

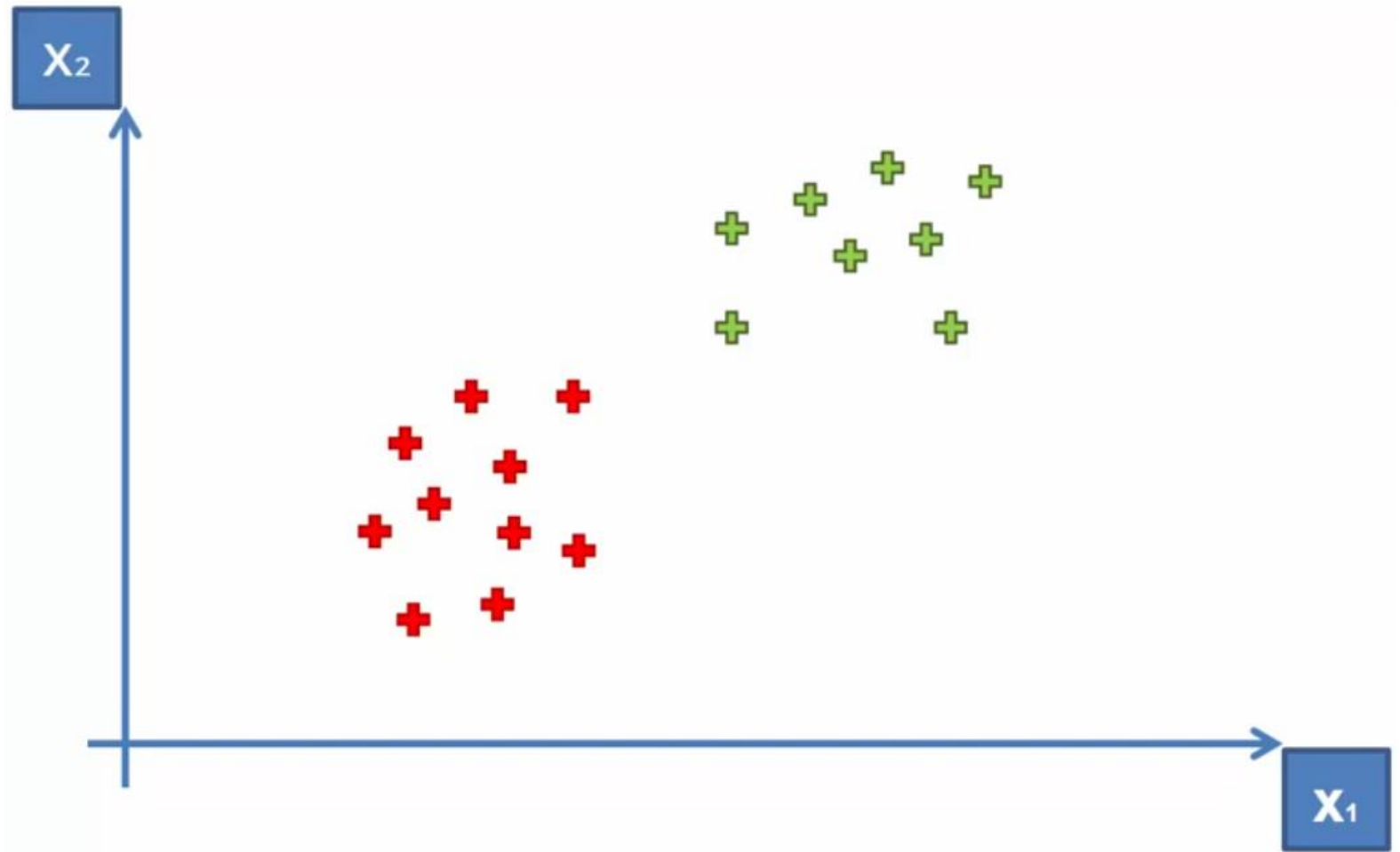


# Introduction to Machine Learning.

## Lec. 10 Support Vector Machines

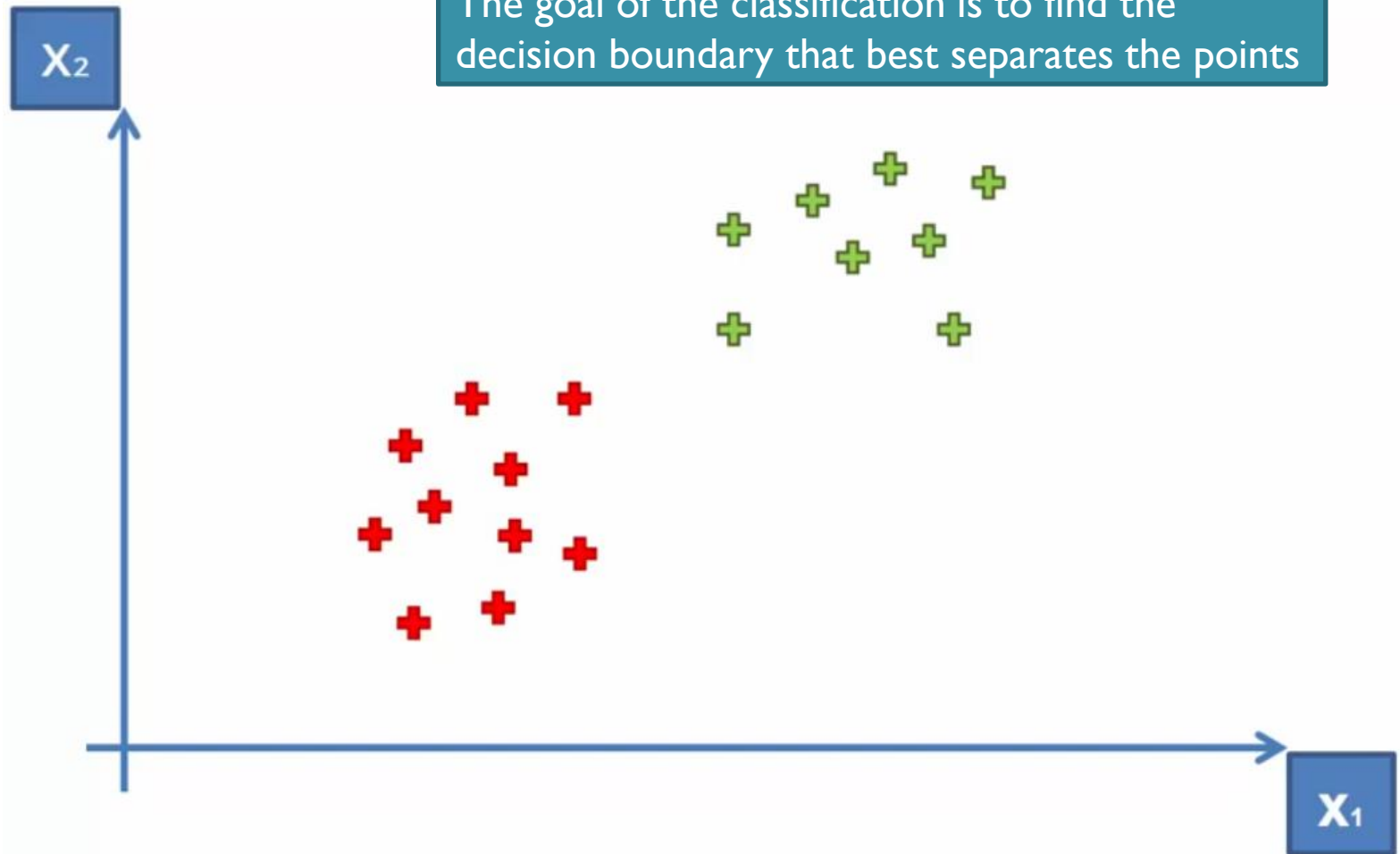
Aidos Sarsembayev, IITU, 2018

# Classification



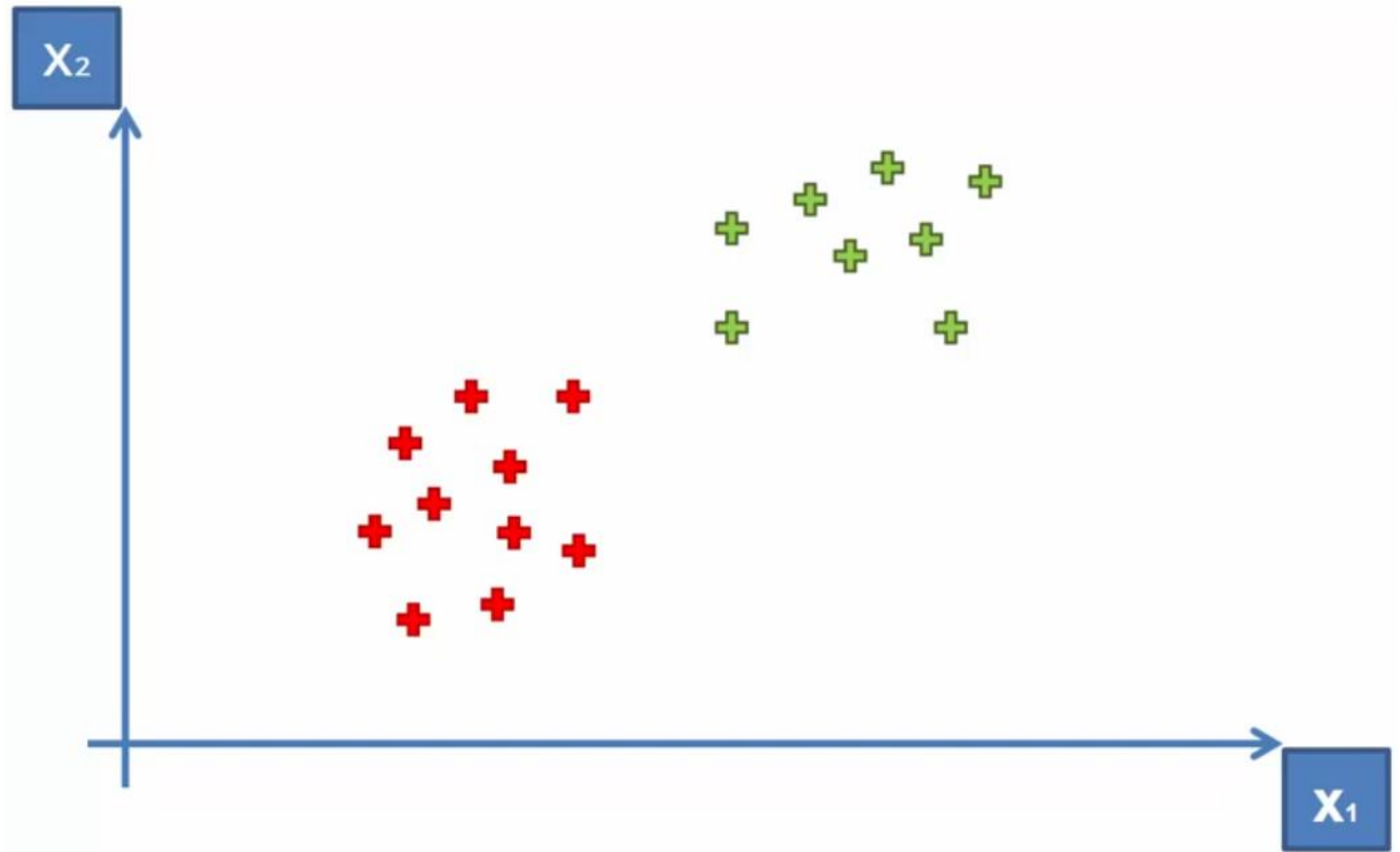
# Classification

Let's refresh some points:  
The goal of the classification is to find the decision boundary that best separates the points

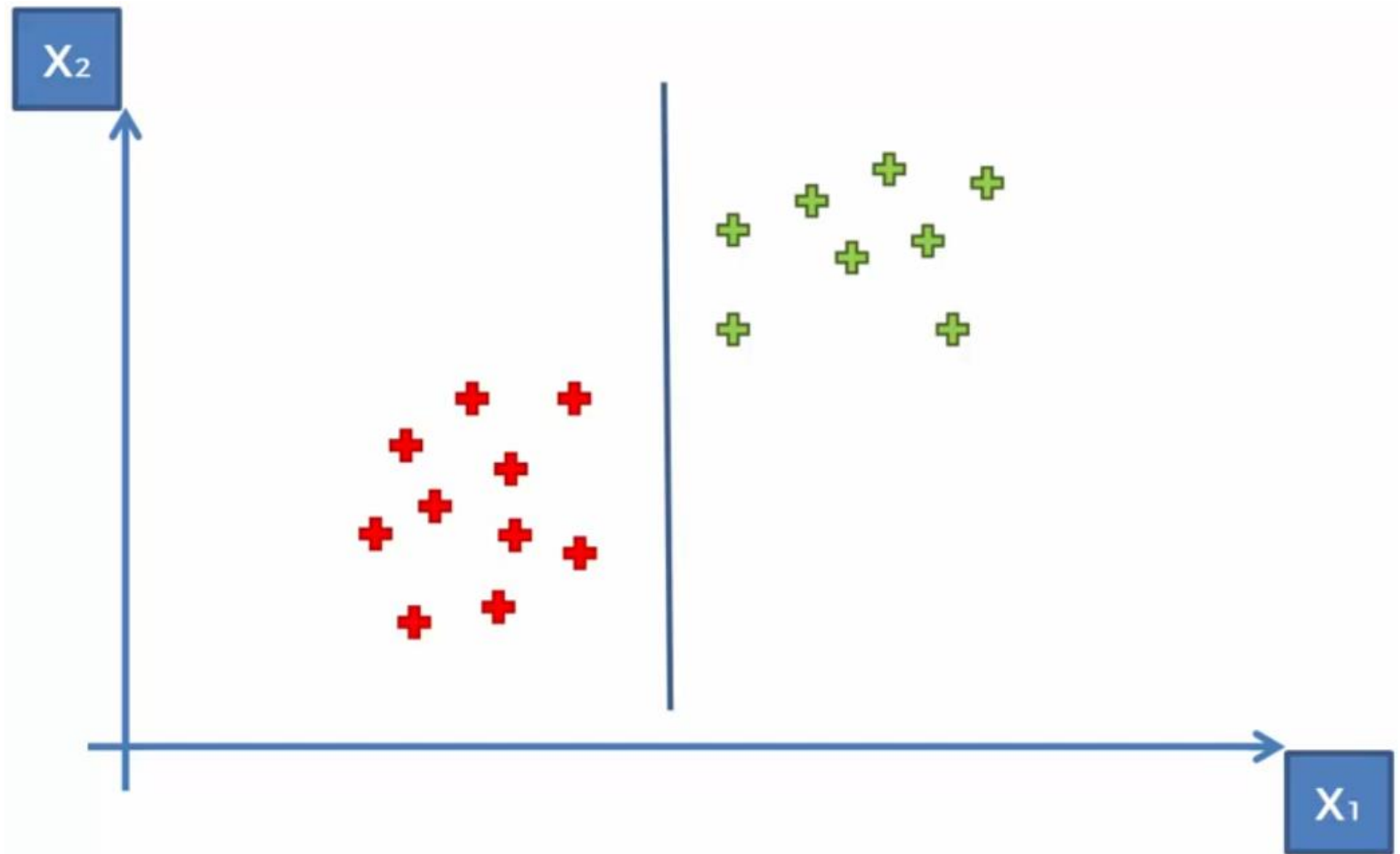


# Classification

HOW?

