Milestone 2

Berechnung eines passiven Skalars mit Hilfe der Finiten Volumen Methode (FVM)

(Instationär, Konvektion, Diffusion, Strömungsfeld bekannt)

Bilanzgleichungen

- Nicht konservativ

$$\rho\frac{\partial\phi}{\partial t}+\rho\vec{v}\cdot\vec{\nabla}\phi=\vec{\nabla}\cdot(a\vec{\nabla}\phi)+s$$

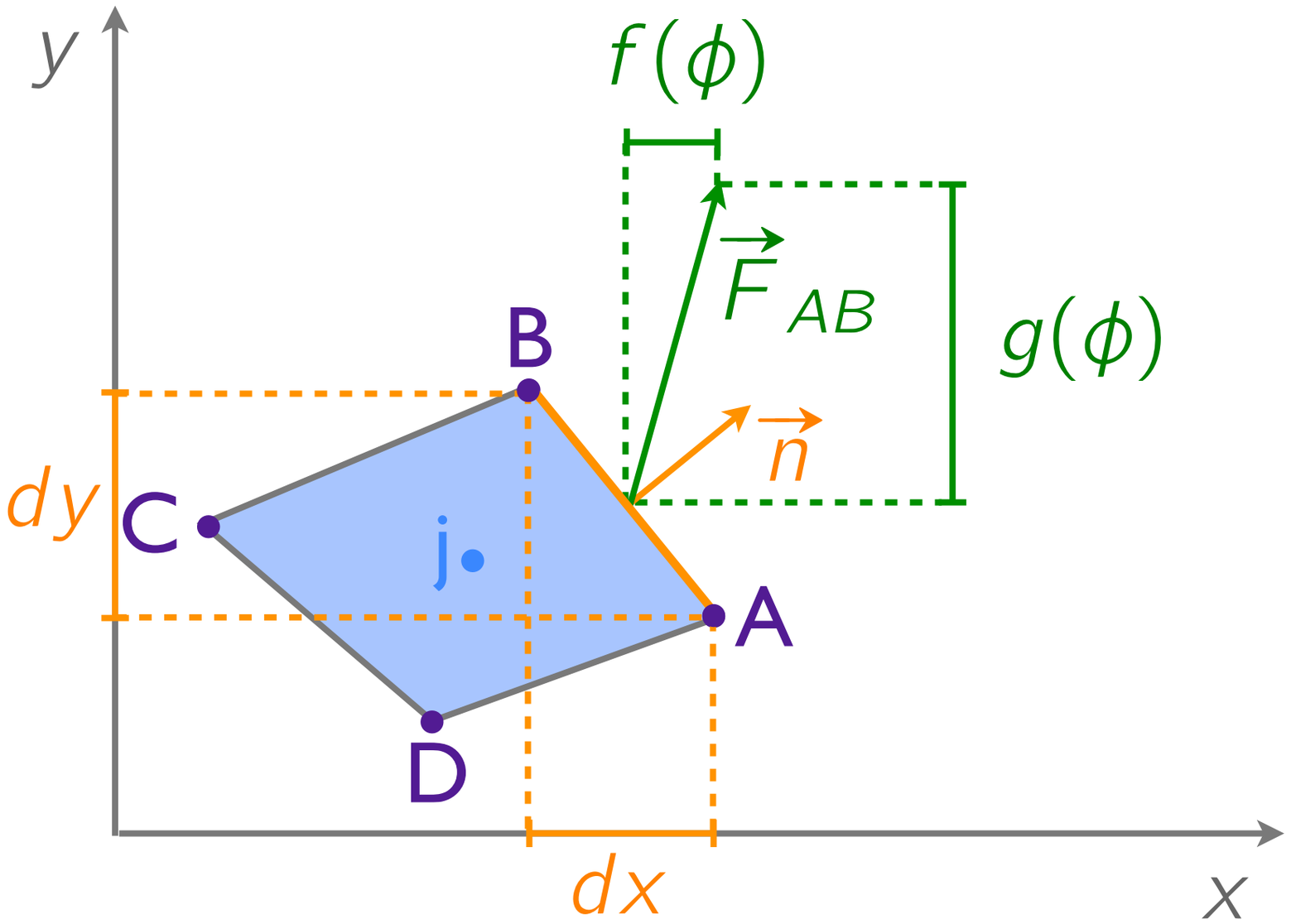
- Konservativ

$$\frac{\partial}{\partial t}\int_{\Omega}\rho\phi dV+\oint_{\partial\Omega}\vec{F}(\phi)\cdot\overrightarrow{dA}=\int_{\Omega}s dV$$

- Für finites Volumen *j*:

