Data Structures

Lecture 3*
AVL Trees

Yair Carmon Spring semester 2022-3

^{*} Based on slides by Uri Zwick, Haim Kaplan, Hanoch Levy, Amir Rubinstein, and TAUOnline

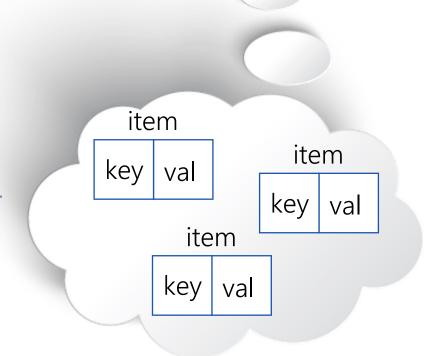
Definition

What Is an AVL tree?

ADT Dictionary - Reminder

- Maintain a set of items, with keys and associated values
 - Assume keys are distinct

- Support insert, delete, search
- If keys are totally ordered support min/max and successor/predecessor



ADT Dictionary - Reminder

Suppose a dictionary item x contains key and value, in the fields x.key, x.val

Dictionary()	Create an emp	ty dictionary
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- Insert(D, x) Insert x to D
- Delete(D, x) Delete a given item x from D (assuming it exists)
- Search(D, k) Return item with a given key k (if exists)
- Min(D) Return item with the minimal key
- Max(D) Return item with the maximal key
- Successor(D, x) Return the successor of a given item x
- Predecessor(D, x) Return the predecessor of a given item x

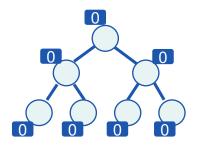
Assume that Items have distinct keys.

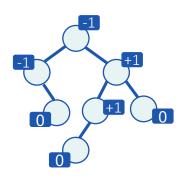
Motivation

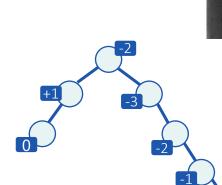
- We saw a dictionary implementation using binary search trees. The complexity of the above operations is O(h + 1) worst case, when h is the tree height.
 - h can be between $O(\log n)$ and O(n)
 - When $h = O(\log n)$ the tree is called balanced.
- Important examples:
 - AVL trees (this lesson)
 and their improved version, WAVL trees
 - B trees, B+ trees
 - Red-Black trees

AVL Trees

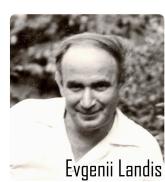
AVL trees were invented by Adelson-Velsky, Landis at 1962.











Balance factor

$$BF(v) = h(v.left) - h(v.right)$$

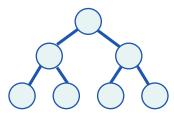
Reminder: The height of an empty tree is set to be -1.

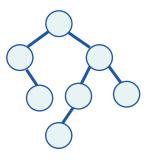
AVL Trees

Definition:

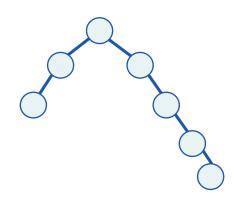
An AVL tree is a binary search tree where each node v maintains the following attribute: $|BF(v)| \leq 1$

Examples:





Non-example:



Upper Bound of an AVL Tree Height

Claim: An AVL tree with n nodes satisfies $h = O(\log n)$.

Proof: next

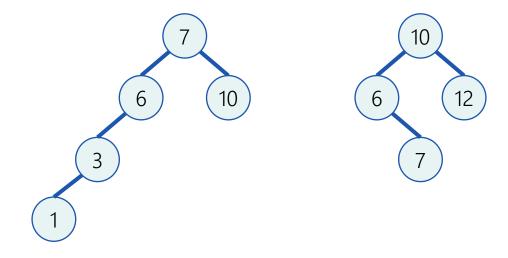
Conclusion

All queries (search, minimum/maximum, predecessor/successor) are executed in $O(\log n)$ time worst case in AVL trees.

AVL Tree Is a Balanced BST

And what about inserting and deleting an item?

Also in logarithmic time, but these operations may violate the tree balance and create nodes that are "AVL criminals". For example:



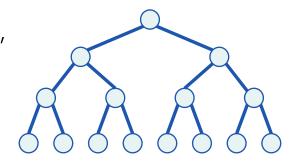
Later on we will understand how to deal with this issue.

Upper Bound of an AVL Tree Height Intuition

In a balanced tree $h = O(\log n)$. Meaning $n = \Omega(\alpha^h)$, for some constant $\alpha > 1$.

This is: the number of nodes in a balanced tree is exponential in the height of the tree.

For example, in a perfectly balanced binary search tree (complete binary tree), $h = O(\log_2 n)$ and $n = \Omega(2^h)$.



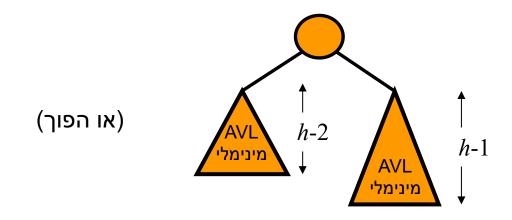
We will prove that the above holds for an AVL tree with the constant $\Phi = \frac{1+\sqrt{5}}{2} \approx 1.618$ (golden ratio), hence $h = O(\log_{\Phi} n)$.

Proof That AVL is Balanced

h = O(logn) for an AVL Tree

חסם לגובה עץ AVL - הוכחה

? בגובה h בעל מספר הצמתים מינימאלי AVL כיצד ניראה עץ



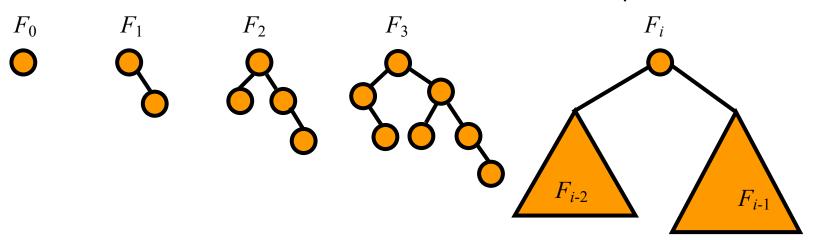
עץ כזה נקרא **עץ פיבונאצ'י**.

$$f_1 = f_2 = 1$$
 $f_n = f_{n-1} + f_{n-2}$: סדרת פיבונאצ'י:

$$\overline{\Phi} = 1 - \Phi = \frac{1 - \sqrt{5}}{2} \approx -0.618$$
 $\Phi = \frac{1 + \sqrt{5}}{2} \approx 1.618$ כאשר $f_n = \frac{\Phi^n - \overline{\Phi}^n}{\sqrt{5}}$

חסם לגובה עץ AVL – הוכחה (2)

הגדרת עצי פיבונאצ'י ברקורסיה:



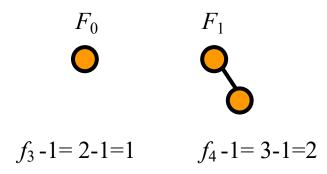
תכונות (תרגיל: הוכיחו כל אחת מהתכונות)

- h גובהו של F_h הוא .1
- $|F_i| = |F_{h-1}| + |F_{h-2}| + 1$.2
- AVL בגובה AVL בעל מספר צמתים מינימלי מבין כל עצי ה-AVL בגובה F_h .3

חסם לגובה עץ AVL – הוכחה (3)

.i -ם יבונצ'י היא מספר פיבונצ'י היא $|F_h| = f_{h+3}$ - הוא מספר פיבונצ'י הי

h באינדוקציה על h



:בסיס: עבור h=0 ו- h=1 הטענה מתקיימת

h' < h צעד: נניח שהטענה נכונה לכל

$$|F_h| = |F_{h-1}| + |F_{h-2}| + 1 = (f_{h+2} - 1) + (f_{h+1} - 1) + 1 = f_{h+3} - 1$$

חסם לגובה עץ AVL – הוכחה (4)

: בעל h מתקיים וגובה $A\!\!\operatorname{VL}$ אם כן, עבור עץ

$$n \ge |F_h|$$

$$n \ge |F_h| = f_{h+3} - 1 = \frac{\Phi^{h+3} - \overline{\Phi}^{h+3}}{\sqrt{5}} - 1 \ge \frac{\Phi^{h+3}}{\sqrt{5}} - 2$$

$$\sqrt{5}(n+2) \ge \Phi^{h+3}$$

$$h + 3 \le \log_{\Phi} \left(\sqrt{5} \left(n + 2 \right) \right)$$

$$h \le \log_{\Phi}(n+2) + \log_{\Phi}(\sqrt{5}) - 3 = O(\log n)$$

$$h \leq \log_{\Phi} n \sim 1.44 \log_2 n$$

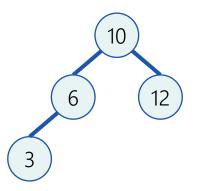
:(עם עוד טיפה מאמץ)

Insertion Into AVL

How to Keep It Balanced?

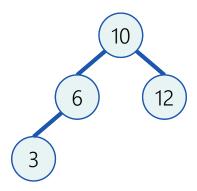
What can we do if an insertion created "AVL criminals"?

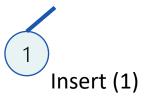
Rotation: change of a few pointers in order to balance the height difference.



What can we do if an insertion created "AVL criminals"?

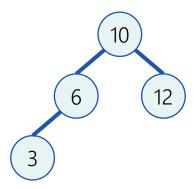
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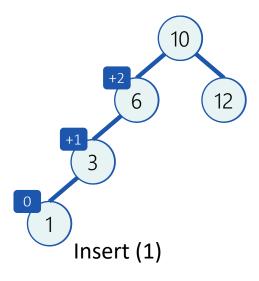




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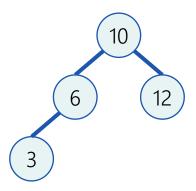
Rotation: change of a few pointers in order to balance the height difference.