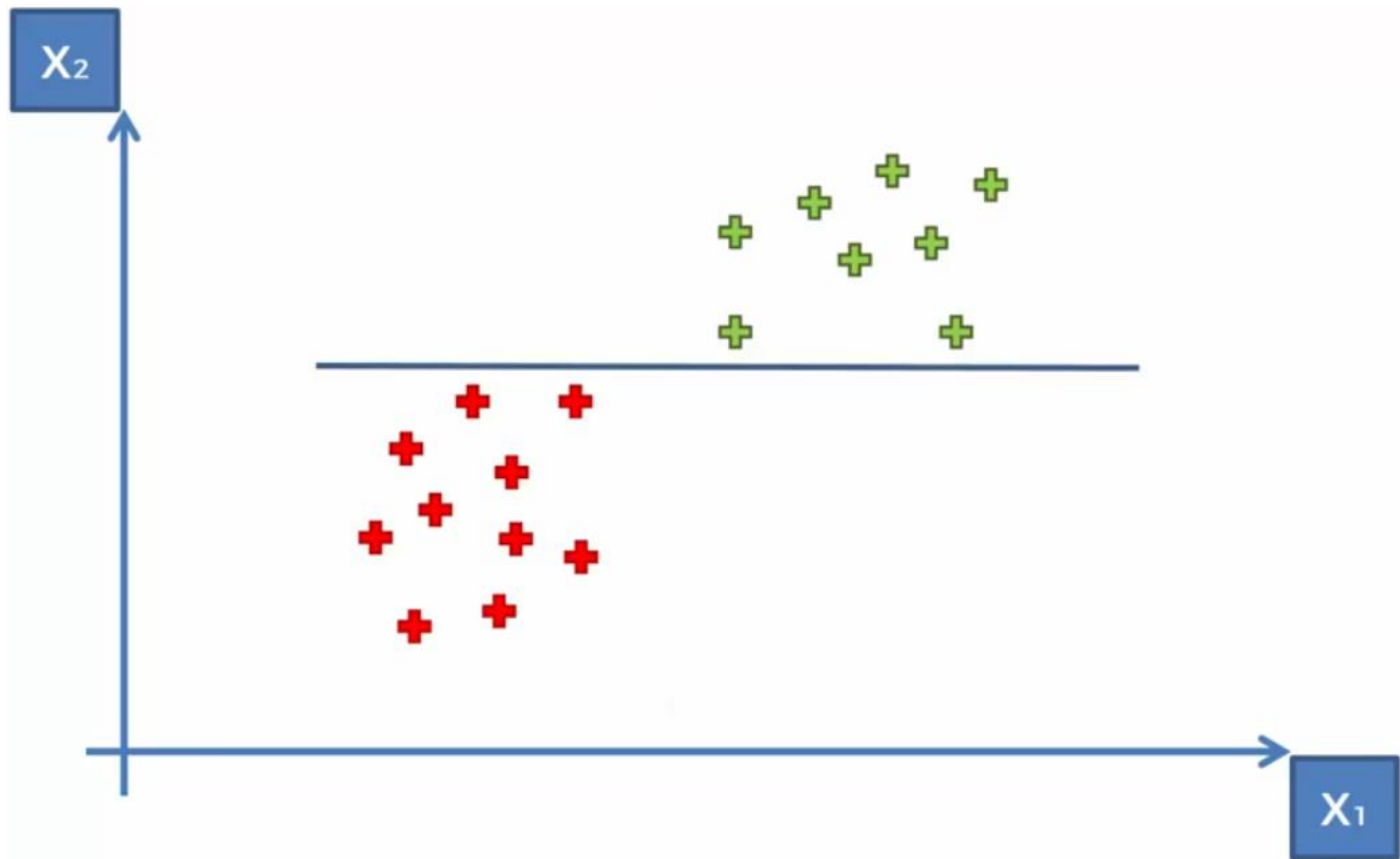


## Here's the one way...



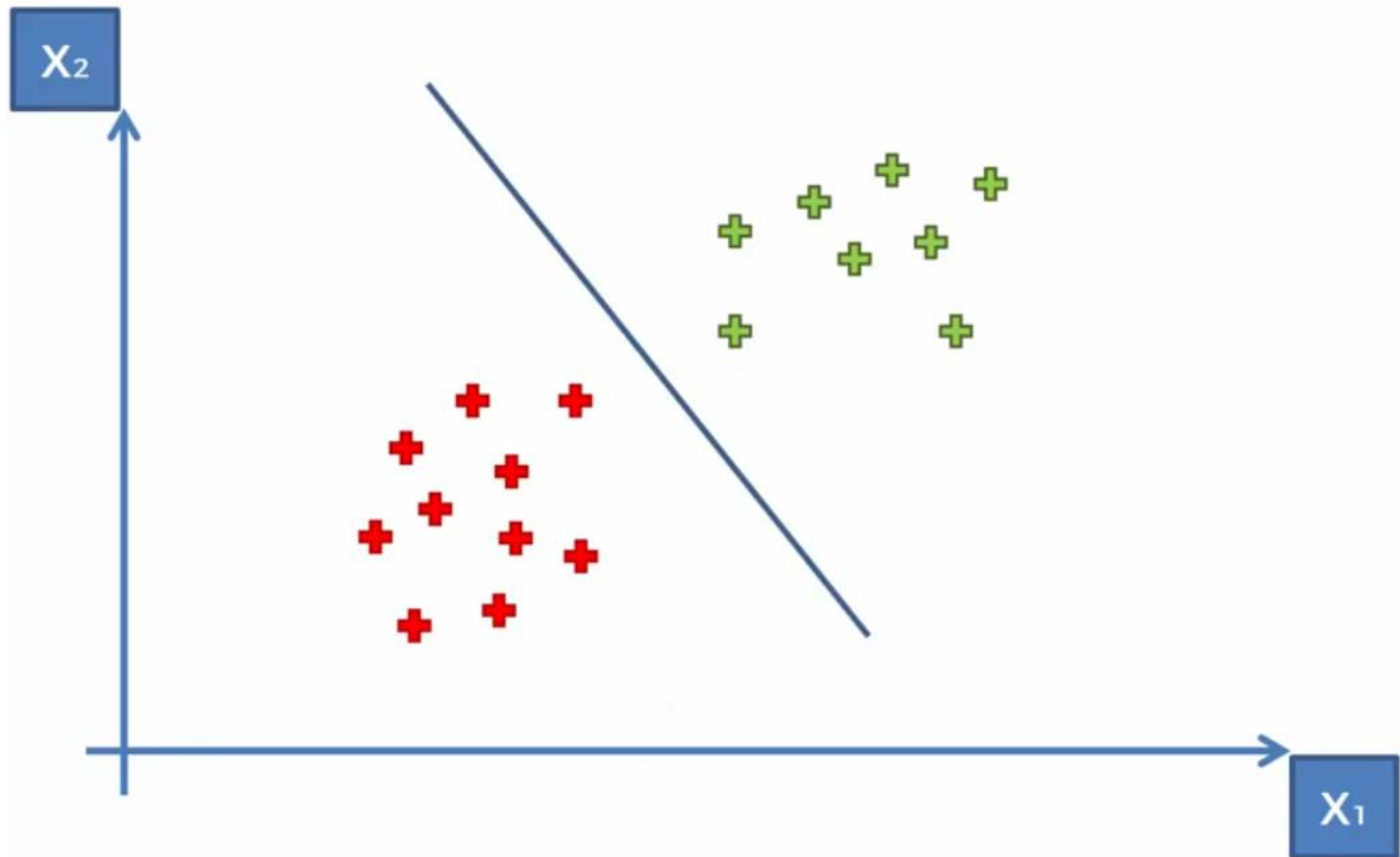
# Classification

Here's another way...



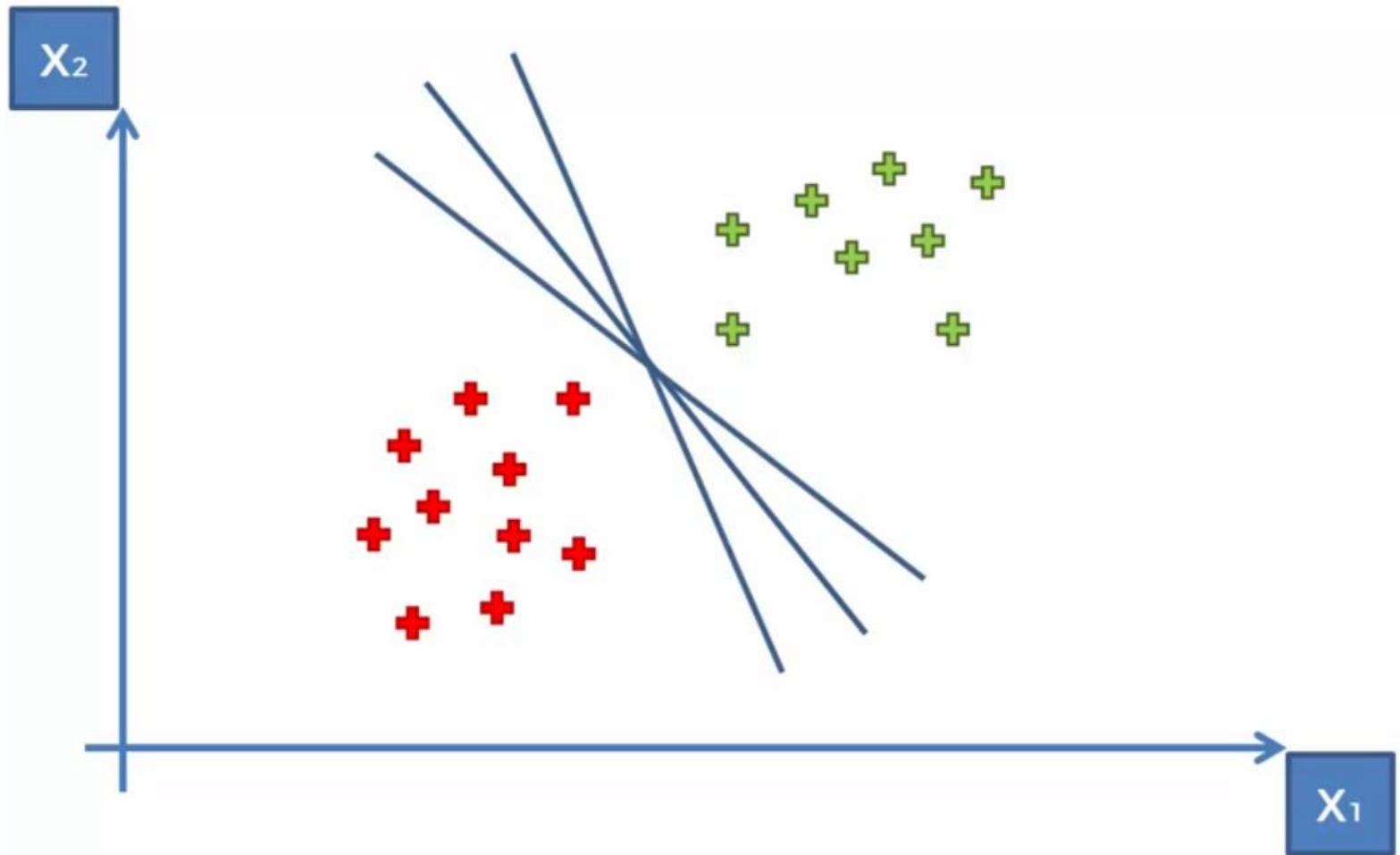
# Classification

Keep going ...



