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Function Approximation

Problem Setting

- Set of possible instances ${\mathcal X}$
- Set of possible labels ${\mathcal Y}$
- Unknown target function $f: \mathcal{X} \to \mathcal{Y}$
- Set of function hypotheses $H = \{h \mid h : \mathcal{X} \to \mathcal{Y}\}$

Input: Training examples of unknown target function f $\{\langle \boldsymbol{x}_i, y_i \rangle\}_{i=1}^n = \{\langle \boldsymbol{x}_1, y_1 \rangle, \dots, \langle \boldsymbol{x}_n, y_n \rangle\}$

Output: Hypothesis $h \in H$ that best approximates f

Sample Dataset

- Columns denote features X_i
- Rows denote labeled instances $\langle \boldsymbol{x}_i, y_i \rangle$
- Class label denotes whether a tennis game was played

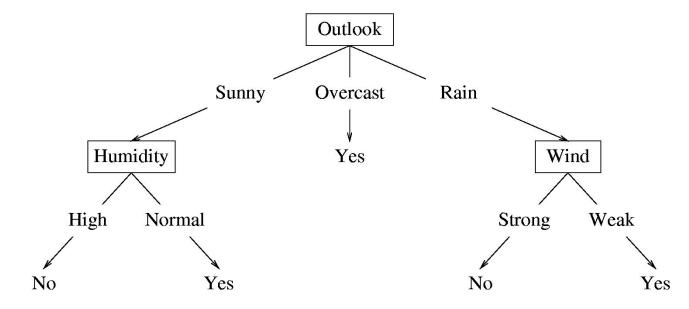
Response

		Response			
	Outlook	Temperature	Humidity	Wind	Class
$\langle oldsymbol{x}_i, y_i angle$	Sunny	Hot	High	Weak	No
	Sunny	Hot	High	Strong	No
	Overcast	Hot	High	Weak	Yes
	Rain	Mild	High	Weak	Yes
	Rain	Cool	Normal	Weak	Yes
	Rain	Cool	Normal	Strong	No
	Overcast	Cool	Normal	Strong	Yes
	Sunny	Mild	High	Weak	No
	Sunny	Cool	Normal	Weak	Yes
	Rain	Mild	Normal	Weak	Yes
	Sunny	Mild	Normal	Strong	Yes
	Overcast	Mild	High	Strong	Yes
	Overcast	Hot	Normal	Weak	Yes
	Rain	Mild	High	Strong	No

Predictors

Decision Tree

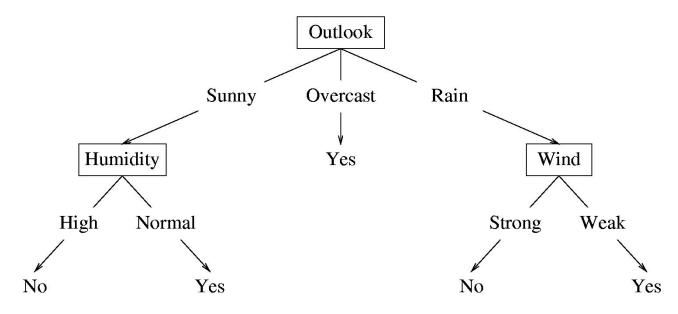
A possible decision tree for the data:



- Each internal node: test one attribute X_i
- Each branch from a node: selects one value for X_i
- Each leaf node: predict Y (or $p(Y \mid m{x} \in \mathrm{leaf})$)

Decision Tree

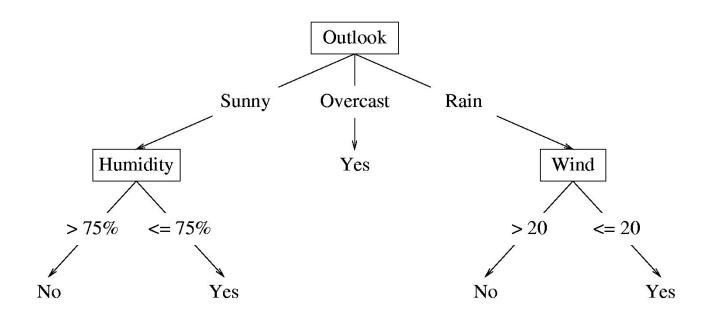
A possible decision tree for the data:



 What prediction would we make for <outlook=sunny, temperature=hot, humidity=high, wind=weak>?