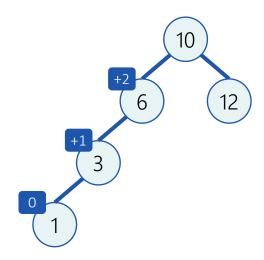


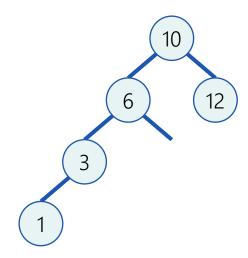


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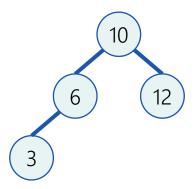


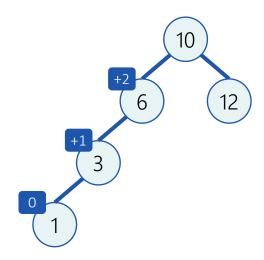


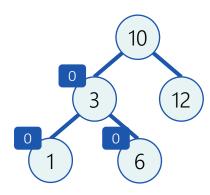


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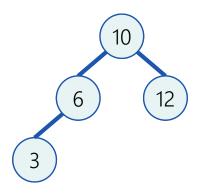






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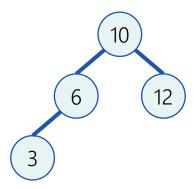
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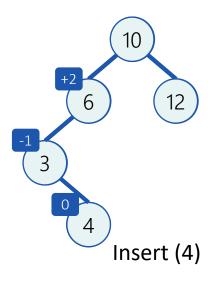




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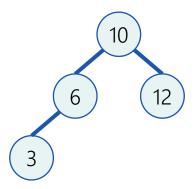
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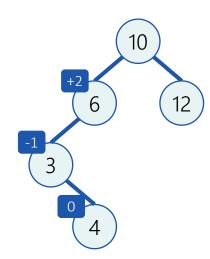


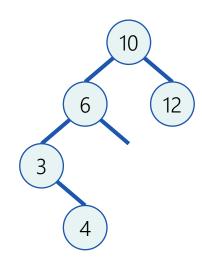


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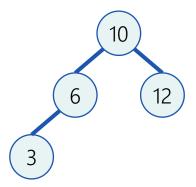


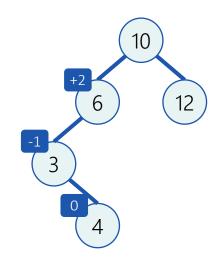


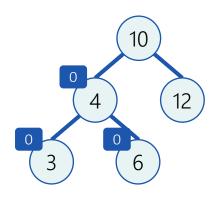


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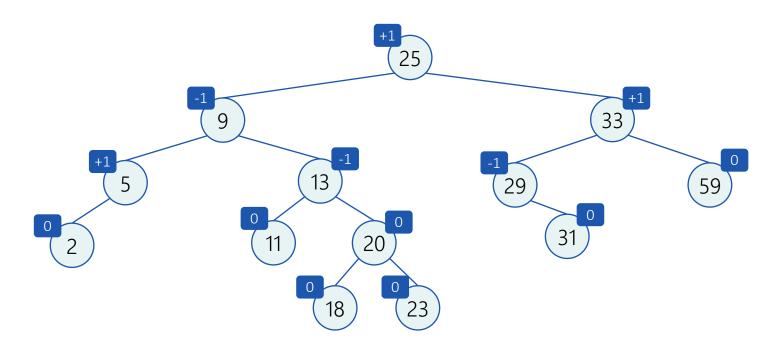
Comic relief

One more simple example: https://vt.tiktok.com/ZS8DsmBew

Fixing After Insertion

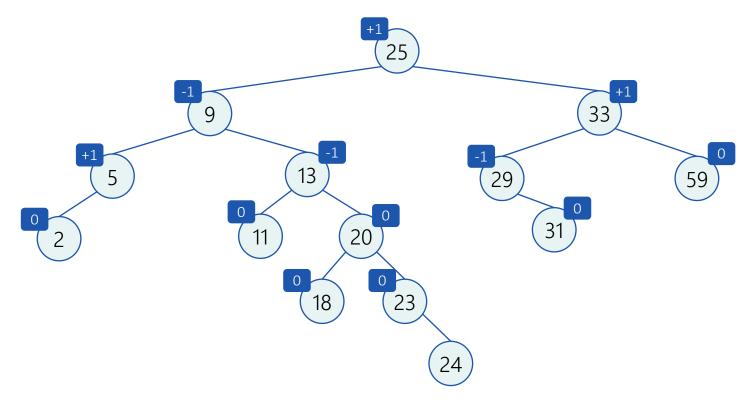
Reminder: BF(v) = height(v.left) - height(v.right)

In a valid AVL tree, each node v satisfies: $|BF(v)| \le 1$



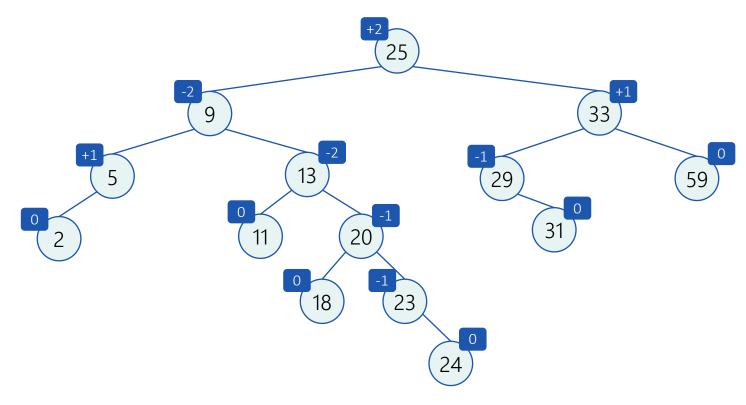
Assume we inserted 24 into the tree.

What are the possible BF values?



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What are the possible BF values?



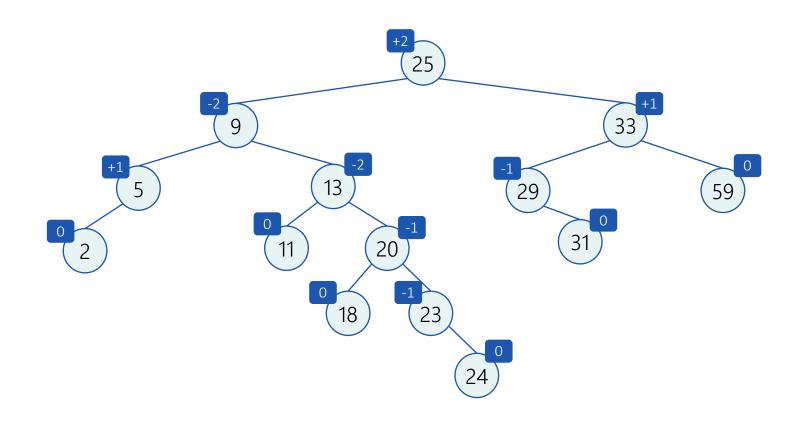
Assume we inserted 24 into the tree.

What are the possible BF values?

Observation 1:

After an insertion, the new balance factors are between -2 and +2, because they can change at most by ± 1 .

Which nodes might change their BF?

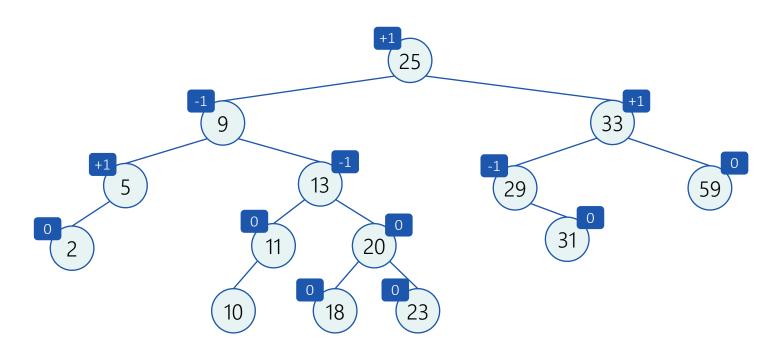


Which nodes might change their BF?

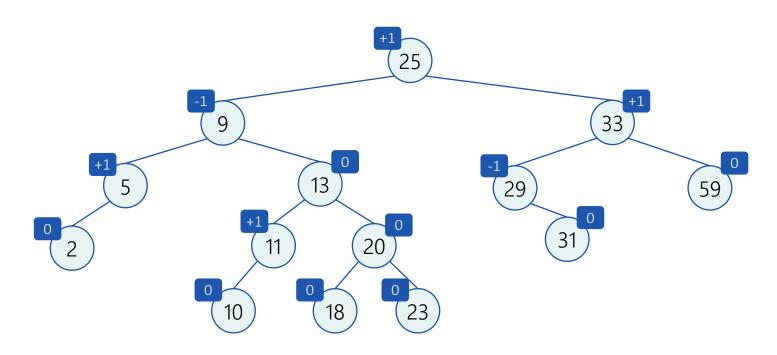
Observation 2:

The only nodes whose balance may have been changed are the nodes on the path from the root to the new node.

Do all nodes on the path from the root to the new node necessarily change their BF? For example, inserting 10:



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Observation 3:

If there's a node on the above-mentioned path, whose **height hasn't changed** after the insertion, then the **BFs** of the nodes **above** it haven't changed.

The Insertion Algorithm The Algorithm

AVL-Insert(*T, z*)

- 1. insert z as usual (as in a BST)
- 2. let y be the parent of the inserted node.
- 3. while $y \neq Null$ do:
 - 3.1. compute $BF(y)^*$
 - 3.2. if |BF(y)| < 2 and y's height hasn't changed: terminate Obs. 3
 - 3.3. else if |BF(y)| < 2 and y's height changed: go back to stage 3 with y's parent
 - 3.4. else (|BF(y)| = 2): perform a rotation and go back to stage 3 with y's parent

Obs. 2

Obs. 1

^{*}Requires maintaining additional information at each node (its height). We will refer to this topic later.

The Insertion Algorithm Time Complexity

AVL-Insert(T, z)

1. Insertion into a BST
$$O(h+1)$$

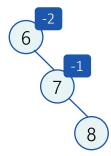
- 2. Go up to the root to spot "AVL criminals" O(h+1)
- 3. Rotations $0(1)\times O(h+1)$

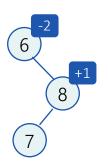
$$O(h+1) = O(log n)$$

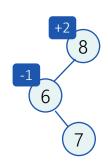
Rotations

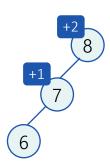
Four Rotations to Rule Them All

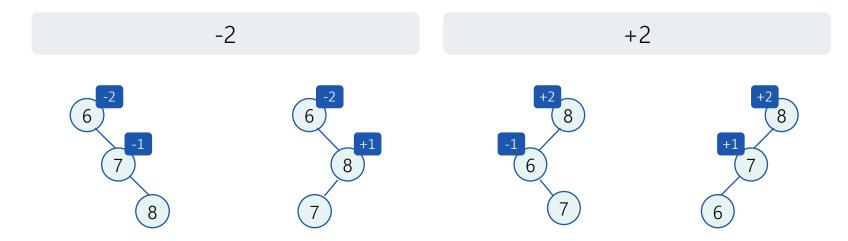
Part A











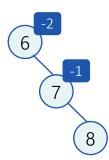
What is the "criminal" BF?