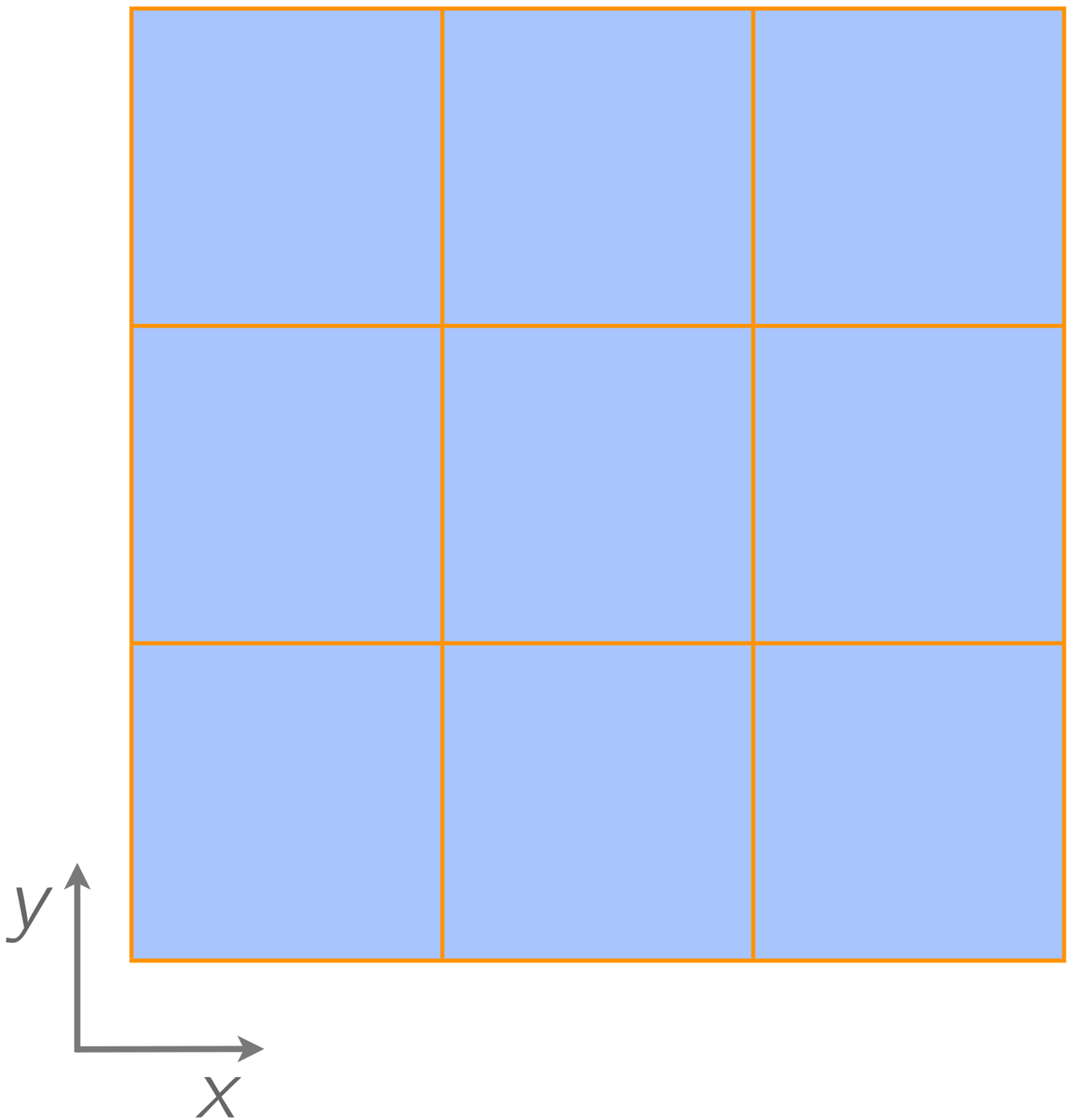
$$\frac{\partial}{\partial t}(\rho_j\phi_j\Delta V_j)+\sum_{f=1}^{n_{\text{faces}}}\vec{F}_f(\phi)\cdot\overrightarrow{dA_f}=s_j\Delta V_j$$

