort	3-5
4. Quick sort	6-8
5. Heap sort	8-10
6. Counting sort	10-11
7. Bucket sort	12-13
8. Radix sort	14
Searching:	
9. Breadth first search(BFS)	15
10. Depth first search(DFS)	
Greedy Algorithms:	
11. Activity selection problem	17
12. 0-1 knapsack algorithm	18
13. Prim's algorithm	19-20
14. Kruskal's algorithm	21-22
15. Dijkstra's algorithm	23-24
16. Bell man-ford algorithm	25-26
17. Floyd Warshall algorithm	27-28
Dynamic Programming:	
18.Rod cutting problem	28-29