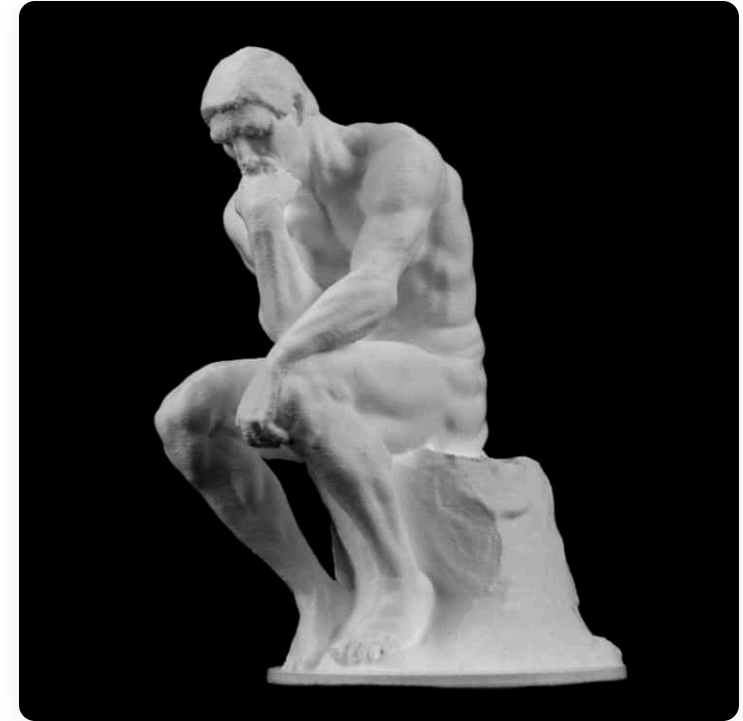




# Photogrammetry for Unity

# Goals

- Develop process to automate photogrammetry (concepts available)
- Create a 3D model of a person using photogrammetry
- Import the model into Unity in the highest possible quality (with textures)



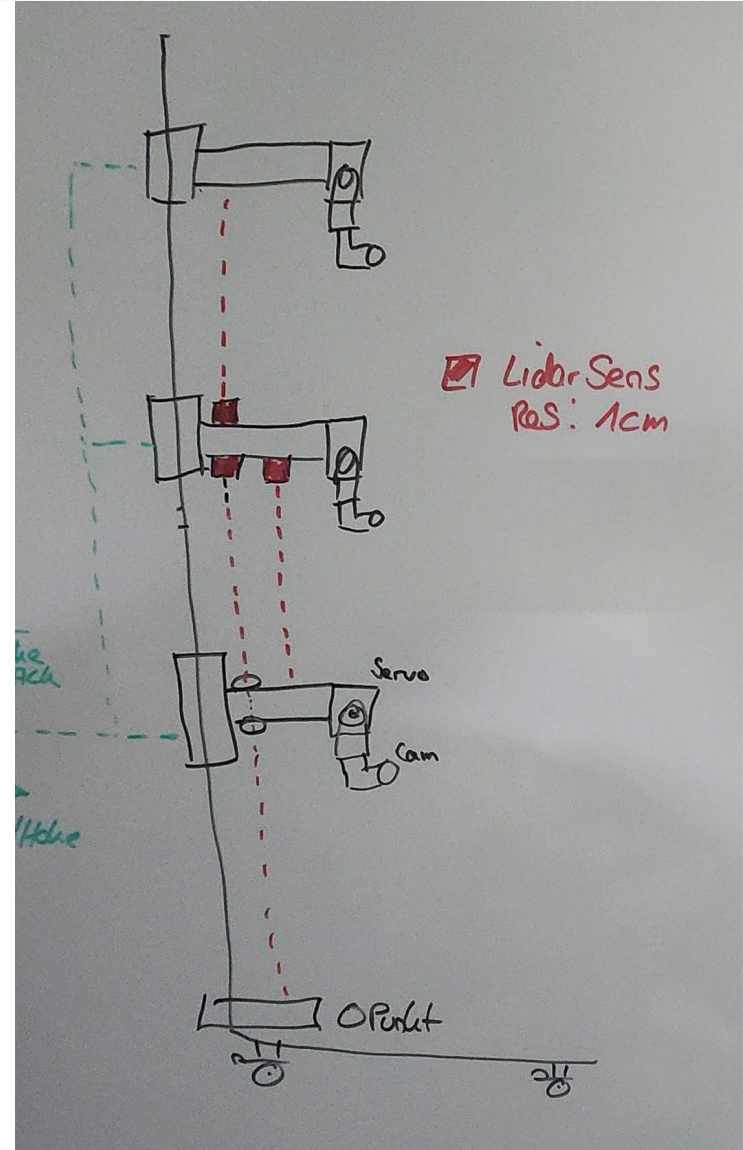
competitor: [Shapify.me](https://shapify.me)