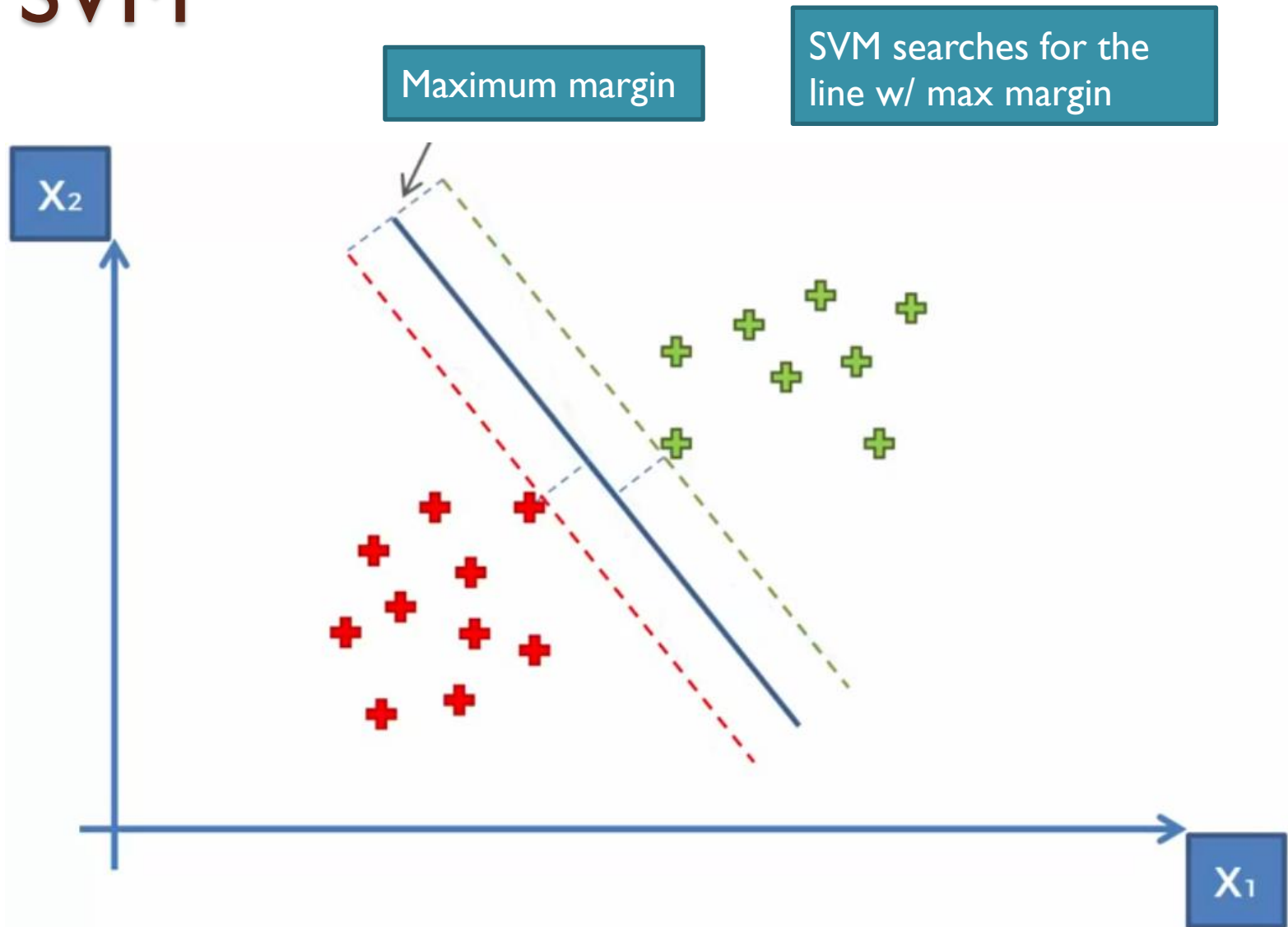
# Classification

And more... We can actually do it infinitely

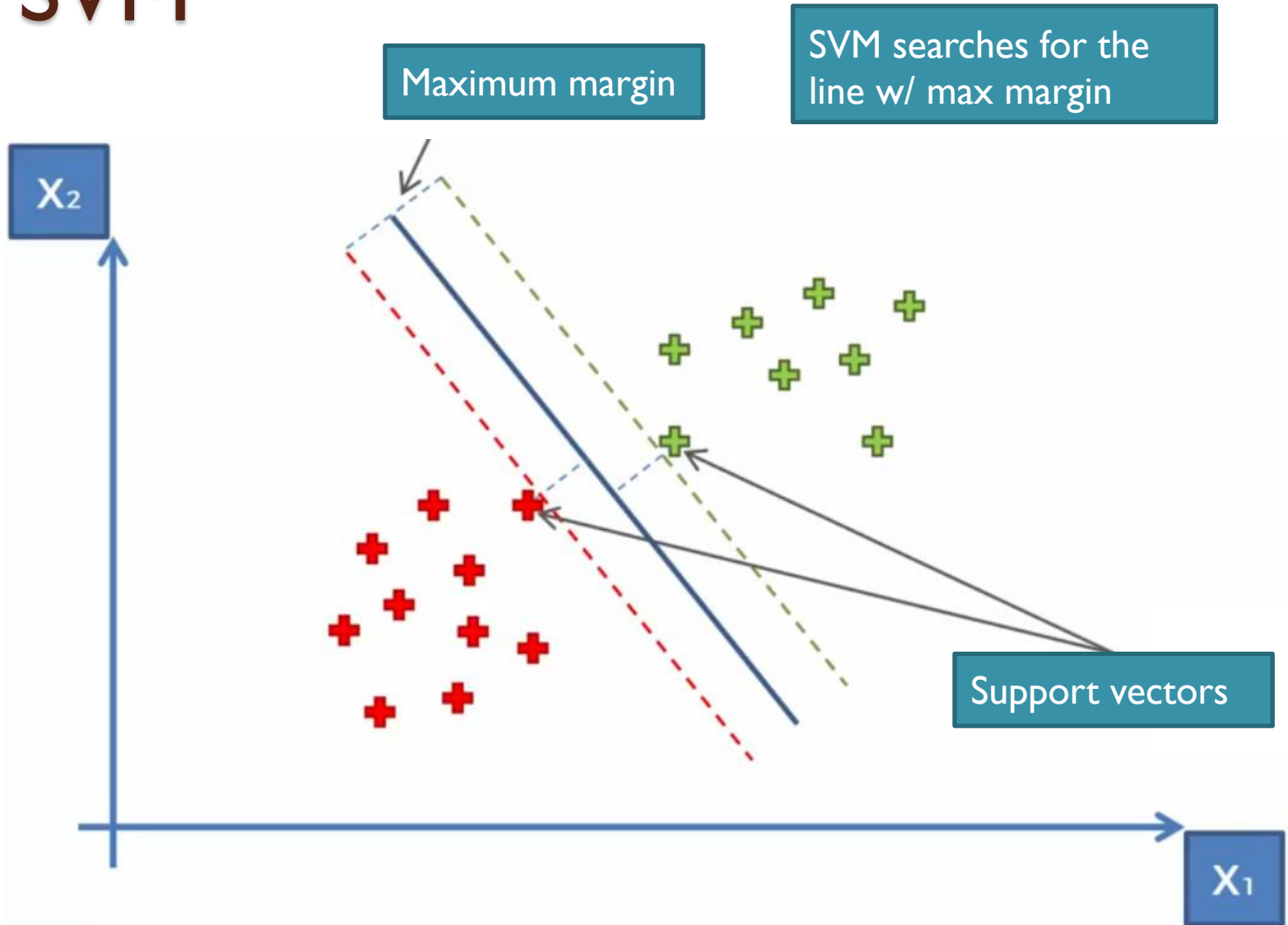




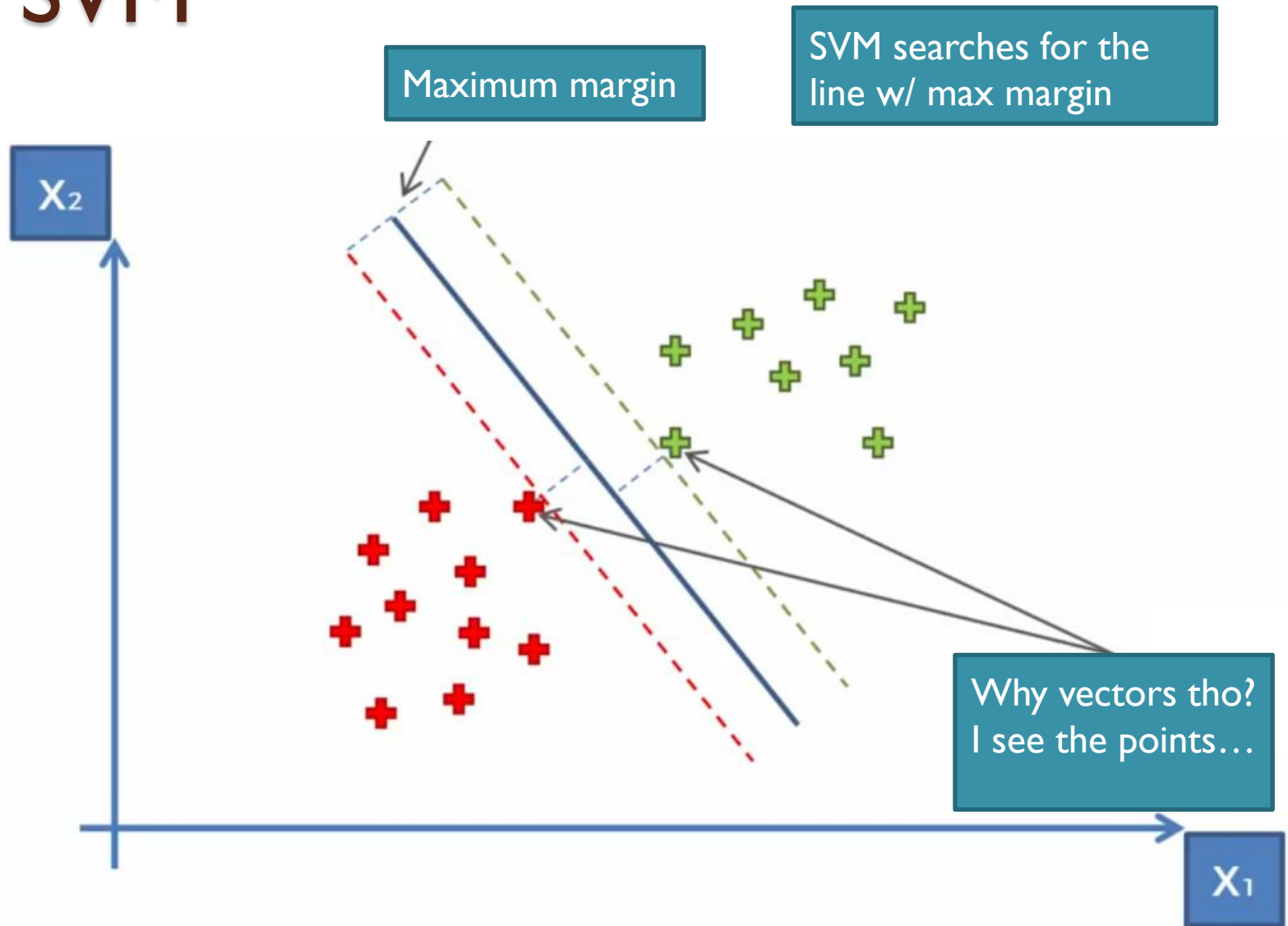
# SVM



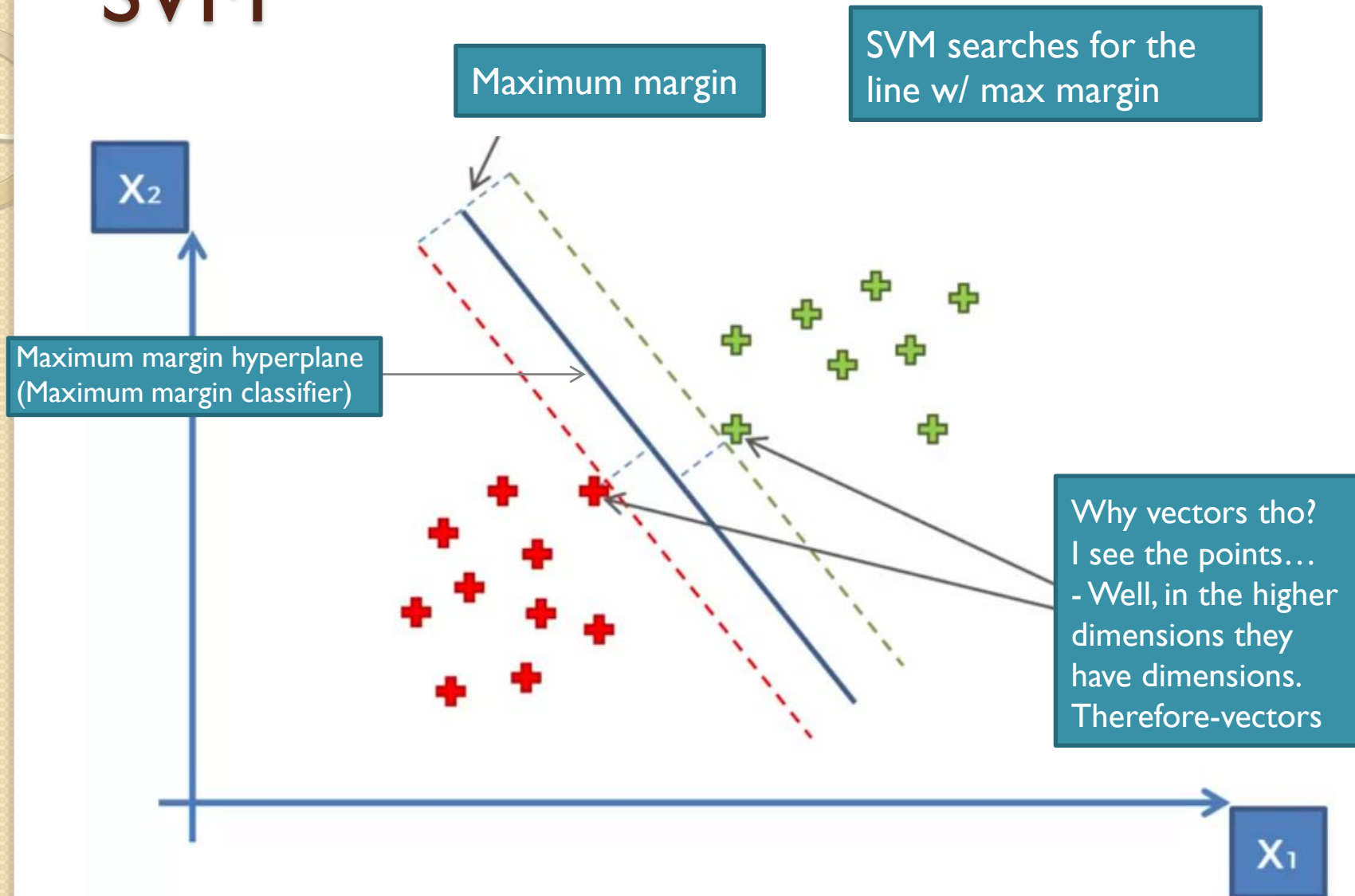
# SVM



# SVM



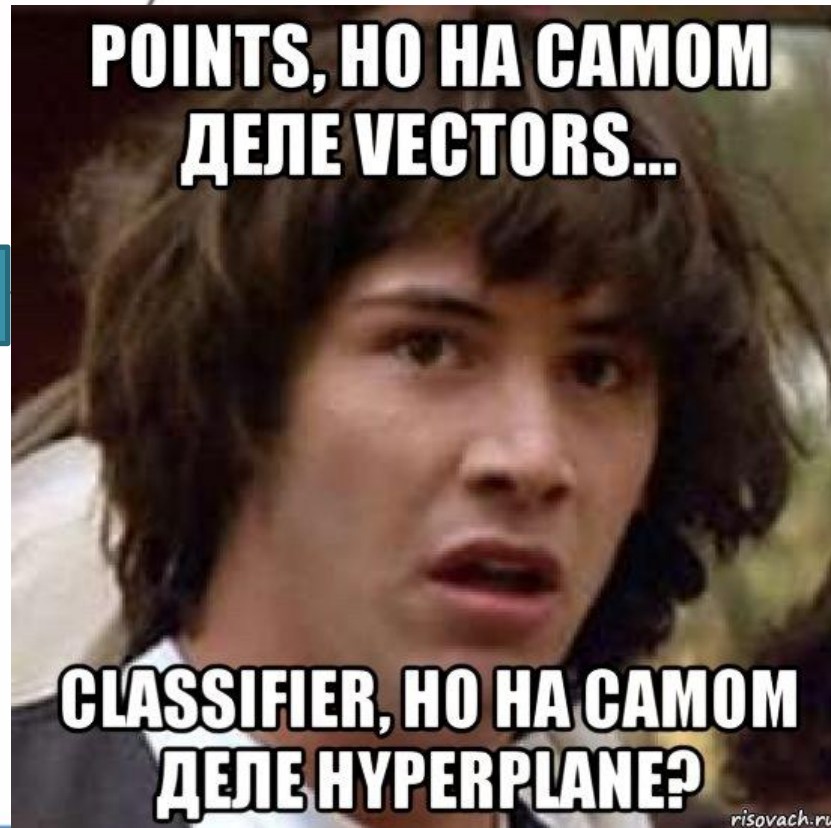
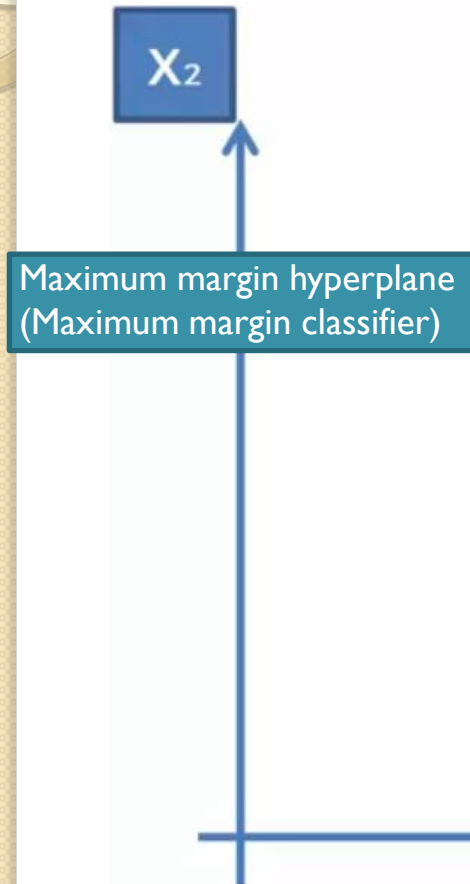
# SVM



