

NATALIE STROMBERG

903-456-7857 | Natalie@Stromberg.me | [Linkedin.com/in/nstrombo](https://www.linkedin.com/in/nstrombo) | nstrombo.com

EDUCATION

University Of Texas at Dallas

Bachelor of Science in Mechanical Engineering

Richardson, TX

Expected May 2027

EXPERIENCE

Mechanical Engineering Intern

Formlabs

Sept – Dec 2025

Somerville, MA

- Owned test planning, mechanical design, electrical and software integration for automated tests to characterize and validate performance of critical components for next generation 3D printers
- Designed parts for sheet metal, injection molding, 3D printing, and CNC for prototypes and test fixtures
- Supported R&D teams in root-causing and problem-solving printer architecture issues
- Engaged in cost down exercises to revalidate components with lower BOM cost without sacrificing functionality
- Expanded my 3D printing toolkit, completed personal projects including an intern hackathon combat robot, presented my accomplishments to the rest of the company

Director of Combat Robotics

Comet Robotics at UT Dallas

April 2023 – July 2025

Richardson, TX

- Created and presented a series of workshops for students, teaching ≈220 students over 3 semesters Solidworks design to produce their first combat robot
- Utilized Solidworks CAD to create 12 combat robots, attending 16 competitions and winning 36+ matches
- Utilized 3D printing to rapidly prototype combat solutions, iteratively designing the drive and survivability of each robot
- Conducted outreach and increased the organization's financial resources by 9x year over year
- Pushed on campus events and workshops that took active members from 12 to over 100, while improving member retention
- Explored high impact materials such as TPU, UHMW, and abrasion resistant steel alloys
- Explored modular design in robotics, created interchangeable sub-assemblies for combat robots

Community Manager

Convex Apps

Sep 2020 – July 2023

Remote

- Owned the creation of events, and managed social media presence for a game toolkit startup
- Conducted regular events, growing platform followers by 80% and increasing member retention
- Flow coordination for support tickets, and implemented a more efficient ticket tracking system, reducing ticket solve times

PROJECTS

Modular Combat Robot Outreach Project | Solidworks, 3D Printing

Sept 2023 – July 2025

- Collaborated with a team of 3 to develop a novel, modular combat robot system for high school outreach
- Designed modular assemblies, creating unique robot building blocks including 7 weapon attachments and 7 armor attachments that are quickly attached using a grid-dovetail system that allowed parts to be reused
- Leveraged 3D printing for rapid development and sustainability on a total budget of \$3,000, printing ≈900 parts
- Hosted 9 workshops with an audience of 40-60 highschoolers each, with all students completing a robot and fighting
- Increased engagement from students, increased interest in workshops from schools over previous workshops
- Presented the robots to Tech Titans of Dallas TX and achieved finalist in *Tech Titans of the Future* award

Molding Machine Project | Solidworks, 3D Printing, Arduino, EasyEDA, C#

Nov 2021 – May 2022

- Worked to develop a innovative, reconfigurable machine for creating molds on a budget, aimed at reducing waste and labor
- Used Solidworks to 3D model and produce drawings for manufacturing sheet metal and 3D printed components
- Designed a custom PCB in EasyEDA to control 16 stepper motors and give simple LED feedback to an operator
- Wrote an Arduino control system with a USB PC connection, allowing a user to import files and control the machine
- Produced engineering documentation and testing, reduced molding time, labor, and increased mold accuracy

SKILLS

Programs: Solidworks, Onshape, Autocad, Adobe CC, MS Office

Languages: Python, C++, Arduino, Matlab

Skills: Mechanical Engineering, 3D Printing, Robotics, PCB Design, Project Management, Modular Design, Iterative Design, Computer skills, Remote Control Systems, Technician Ham Radio License