CLEAN CITY

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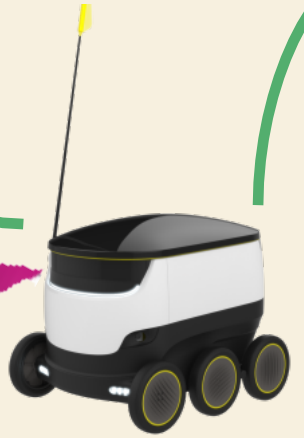
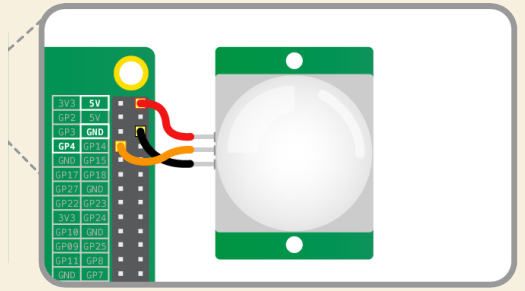
ARCHITECTURE

OVERVIEW

ARCHITECTURE OVERVIEW



NEW



WORKFLOW

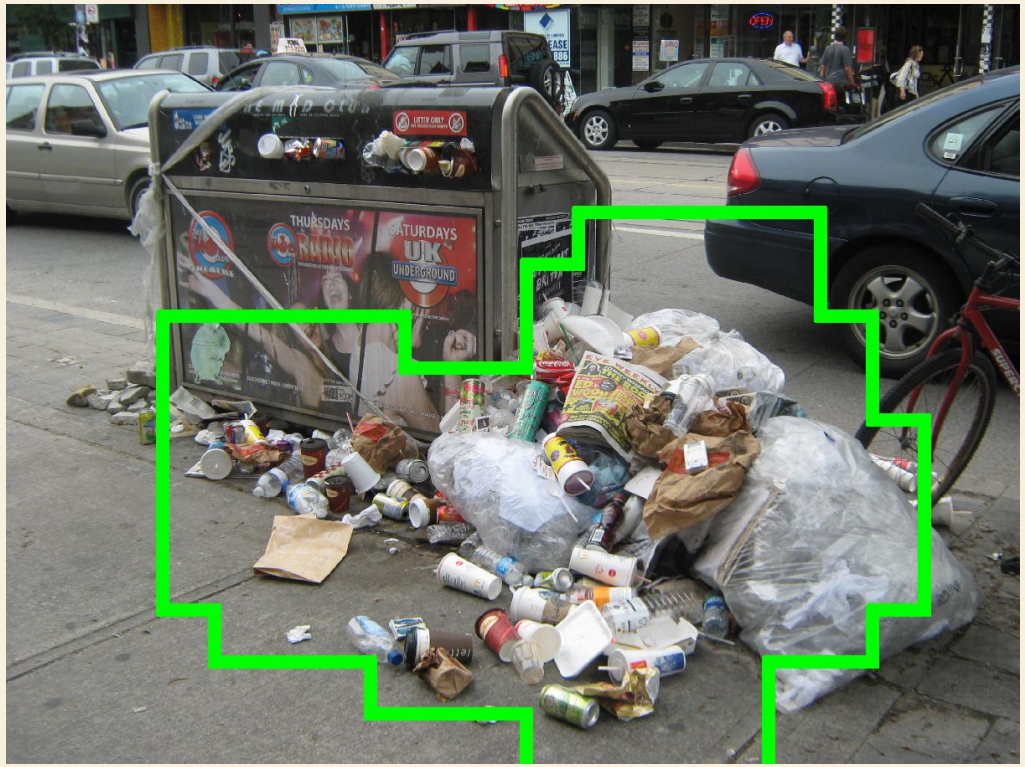
OVERVIEW

WORKFLOW OVERVIEW

- Self-driving robot will be left on the streets of the city and real-time updates regarding garbage detection will be collected using AI and deep learning.

WORKFLOW OVERVIEW (CONT..)

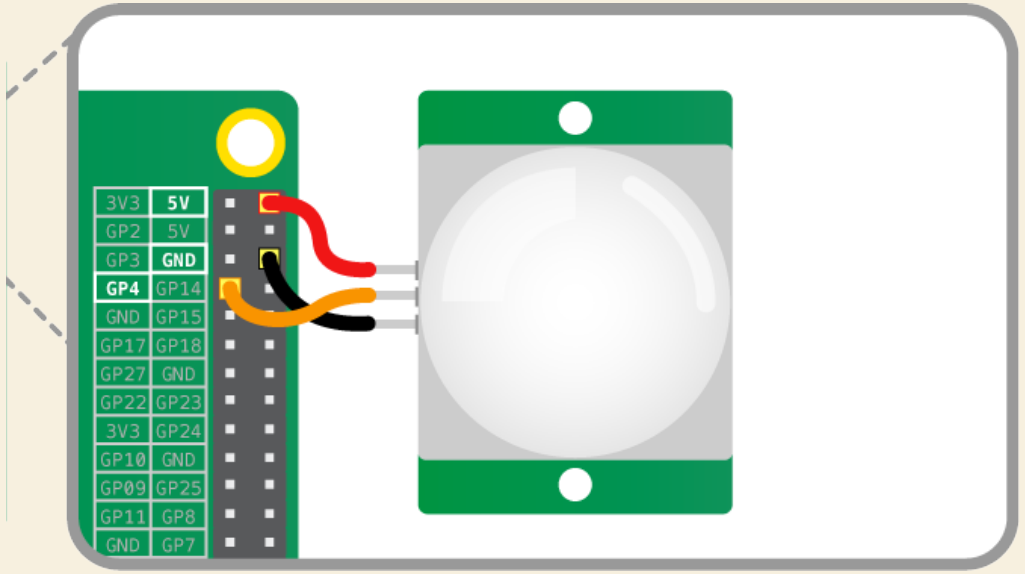
- Deep Learning will be used to segment the garbage from collected images by the robot. Trained model will be used to compare images to GINI (Garbage IN Images) dataset for garbage detection.



WORKFLOW OVERVIEW (CONT..)

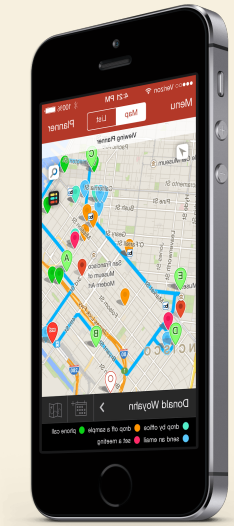
NEW

- Use Odor Sensor to detect smell relating to garbage which has a specific characteristic.
- This will help categorize garbage when visual data is not very clear.



WORKFLOW OVERVIEW (CONT..)

- Optimized route will be prepared by the Robot and sent to the cleaning trucks in the city so that maximum garbage can be collected in one go.



PHASE

DISCTRIBUTION

PHASE DISTRIBUTION

- The entire solution is divided into **four** phases:
  - Enhance current Garbage detection system.
  - Prepare the robot for detecting garbage.
  - Add other capabilities to robot that are present in humans.
  - Train the robot for generating optimized path.
  - Create an application for Cleaning trucks to get the real-time updates.

THANK YOU

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