Der Flussvektor $\vec{F}(\phi)$



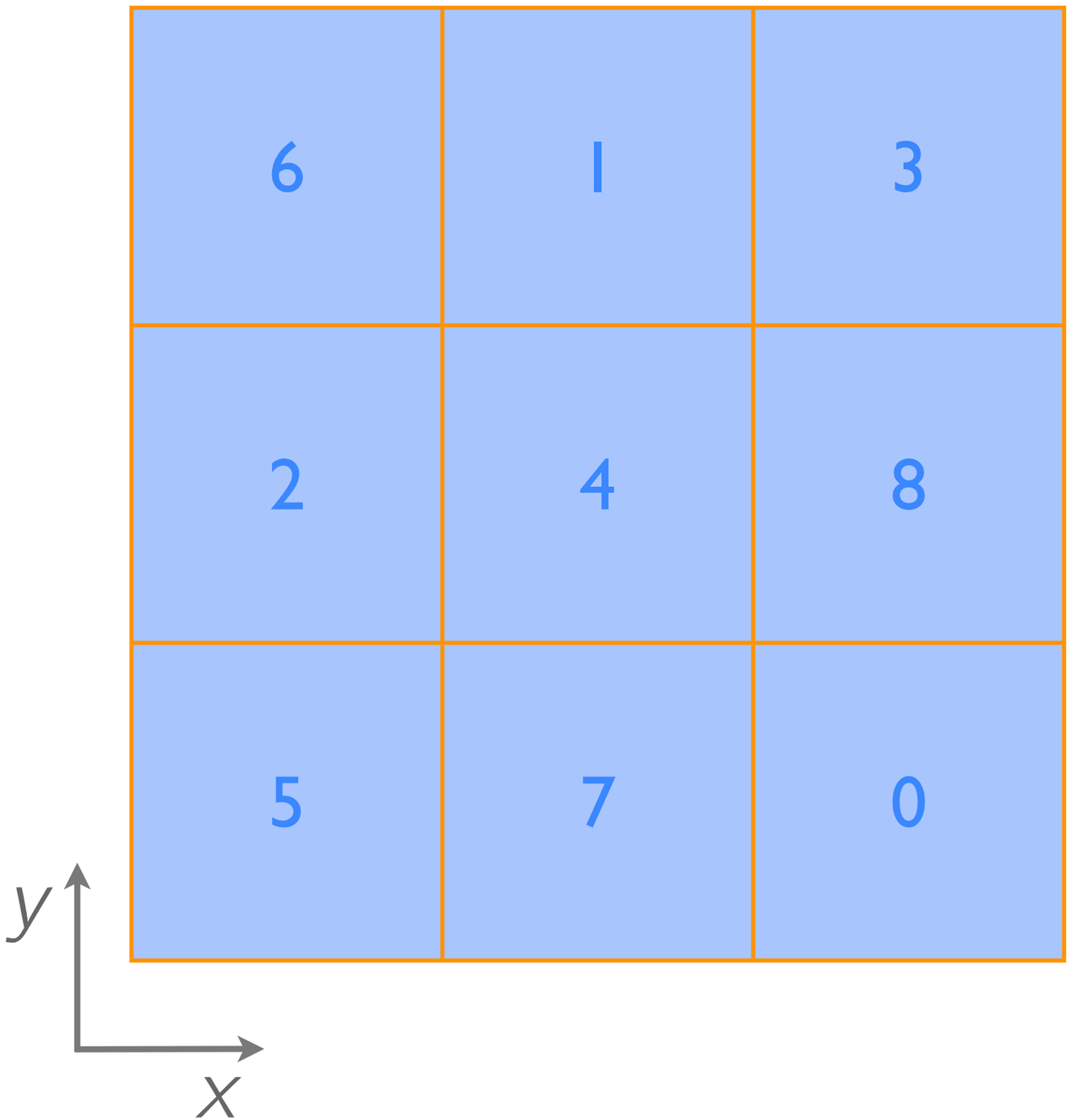
$$\vec{F}_{AB}(\phi) \cdot \overrightarrow{d\vec{A}} = f(\phi)\Delta y - g(\phi)\Delta x$$