Decision Tree

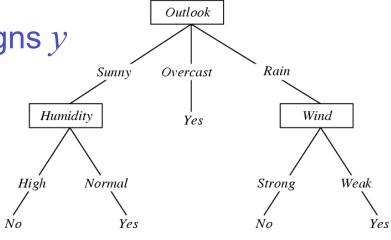
 If features are continuous, internal nodes can test the value of a feature against a threshold



Decision Tree Learning

Problem Setting:

- Set of possible instances X
 - each instance x in X is a feature vector
 - e.g., <Humidity=low, Wind=weak, Outlook=rain, Temp=hot>
- Unknown target function $f: X \rightarrow Y$
 - Y is discrete valued
- Set of function hypotheses $H = \{ h \mid h : X \rightarrow Y \}$
 - each hypothesis h is a decision tree
 - trees sorts x to leaf, which assigns y



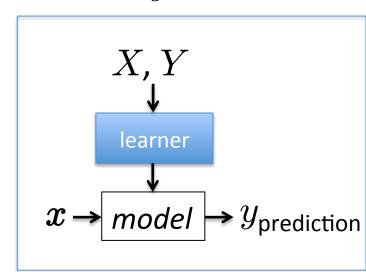
Stages of (Batch) Machine Learning

Given: labeled training data $X, Y = \{\langle \boldsymbol{x}_i, y_i \rangle\}_{i=1}^n$

• Assumes each $\boldsymbol{x}_i \sim \mathcal{D}(\mathcal{X})$ with $y_i = f_{target}(\boldsymbol{x}_i)$

Train the model:

 $model \leftarrow classifier.train(X, Y)$



Apply the model to new data:

• Given: new unlabeled instance $x \sim \mathcal{D}(\mathcal{X})$ $y_{\text{prediction}} \leftarrow \textit{model}. \textit{predict}(x)$

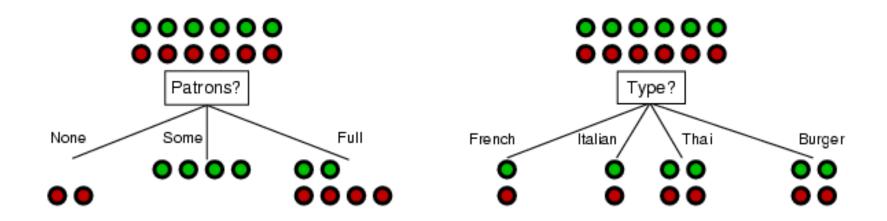
Choosing the Best Attribute

Key problem: choosing which attribute to split a given set of examples

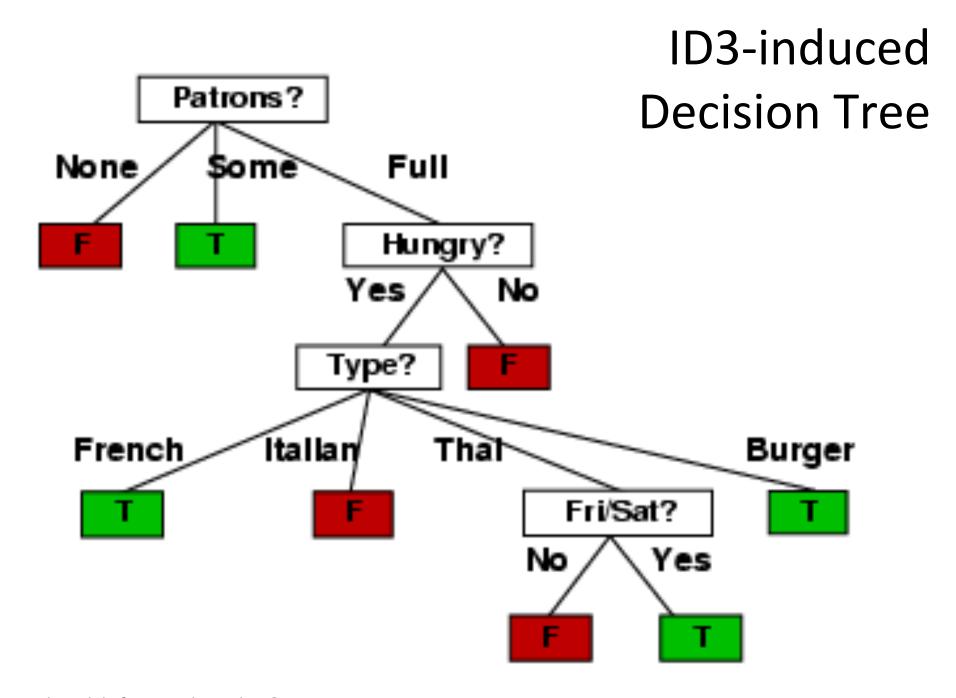
- Some possibilities are:
 - Random: Select any attribute at random
 - Least-Values: Choose the attribute with the smallest number of possible values
 - Most-Values: Choose the attribute with the largest number of possible values
 - Max-Gain: Choose the attribute that has the largest expected information gain
 - i.e., attribute that results in smallest expected size of subtrees rooted at its children
- The ID3 algorithm uses the Max-Gain method of selecting the best attribute