# SVM

Maximum margin


SVM searches for the line w/ max margin



Why vectors tho?  
I see the points...  
- Well, in the higher  
dimensions they  
have dimensions.  
Therefore-vectors

Maximum margin

SVM searches for the line w/ max margin



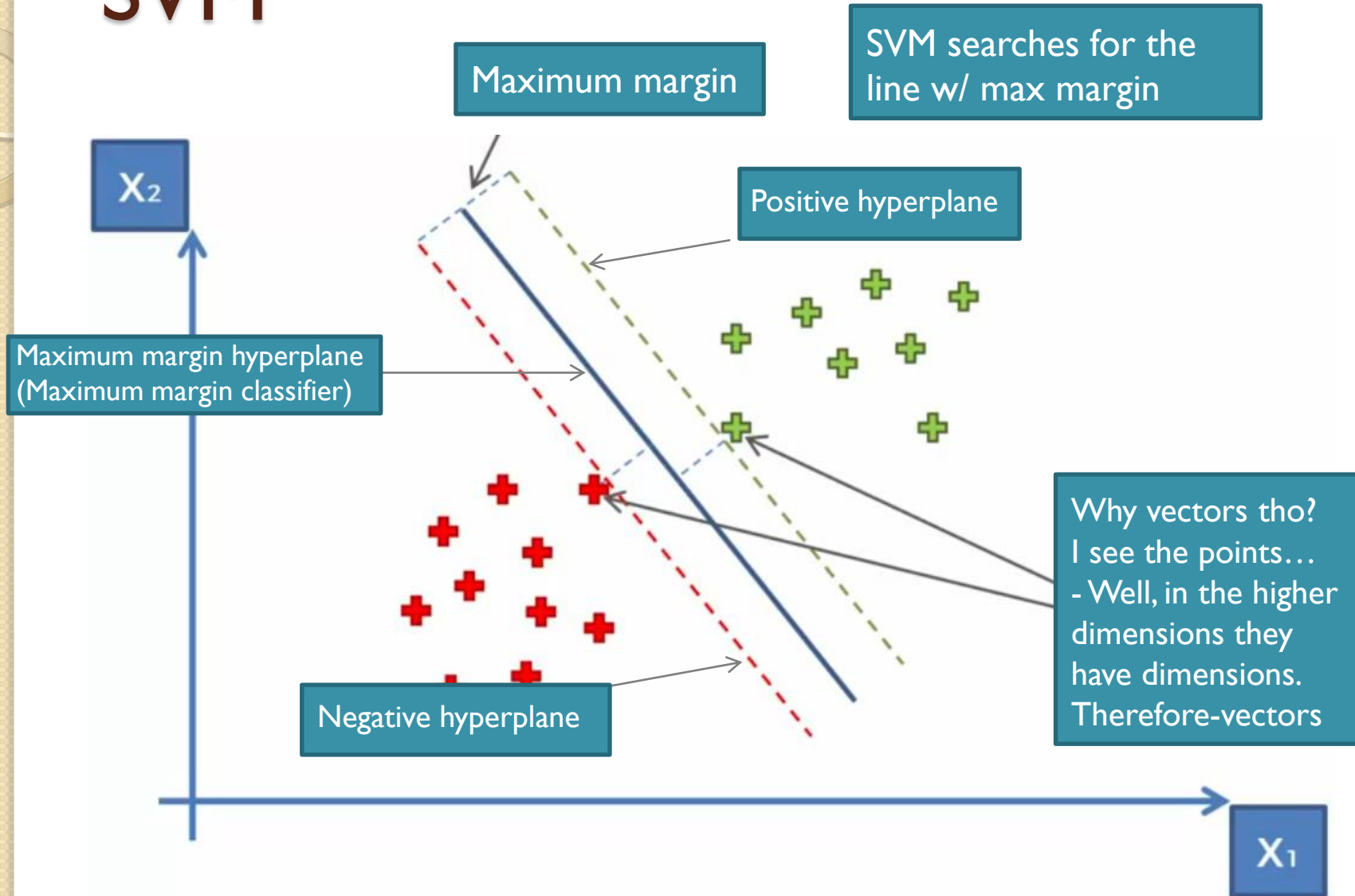
## Maximum margin hyperplane (Maximum margin classifier)

It's all about dimensionality.  
In 2D these are points and  
maximum margin classifier  
But in xD these are vectors and  
maximum margin hyperplane.

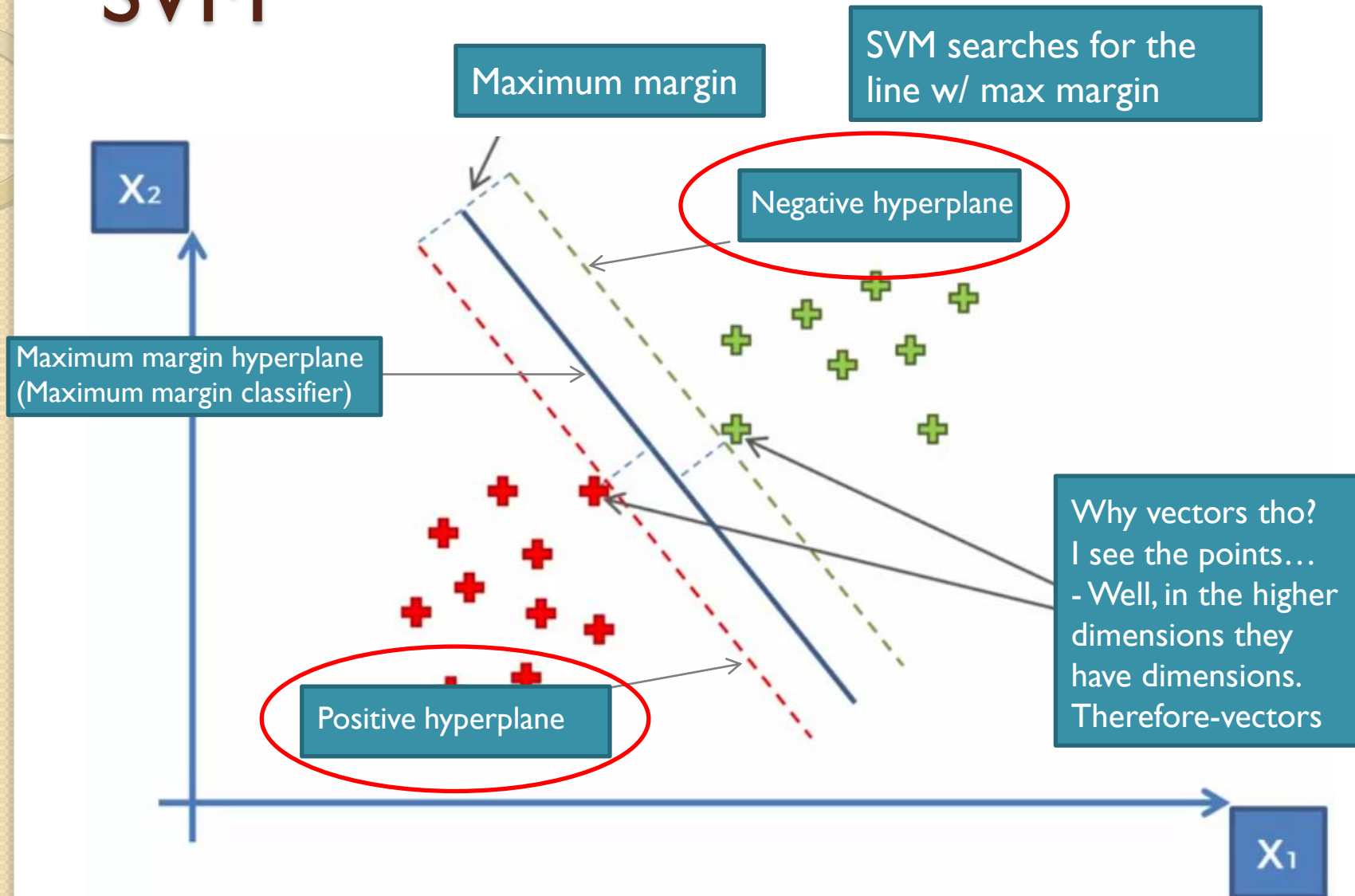
Why vectors tho?  
I see the points...  
- Well, in the higher dimensions they have dimensions.  
Therefore-vectors


 $X_1$

# SVM



# SVM







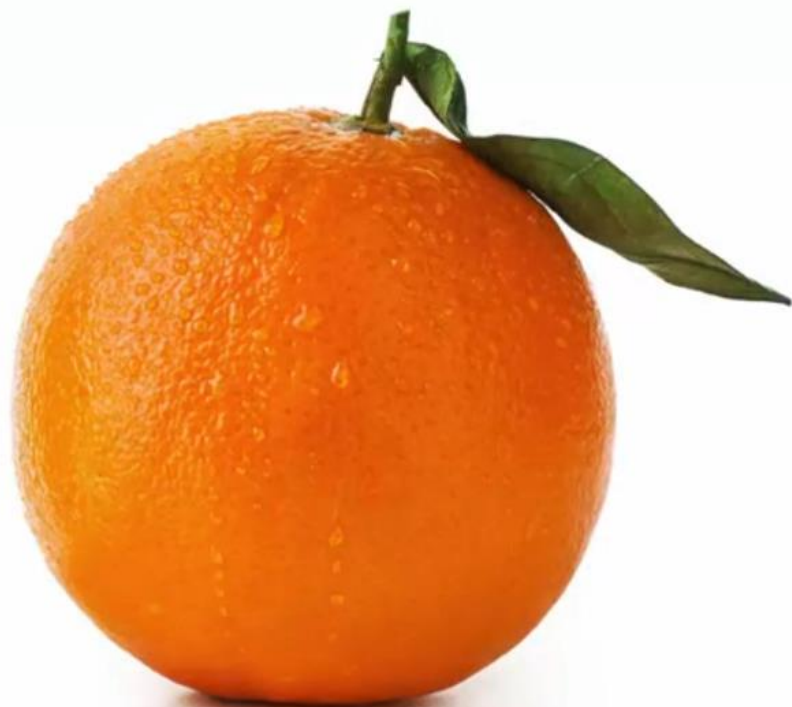
So what's that special about  
SVM?