Datenstruktur



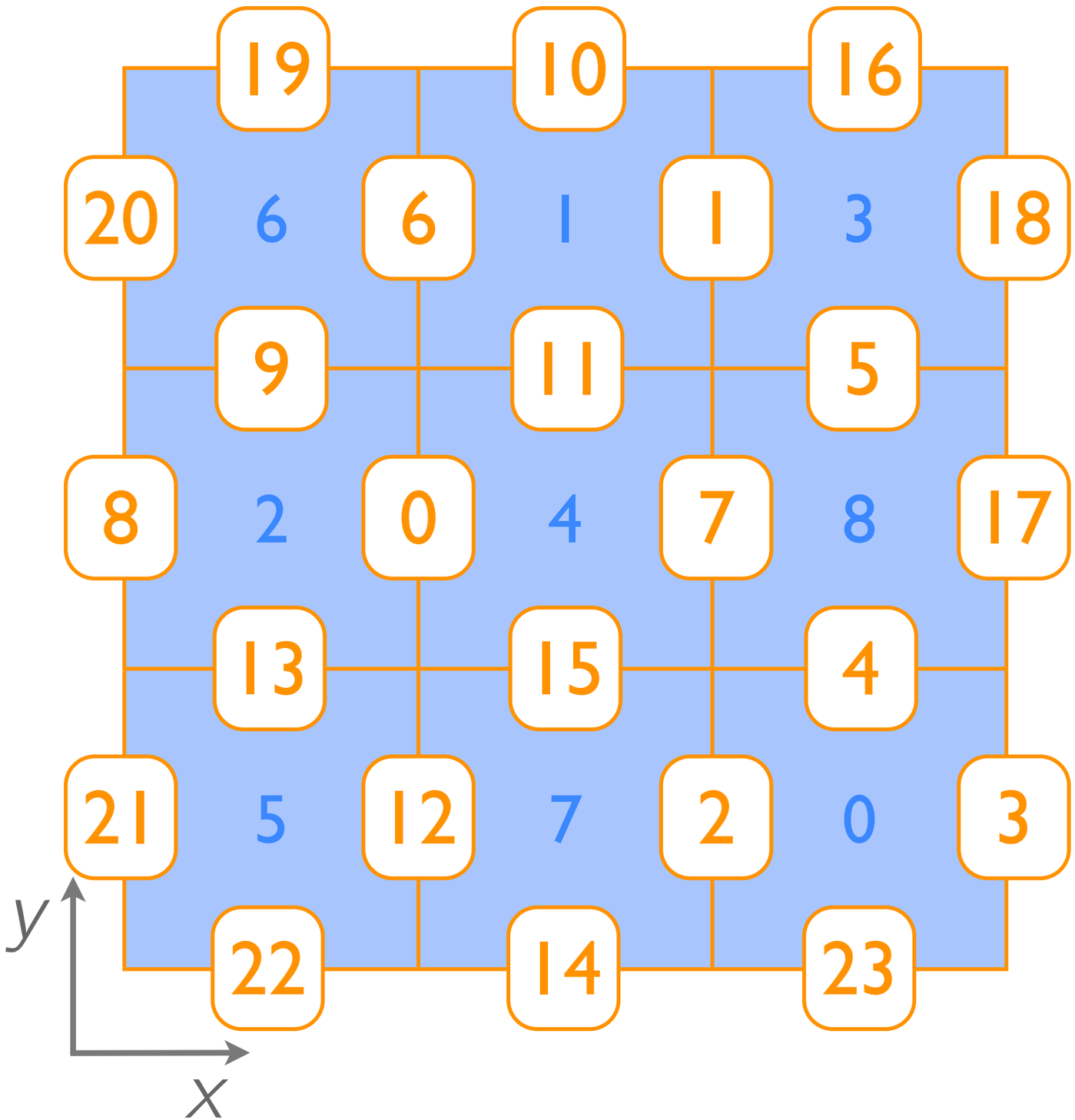

```
struct sData{

};
```

Datenstruktur



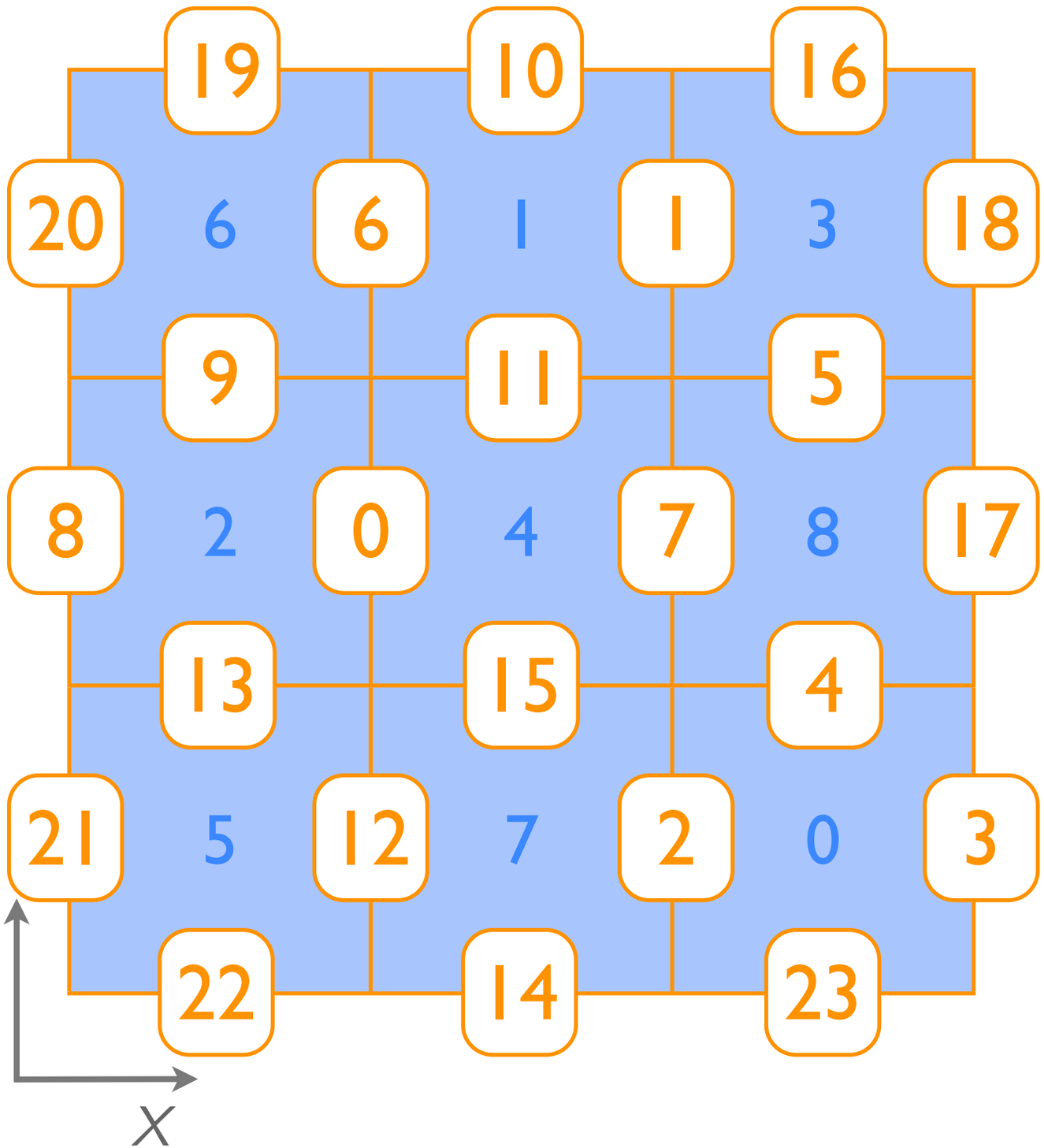

```
struct sData{
        sCell* cells;

};
struct sCell{
        int id;
        double xy[2];

};
```

