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**BANGLADESH UNIVERSITY OF
BUSINESS AND TECHNOLOGY**

Lab Performance-2

Course Code: CSE 478

Course Title: Neural Network and Fuzzy Systems & Lab

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Problem: Sine wave sequence prediction using RNN.

Solution: RNNs have become extremely popular in the deep learning space which makes learning them even more imperative. We can do sequence prediction problem using RNN. One of the simplest tasks for this is sine wave prediction. The sequence contains a visible trend and is easy to solve using heuristics. This is what a sine wave looks like:

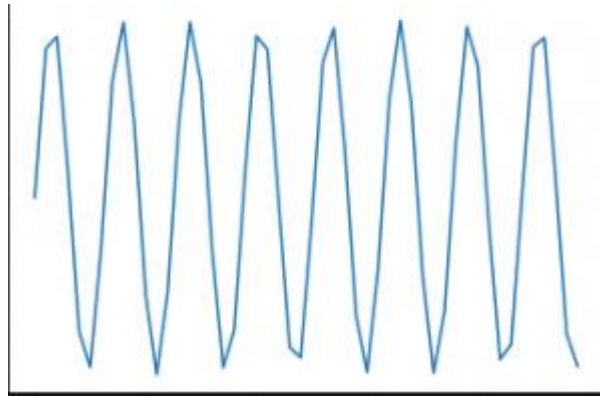


Figure: Sine Wave

Code:

```
%pylab inline

import math

sin_wave = np.array([math.sin(x) for x in np.arange(200)])

plt.plot(sin_wave[:50])

X = []

Y = []

seq_len = 50

num_records = len(sin_wave) - seq_len
```

```
for i in range(num_records - 50):

    X.append(sin_wave[i:i+seq_len])

    Y.append(sin_wave[i+seq_len])

X = np.array(X)

X = np.expand_dims(X, axis=2)

Y = np.array(Y)

Y = np.expand_dims(Y, axis=1)

X.shape, Y.shape

X_val = []

Y_val = []

for i in range(num_records - 50, num_records):

    X_val.append(sin_wave[i:i+seq_len])

    Y_val.append(sin_wave[i+seq_len])

X_val = np.array(X_val)

X_val = np.expand_dims(X_val, axis=2)

Y_val = np.array(Y_val)

Y_val = np.expand_dims(Y_val, axis=1)

learning_rate = 0.0001

nepoch = 25
```

```

T = 50 # length of sequence

hidden_dim = 100

output_dim = 1

bptt_truncate = 5

min_clip_value = -10

max_clip_value = 10

U = np.random.uniform(0, 1, (hidden_dim, T))

W = np.random.uniform(0, 1, (hidden_dim, hidden_dim))

V = np.random.uniform(0, 1, (output_dim, hidden_dim))

def sigmoid(x):

    return 1 / (1 + np.exp(-x))

for epoch in range(nepoch):

    # check loss on train

    loss = 0.0

    # do a forward pass to get prediction

    for i in range(Y.shape[0]):

        x, y = X[i], Y[i] # get input, output values of each record

        prev_s = np.zeros((hidden_dim, 1)) # here, prev-s is the value of the previous activation of
        hidden layer; which is initialized as all zeroes

```

```

for t in range(T):

    new_input = np.zeros(x.shape) # we then do a forward pass for every timestep in the sequence

    new_input[t] = x[t]           # for this, we define a single input for that timestep

    mulu = np.dot(U, new_input)

    mulw = np.dot(W, prev_s)

    add = mulw + mulu

    s = sigmoid(add)

    mulv = np.dot(V, s)

    prev_s = s

    # calculate error

    loss_per_record = (y - mulv)**2 / 2

    loss += loss_per_record

    loss = loss / float(y.shape[0])

    # check loss on val

    val_loss = 0.0

    for i in range(Y_val.shape[0]):

        x, y = X_val[i], Y_val[i]

        prev_s = np.zeros((hidden_dim, 1))

        for t in range(T):