# SVM



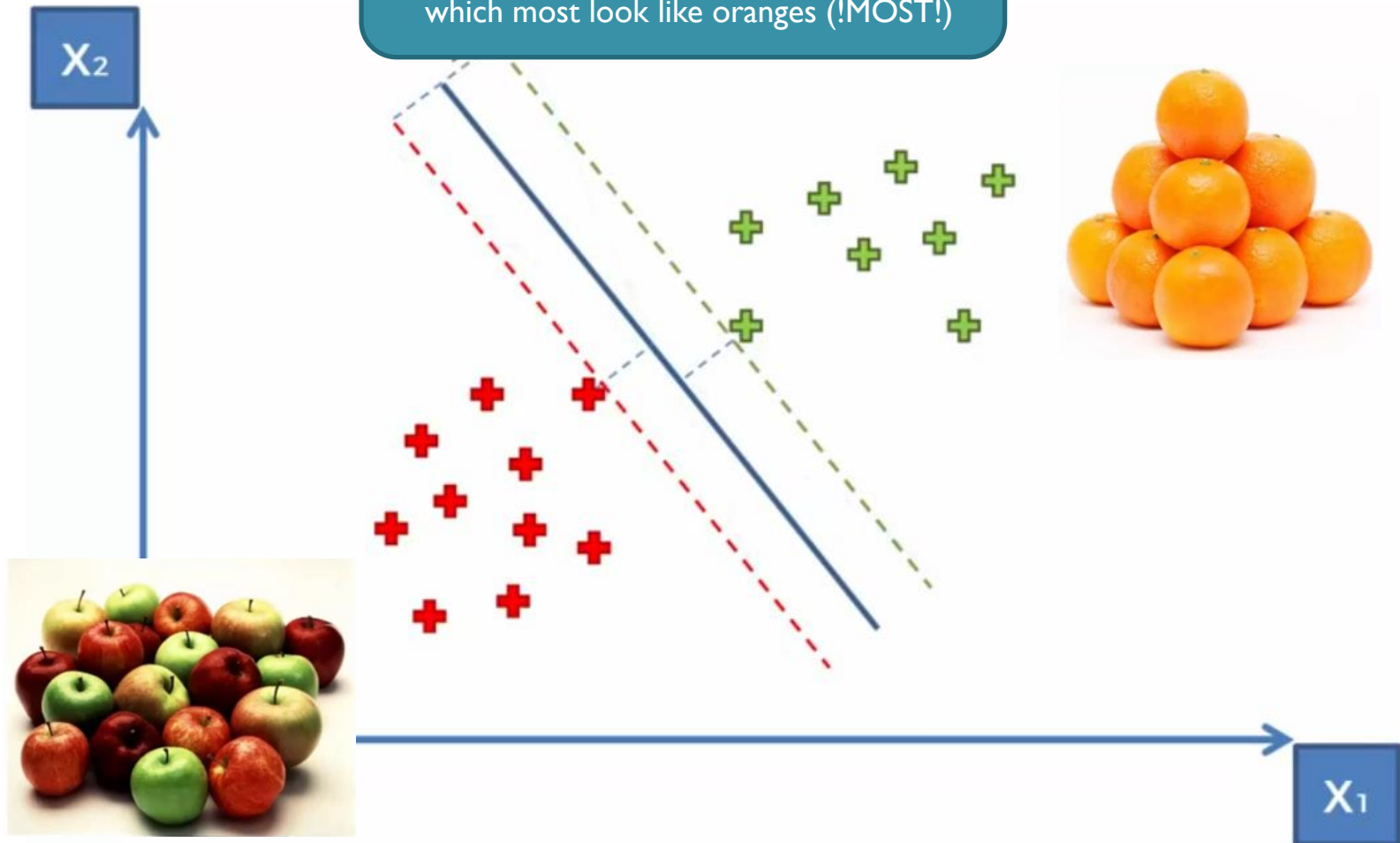
# SVM

Let's say you want to teach the model to classify oranges and apples



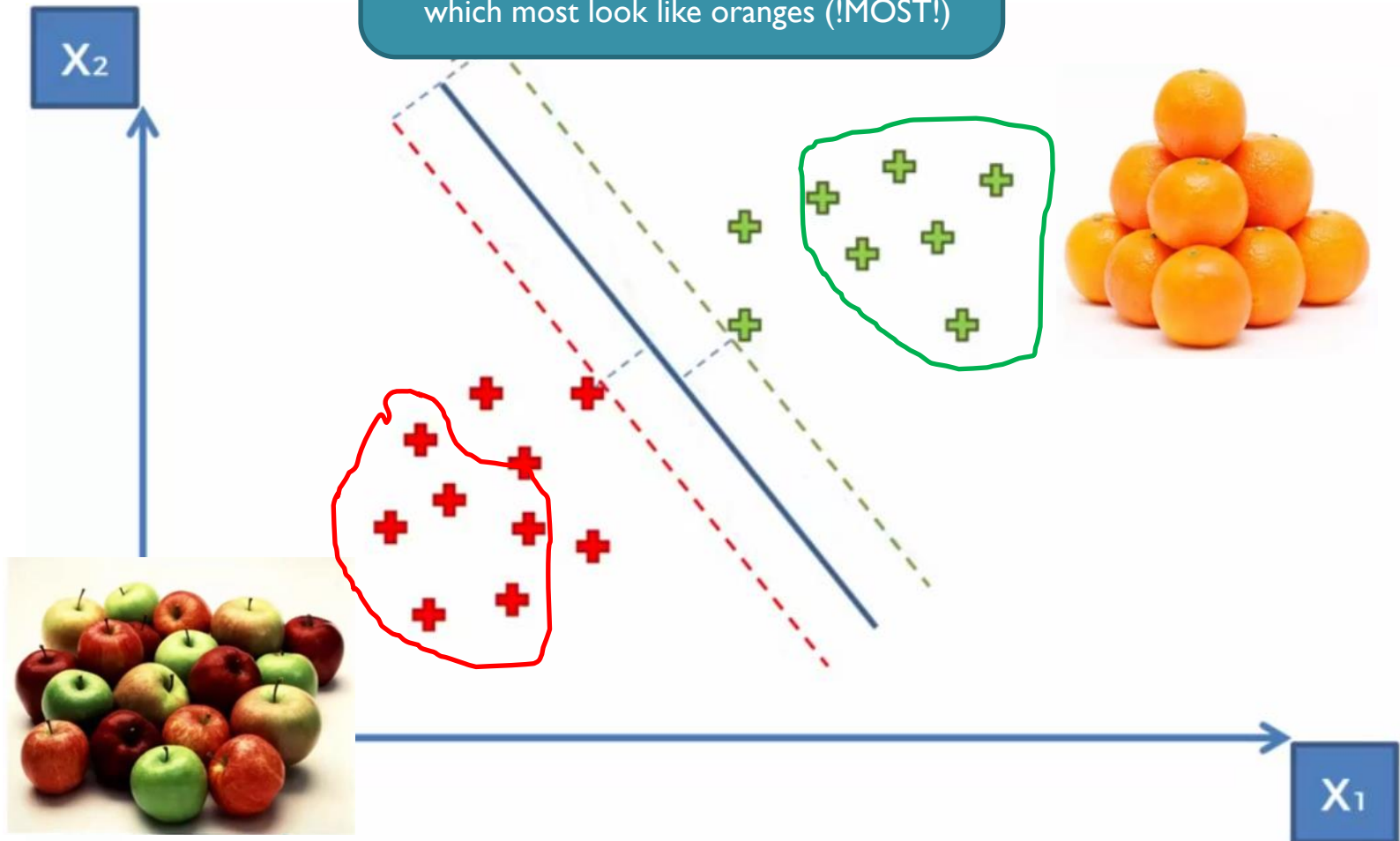
# SVM

What the most algorithm will do?  
They will search for the points which  
most look like apples and the points  
which most look like oranges (!MOST!)



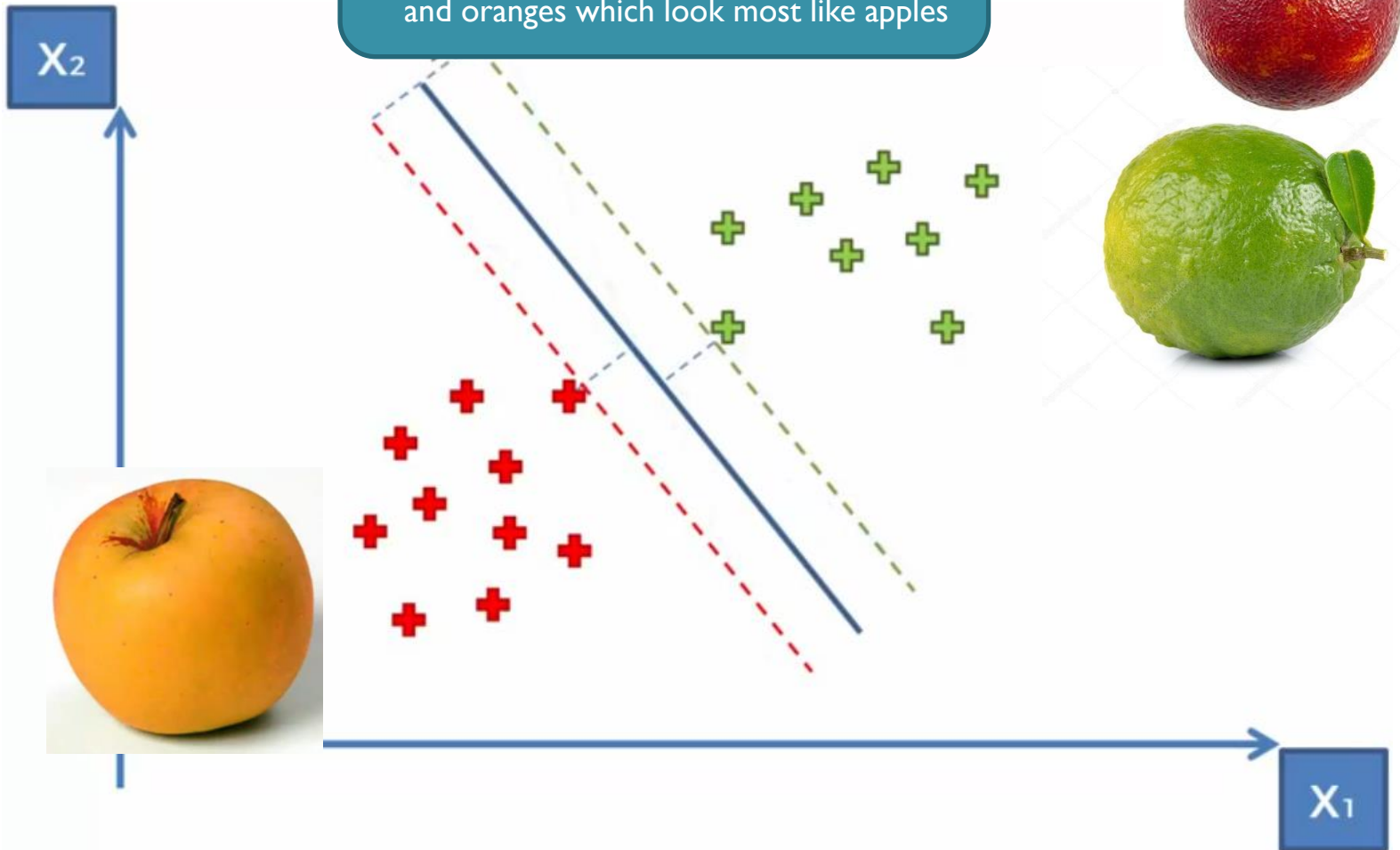
# SVM

What the most algorithm will do?  
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# SVM

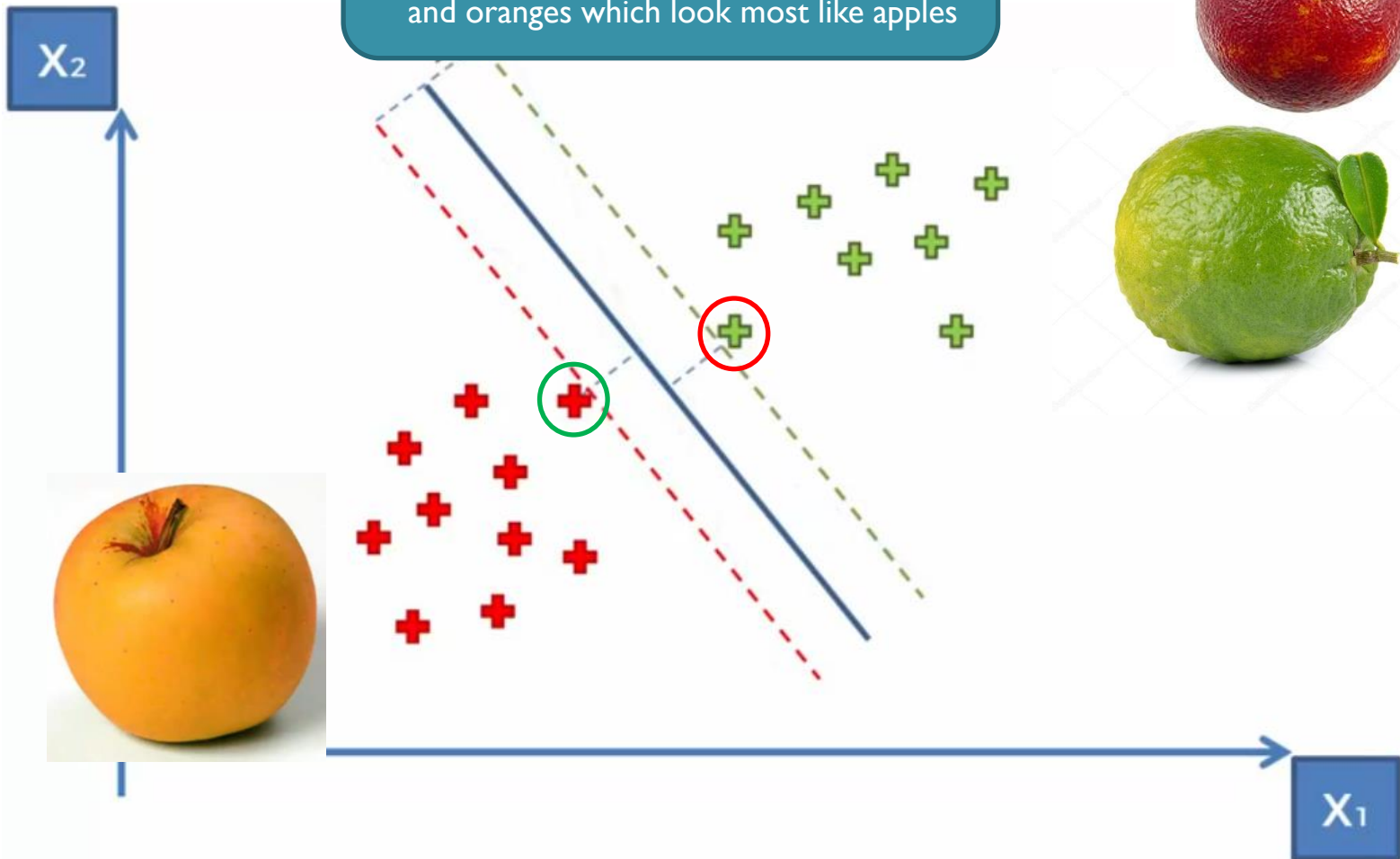
What SVM does on its turn?  
It searches for the apples which look most like oranges  
and oranges which look most like apples



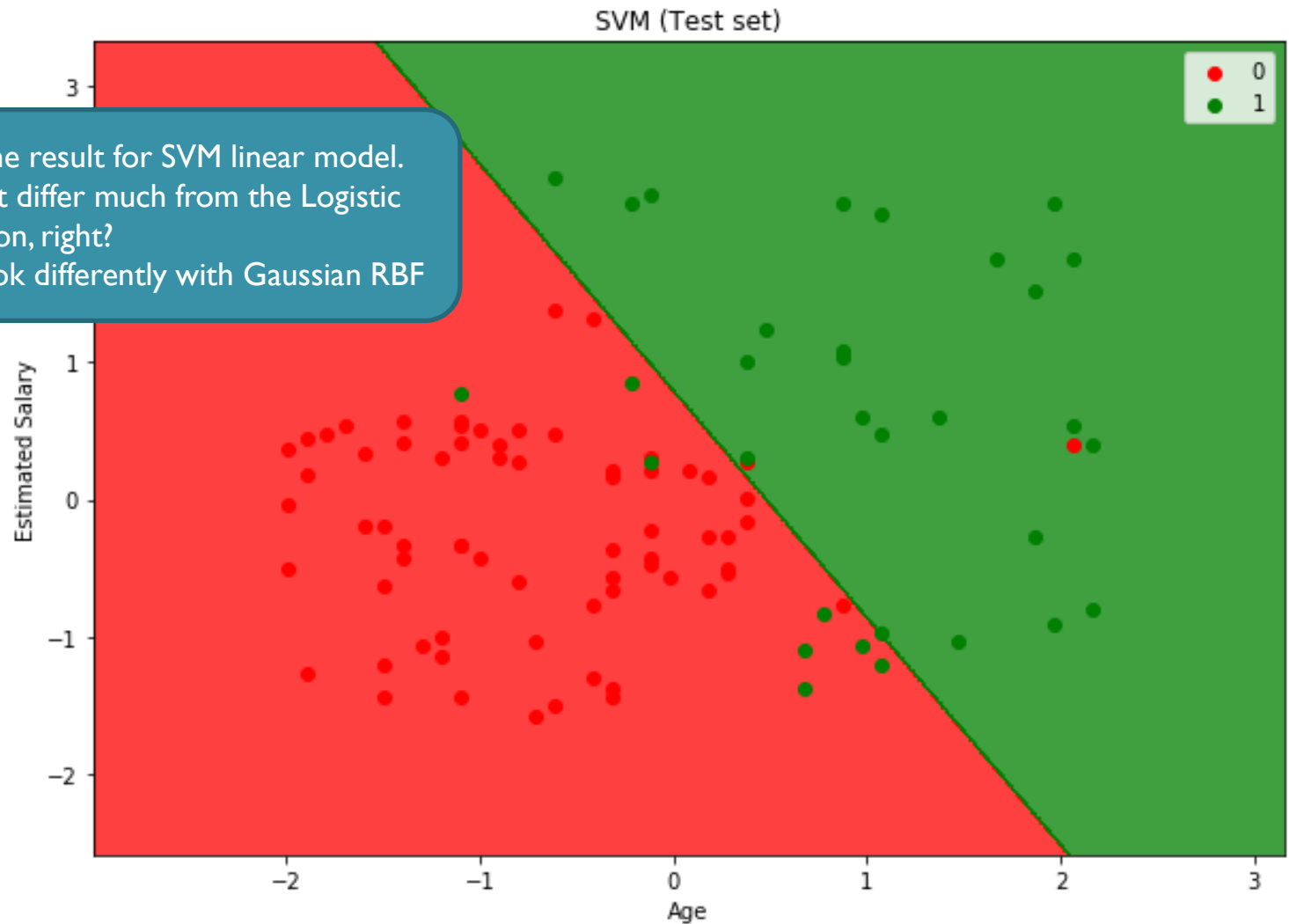


# SVM

What SVM does on its turn?  
It searches for the apples which look most like oranges  
and oranges which look most like apples

