## Fall 2017 Math 395 Written Homework 6 Key 100 total. -5 for no stapling

6.2 Find the full QR decomposition of  $\begin{bmatrix} 1 & 1 & 4 \\ -1 & 0 & 0 \\ 1 & 1 & 2 \\ -1 & 0 & -2 \end{bmatrix}$  using the reduced one (6.4).

Solution 
$$\begin{bmatrix} 1 & 1 & 4 \\ -1 & 0 & 0 \\ 1 & 1 & 2 \\ -1 & 0 & -2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 1 & 1 & -1 \\ -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix} := \hat{Q}\hat{R}.$$
 To find the full Q, we just need

to add a unit norm column that is orthogonal to all 3 columns in  $\hat{Q}$ , which is to find the null space of  $\hat{Q}^T$ .

We can pick  $x_4 = 1$ , after normalization, we get  $q_4 = \frac{1}{2}(1, -1, -1, 1)$ .

6.3 Let A be an  $n \times n$  matrix. Prove that if Ax = 0 for every vector  $x \in \mathbb{R}^d$ , then A must be the zero matrix.

*Proof.* Let  $A = [a_1, a_2, \dots, a_n]$  where  $a_i$  are its columns. Since Ax = 0 for every vector x, in particular, it is true for  $e_1 = (1, 0, \dots, 0)$ .  $0 = Ae_1 = a_1$ , meaning the first column must be a zero column.

Using the same idea, we can let x be  $e_j$ , then  $0 = Ae_j = a_j$ , which says that the jth column of A has to be 0. This is saying all columns of A are 0 columns, thus A is the zero matrix.

6.4 Show that  $H_u$  in (6.6) is symmetric and orthonormal.

Solution 
$$H_u = I - 2\frac{uu^T}{u^Tu}$$
.

Symmetry: Both I and  $uu^T$  are symmetric, so  $H_u$  is symmetric.

Orthonormal:  $H_u$  is square, and  $H_u^T H_u = (I - 2\frac{uu^T}{u^T u})(I - 2\frac{uu^T}{u^T u}) = I - 4\frac{uu^T}{u^T u} + 4\frac{uu^T uu^T}{(u^T u)^2} = I - 4\frac{uu^T}{u^T u} + 4\frac{uu^T}{u^T u} + 4\frac{uu^T}{u^T u} + 4\frac{uu^T}{u^T u} = I.$ 

In general,  $(A - B)(A - B) = A^2 + B^2 - AB - BA \neq A^2 - 2AB + B^2$ .

6.5 Show that  $H_{-2u} = H_u$ .

$$H_{-2u} = I - 2\frac{(-2u)(-2u)^T}{(-2u)^T(-2u)} = I - 2\frac{4uu^T}{4u^Tu} = I - 2\frac{uu^T}{u^Tu} = H_u.$$

- 6.6 Given x = (1, 2, -2),
  - (a) find an orthonormal matrix Q such that  $Qx = 3e_1$ .
  - (b) find an orthonormal matrix Q' such that  $Q'x = -3e_2$ .

(c) can you find an orthonormal matrix Q'' such that  $Q''x = 2e_1$ ? Why?

## Solution

(a) 
$$||x|| = 3$$

$$u = x - 3e_1 = (1, 2, -1) - (3, 0, 0) = (-2, 2, -2).$$

Since any scalar multiple of u will produce the same  $H_u$ , we will take u = (-1, 1, -1)

$$Q = H_u = I - 2\frac{uu^T}{u^Tu} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{2}{3} \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 2 & -2 \\ 2 & 1 & 2 \\ -2 & 2 & 1 \end{bmatrix}.$$

(b) 
$$u' = x + 3e_2 = (1, 2, -1) + (0, 3, 0) = (1, 5, -1).$$

$$Q' = H_{u'} = I - 2\frac{u'u'^T}{u'^Tu'} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{2}{27} \begin{bmatrix} 1 & 5 & -1 \\ 5 & 25 & -5 \\ -1 & -5 & 1 \end{bmatrix} = \frac{1}{27} \begin{bmatrix} 25 & -10 & 2 \\ -10 & -23 & 10 \\ 2 & 10 & 25 \end{bmatrix}.$$

By the way, householder reflector is a good way to generate orthonormal matrices, if you ever need one.

- (c) An orthonormal matrix preserves the length/norm. See (3.2) of the notes (page 16).
- ||Q''x|| = ||x||, should be 3, but it is 2 instead.
- 6.7 Let U be an  $n \times n$  matrix. It is in the partitioned form as  $U = \begin{bmatrix} I_{k \times k} & 0 \\ 0 & B \end{bmatrix}$ , where B is an  $(n-k) \times (n-k)$  orthonormal matrix. Show that
  - (a) The first k rows of UA is the same as the first k rows of A using block matrix multiplication.
  - (b) U is orthonormal using block matrix multiplication.

## Solution

(a) Partition A as  $A = \begin{bmatrix} A_k \\ D \end{bmatrix}$ , where  $A_k$  is the first k rows of A.

$$UA = \left[ \begin{array}{cc} I_{k \times k} & 0 \\ 0 & B \end{array} \right] \left[ \begin{array}{c} A_k \\ D \end{array} \right] = \left[ \begin{array}{c} I_{k \times k} A_k \\ BD \end{array} \right] = \left[ \begin{array}{c} A_k \\ BD \end{array} \right].$$

(b) 
$$U^T U = \begin{bmatrix} I_{k \times k} & 0 \\ 0 & B^T \end{bmatrix} \begin{bmatrix} I_{k \times k} & 0 \\ 0 & B \end{bmatrix} = \begin{bmatrix} I_{k \times k} & 0 \\ 0 & B^T B \end{bmatrix} = \begin{bmatrix} I_{k \times k} & 0 \\ 0 & I_{(n-k) \times (n-k)} \end{bmatrix} = I_n$$

6.8 Redo Example 6.12 where Step 1 is kept, but in Step 2 and Step 3, we let  $u_i = a_i + ||a_i||e_1$ .

**Step 1:**  $a_1 = (1, -1, 1, -1), u_1 = a_1 - ||a_1|| e_1 = (1, -1, 1, -1) - (2, 0, 0, 0) = (-1, -1, 1, -1).$  (We could also choose  $u_1 = a_1 + ||a_1|| e_1$ .)

**Step 2:**  $a_2 = (0,1,0), u_2 = a_2 + ||a_2||e_1 = (0,1,0) + (1,0,0) = (1,1,0).$ 

$$H_{u_2} = I_3 - 2\frac{u_2 u_2^T}{u_2^T u_2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, Q_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & H_{u_2} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

$$A_2 = Q_2 A_1 = \begin{bmatrix} 2 & 1 & 4 \\ 0 & -1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{bmatrix}.$$

**Step 3:**  $a_3 = (0, -2), u_3 = a_3 + ||a_3|| e_1 = (2, -2).$ 

$$H_{u_3} = I_2 - 2\frac{u_3 u_3^T}{u_3^T u_3} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, Q_3 = \begin{bmatrix} I_2 & 0 \\ 0 & H_{u_3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix},$$

$$A_3 = Q_3 A_2 = \begin{bmatrix} 2 & 1 & 4 \\ 0 & -1 & -2 \\ 0 & 0 & -2 \\ 0 & 0 & 0 \end{bmatrix}.$$

In the end,  $Q = Q_1^T Q_2^T Q_3^T, R = A_3$ .