Choosing an Attribute

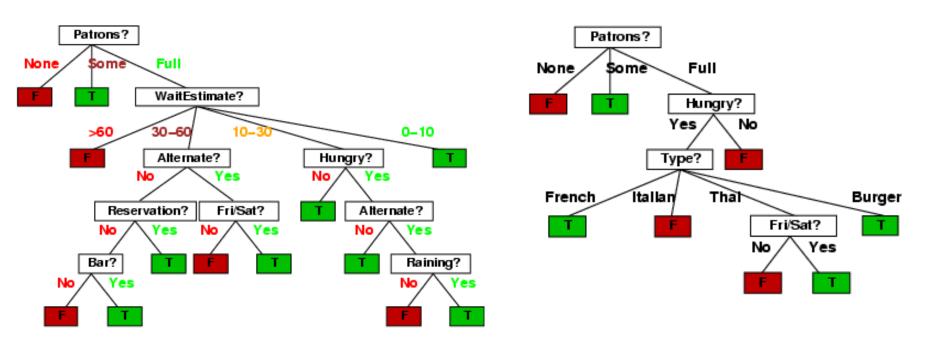
Idea: a good attribute splits the examples into subsets that are (ideally) "all positive" or "all negative"



Which split is more informative: *Patrons?* or *Type?*



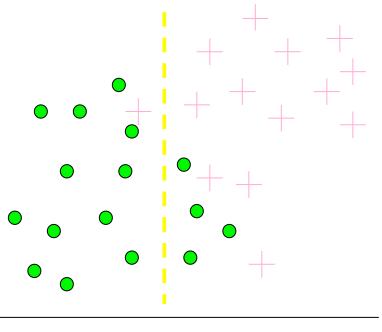
Compare the Two Decision Trees



Information Gain

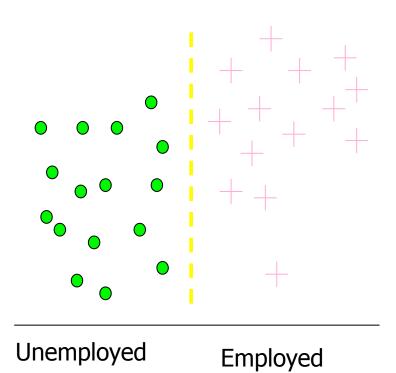
Which test is more informative?

Split over whether Balance exceeds 50K



Less or equal 50K Over 50K

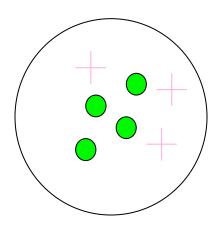
Split over whether applicant is employed

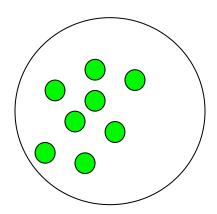


Information Gain

Impurity/Entropy (informal)

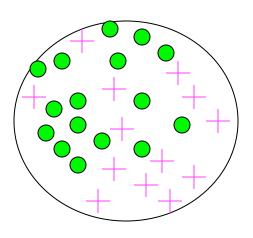
Measures the level of impurity in a group of examples



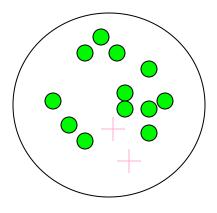


Impurity

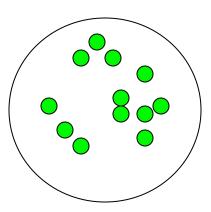
Very impure group



Less impure



Minimum impurity



Entropy: a common way to measure impurity

of possible values for X

Entropy H(X) of a random variable X

$$H(X) = -\sum_{i=1}^{n} P(X = i) \log_2 P(X = i)$$

H(X) is the expected number of bits needed to encode a randomly drawn value of X (under most efficient code)