# Roadmap

1. Automate photoshoot process (external project)
2. Preprocess images (lighting, cropping, etc.) + machine settings
3. Process images in Meshroom (photogrammetry software)
4. Post-process 3D model (Blender, retopology, texturing)
5. Export model for Unity (FBX, glTF, etc.)
6. Integrate into Unity

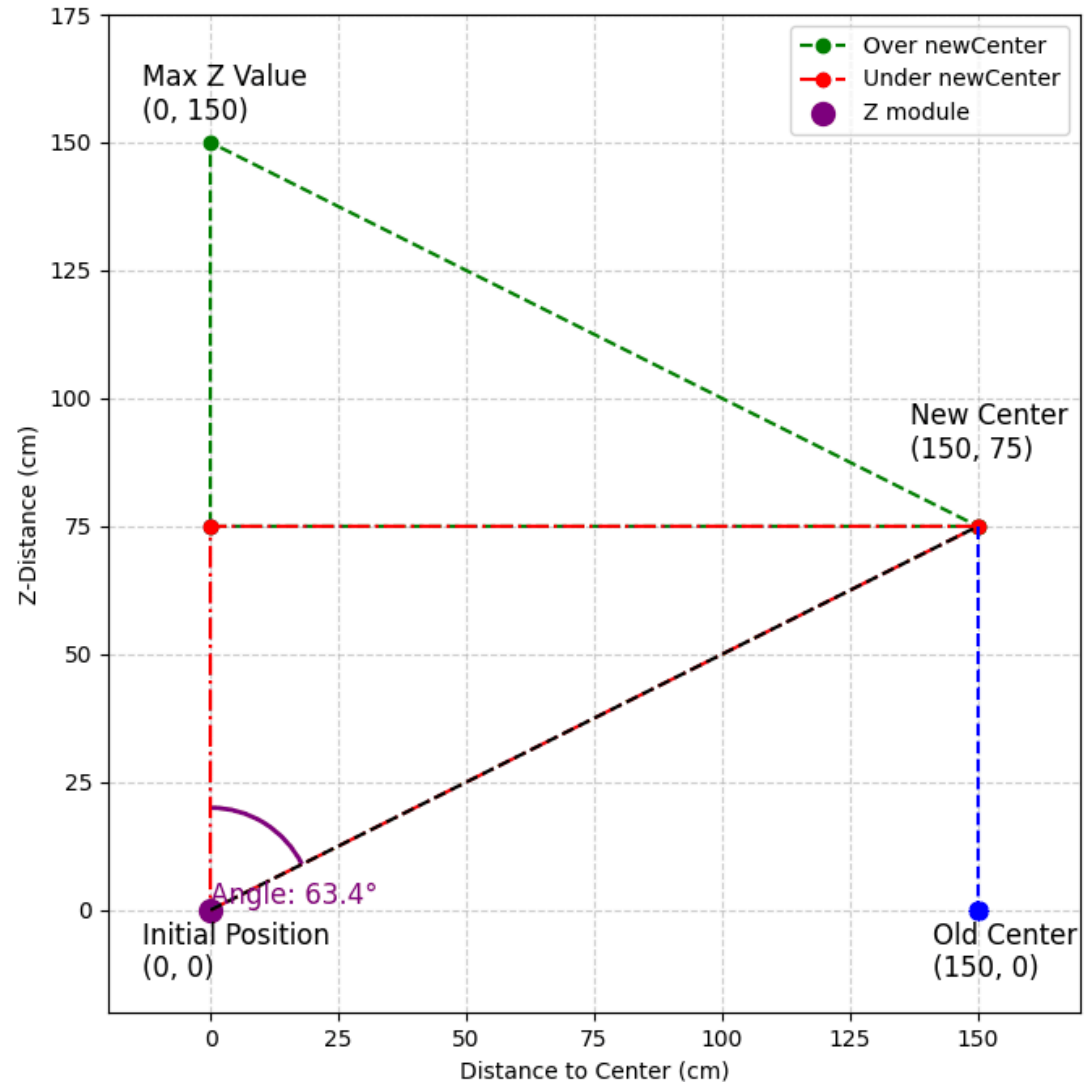
# Scanner concept

- Moveable Camera setup vertical
- Diverse Hardware should be useable
- Modular system | scalable/changeable

