## CS4248 AY 2022/23 Semester 1 Tutorial 4

1. A perceptron F receives inputs  $x_1, ..., x_n$  and outputs the following:

$$F(x_1, \dots, x_n) = \begin{cases} 1 & \text{if } w_0 + w_1 x_1 + \dots + w_n x_n > 0 \\ 0 & \text{otherwise} \end{cases}$$

- (a) Give 3 weights  $w_0$ ,  $w_1$ ,  $w_2$  such that F implements the Boolean function  $x_1 \vee x_2$ .
- (b) Give 3 weights  $w_0$ ,  $w_1$ ,  $w_2$  such that F implements the Boolean function  $\neg x_1 \land x_2$ .
- 2. Consider a neural network defined as follows:

$$s_1 = \begin{bmatrix} i_1 & i_2 & 1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$$

$$h_1 = \tanh(s_1) = \frac{e^{s_1} - e^{-s_1}}{e^{s_1} + e^{-s_1}}$$

$$\begin{bmatrix} o_1 & o_2 & o_3 \end{bmatrix} = \begin{bmatrix} h_1 & 1 \end{bmatrix} \begin{bmatrix} w_4 & w_5 & w_6 \\ w_7 & w_8 & w_9 \end{bmatrix}$$

$$L = (o_1 - t_1)^2 + (o_2 - t_2)^2 + (o_3 - t_3)^2$$

where  $[i_1 \quad i_2]$  is the input vector,  $[o_1 \quad o_2 \quad o_3]$  is the output vector,  $[t_1 \quad t_2 \quad t_3]$  is the target output vector, L is the loss function, and  $w_1, w_2, \ldots, w_9$  are the weight parameters to be learned.

The weights  $w_i$  are initialized as follows:

$w_1$	$W_2$	$W_3$	$W_4$	$W_5$	$W_6$	$w_7$	$W_8$	$W_9$
0.25	0.25	0.1	0.1	-0.1	0.2	0.3	-0.2	-0.3

The learning rate is 0.5. The neural network is given one training example as follows:  $i_1 = 0.2$ ,  $i_2 = 0.8$ ,  $t_1 = 1$ ,  $t_2 = 0$ ,  $t_3 = 0$ .

- (a) Derive an expression for  $\frac{\partial L}{\partial w_3}$  in terms of (some of)  $i_1, i_2, o_1, o_2, o_3, t_1, t_2, t_3, h_1, w_1, w_2, \dots, w_9$ . Show clearly the steps of your derivation and provide appropriate justification.
- (b) For the given training example, carry out forward computation to compute the value of

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the loss function L. Show clearly all your intermediate calculations.

- (c) Use backpropagation to compute the weight  $w_3$  after one iteration of weight update. Show clearly the steps of your calculation.
- 3. Consider the use of dropout in neural network training when the non-linear activation function is tanh. Dropout applies a random masking vector m to a hidden layer vector h, as follows:

$$h = \tanh(xW + b)$$
$$\widetilde{h_1} = m \odot h$$

where  $\odot$  is element-wise multiplication, and  $tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$ 

John proposes a different formula for computation:

$$\widetilde{h_2} = \tanh(m \odot (xW + b))$$

- (a) Is John's proposal a correct approach of implementing dropout? Give your justification. Be as precise as possible.
- (b) Suppose the nonlinear activation function is changed from tanh to the sigmoid function  $\sigma$ :

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

Is John's proposal a correct approach of implementing dropout? Give your justification. Be as precise as possible.