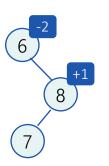
-2

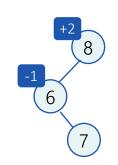
+2

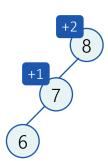
What is the BF of the **right** son?

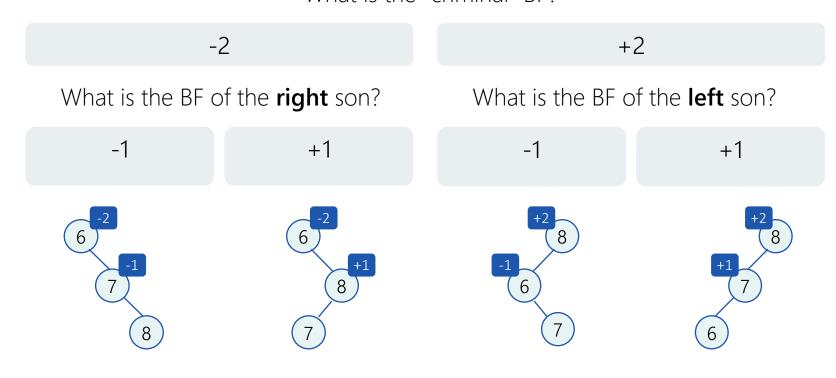
What is the BF of the **left** son?