Datenstruktur



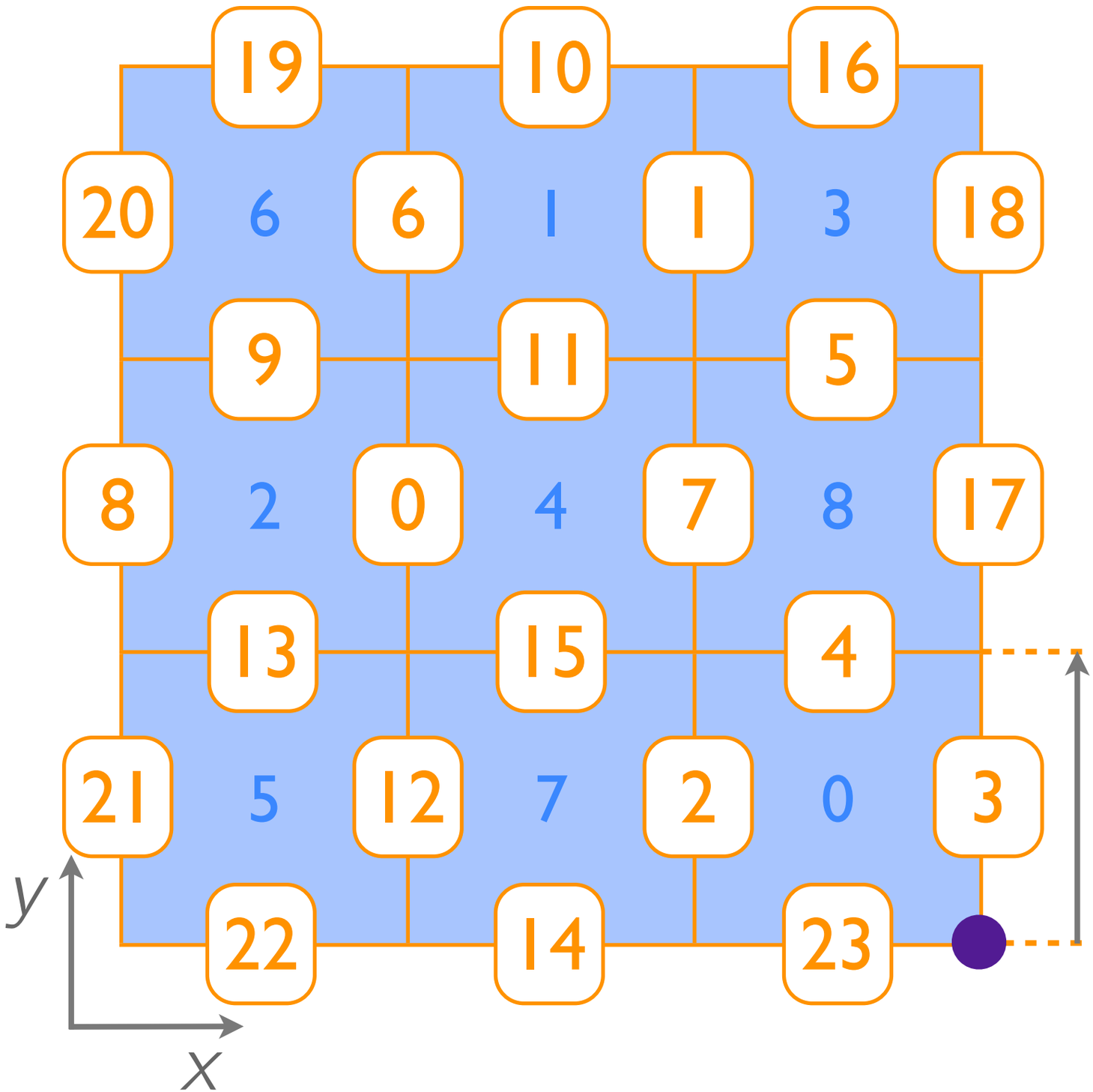

```
struct sData{
        sCell* cells;
        sFace* faces;
};
struct sCell{
        int id;
        double xy[2];

};
struct sFace{
        int id;

};
```