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Why? Information theory:

- Most efficient code assigns -log₂P(X=i) bits to encode the message X=i
- So, expected number of bits to code one random *X* is:

$$\sum_{i=1}^{n} P(X=i)(-\log_2 P(X=i))$$

Information Gain

- We want to determine which attribute in a given set of training feature vectors is most useful for discriminating between the classes to be learned.
- Information gain tells us how important a given attribute of the feature vectors is.
- We will use it to decide the ordering of attributes in the nodes of a decision tree.

Entropy *H*(*X*) of a random variable *X*

$$H(X) = -\sum_{i=1}^{n} P(X = i) \log_2 P(X = i)$$

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Specific conditional entropy H(X|Y=v) of X given Y=v:

$$H(X|Y = v) = -\sum_{i=1}^{n} P(X = i|Y = v) \log_2 P(X = i|Y = v)$$

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$$H(X|Y) = \sum_{v \in values(Y)} P(Y = v)H(X|Y = v)$$

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Mututal information (aka Information Gain) of *X* and *Y*:

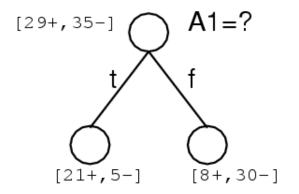
$$I(X,Y) = H(X) - H(X|Y) = H(Y) - H(Y|X)$$

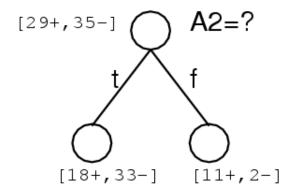
Information Gain

Information Gain is the mutual information between input attribute A and target variable Y

Information Gain is the expected reduction in entropy of target variable Y for data sample S, due to sorting on variable A

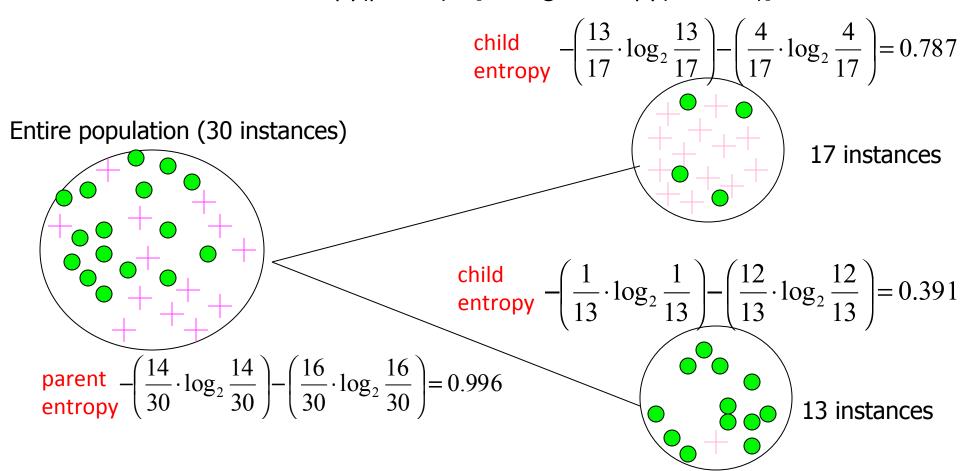
$$Gain(S, A) = I_S(A, Y) = H_S(Y) - H_S(Y|A)$$





Calculating Information Gain

Information Gain = entropy(parent) - [average entropy(children)]



(Weighted) Average Entropy of Children =
$$\left(\frac{17}{30} \cdot 0.787\right) + \left(\frac{13}{30} \cdot 0.391\right) = 0.615$$

Information Gain = 0.996 - 0.615 = 0.38

Entropy-Based Automatic Decision Tree Construction

```
Training Set X
x1=(f11,f12,...f1m)
x2=(f21,f22, f2m)

.
xn=(fn1,f22, f2m)
```

Node 1
What feature
should be used?
What values?

Quinlan suggested information gain in his ID3 system and later the gain ratio, both based on entropy.

