Class 27

Introduction

- two of the most fundamental concepts in computer science are, given an array of values:
 - search through the values to see if a specific value is present and, if so, where
 - sort the values in nondecreasing order

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Introduction

- two of the most fundamental concepts in computer science are, given an array of values:
 - search through the values to see if a specific value is present and, if so, where
 - sort the values in nondecreasing order
- as a computer scientist, you must be able to understand and program several different algorithms for each of these tasks
- in all of these slides, "array" is a generic term
- it means either an old-fashioned C-array or a modern STL vector

- an array that contains an arbitrary number of values
- each value is in a specific array location, but the values are not sorted

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- search for the value 11
- do a comparison on 17, 23, 5, 11 (4 comparisons)
- return 3 (the position where 11 was found)
- search for the value 7
- do comparisons on 17, 23, 5, 11, 2, 29, 3 (7 comparisons)
- return a not-found indicator



Linear Search

Program 8-1, page 464, a function to do this

```
int linearSearch(const int arr[], int size, int value);
```

- up to size elements of the array arr are searched for the existence of value
- if value is found within the first size elements of arr, the first position where value is encountered is returned by the function
- if value is not found, the sentinel value -1 is returned

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- if value is found within the first size elements of arr, the first position where value is encountered is returned by the function
- if value is not found, the sentinel value -1 is returned
- the search is called linear search because the algorithm searches along the line of array elements, one by one, starting at the beginning, trying to find value

Problems

- there are several problems with Gaddis' approach
- the biggest one is that none of his int data types will be accepted by a modern compiler like clang
- the data type for a size is size_t, and size_t is an unsigned integer; thus, it is impossible to return -1 as a sentinel value for the not-found condition

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- the data type for a size is size_t, and size_t is an unsigned integer; thus, it is impossible to return -1 as a sentinel value for the not-found condition
- a solution to this problem is to return the size of the array as the not-found sentinel value
- in an array of size, say 10, the largest valid index is 9
- if the searched-for value is not found, we return 10, which is not a valid index, indicating not-found
- look at the complete program, using a vector: program_8_1_modified.cpp



Notice

- several things to note in the modified program:
 - the return type of the function is size_t
 - the index and position are also of type size_t
 - there is no parameter for size because a vector knows how big it is

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 - 3. repeat step 2 10,000 times

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 - 1. put 1,000 random values, chosen from 0 10,000, into a vector
 - 2. at random, pick a value in the range 0 10,000 and
 - 2.1 see if it is in the vector or not
 - 2.2 count how many comparisons it takes to find out
 - 3. repeat step 2 10,000 times
 - 4. calculate the average number of comparisons from step 2

results:

```
Total hits: 930 Total misses: 9070
Minimum comparisons: 1 Maximum comparisons: 1000
Average number of comparisons: 954.747
```

- with 1,000 random values from 0 to 10,000
- the average number of comparisons is about 955
- have to search almost the entire array almost every time

Linear Search

Linear Search Pros

- very easy algorithm to understand
- easy algorithm to code correctly
- the only practical algorithm for unsorted values

Linear Search Cons

- inefficient for sorted values
- must examine n/2 elements on average for a value that is in the array
- must examine all n elements for a value not in the array

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Searching a Sorted List

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Searching a Sorted List

- linear search works perfectly on an unsorted array of values
- for unsorted values, it is the only practical searching algorithm
- linear search also works perfectly on a sorted array of values
- however, is it not the only search algorithm for sorted values
- furthermore, it is not a even a good algorithm in this case

Enhanced Linear Search

- if the elements of the array are sorted, we can do much better
- we can stop when any of three conditions is true:
 - 1. we find the item
 - 2. we reach the end of the list
 - we reach an element bigger than the element we're searching for

2	3	5	11	27	23	29
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2 3 5 11 27 23 29

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- search for the value 11
- do a comparison on 2, 3, 5, 11 (4 comparisons)
- return 3 (the position where 11 was found)
- search for the value 12
- do comparisons on 2, 3, 5, 11, 27 (just 5 comparisons)
- return a not-found indicator



2	3	5	11	17	23	29
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1. divide the range of elements to search into 3:

2	3	5	11	17	23	29
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 - 1.2 the elements to the **left** of middle
 - 1.3 the elements to the right of middle
- 2. if the range of elements is empty, return not-found sentinel



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- 3. else if the searched-for value is the middle element, you've found it and you're done



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- 5. else repeat step 1 on the right half

2	3	5	11	17	23	29
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• search for 11

2	3	5	11	17	23	29
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- search for 11
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- search for 11
- do a comparison on 11 (1 comparison)
- return 3 (the position where 11 was found) done
- search for 7

2	3	5	11	17	23	29
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- search for 11
- do a comparison on 11 (1 comparison)
- return 3 (the position where 11 was found) done
- search for 7
- do a comparison on 11, 3, 5 (3 comparisons)

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- search for 11
- do a comparison on 11 (1 comparison)
- return 3 (the position where 11 was found) done
- search for 7
- do a comparison on 11, 3, 5 (3 comparisons)
- report not-found done

Binary Search Implementation

- as with linear search, Gaddis' implementation won't compile on clang
- see program_8_2_modified.cpp

- do the same simulation with binary search as with linear search
- 10,000 times, search for a random number 0 1,000
- results:

Total hits: 971 Total misses: 9029

Minimum comparisons: 1 Maximum comparisons: 10

Average number of comparisons: 9.8768

remember the linear results:

Total hits: 930 Total misses: 9070

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Average number of comparisons: 954.747

- on average linear search takes a hundred times as many steps as binary search!
- binary search never takes more than ten comparisons



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- how many steps does it take to repeatedly divide a number by 2 until you get to zero?

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- binary search also starts with a search space of size n
- with each comparison, the search space decreases by half
- how many steps does it take to repeatedly divide a number by 2 until you get to zero?
- the term for this is logarithm

Logarithms

- logarithms are particularly important in algorithm analysis
- computer scientists deal mainly with base-2 logarithms
- the simplest working definition of a base-2 logarithm is

Base-2 Logarithm

How many times can you divide a number n by 2 using integer division before the result is 1 or 0?

- the answer to this question is approximately the base-2 logarithm of n
- you can estimate base-2 logarithms directly from the powers of 2 table

Powers of 2

you should learn all the powers of 2 from 0 to 10

$$2^{0} = 1$$
 $2^{1} = 2$
 $2^{2} = 4$
 $2^{3} = 8$
 $2^{4} = 16$
 $2^{5} = 32$
 $2^{6} = 64$
 $2^{7} = 128$
 $2^{8} = 256$
 $2^{9} = 512$
 $2^{10} = 1024$

- remember the simulation results searching in an array with 1,000 elements
- the most comparisons ever needed was 10
- the base-2 logarithm of 1,000 is approximately 10
- the number of comparisons needed for binary search for an array of size n is at most log₂ n

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- the most comparisons ever needed was 10
- the base-2 logarithm of 1,000 is approximately 10
- the number of comparisons needed for binary search for an array of size n is at most log₂ n
- compare this to linear search, which needs at most 1,000 comparisons for a 1,000-element array

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- requires at most log₂ n comparisons
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Binary Search Cons

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clearly, sorting is an issue, and we turn to that next

Binary Search Cons

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