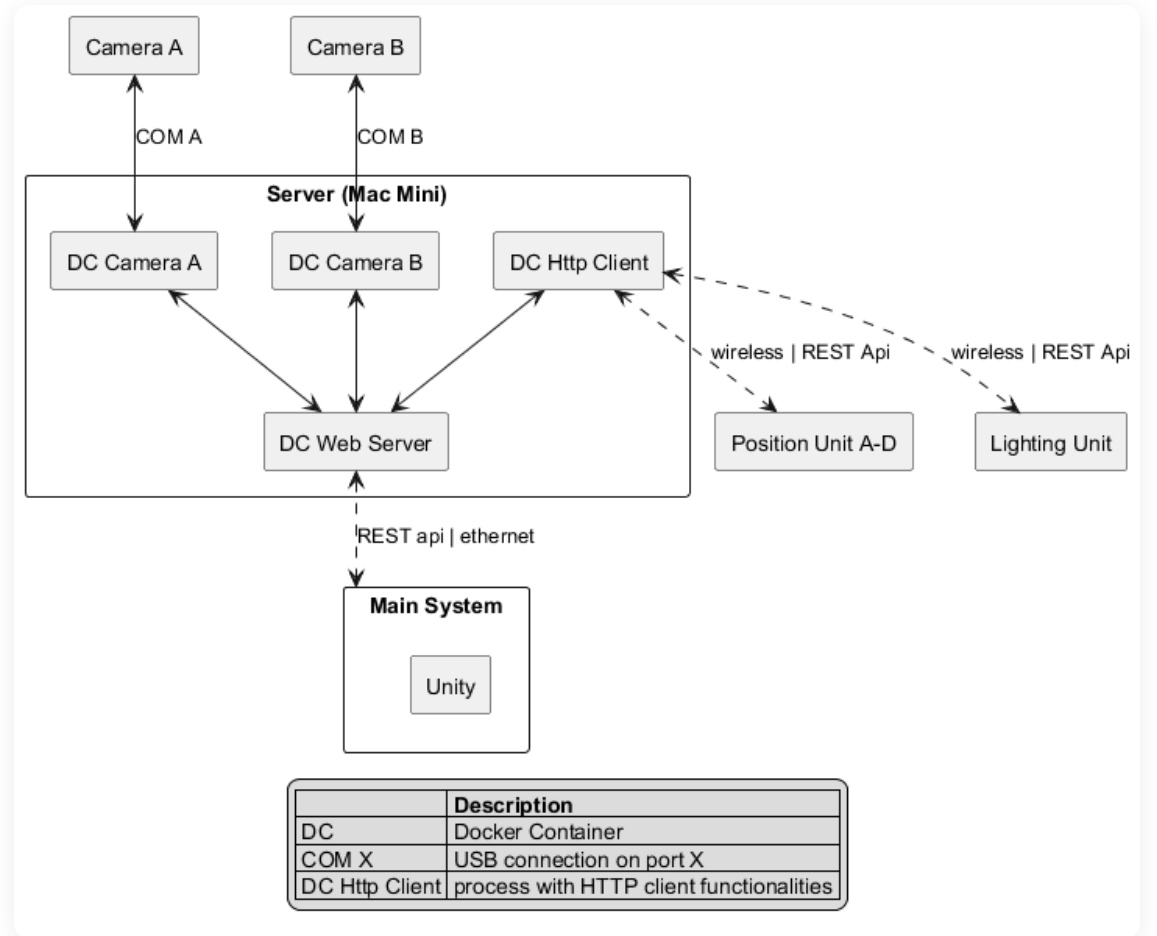


# Z Module

- The Z module aligns itself to the new center (previous center = center of the scanner on the ground)
- Targeted focusing on specific areas enables more precise detail measurement