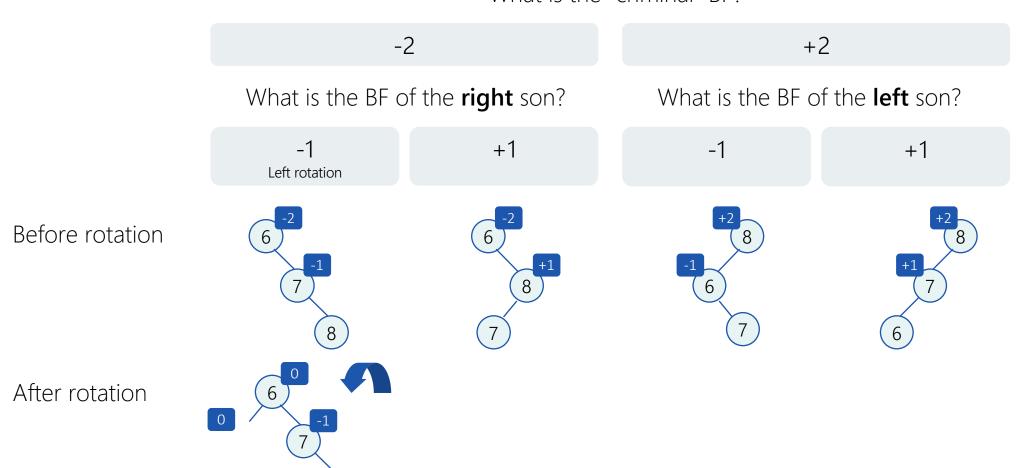


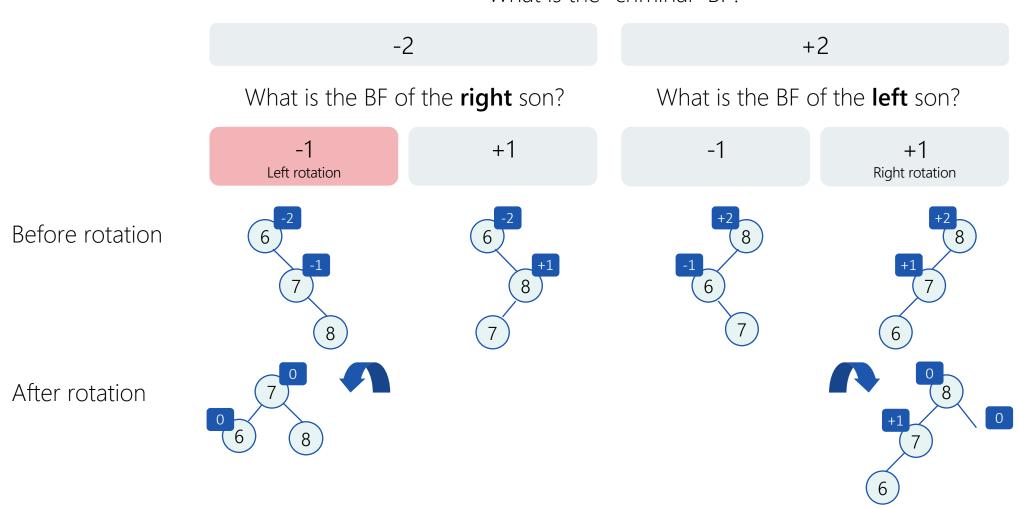


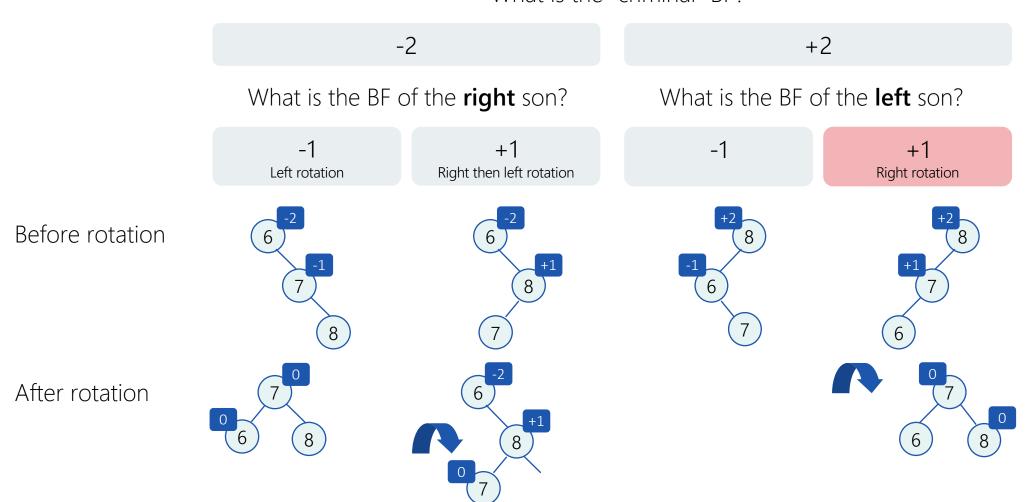


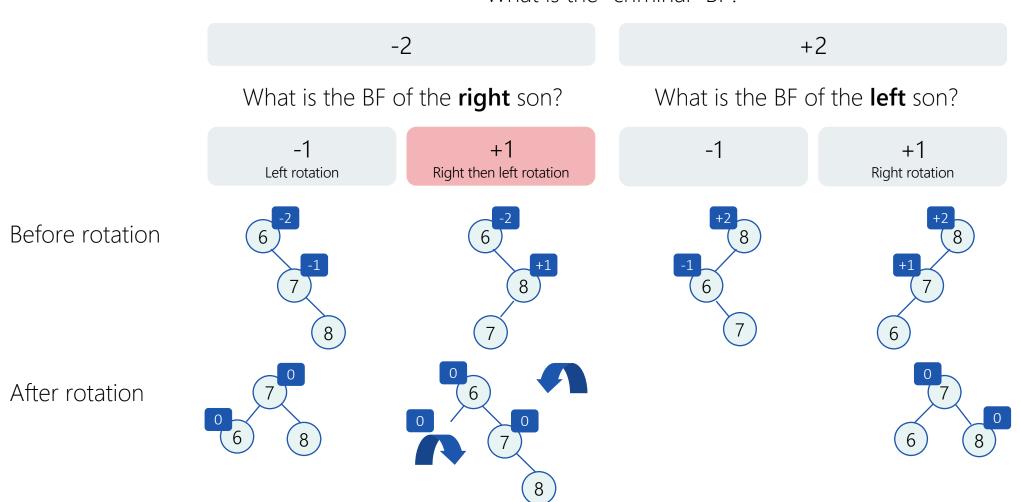


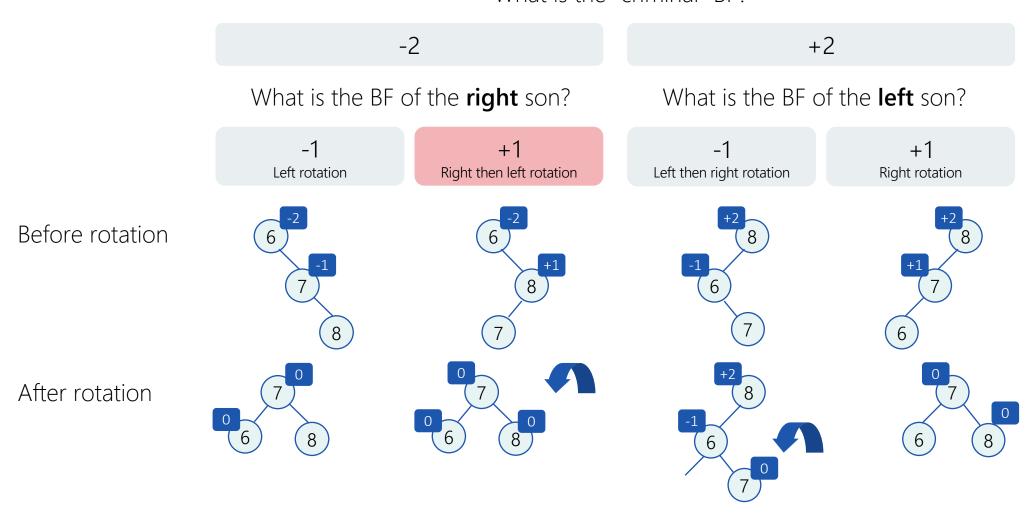


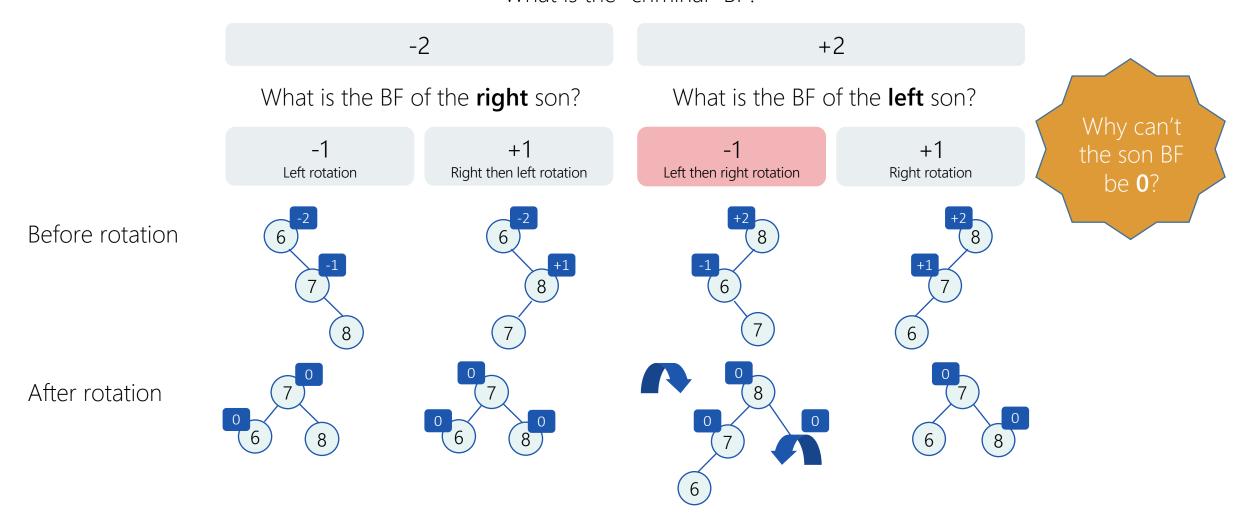








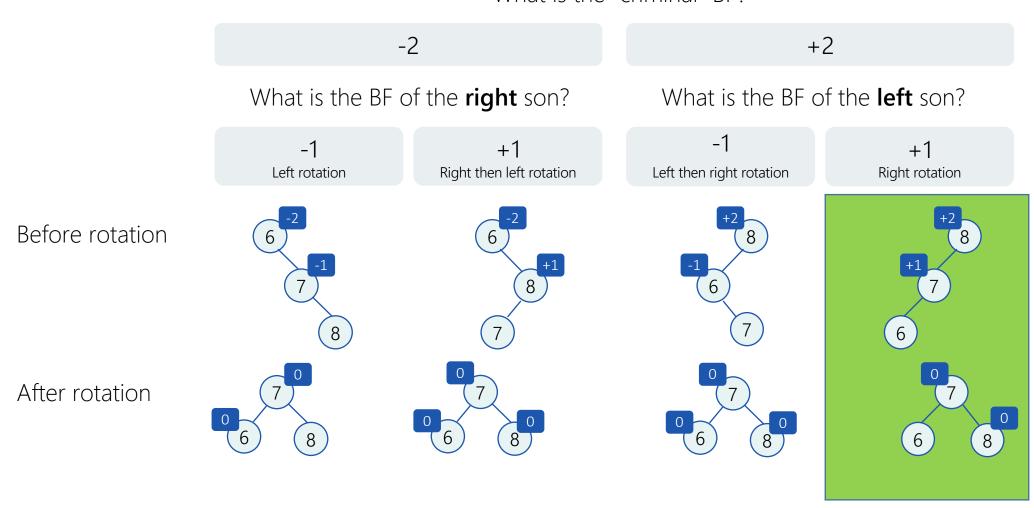




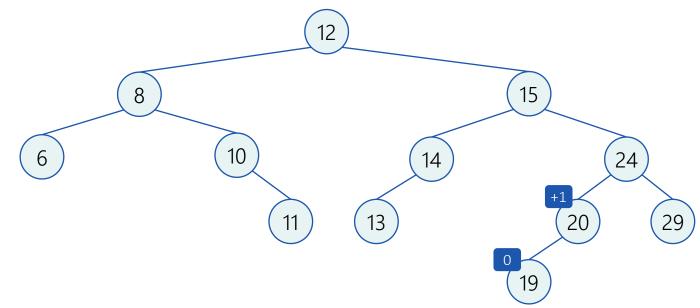
Rotations

Four Rotations to Rule Them All

Part B



Right Rotation Example



Before insertion

Insert 18

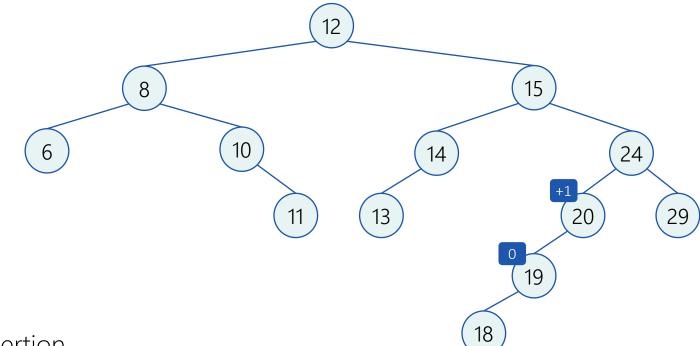
Temporarily after insertion

Rotate Right

After Rotation

Interactive (https://visualgo.net)