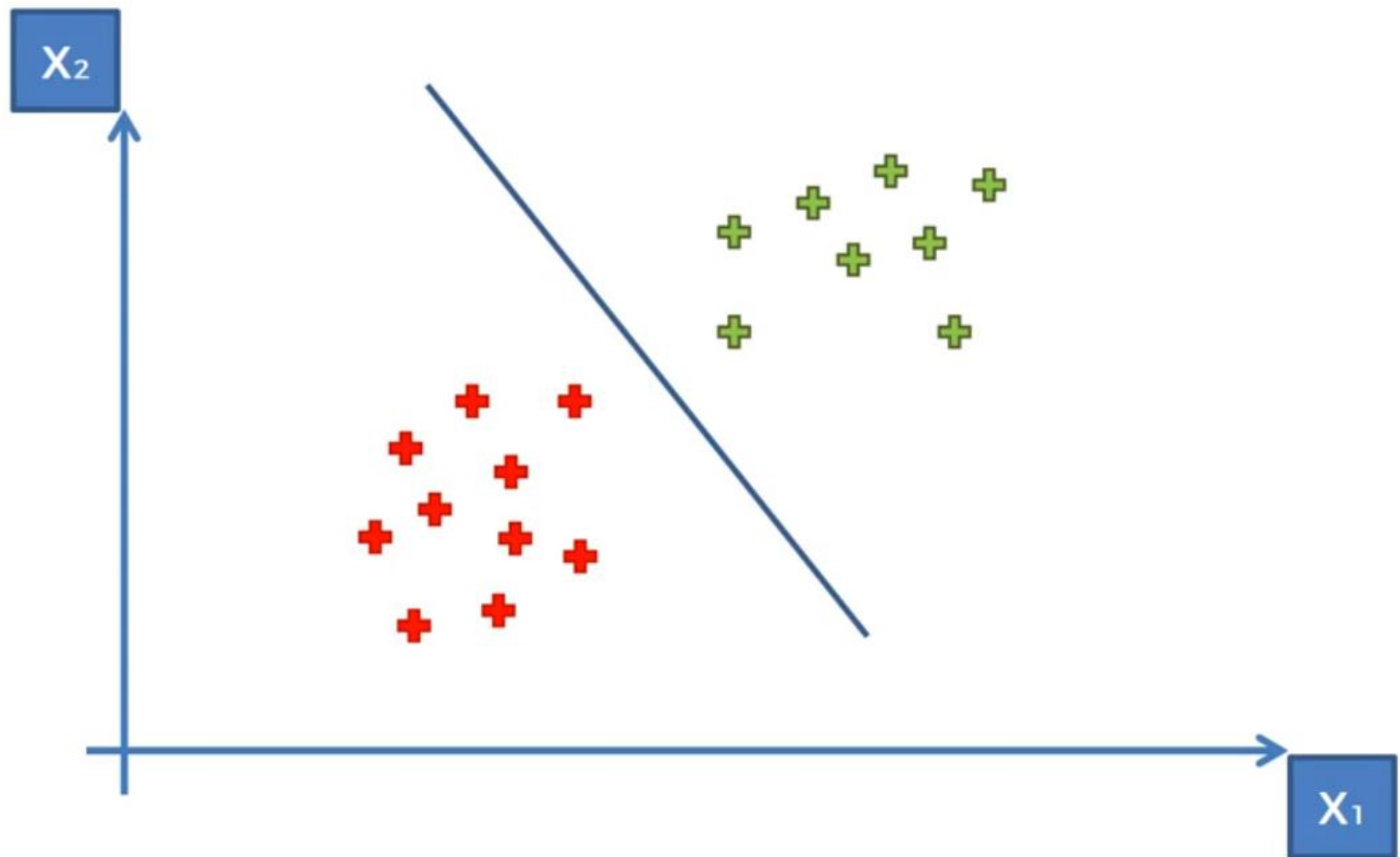


# Lab's output

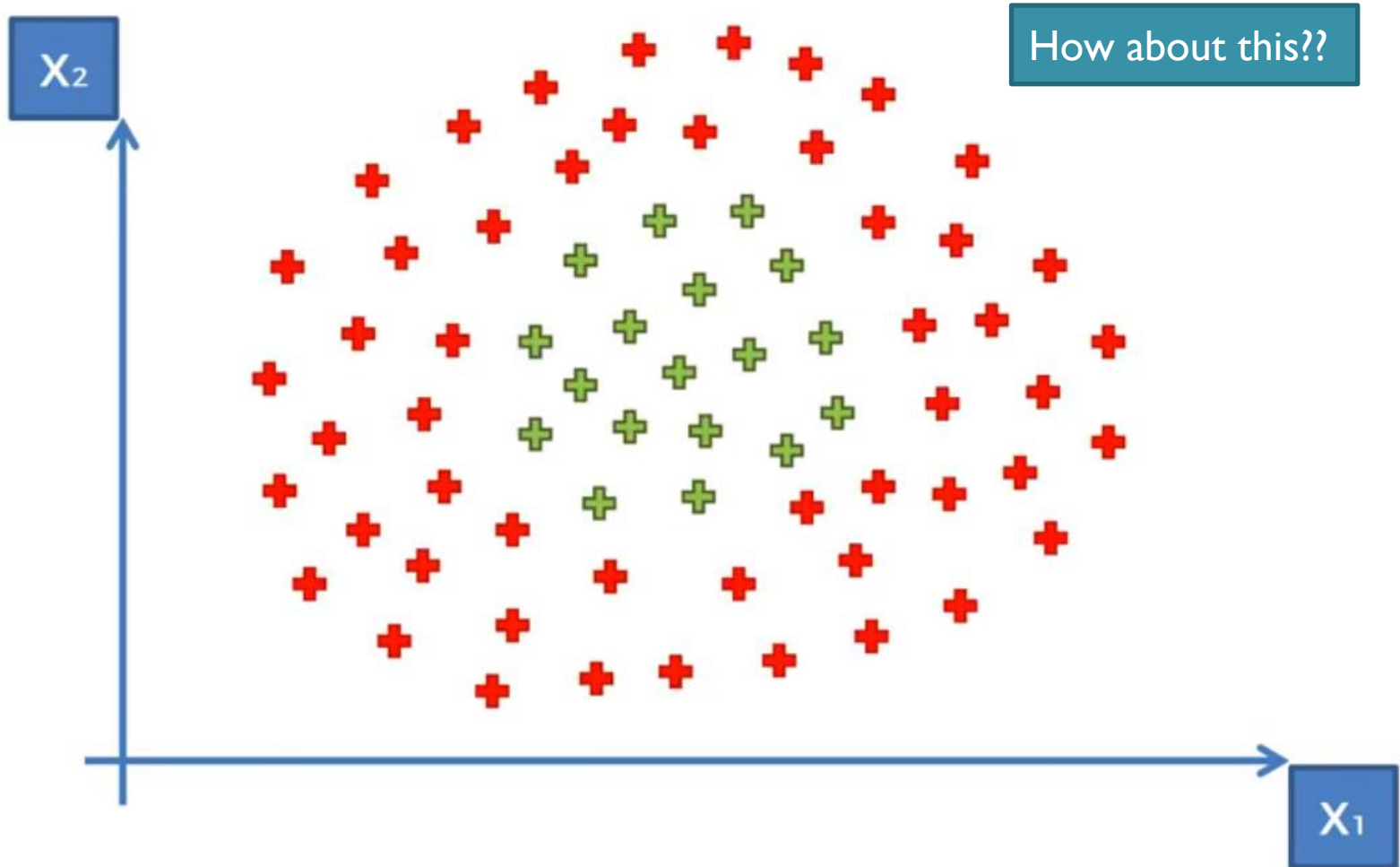




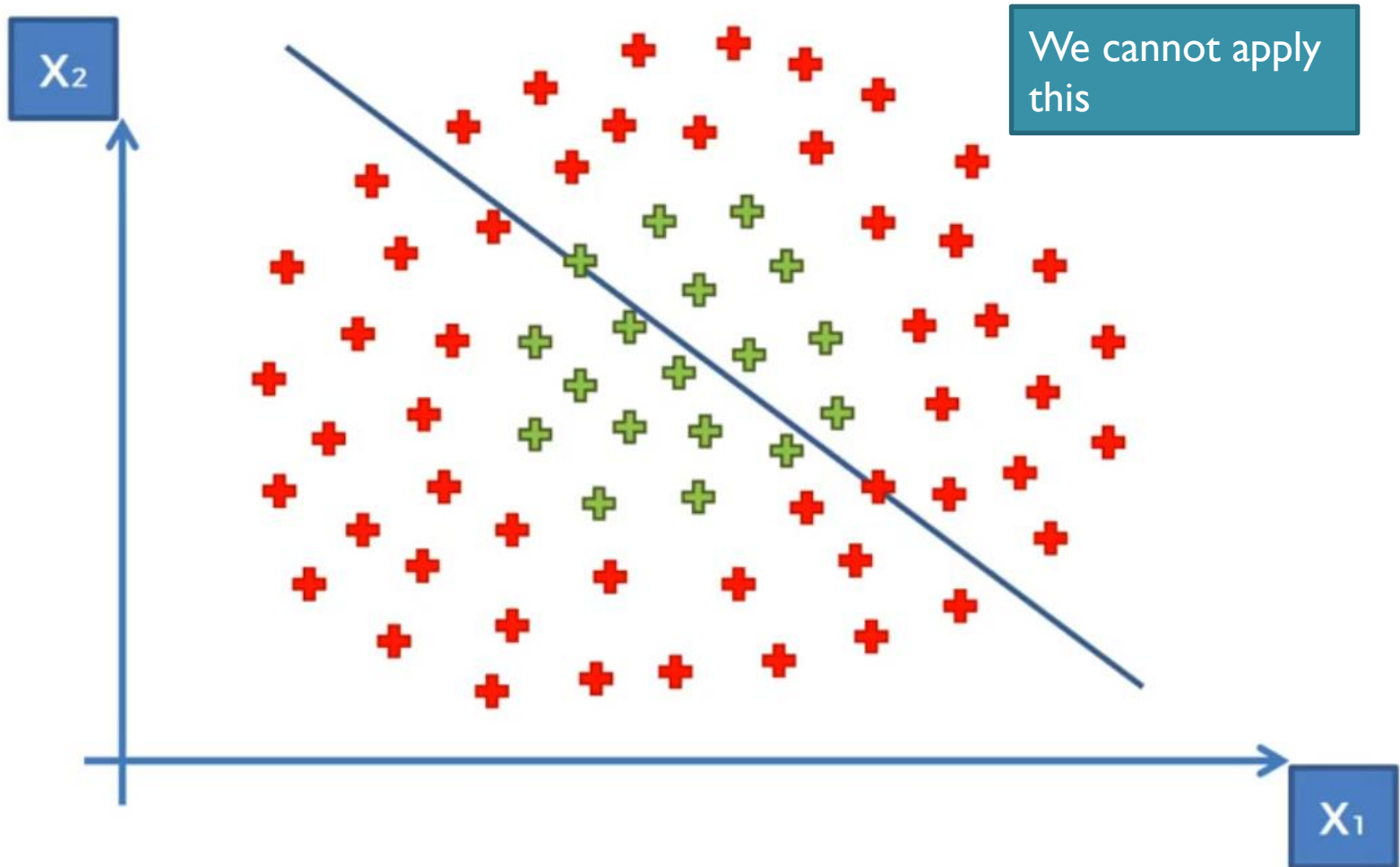
# SVM. Part 2



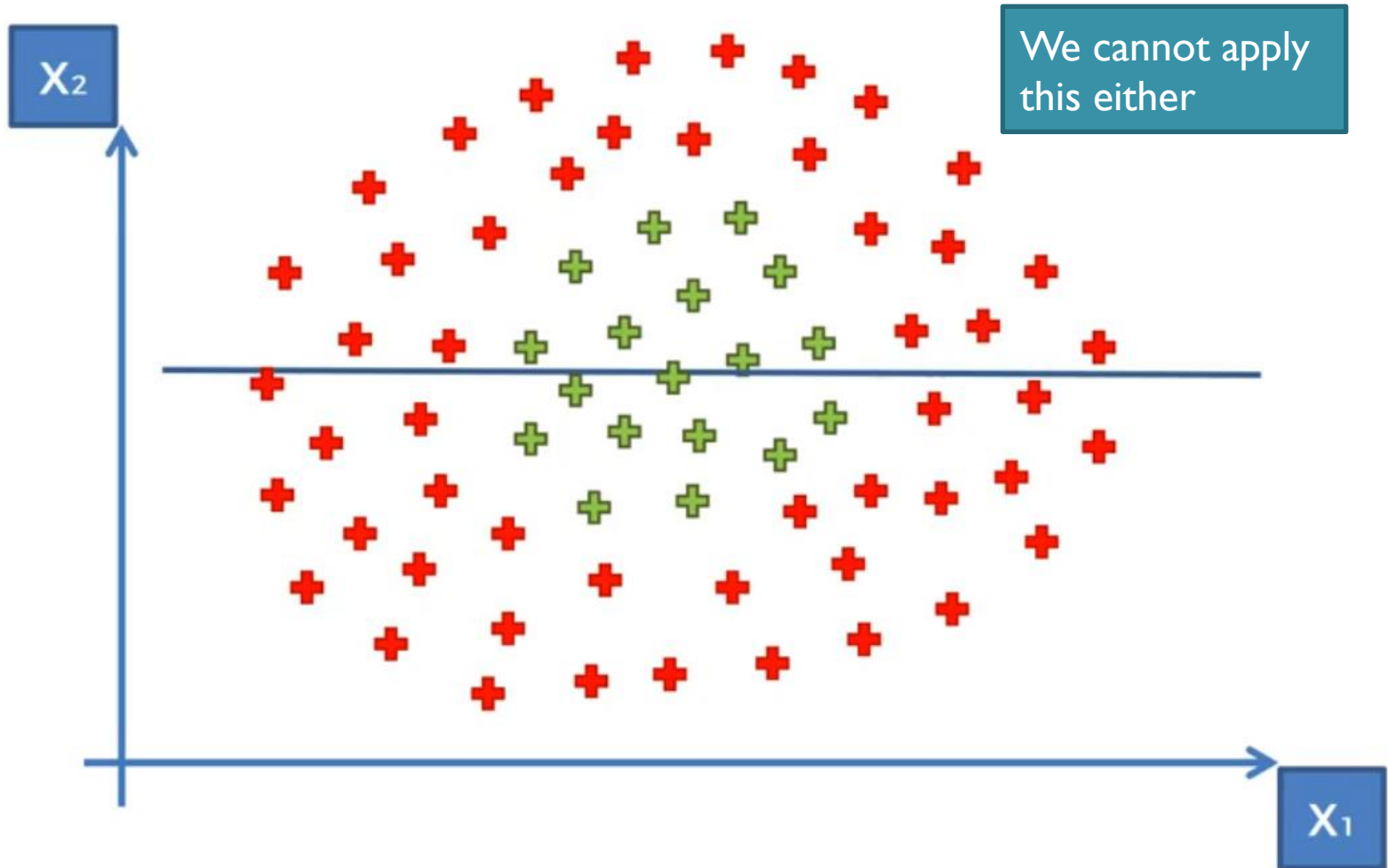
# SVM. Part 2



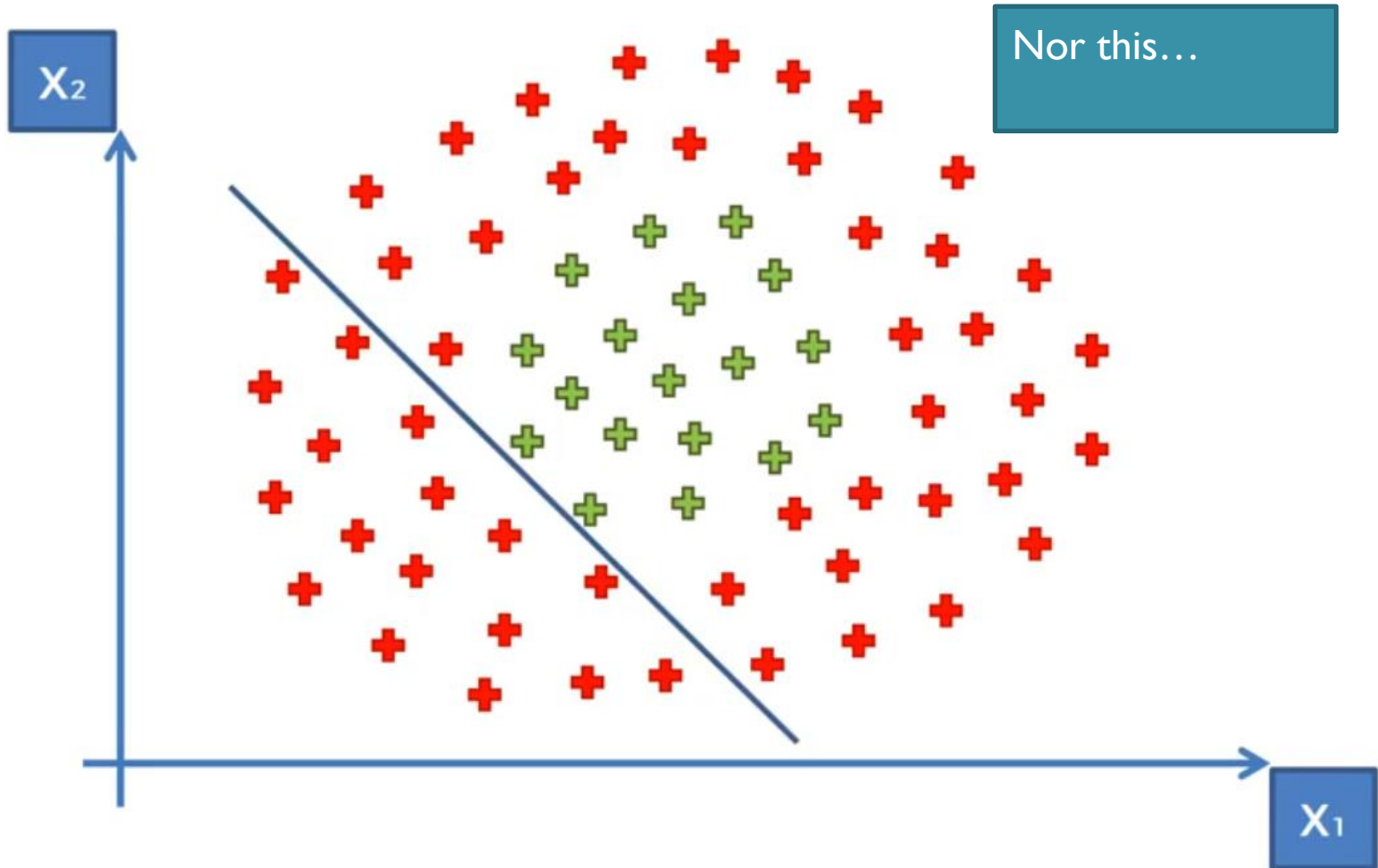