Datenstruktur



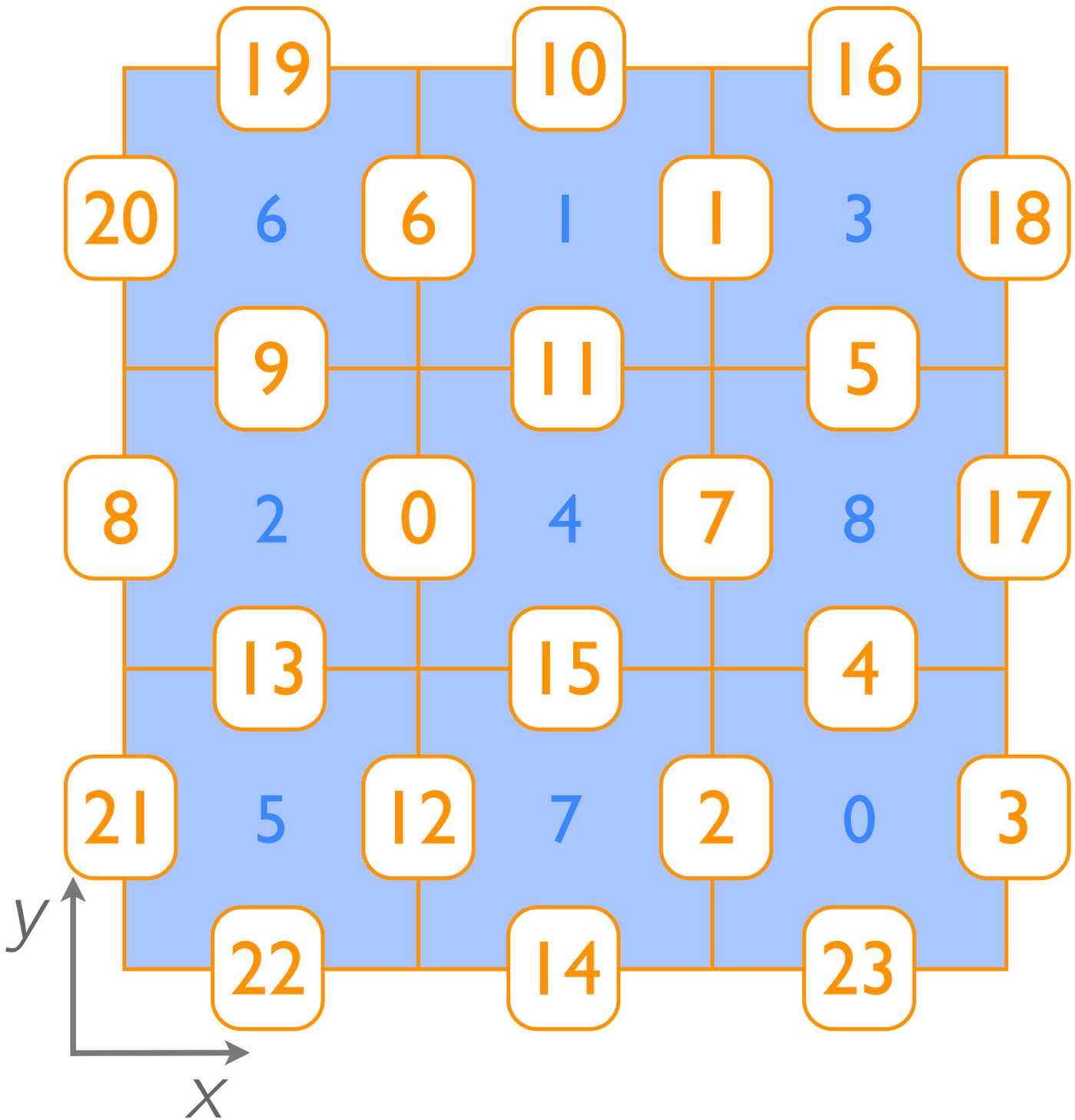

```
struct sData{
        sCell* cells;
        sFace* faces;
};
struct sCell{
        int id;
        double xy[2];
        sFace* cFaces[4];

};

struct sFace{
        int id;



};
```