Right Rotation Example



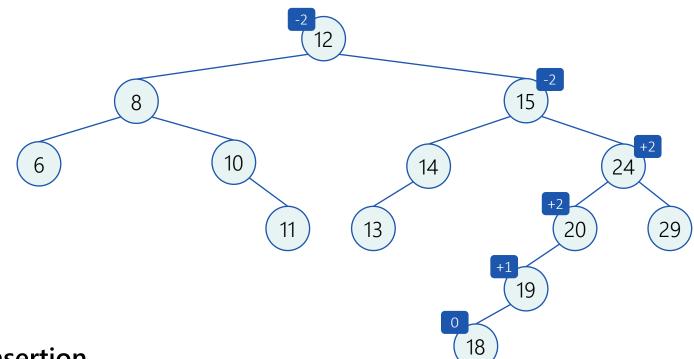
Before insertion

Insert 18

Temporarily after insertion

Rotate Right

Right Rotation Example



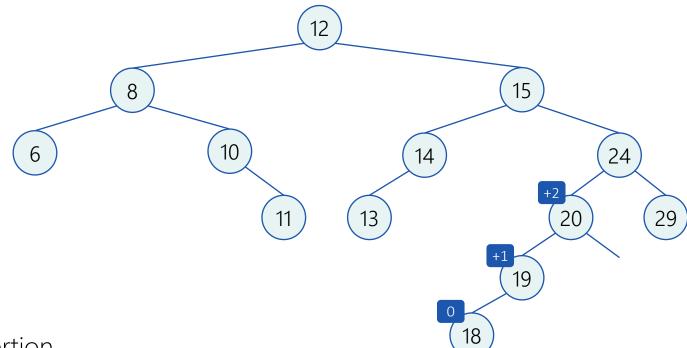
Before insertion

Insert 18

Temporarily after insertion

Rotate Right

Right Rotation Example



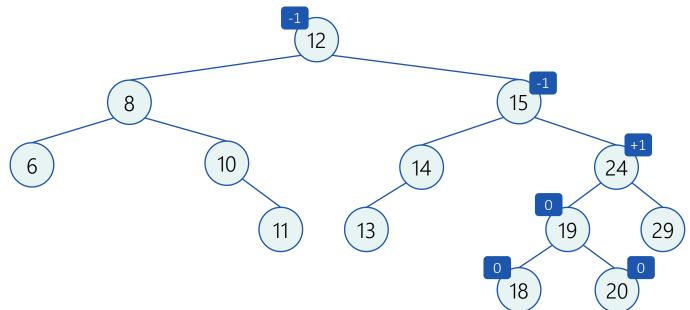
Before insertion

Insert 18

Temporarily after insertion

Rotate Right

Right Rotation Example

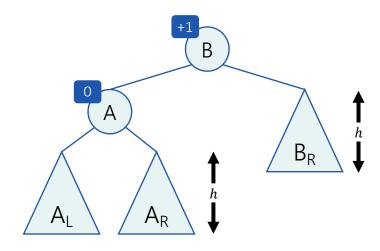


Before insertion

Insert 18

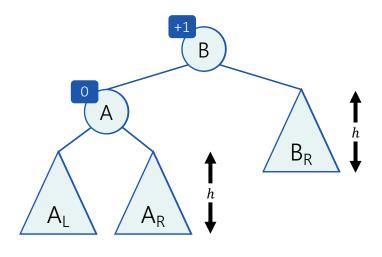
Temporarily after insertion

Rotate Right



Before insertion

Insert v
Temporarily after insertion

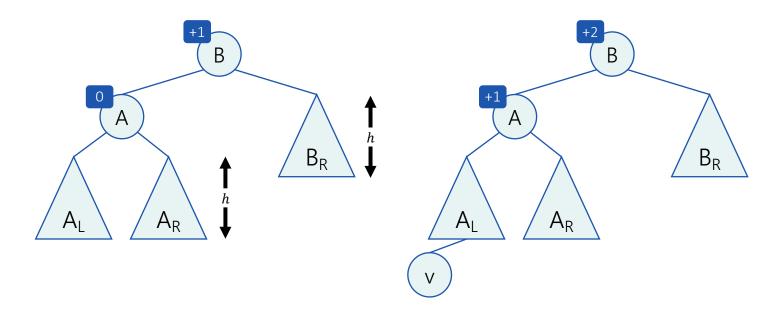


Before insertion



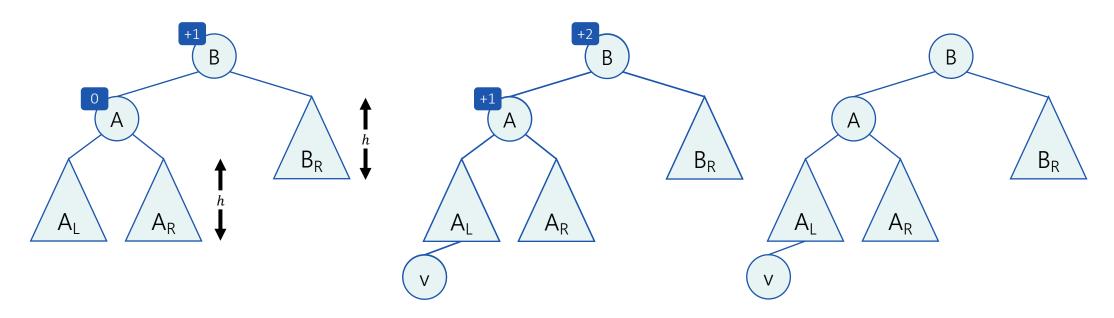
Insert v

Temporarily after insertion



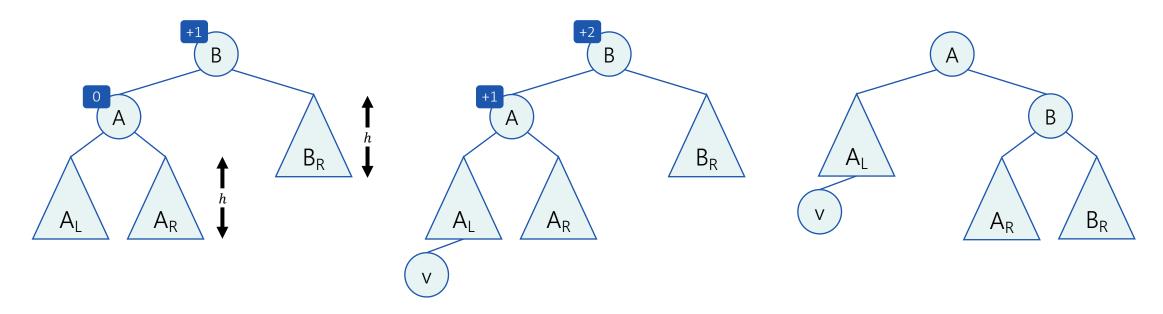
Before insertion

Insert v **Temporarily after insertion**



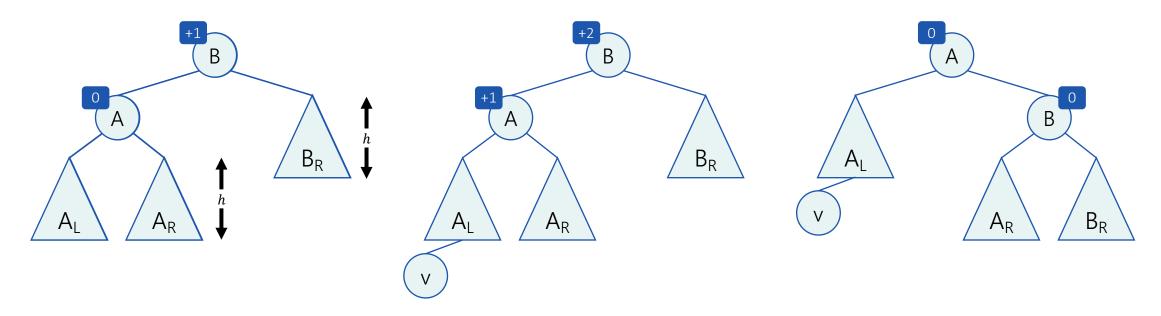
Before insertion

Insert v
Temporarily after insertion



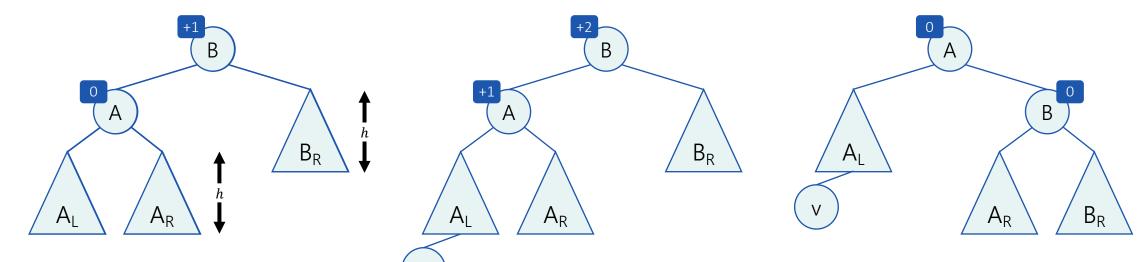
Before insertion

Insert v
Temporarily after insertion



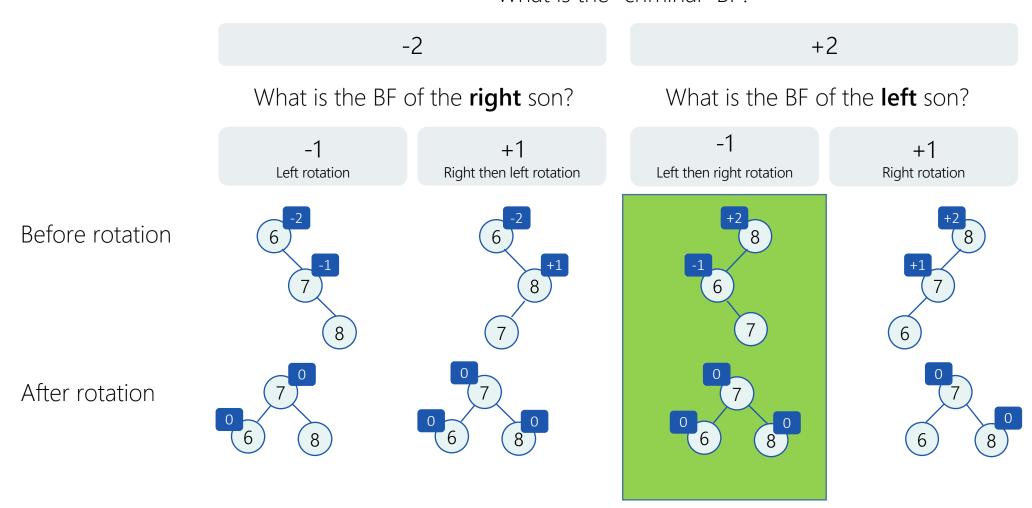
Before insertion

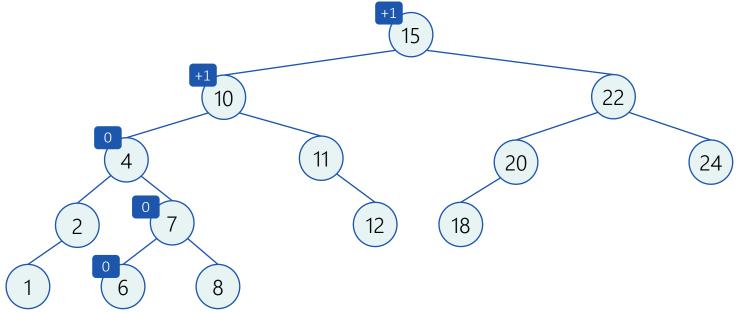
Insert v
Temporarily after insertion



- The search tree property is preserved
- The violation of balance was fixed in this subtree
- Left rotation is symmetric

- Pointers changed:
 - $B.left \leftarrow A.right$
 - $B.left.parent \leftarrow B$
 - $A.right \leftarrow B$
 - $A.parent \leftarrow B.parent$
 - $A.parent.left/right \leftarrow A$
 - $B.parent \leftarrow A$





Before insertion

Insert 5
Temporarily after insertion
Rotate left then right
After rotation

Interactive (https://visualgo.net)