# SVM. Part 2



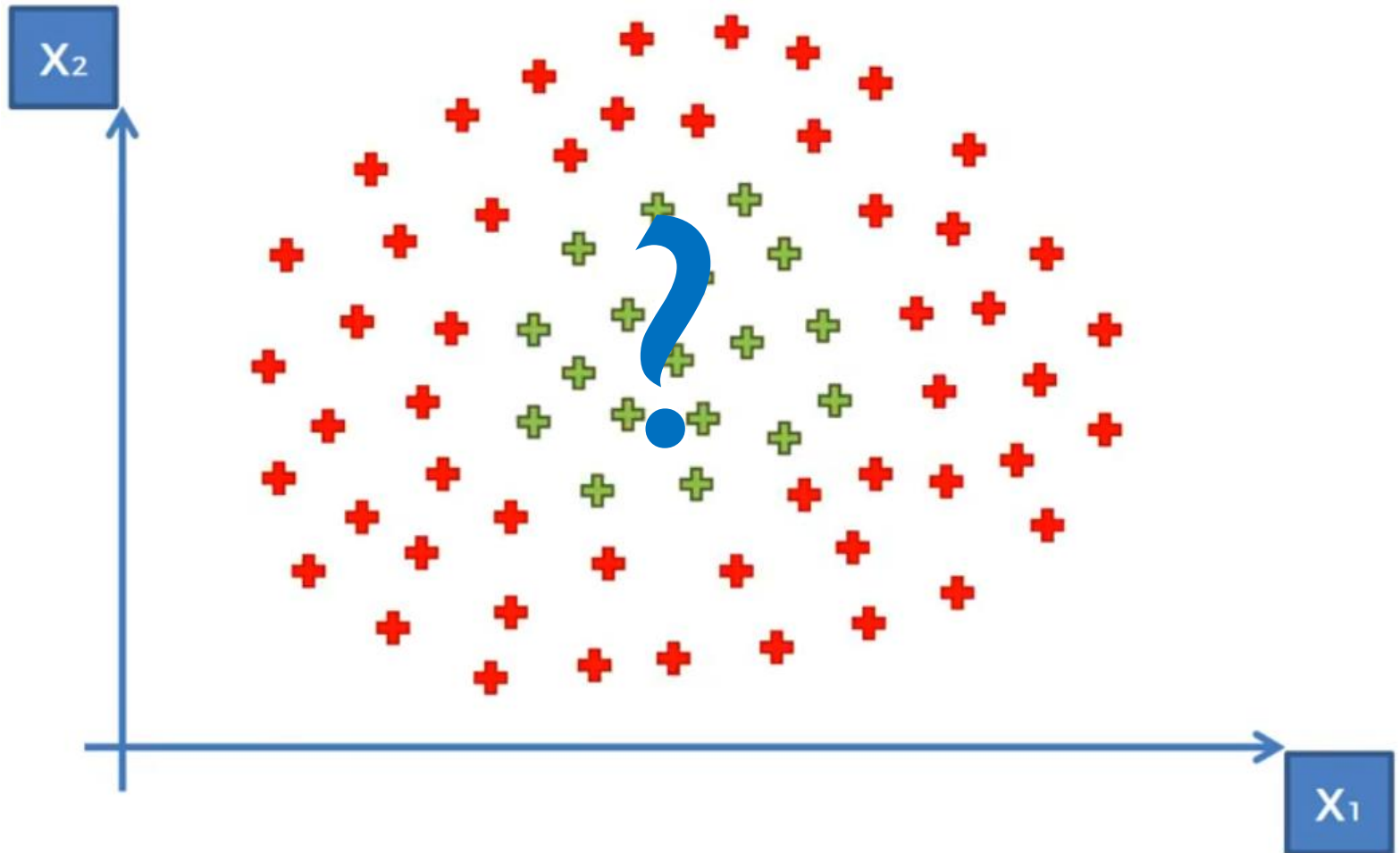
# SVM. Part 2



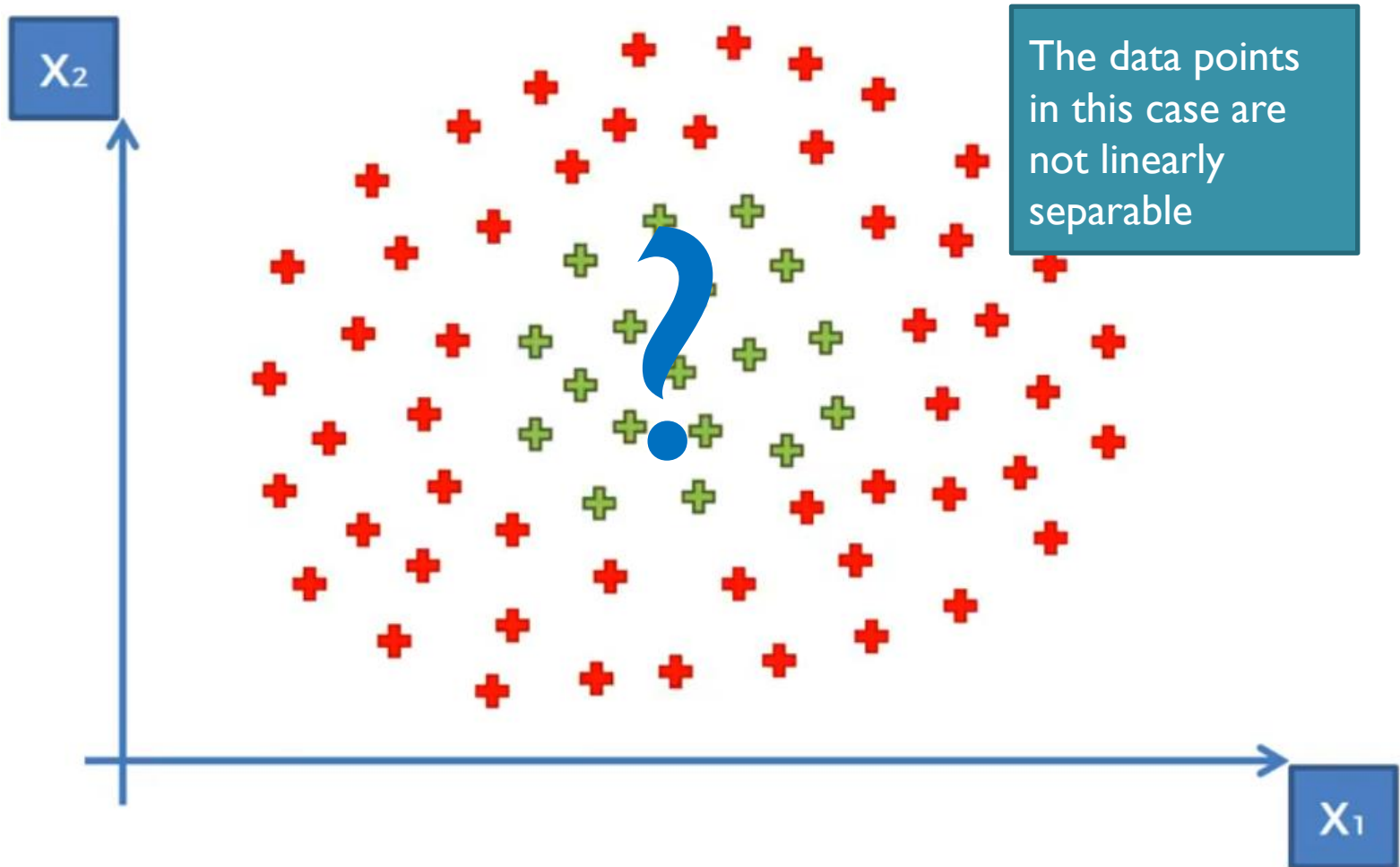
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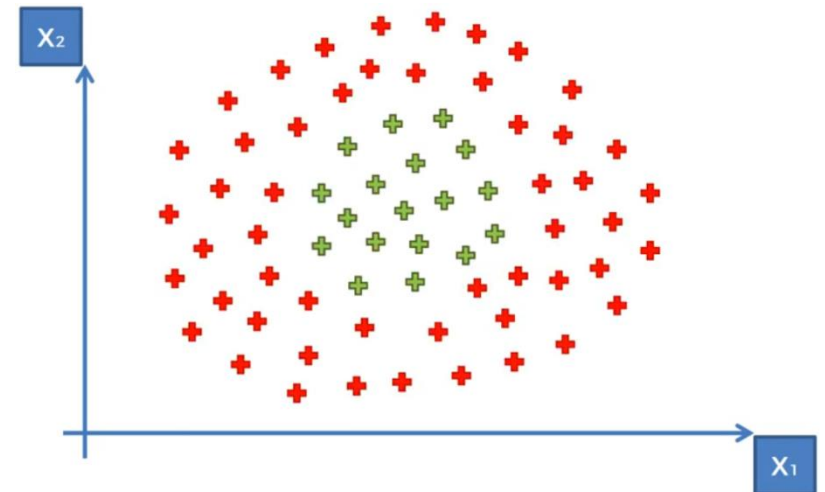
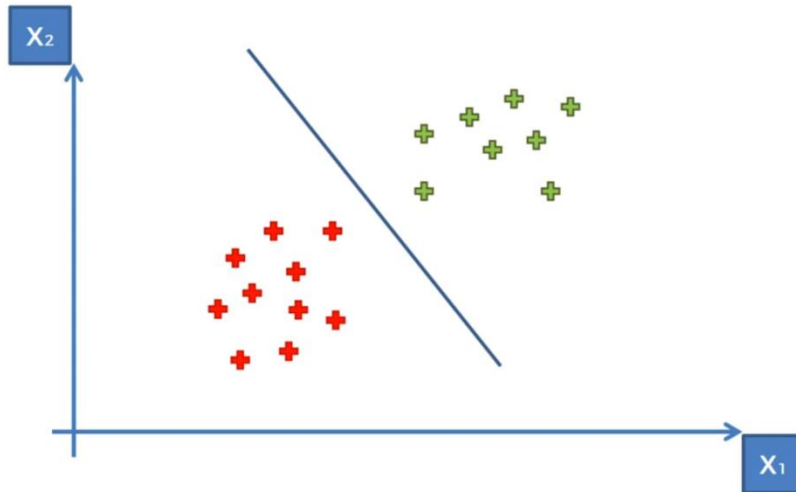
# SVM. Part 2