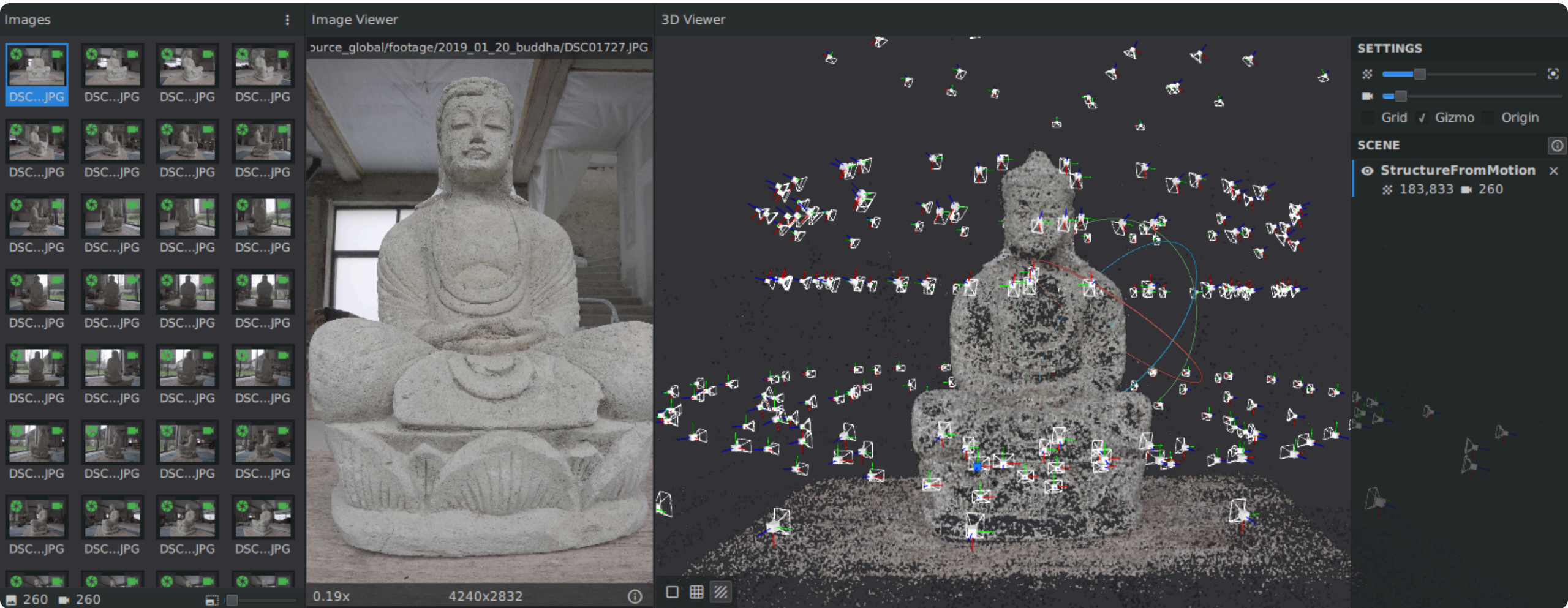


# System Architecture





# AliceVision Meshroom



# Base tasks

- import images automatically into Meshroom
- create a point cloud from images & camera positions
- export the model in a format that Unity can use (FBX, glTF, etc.)
- import the model into Unity
- create a simple Unity scene to display the model
- add textures to the model in Unity



# Advanced tasks

- lighting conditions combined with the camera settings/processing
- multiple scans overlapp (for better results)
- selective focus (special parts for better details)
- transparent or reflective surfaces. (lightcolor change has impact?)

# Output:

A **cost-effective 3D scanner** for large objects (e.g., people). The base can be equipped with any cameras, allowing for flexible hardware testing.

The system is not limited to traditional cameras, other sensors such as **LiDAR can also be used**.

**Future:** Combining data from multiple sensors for better [results](#).

# Livedemo Prototyp I

# Possible following projects

**Movable Scanner:** Scanner Module can rotate around the object to capture all angles (bottom marks).

**Multi-sensor integration:** Data from multiple sensors (e.g., cameras, LiDAR, spectral) improved results & usecases

**User-friendly interface:** "Casual" friendly interface for controlling the scanning process and visualizing results.

**Cloud-based processing:** solution for processing and storing 3D models.

**Machine learning for model improvement:** Machine learning techniques to improve the quality in preprocessing.

# Questions?

[GitHub](#)