Before insertion 1 6 8

5

15

22

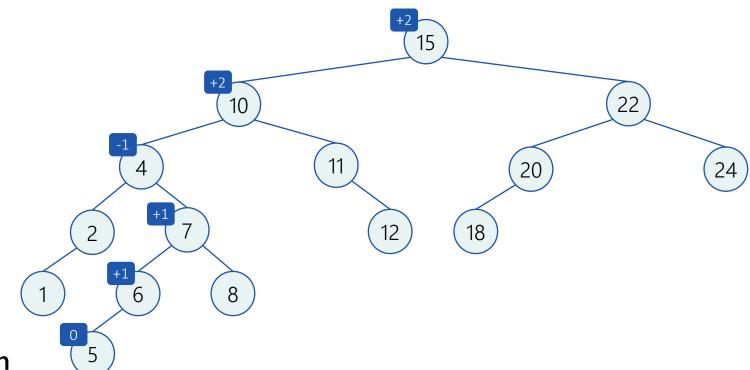
24

20

18

Insert 5

Temporarily after insertion Rotate left then right After rotation

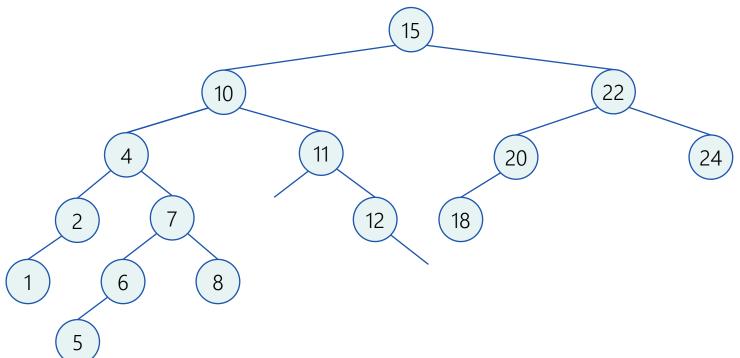


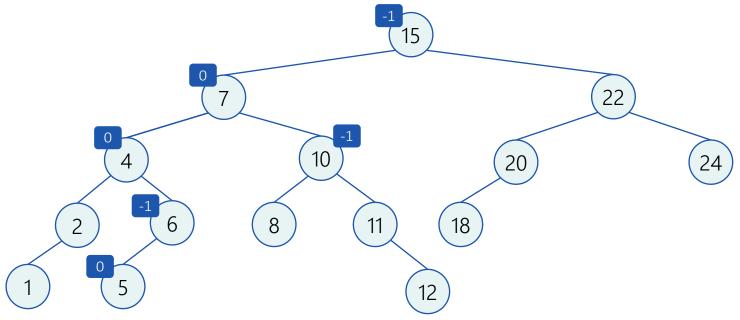
Before insertion Insert 5

Temporarily after insertion

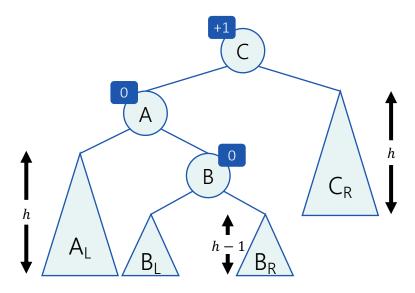
Rotate left then right

Before insertion
Insert 5
Temporarily after insertion
Rotate left then right



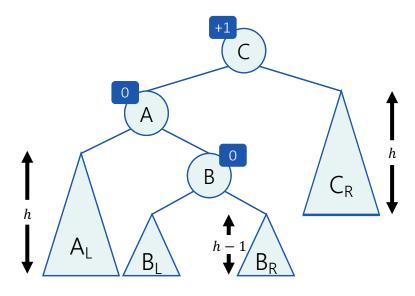


Before insertions
Insert 5
Temporarily after insertion
Rotate left then right



Before insertion

Insert v
Temporarily after insertion

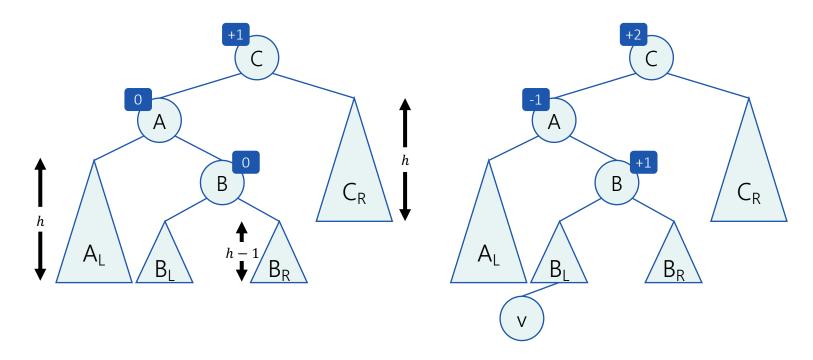


Before insertion



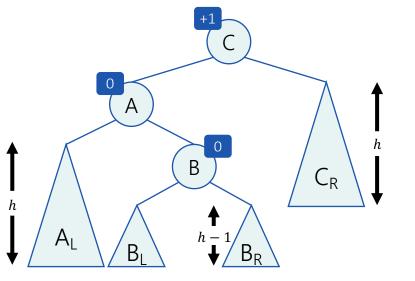
Insert v

Temporarily after insertion

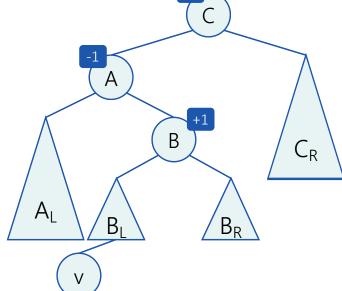


Before insertion

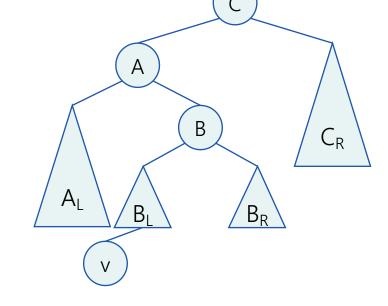
Insert v
Temporarily after insertion



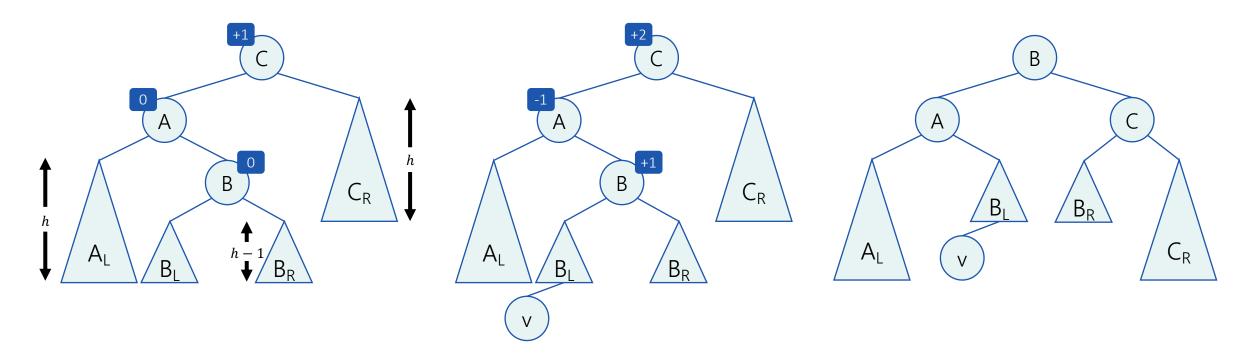
Before insertion



Insert v
Temporarily after insertion



Left Then Right Rotation

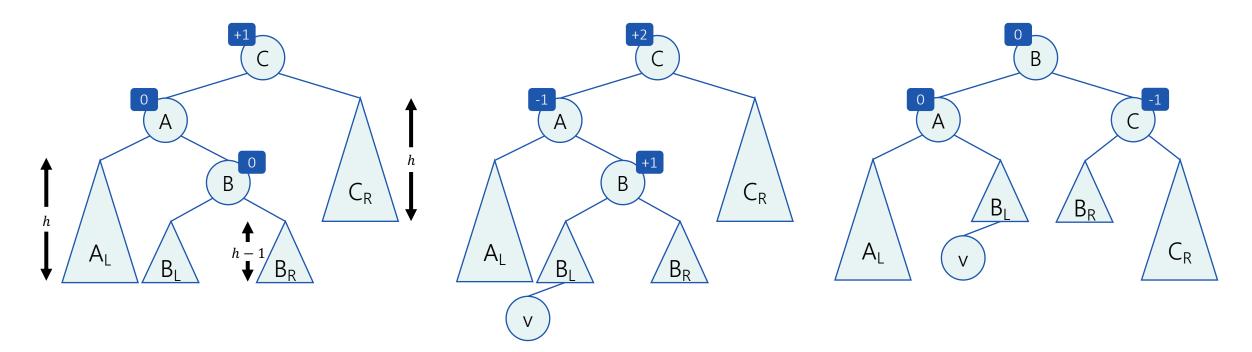


Before insertion

Insert v
Temporarily after insertion

Rotate left then right After rotation

Left Then Right Rotation

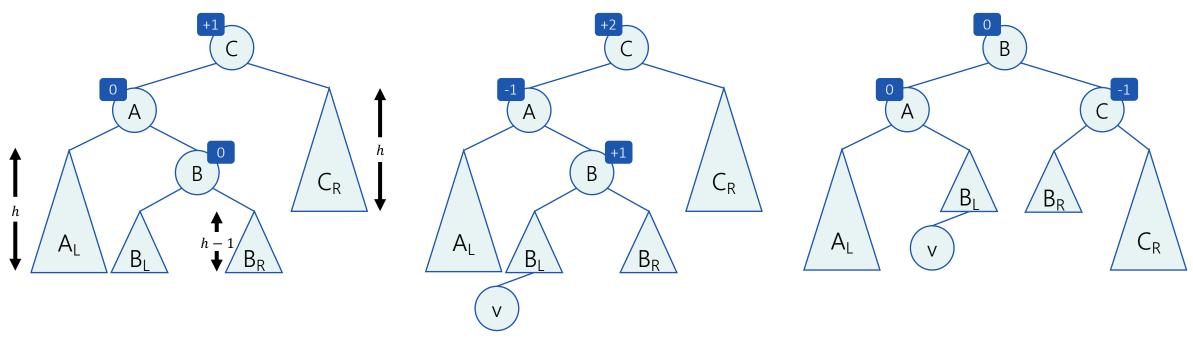


Before insertion

Insert v
Temporarily after insertion

Rotate left then right **After rotation**

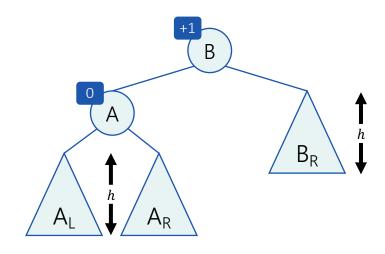
Left Then Right Rotation

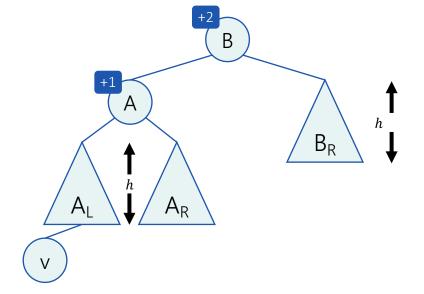


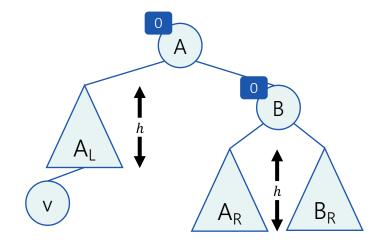
- The search tree property is preserved
- The violation of balance was fixed in this subtree
- Right then left rotation is symmetric

AVL Insertion: One Rotation At Most

Number of Rotations After Insertion Right Rotation (Left Rotation is symmetric):





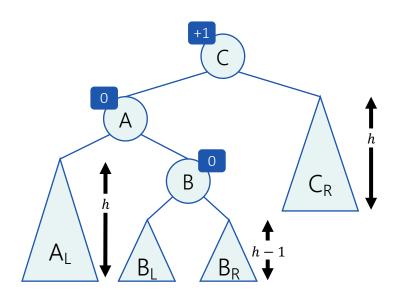


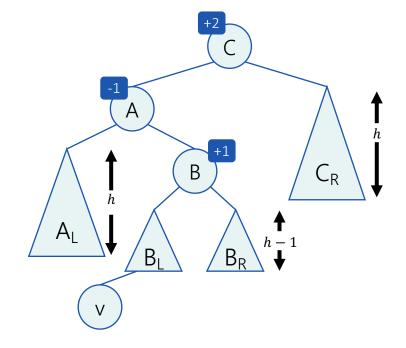
Before insertion height(B) = h + 2

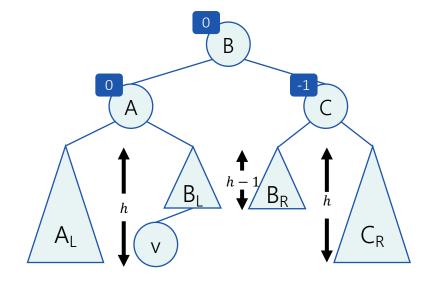
Right after insertion

After rotation
$$height(A) = h + 2$$

Number of Rotations After Insertion Left Then Right Rotation (Right Then Left is symmetric):







Before insertion height(C) = h + 2

Right after insertion

After rotation
$$height(B) = h + 2$$

Number of Rotations After Insertion

Conclusion:

After insertion, it takes one rotation at most in order to fix the tree.

Proof:

Rotation after insertion always restores the height of the sub-tree prior to the insertion.

