

# Trust Model for Human Agent Interaction

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## 1 Introduction

## 2 Model

In an effort to create a working trust model iteratively, we will start by simplifying the model described by Castelfranchi and Falcone [1], by removing the effects of outside influence in Trust representation. We also do not take into account long term considerations of the trustor's goal, reducing contextual scope to just the task being performed by the trustor. So Trust is represented by a 3-tuple:

- The trustor ( $\mathbf{X}$ );
- The trustee ( $\mathbf{Y}$ );
- A task ( $\tau$ ) defined by the pair  $(\alpha, \rho)$ , where  $\alpha$  is the action entrusted to the trustee, that possibly produces an outcome  $\rho$ , contained in the goal of X.

$$TRUST(X \ Y \ \tau) \tag{1}$$

The focus will be in properly representing a certain agent's features that contribute to a trust evaluation, as represented in Figure 1. These features must be able to provide 2 values:

- trust - a value for how much trust we have in this trustee's specific feature;
- believability - the degree of how much we believe this trust assumption to be true, as factors like how many times, or how long ago, did we last affirm this belief may affect the believability of our assumptions.

Trust and believability are calculated through a collection of belief sources, which in the first version will be a history of direct contacts. The environment must be able to provide some way to access these contacts, either by a callback function or through open access to an action history. If the environment does not provide such features, a perception module, capable of checking action results, will be required.

The task is composed by a set of related features with a given weight. This represents the features most closely related to the task at hand, and their importance to the completion of the task.

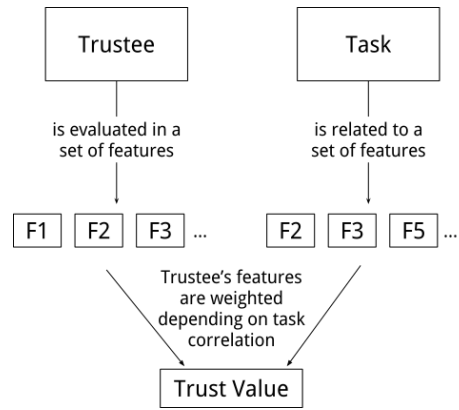


Figure 1: Trustee Features Representation

### 3 Conclusion

## References

1. Castelfranchi, C., Falcone, R.: Principles of trust for MAS: cognitive anatomy, social importance, and quantification. *Proceedings of the International Conference on Multi Agent Systems* (1998) 72–79