Datenstruktur



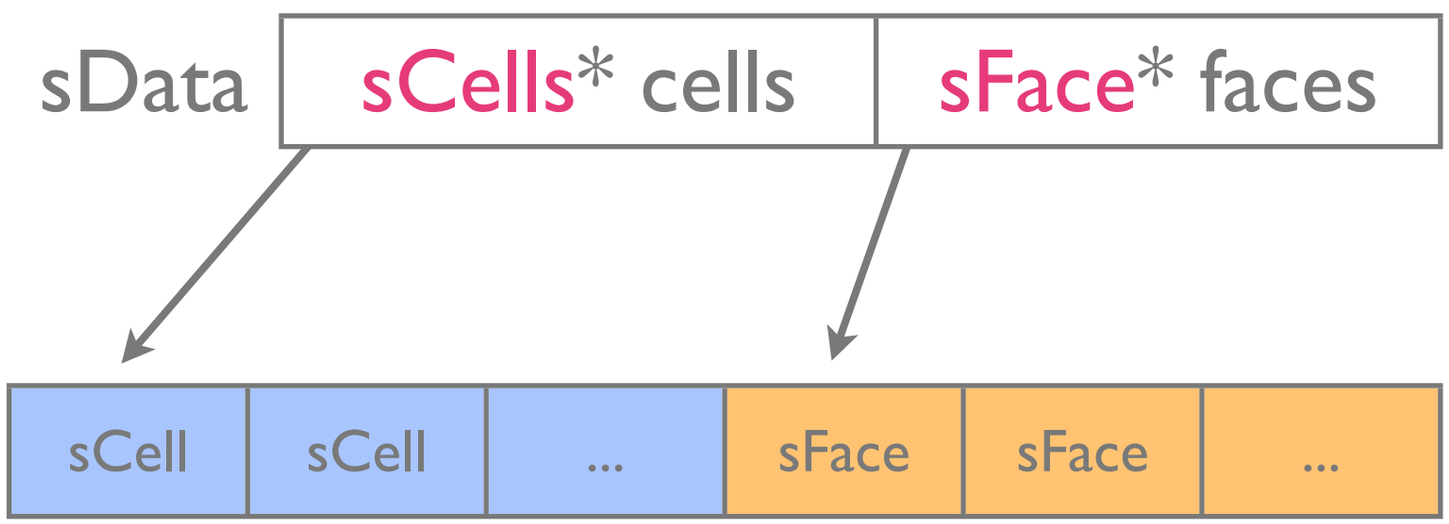

```
struct sData{
        sCell* cells;
        sFace* faces;
};
struct sCell{
        int id;
        double xy[2];
        sFace* cFaces[4];

};
struct sFace{
        int id;
        double xy[2];
        double deltaxy[2];

};
```

