

# threads

## thread creation

```
int pthread_create(pthread_t *thread, const pthread_attr_t *attr, void *
(*start_function)(void *), void *arg);
// creates a new thread
// after a call to pthread_create(), a program has no guarantee about which thread
will next be scheduled
```

- thread: pointer to where the new thread's identifier will be
- attr: use `NULL` for default attributes
- start\_function:
  - the new thread start execution by calling start\_function
  - start\_function must return `void \*` and take `void \*` argument
  - void \* start\_function(void \*arg);
- arg:
  - arguments which start\_function is called with
  - if multiple arguments are needed, `arg` should point to a structure

## thread termination

A thread can terminate in one of the following ways:

- thread's start function performs a return
- thread calls `pthread_exit()`
- thread is canceled using `pthread_cancel()`
- any of the threads calls `exit()`, or the main thread performs a return (in the `main()` function), which causes all threads in the process to terminate immediately

### pthread\_exit

```
int pthread_exit(void *retval);
// terminates the calling thread
```

- retval: return value for the thread



if the main thread calls `pthread_exit()` instead of calling `exit()` or performing a return, the other threads continue to execute

## pthread\_cancel

```
int pthread_cancel(pthread_t thread);  
// requests a thread cancelation  
// returns immediately, it does NOT wait for the target thread to terminate  
// a thread can be cancelable or not (by default, new threads are cancelable) and  
cancelation can remain pending until a cancellation point
```

## thread\_join

```
int pthread_join(pthread_t thread, void **retval);  
// waits for the specified thread to terminate
```

– `retval`: if not-NULL, it receives the terminated thread return value (value specified when the thread performs a return or calls `pthread_exit()`)

### Warning

detached threads cannot be joined - detached threads are automatically removed when they terminate, their return value does not matter

a thread can be marked as detached using `pthread_detach()`

## pthread\_self

```
pthread_t pthread_self();  
// returns the thread ID of the calling thread
```

## notes

## compilation

```
gcc -lpthread -D_REENTRANT -Wall file.c -o executable
```

- `D_REENTRANT` is called implicitly

### Warning

USING [NON-REENTRANT](#) ROUTINES WON'T WORK AS EXPECTED SINCE THEY USE COMMON STORAGE IN AND UNSYNCHRONIZED WAY

## reentrant vs. non-reentrant

non reentrant routines are **NOT** thread-safe!

how to identify them?

- use of global/static variables
- lack of synchronization mechanisms
- modification of values passed as reference

thread-unsafe	reentrant version
<code>strtok</code>	<code>strtok_r</code>
<code>asctime</code>	<code>asctime_r</code>
<code>ctime</code>	<code>ctime_r</code>
<code>gethostbyaddr</code>	<code>gethostbyaddr_r</code>
<code>gethostbyname</code>	<code>gethostbyname_r</code>
<code>inet_ntoa</code>	(none)
<code>localtime</code>	<code>localtime_r</code>
<code>rand</code>	<code>rand_r</code>

## [forking](#) in a thread

only the calling thread is replicated in the child process

## [exec\(\)](#) in a thread

when any thread calls one of the `exec()` functions, the calling program is completely replaced

## thread synchronization

<a href="#">mutexes</a>	<a href="#">POSIX semaphores</a>	condition variables
<ul style="list-style-type: none"> <li>- mutual exclusion zones between threads (processes can also use them if shared memory is used)</li> <li>- similar to a binary semaphore, but the thread who locks the mutex must be the one to unlock it</li> </ul>	<ul style="list-style-type: none"> <li>- signal events across thread</li> <li>- count objects in a synchronized way</li> </ul>	<ul style="list-style-type: none"> <li>- allow a thread to block/notify others in any condition</li> <li>- semaphores are a kind of condition variables</li> <li>- the implicit condition is the semaphore value being greater than 0</li> </ul>

## [POSIX](#) mutexes

```
int pthread_mutex_init(pthread_mutex_t *restrict mutex, const pthread_mutexattr_t
*restrict attr);
// initialize a mutex with the specified attributes
```

– attr: if `NULL`, the attributes used are the default

```
pthread_mutex_t fastmutex = PTHREAD_MUTEX_INITIALIZER;
// declares and creates a mutex with default attributes
```

– does not generate errors!

```
int pthread_mutex_lock(pthread_mutex_t *mutex);
// performs a lock on a mutex
```

```
int pthread_mutex_unlock(pthread_mutex_t *mutex);
// performs an unlock on a mutex
```

```
int pthread_mutex_trylock(pthread_mutex_t *mutex);
// tries to performs a lock on a mutex
```

```
int pthread_mutex_destroy(pthread_mutex_t *mutex);
// destroys a mutex
```