Using Information Gain to Construct a Decision Tree

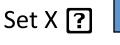
Full Training Set X

illing Set A

Attribute A vk

Choose the attribute A with highest information gain for the full training set at the root of the tree.

Construct child nodes for each value of A. Each has an associated subset of vectors in which A has a particular value.





repeat recursively till when?

Disadvantage of information gain:

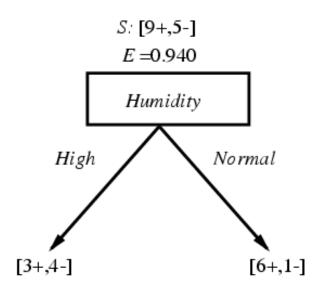
- It prefers attributes with large number of values that split the data into small, pure subsets
- Quinlan's gain ratio uses normalization to improve this

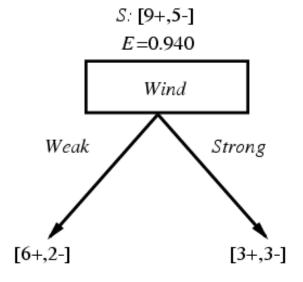
Training Examples

Day	Outlook	Temperature	Humidity	Wind	PlayTenr
D1	Sunny	Hot	High	Weak	No
D2	Sunny	Hot	High	Strong	No
D3	Overcast	Hot	High	Weak	Yes
D4	Rain	Mild	High	Weak	Yes
D5	Rain	Cool	Normal	Weak	Yes
D6	Rain	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	Sunny	Mild	High	Weak	No
D9	Sunny	Cool	Normal	Weak	Yes
D10	Rain	Mild	Normal	Weak	Yes
D11	Sunny	Mild	Normal	Strong	Yes
D12	Overcast	Mild	High	Strong	Yes
D13	Overcast	Hot	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

Selecting the Next Attribute

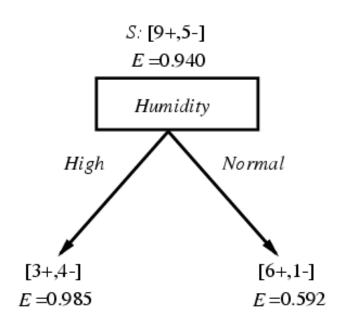
Which attribute is the best classifier?



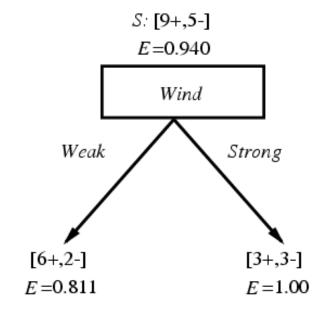


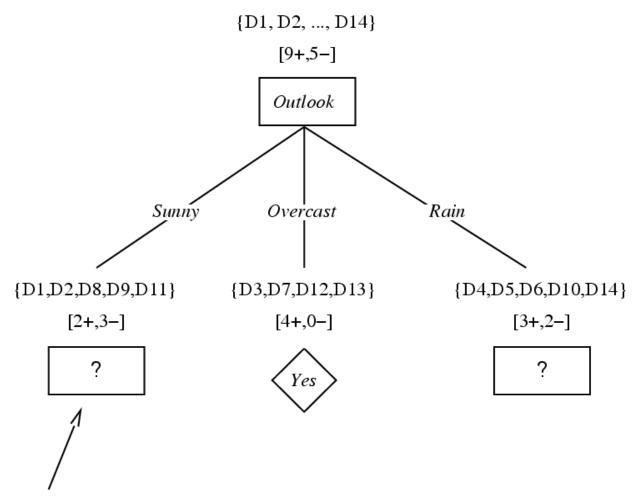
Selecting the Next Attribute

Which attribute is the best classifier?



Gain (S, Humidity) = .940 - (7/14).985 - (7/14).592 = .151





Which attribute should be tested here?

$$S_{sunny} = \{D1,D2,D8,D9,D11\}$$

$$Gain (S_{sunny}, Humidity) = .970 - (3/5) 0.0 - (2/5) 0.0 = .970$$

$$Gain (S_{sunny}, Temperature) = .970 - (2/5) 0.0 - (2/5) 1.0 - (1/5) 0.0 = .570$$

$$Gain (S_{sunny}, Wind) = .970 - (2/5) 1.0 - (3/5) .918 = .019$$

Slide by Tom Mitchell