Datenstruktur



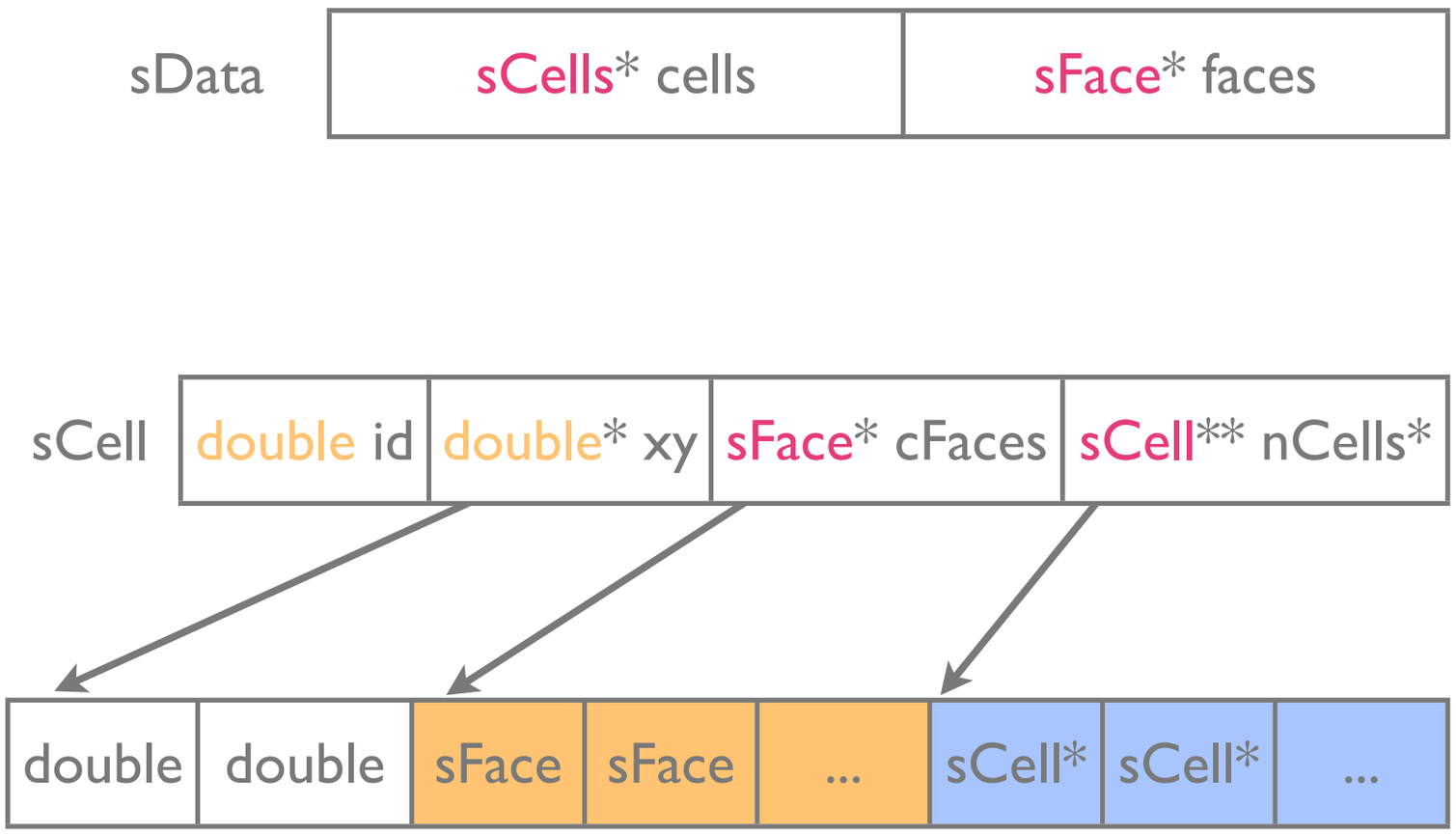

```
struct sData{
        sCell* cells;
        sFace* faces;
};
struct sCell{
        int id;
        double xy[2];
        sFace* cFaces[4];
        sCell** nCells;
};
struct sFace{
        int id;
        double xy[2];
        double deltaxy[2];
        sCell* nCells[2];
};
```

Datenstruktur




```
struct sData{
        sCell* cells;
        sFace* faces;
};
struct sCell{
        int id;
        double xy[2];
        sFace* cFaces[4];
        sCell** nCells;
};
struct sFace{
        int id;
        double xy[2];
        double deltaxy[2];
        sCell* nCells[2];
};
```

Datenstruktur




```
struct sData{
        sCell* cells;
        sFace* faces;
};
struct sCell{
        int id;
        double xy[2];
        sFace* cFaces[4];
        sCell** nCells;
};
struct sFace{
        int id;
        double xy[2];
        double deltaxy[2];
        sCell* nCells[2];
};
```

Datenstruktur

cells.cfg

cells 9

#	cType = 4	(Pixel)					
#	id	cType	x	y	face1	face2	face3	face4
	0	4	2.5	0.5	23	3	4	2
	1	4	1.5	2.5	11	1	10	6
	2	4	0.5	1.5	13	0	9	8
	3	4	2.5	2.5	5	18	16	1
	4	4	1.5	1.5	15	7	11	0
	5	4	0.5	0.5	22	12	13	21
	6	4	0.5	2.5	9	6	19	20
	7	4	1.5	0.5	14	2	15	12
	8	4	2.5	1.5	4	17	5	7

boundaries

#	id	bType	value0
	0	1	3.0
	1	1	1.755
	2	1	1.0
	3	1	3.0
	5	1	1.0
	6	1	1.0
	7	1	1.755
	8	1	3.0

initvalues

#	id	phi	
	-1	2.0	# default

Datenstruktur

faces.cfg

```
faces 24
#          id     x     y     dx      dy
           0      1     1     0       1
           1      2     2     0       1
           2      2     0     0       1
           3      3     0     0       1
           4      2     1     1       0
           5      3     2     -1      0
           6      1     3     0       -1
           7      2     2     0       -1
           8      0     1     0       1
...
```

```
boundaries 12
#                  type:   1=Skip,   2=Const.
#                  id      bType     value0      value1
                   3       1         9999        9999
                   8       1         9999        9999
                   10      2         9999        0.0
                   14      2         9999        0.0
                   16      2         9999        0.0
                   17      1         9999        9999
                   18      1         9999        9999
                   19      2         9999        0.0
...
```