```

```

new_input = np.zeros(x.shape)

new_input[t] = x[t]

mulu = np.dot(U, new_input)

mulw = np.dot(W, prev_s)

add = mulw + mulu

s = sigmoid(add)

mulv = np.dot(V, s)

prev_s = s

loss_per_record = (y - mulv)**2 / 2

val_loss += loss_per_record

val_loss = val_loss / float(y.shape[0])

print('Epoch: ', epoch + 1, ', Loss: ', loss, ', Val Loss: ', val_loss)

# train model

for i in range(Y.shape[0]):

    x, y = X[i], Y[i]

    layers = []

    prev_s = np.zeros((hidden_dim, 1))

    dU = np.zeros(U.shape)

    dV = np.zeros(V.shape)

```

```
dW = np.zeros(W.shape)

dU_t = np.zeros(U.shape)

dV_t = np.zeros(V.shape)

dW_t = np.zeros(W.shape)

dU_i = np.zeros(U.shape)

dW_i = np.zeros(W.shape)

# forward pass

for t in range(T):

    new_input = np.zeros(x.shape)

    new_input[t] = x[t]

    mulu = np.dot(U, new_input)

    mulw = np.dot(W, prev_s)

    add = mulw + mulu

    s = sigmoid(add)

    mulv = np.dot(V, s)

    layers.append({'s':s, 'prev_s':prev_s})

    prev_s = s

# derivative of pred

dmulv = (mulv - y)
```

```

# backward pass

for t in range(T):

    dV_t = np.dot(dmuly, np.transpose(layers[t]['s']))

    dsv = np.dot(np.transpose(V), dmuly)

    ds = dsv

    dadd = add * (1 - add) * ds

    dmuly = dadd * np.ones_like(muly)

    dprev_s = np.dot(np.transpose(W), dmuly)

    for i in range(t-1, max(-1, t-bptt_truncate-1), -1):

        ds = dsv + dprev_s

        dadd = add * (1 - add) * ds

        dmuly = dadd * np.ones_like(muly)

        dmulu = dadd * np.ones_like(mulu)

        dW_i = np.dot(W, layers[t]['prev_s'])

        dprev_s = np.dot(np.transpose(W), dmuly)

    new_input = np.zeros(x.shape)

    new_input[t] = x[t]

    dU_i = np.dot(U, new_input)

    dx = np.dot(np.transpose(U), dmulu)

