IIR Filter IP

□ System Design

- □ System Design
- □ IIR IP

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- □ Zynq Communication

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- □ IIR IP
- □ Zynq Communication
- Example Outputs



Picture of the entire system, zoom in to see/explain things.



This frame will contain a picture of the IP. Discuss the I/O pins.

IIR IP — Data Input Process

These frames will contain code snippets from the IP. Namely the important parts such as data (feedforward)/feedback input, arithmetic, data output, and the elaborated design.

IIR IP — Arithmetic

Arithmetic

IIR IP — Data Output

Data Output

IIR IP — Elaborated Design

Big Picture, will need to zoom in.

IIR IP — IIR Troubles

□ Single Stage vs BiQuad

IIR IP — IIR Troubles

- ☐ Single Stage vs BiQuad
- □ Floating Point to Fixed Point

IIR IP — IIR Troubles

- ☐ Single Stage vs BiQuad
- ☐ Floating Point to Fixed Point
- ☐ Gains and Scaling

IIR IP — Single Stage Problems

This will probably have 2 pictures and some bullets: one of a completely fine set of coefficients and another with a bad set on one side and on the other side there will be a list of things that are wrong.

Number of coefficients increases dramatically

IIR IP — Single Stage Problems

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- Number of coefficients increases dramatically
- □ Numerator coefficients approach zero

IIR IP — Single Stage Problems

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- □ Number of coefficients increases dramatically
- □ Numerator coefficients approach zero
- Denominator coefficients approach infinity

This will have a picture of the coefficients generated for a BiQuad to one side. The other side will have some bulleted information. Pros:

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Cons:

□ Numerator coefficients need scaled

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- □ Number of coefficients never change
- □ Small coefficient magnitudes
- □ Easy to make generic

- □ Numerator coefficients need scaled
- □ Requires more hardware

IIR IP — Fixed Point

A discussion on why the coefficients need to be scaled. Probably will just contain pictures.

IIR IP — Scaling

A discussion on how to scale coefficients in MATLAB and the remaining issues with scaling.

Zyng Communication — Outside the IP

Picture of the GPIOs that connect with the IPs, probably won't be using the mux/dmux design for this, so I'll be super basic. I might remove this entire section because it is so basic.

Zynq Communication — Inside the IP

Snippet of the coefficient input process

Example Outputs — Lowpass

Picture of a lowpass filter, and the properties listed somewhere on here.

Example Outputs — Highpass

Picture of a highpass filter, and the properties listed somewhere on here.

Example Outputs — Something Else

Picture of a something else filter, and the properties listed somewhere on here.