The Insertion Algorithm The Algorithm

AVL-Insert(*T, z*)

- 1. insert z as usual (as in a BST)
- 2. let y be the parent of the inserted node.
- 3. while $y \neq Null$ do:
 - 3.1. compute $BF(y)^*$
 - 3.2. if |BF(y)| < 2 and y's height hasn't changed: terminate
 - 3.3. else if |BF(y)| < 2 and y's height changed: go back to stage 3 with y's parent
 - 3.4. else (|BF(y)| = 2): perform a rotation and go back to stage 3 with y's parent

^{*}Requires maintaining additional information at each node. We will refer to this topic later.

The Insertion Algorithm The Algorithm

AVL-Insert(*T, z*)

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 - 3.4. else (|BF(y)| = 2): perform a rotation and terminate

^{*}Requires maintaining additional information at each node. We will refer to this topic later.

Deletion From AVL

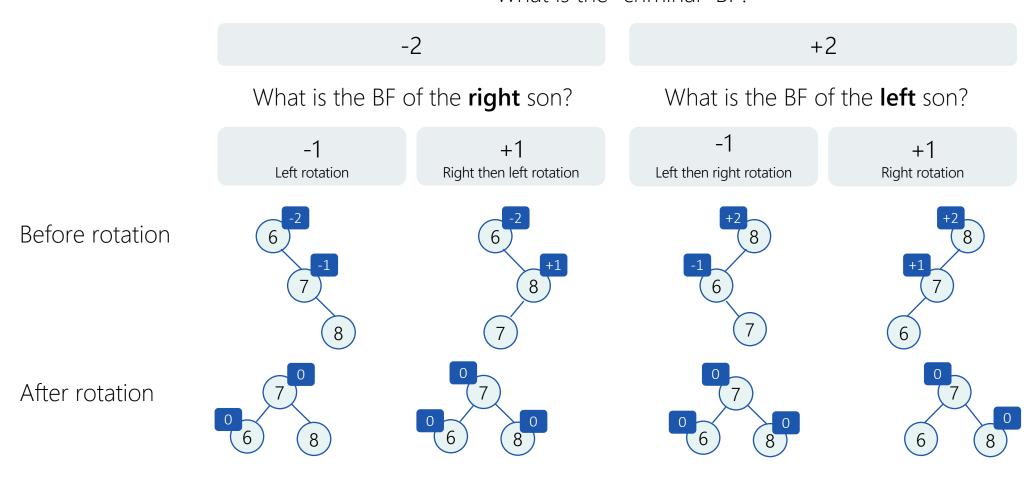
How to Keep It Balanced?

Fixing After Deletion Rotations

- Deletion may also cause balance factor violation
- "Criminals" may appear on the path from the deleted node to the root
 - Deleted node = physically deleted (not necessarily the element removed)
- The 4 types of rotations are also used here to fix the violation.

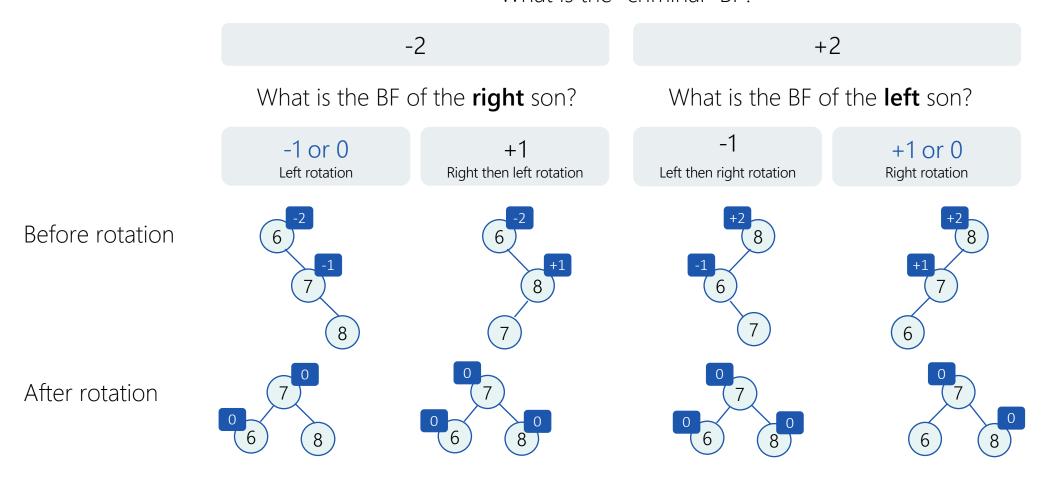
Fixing After Insertion Rotations

What is the "criminal" BF?

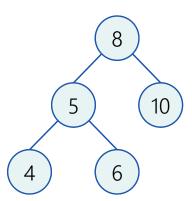


Fixing After Deletion Rotations

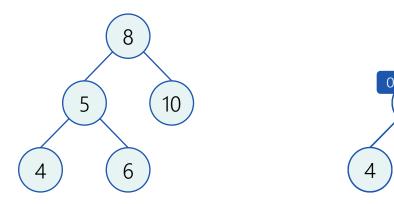
What is the "criminal" BF?



In deletion, there may be cases that cannot occur in insertion. For example: criminal with BF=+2 whose left son has BF=0:

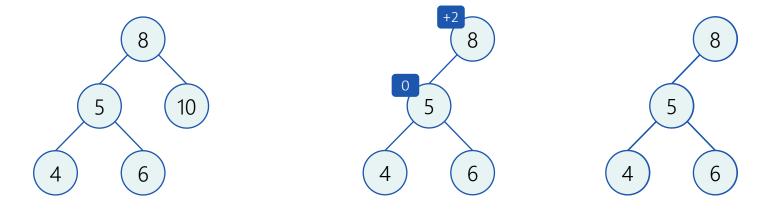


In deletion, there may be cases that cannot occur in insertion. For example: criminal with BF=+2 whose left son has BF=0:



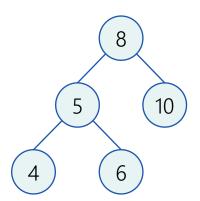
Delete 10Rotate right

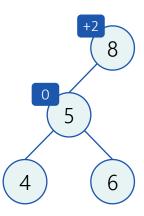
In deletion, there may be cases that cannot occur in insertion. For example: criminal with BF=+2 whose left son has BF=0:

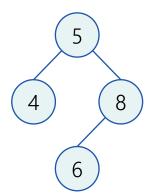


Delete 10 Rotate right

In deletion, there may be cases that cannot occur in insertion. For example: criminal with BF=+2 whose left son has BF=0:

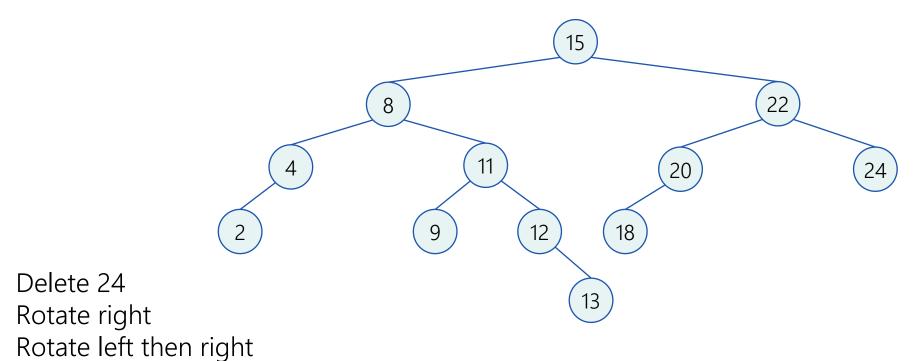




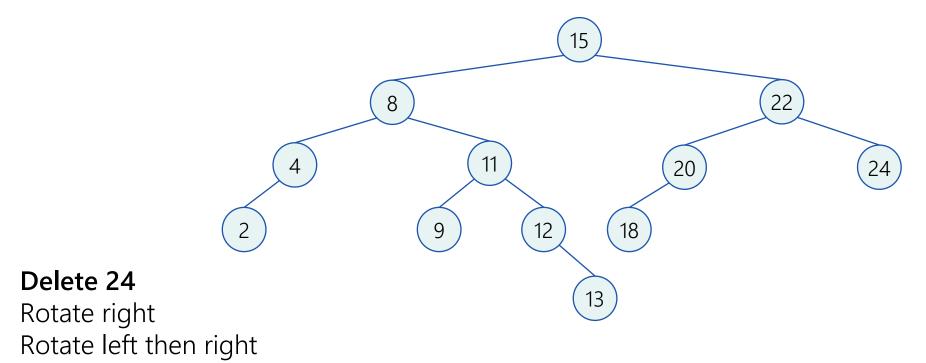


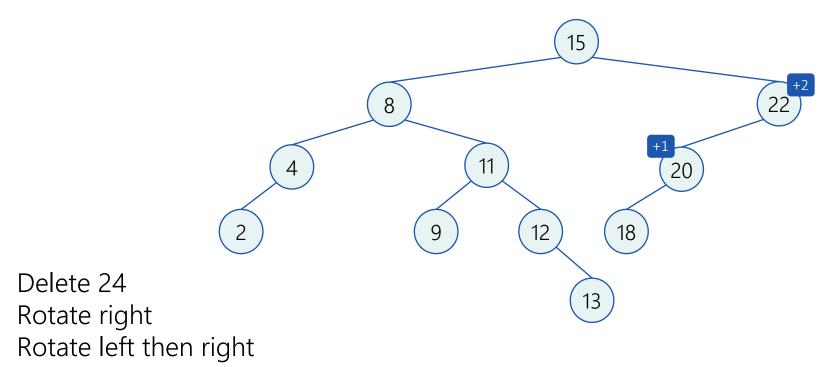
Delete 10 **Rotate right**

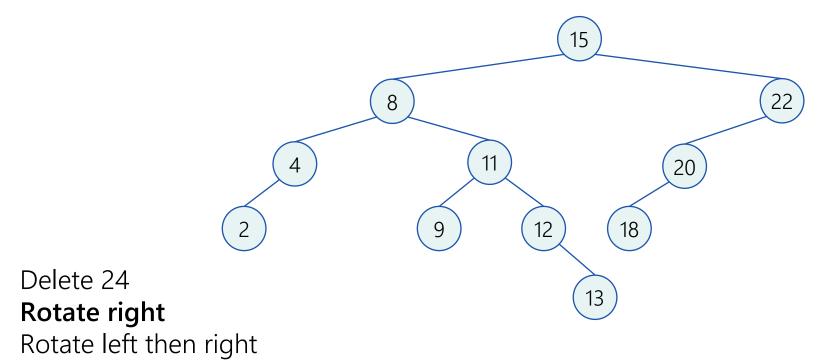
In deletion, more than one rotation is possible (one rotation may be performed at each level of the tree)