```



```
dU_t += dU_i
```

```
dW_t += dW_i
```

```
dV += dV_t
```

```
dU += dU_t
```

```
dW += dW_t
```

```
if dU.max() > max_clip_value:
```

```
dU[dU > max_clip_value] = max_clip_value
```

```
if dV.max() > max_clip_value:
```

```
dV[dV > max_clip_value] = max_clip_value
```

```
if dW.max() > max_clip_value:
```

```
dW[dW > max_clip_value] = max_clip_value
```

```
if dU.min() < min_clip_value:
```

```
dU[dU < min_clip_value] = min_clip_value
```

```
if dV.min() < min_clip_value:
```

```
dV[dV < min_clip_value] = min_clip_value
```

```
if dW.min() < min_clip_value:
```

```
dW[dW < min_clip_value] = min_clip_value
```

```
# update
```

```
U -= learning_rate * dU
```

```
V -= learning_rate * dV
```

```
W -= learning_rate * dW
```

```
preds = []
```

```
for i in range(Y.shape[0]):
```

```
    x, y = X[i], Y[i]
```

```
    prev_s = np.zeros((hidden_dim, 1))
```

```
    # Forward pass
```

```
    for t in range(T):
```

```
        mulu = np.dot(U, x)
```

```
        mulw = np.dot(W, prev_s)
```

```
        add = mulw + mulu
```

```
        s = sigmoid(add)
```

```
        mulv = np.dot(V, s)
```

```
        prev_s = s
```

```
    preds.append(mulv)
```

```
preds = np.array(preds)
```

```
plt.plot(preds[:, 0, 0], 'g')
```

```
plt.plot(Y[:, 0], 'r')
```

```
plt.show()
```

```
preds = []

for i in range(Y_val.shape[0]):

    x, y = X_val[i], Y_val[i]

    prev_s = np.zeros((hidden_dim, 1))

    # For each time step...

    for t in range(T):

        mulu = np.dot(U, x)

        mulw = np.dot(W, prev_s)

        add = mulw + mulu

        s = sigmoid(add)

        mulv = np.dot(V, s)

        prev_s = s

    preds.append(mulv)

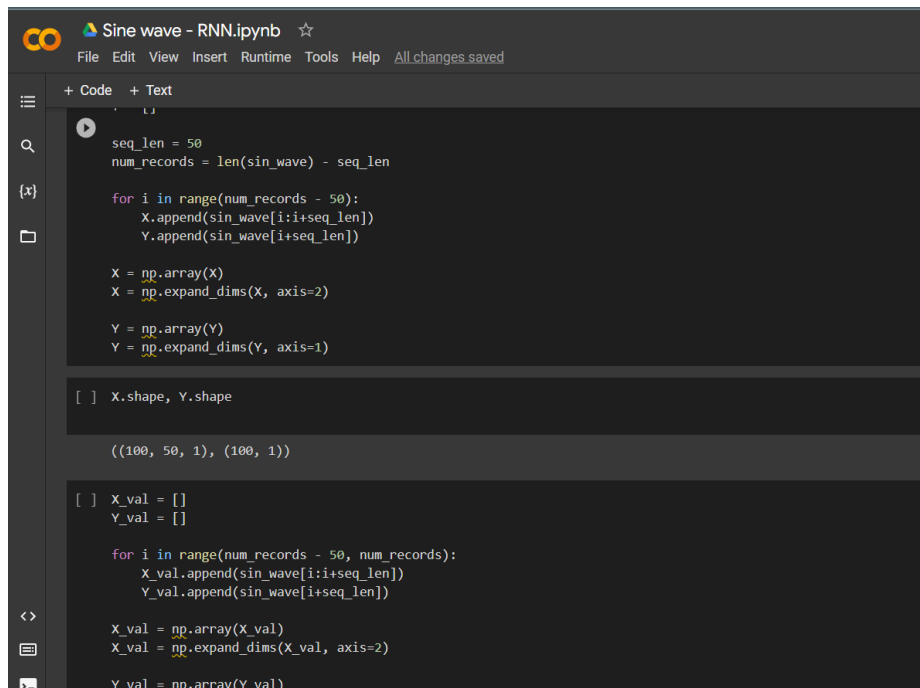
preds = np.array(preds)

plt.plot(preds[:, 0, 0], 'g')

plt.plot(Y_val[:, 0], 'r')

plt.show()
```

Input Snapshot:



```
seq_len = 50
num_records = len(sin_wave) - seq_len

for i in range(num_records - 50):
    X.append(sin_wave[i:i+seq_len])
    Y.append(sin_wave[i+seq_len])

X = np.array(X)
X = np.expand_dims(X, axis=2)

Y = np.array(Y)
Y = np.expand_dims(Y, axis=1)

[ ] X.shape, Y.shape

((100, 50, 1), (100, 1))

[ ] X_val = []
    Y_val = []

for i in range(num_records - 50, num_records):
    X_val.append(sin_wave[i:i+seq_len])
    Y_val.append(sin_wave[i+seq_len])

X_val = np.array(X_val)
X_val = np.expand_dims(X_val, axis=2)

Y_val = np.array(Y_val)
```

Figure1: Implementation of Sine wave sequence prediction using RNN in Colab.

Output Snapshot:

Some of the snaps of output.

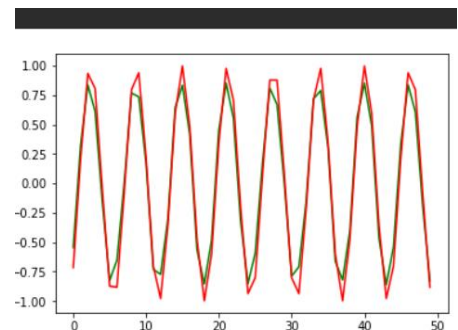
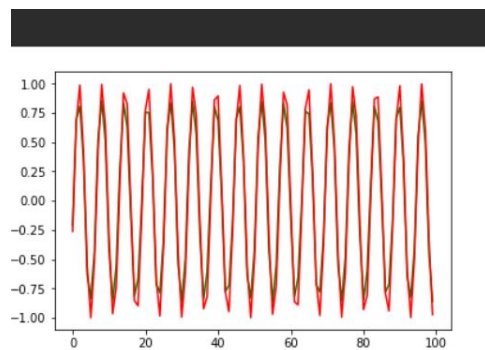


Figure2: Output Snaps.