```
CODE:
#include <BitBool.h>
#include <OnewireKeypad.h>
#include <SPI.h>
#include <MFRC522.h>
#include <Servo.h>
#include<LiquidCrystal_I2C.h>
#define SS_PIN 10 //MOSI of RFID
#define RST_PIN 9 //RST of RFID
#define LED_DENIED_PIN 7
#define LED_ACCESS_PIN 6
#define sensorPin1 A2
#define sensorPin2 A3
int senval1=0;
int senval2=0;
int card1Balance = 2000;
int card2Balance = 400;
int due1=0;
int due2=0;
String num1, num2, card, card2;
int a, b;
char Key;
bool recharge = true;
```

```
LiquidCrystal_I2C lcd(0x3F, 16, 2);
MFRC522 mfrc522(SS_PIN, RST_PIN); // Create MFRC522 instance.
Servo myservo; //define servo name
int state=0;
void setup()
{
lcd.init();
 lcd.backlight();
 Serial.begin(9600); // Initiate a serial communication
 SPI.begin(); // Initiate SPI bus
 mfrc522.PCD_Init(); // Initiate MFRC522
 pinMode(sensorPin1, INPUT);
 pinMode(sensorPin2, INPUT);
 pinMode(LED_DENIED_PIN, OUTPUT);
 pinMode(LED_ACCESS_PIN, OUTPUT);
 myservo.attach(3); //servo pin
 myservo.write(90); //servo start position
 Serial.println();
 lcd.setCursor(1, 0);
lcd.print("Automatic Toll");
```

```
lcd.setCursor(2, 1);
lcd.print("Tax System");
delay(2000);
}
void loop()
{
// lcd.clear();
// lcd.setCursor(0, 0);
// lcd.print(" Welcome!!");
// delay(1000);
// lcd.clear();
// if(recharge==0)
// {
// reCharge();
//}
// else
// {
sensorRead();
rfid();
if(senval1==0)
 {
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print("Vehicle Detected");
  myservo.write(0);
  delay(1000);
  lcd.clear();
```

```
lcd.setCursor(0, 0);
 lcd.print("Scan your card");
 delay(1000);
}
else if(senval2==0 && state==1){
lcd.clear();
 lcd.setCursor(0,0);
 lcd.print("Have a safe");
 lcd.setCursor(0, 1);
 lcd.print("journey");
 myservo.write(90);
 delay(4000);
 myservo.write(0);
 delay(1000);
 lcd.clear();
 state=0;
}
else if(senval2==0 && state==0){
lcd.clear();
 lcd.setCursor(0,0);
 lcd.print("
              NOT");
 lcd.setCursor(0, 1);
 lcd.print(" ALLOWED");
 delay(1000);
 lcd.clear();
state=0;
}
```

```
//}
}
void sensorRead()
{
senval1 = digitalRead(sensorPin1);
senval2 = digitalRead(sensorPin2);
}
void rfid()
{
// Look for new cards
if ( ! mfrc522.PICC_IsNewCardPresent())
 {
  return;
 }
// Select one of the cards
if ( ! mfrc522.PICC_ReadCardSerial())
 {
  return;
 }
//Show UID on serial monitor
Serial.print("UID tag :");
 String content= "";
 byte letter;
for (byte i = 0; i < mfrc522.uid.size; i++)
 {
  Serial.print(mfrc522.uid.uidByte[i] < 0x10 ? " 0" : " ");</pre>
```

```
Serial.print(mfrc522.uid.uidByte[i], HEX);
  content.concat(String(mfrc522.uid.uidByte[i] < 0x10 ? " 0" : " "));</pre>
  content.concat(String(mfrc522.uid.uidByte[i], HEX));
 }
 Serial.println();
 Serial.print("Message : ");
 content.toUpperCase();
 if (content.substring(1) == "1C BA 59 4A") //change here the UID of the card/cards that you
want to give access
{
   digitalWrite(LED ACCESS PIN, HIGH);
   lcd.clear();
   lcd.setCursor(0, 0);
   lcd.print("Authorized");
   lcd.setCursor(0, 1);
   lcd.print("Vehicle");
   delay(1000);
   lcd.clear();
  if(card1Balance>=500)
   card1Balance = card1Balance-500;
   lcdPrint();
   lcd.setCursor(9, 1);
   lcd.print(card1Balance);
   //delay(1000);
   //lcd.clear();
   state=1;
```

```
}
 else
{
  card = content.substring(1);
  LcdPrint();
  //lcd.setCursor(9, 1);
  due1+=500;
  lcd.print(card1Balance);
  lcd.print(" Tk");
  // delay(1000);
  // lcd.clear();
  lcd.setCursor(0, 1);
  lcd.print("Due: ");
  lcd.print(due1);
  lcd.print(" Tk");
  //delay(2000);
 // lcd.clear();
  state = 1;
}
}
else if(content.substring(1) == "33 9E 20 0F")
{
 digitalWrite(LED_ACCESS_PIN, HIGH);
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print("Authorized");
  lcd.setCursor(0, 1);
```

```
lcd.print("Vehicle");
 delay(1000);
 lcd.clear();
if(card2Balance>=500)
{
 card2Balance = card2Balance-500;
 lcdPrint();
 due2+=500;
 lcd.setCursor(9, 1);
 lcd.print(card2Balance);
 //delay(1000);
 //lcd.clear();
 state=1;
}
else
{
 card = content.substring(1);
 due2+=500;
 LcdPrint();
 //lcd.setCursor(9, 1);
 //ekhaneeeeeeeee
 lcd.print(card2Balance);
 lcd.print(" Tk");
 // delay(1000);
 // lcd.clear();
 lcd.setCursor(0, 1);
 lcd.print("Due: ");
```

```
lcd.print(due2);
   lcd.print(" Tk");
  // delay(1000);
   //lcd.clear();
   state = 1;
  }
 }
else{
  Serial.println(" Access denied");
  digitalWrite(LED_DENIED_PIN, HIGH);
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print("Access denied..");
  delay(1000);
  lcd.clear();
  state=0;
}
}
void lcdPrint()
{
lcd.clear();
lcd.setCursor(0, 0);
lcd.print(" Successfully");
lcd.setCursor(0, 1);
```

```
lcd.print(" paid your bill");
 delay(2000);
 lcd.clear();
lcd.setCursor(0, 0);
lcd.print("Your Remaining");
lcd.setCursor(0, 1);
lcd.print("Balance: ");
}
void LcdPrint()
{
lcd.clear();
lcd.setCursor(0, 0);
lcd.print(" Your balance");
lcd.setCursor(0, 1);
lcd.print(" is insufficent");
 delay(2000);
 lcd.clear();
lcd.setCursor(0, 0);
lcd.print("Due Added!!");
lcd.setCursor(0, 1);
lcd.print("to your account");
 delay(2000);
lcd.clear();
lcd.setCursor(0, 0);
lcd.print("Balance: ");
}
```