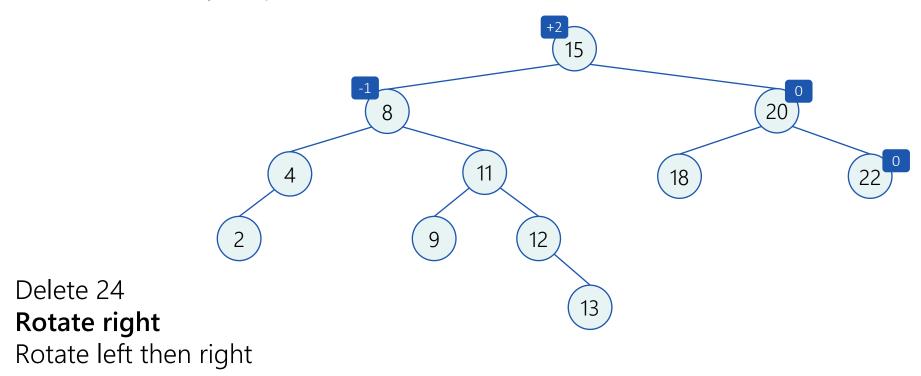


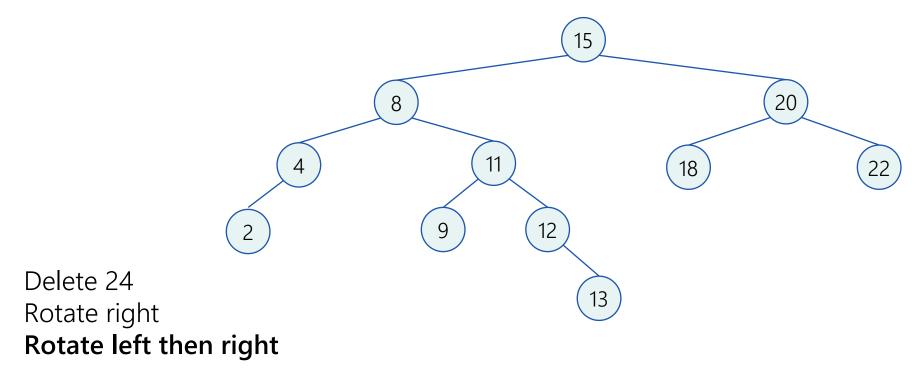
Interactive (https://visualgo.net)



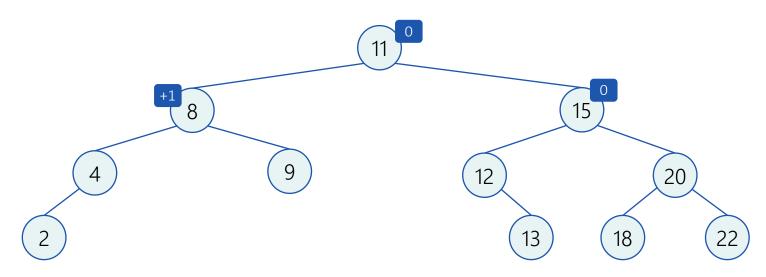








In deletion, more than one rotation is possible (one rotation may be performed at each level of the tree)



Delete 24
Rotate right
Rotate left then right

Fixing After Deletion The Algorithm

AVL-Delete(*T, z*)

- 1. delete z as usual (as in a BST).
- 2. Let y be the parent of the (physically) deleted node.
- 3. while $y \neq Null$ do:
 - 3.1. compute $BF(y)^*$
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 - 3.4. else (|BF(y)| = 2): perform a rotation and go back to stage 3 with y's parent

^{*}Requires maintaining additional information at each node. We will refer to this topic later.

The Deletion Algorithm Time Complexity

AVL-Delete(T, z)

- 1. Deleting from a BST
- 2. At most one rotation at each level

$$O(h+1)$$

$$O(h+1)$$

$$O(h+1) = O(\log n)$$

Recommended Animations on the Web

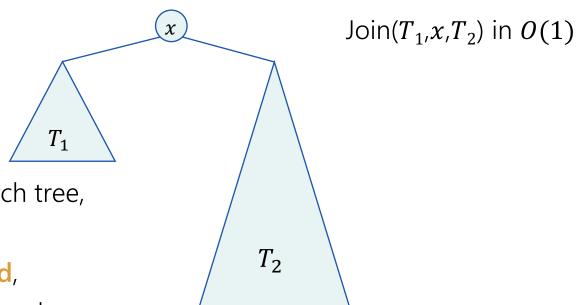
- https://people.ksp.sk/~kuko/gnarley-trees/Balance.html
 Explains rotations
- https://people.ksp.sk/~kuko/gnarley-trees/AVL.html
 Explains AVL, accompanied by a nice summary
- https://visualgo.net/en/bst?mode=AVL
 Explains AVL

Joining and Splitting AVL Trees

Joining Trees

Joining Two BST's

Suppose that for all nodes
$$x_1 \in T_1$$
 and $x_2 \in T_2$
 x_1 .key < x .key < x_2 .key



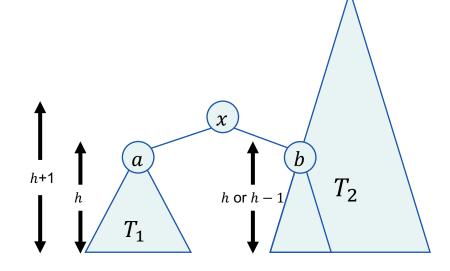
The tree formed is a valid search tree, but

may be **very unbalanced**, even if T_1 and T_2 are balanced

Joining Two AVL Trees Efficiently, Maintaining Balance

 $Join(T_1, x, T_2)$ when " $T_1 < x < T_2$ "

Assume $height(T_1) \leq height(T_2)$



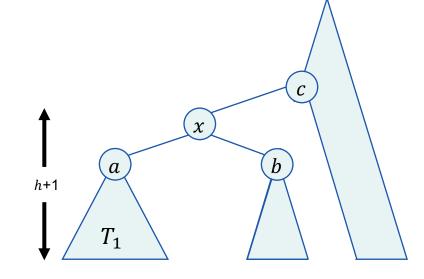
Idea: x.right will be a subtree of T_2 of similar height as T_1 Denote $height(T_1) = h$

b – first vertex on the left spine of T_2 with $height \leq h$

Joining Two AVL Trees Efficiently, Maintaining Balance

 $Join(T_1, x, T_2)$ when " $T_1 < x < T_2$ "

Assume $height(T_1) \leq height(T_2)$



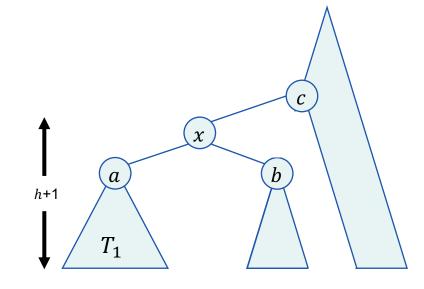
Attach x to b's former parent (denoted c)

Do rebalancing from x upwards, if needed (when?)

Joining Two AVL Trees Efficiently, Maintaining Balance

Join (T_1, x, T_2) when " $T_1 < x < T_2$ "

Assume $height(T_1) \leq height(T_2)$



 $O(\log n)$ time

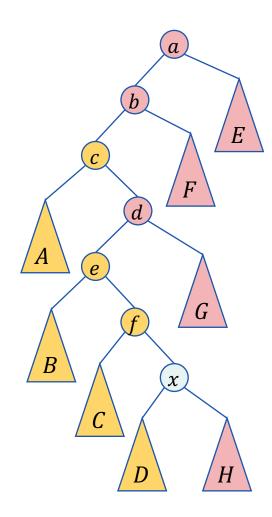
And even $O(height(T_2) - height(T_1) + 1)$ time

(if heights maintained explicitly, so we can **find b** while going **down**)

Splitting Trees

Splitting BST (by Joins)

Given a BST and a node x, we want to split the tree into T_1, T_2 such that " $T_1 < x < T_2$ "



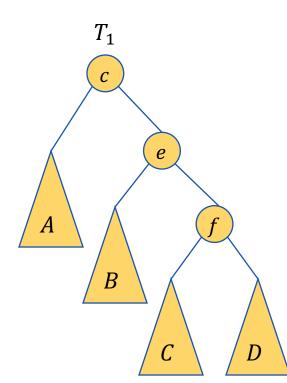
Splitting BST (by Joins)

Given a BST and a node x, we want to split the tree into T_1, T_2 such that " $T_1 < x < T_2$ "

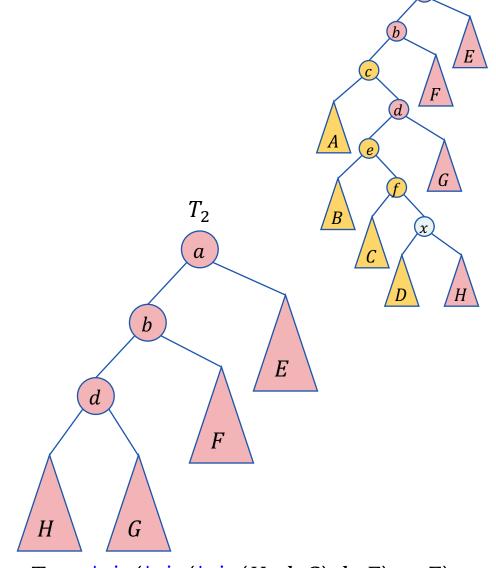
Time:

O(h) for BST

 $O(\log^2 n)$ for AVL (naïve analysis)



 $T_1 = Join(A, c, Join(B, e, Join(C, f, D)))$



 $T_2 = \text{Join}(\text{Join}(\text{Join}(H, d, G), b, F), a, E)$

Splitting AVL (by Efficient Joins) Tighter Analysis

Recall each join really takes only O(height difference+1)

To generate each of T_1 , T_2 ,

we need to make a telescopic join series: $(...((t_1,t_2),t_3),t_4),...,t_k)$

$$time = O\left(\sum_{i=2}^{k} |height(t_i) - height(join(t_1, ..., t_{i-1}))| + 1\right) = O(logn)$$