# SVM. Part 2

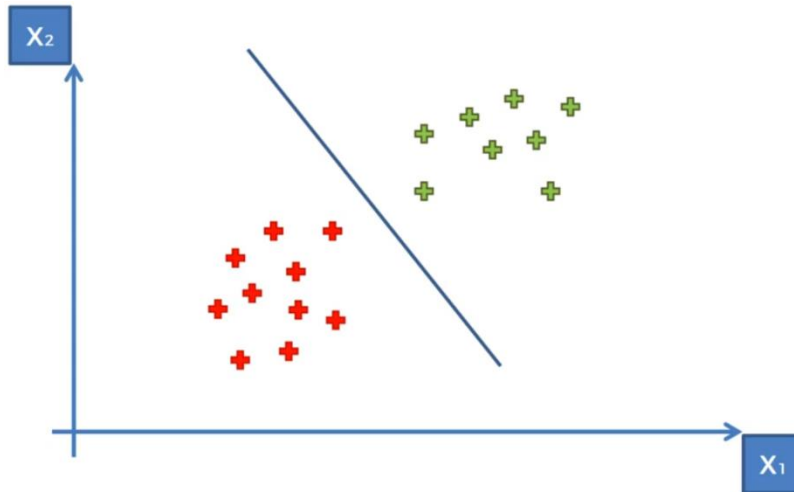


# Linearly separable vs not separable

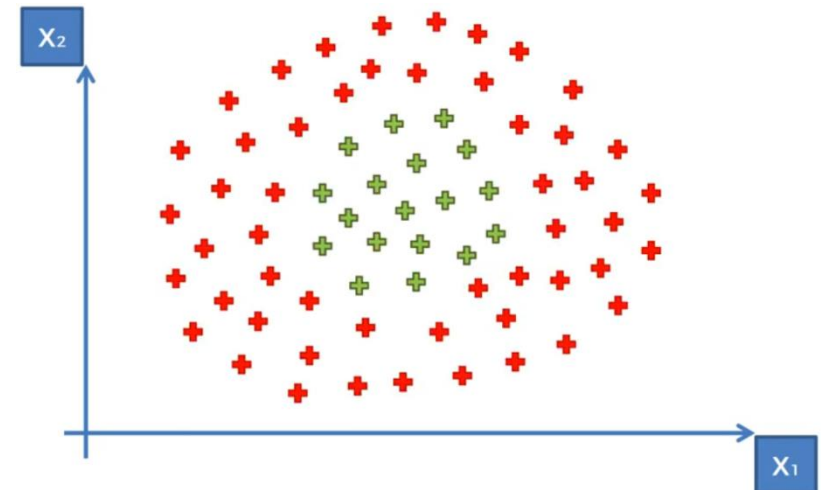




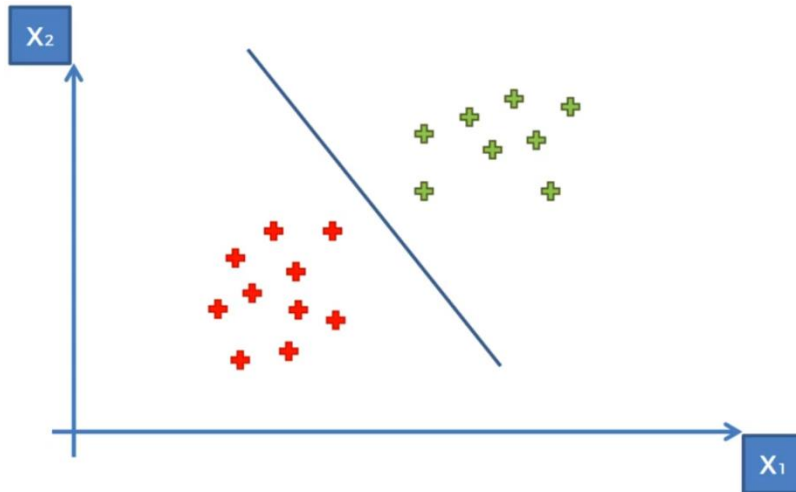
# Linearly separable vs not separable



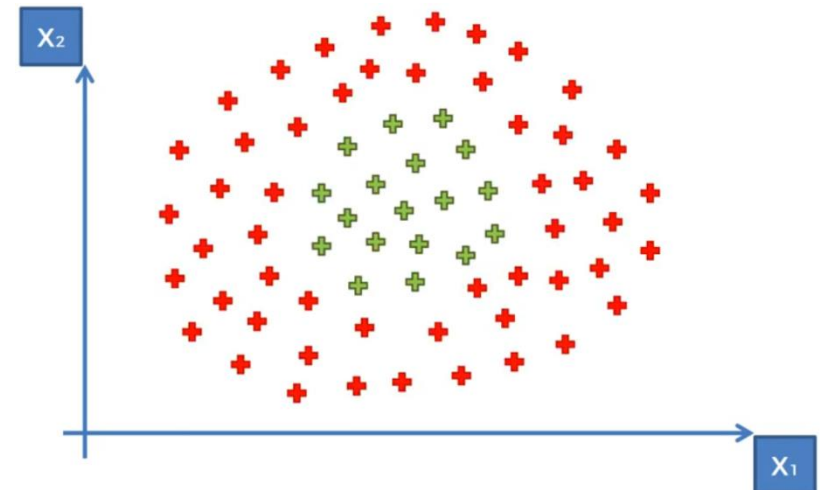
SVM has an assumption that it can be linearly separated



# Linearly separable vs not separable



SVM has an assumption that it can be linearly separated.  
How?  
By adding extra dimension



# Mapping to a higher dimension

Let's start w/ the  
simple example –  
1D



# Mapping to a higher dimension

Let's apply a  
function  
 $f = x - 5$



# Mapping to a higher dimension

Let's apply a  
function  
 $f = x - 5$

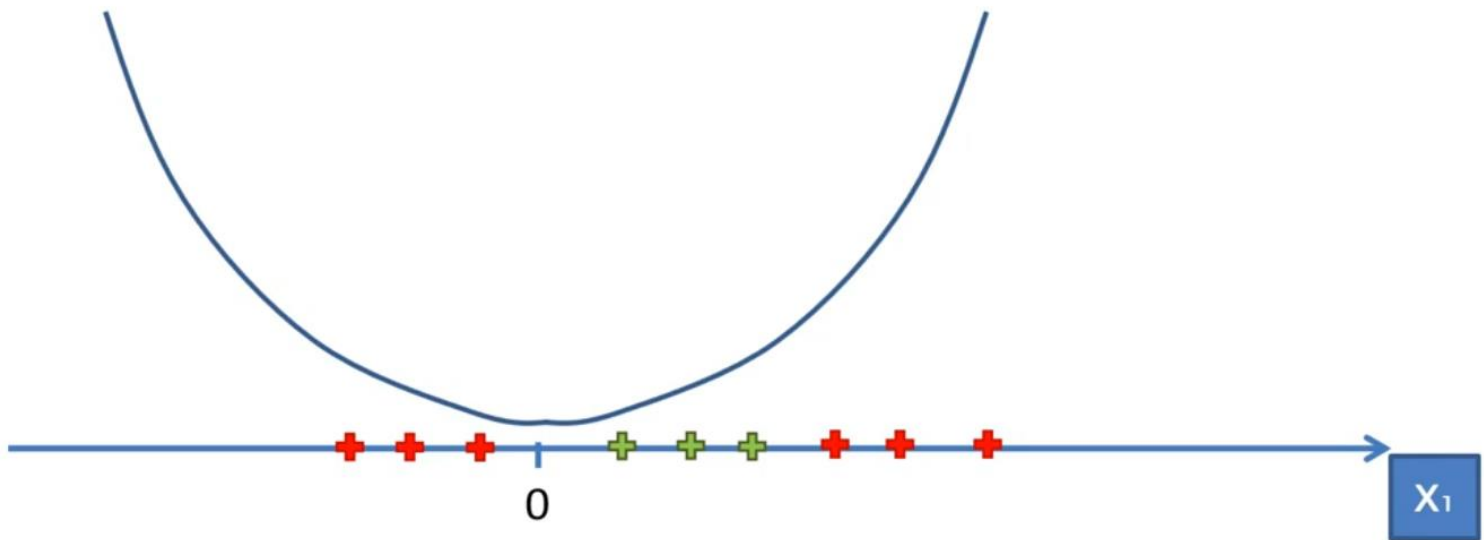


# Mapping to a higher dimension

Now let's square  
all that:  
 $f = (x-5)^2$

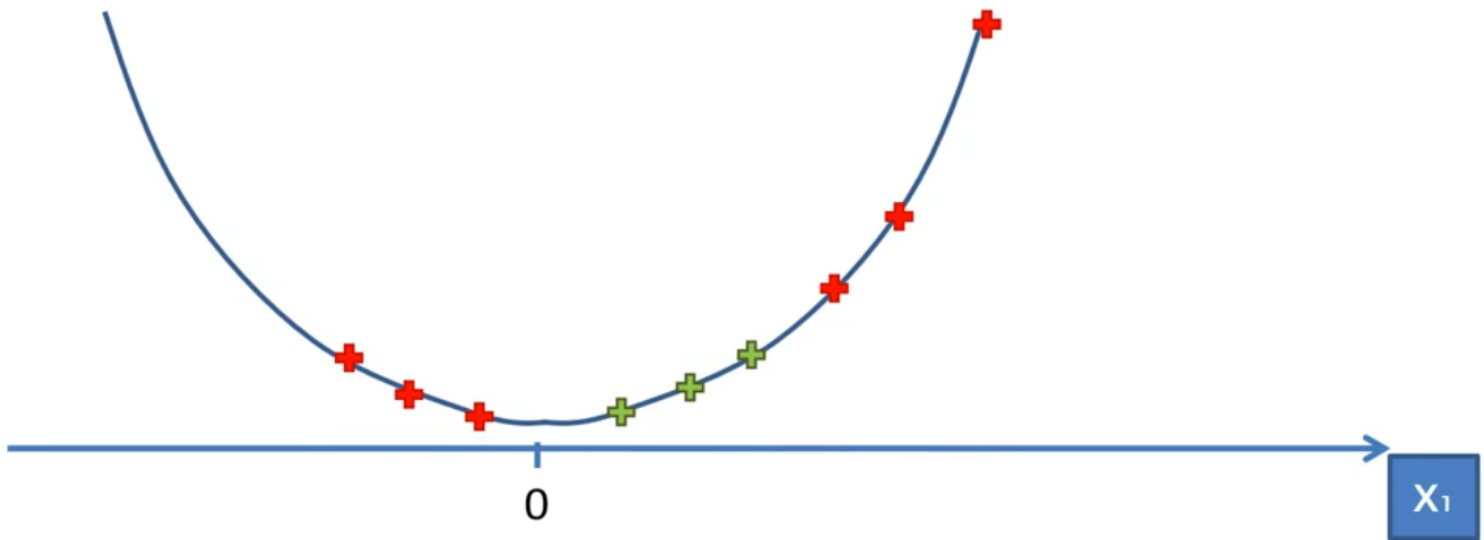


# Mapping to a higher dimension



Now let's square  
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 $f = (x-5)^2$

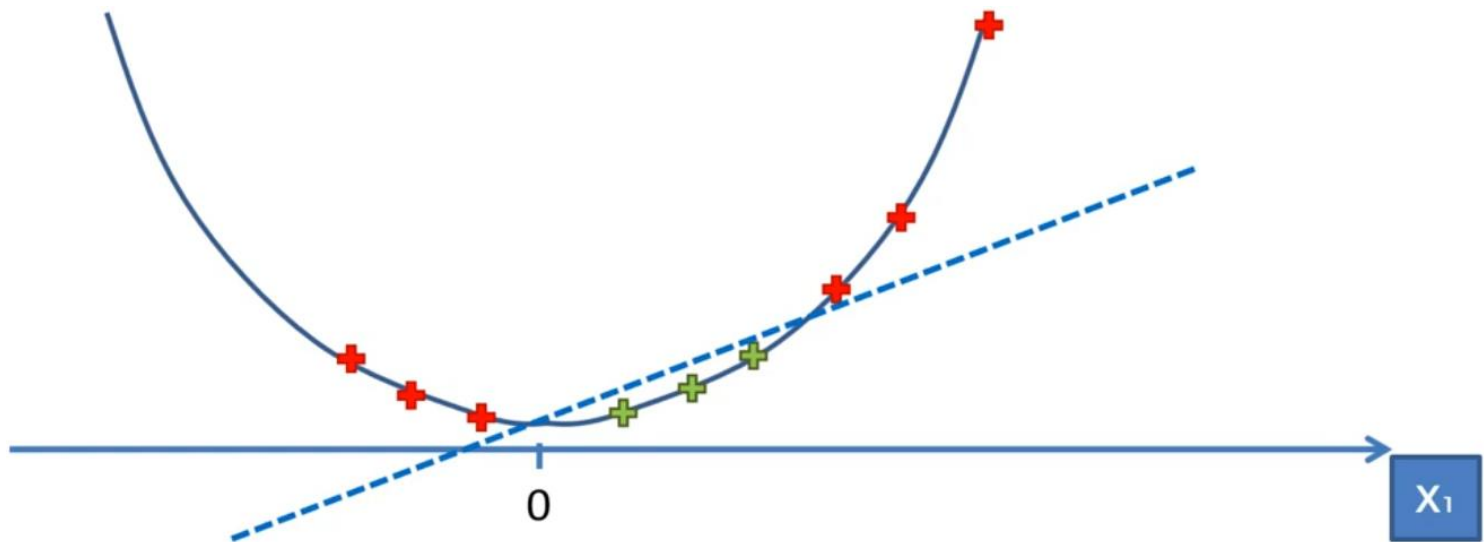
# Mapping to a higher dimension



Now let's square  
all that:  
 $f = (x-5)^2$

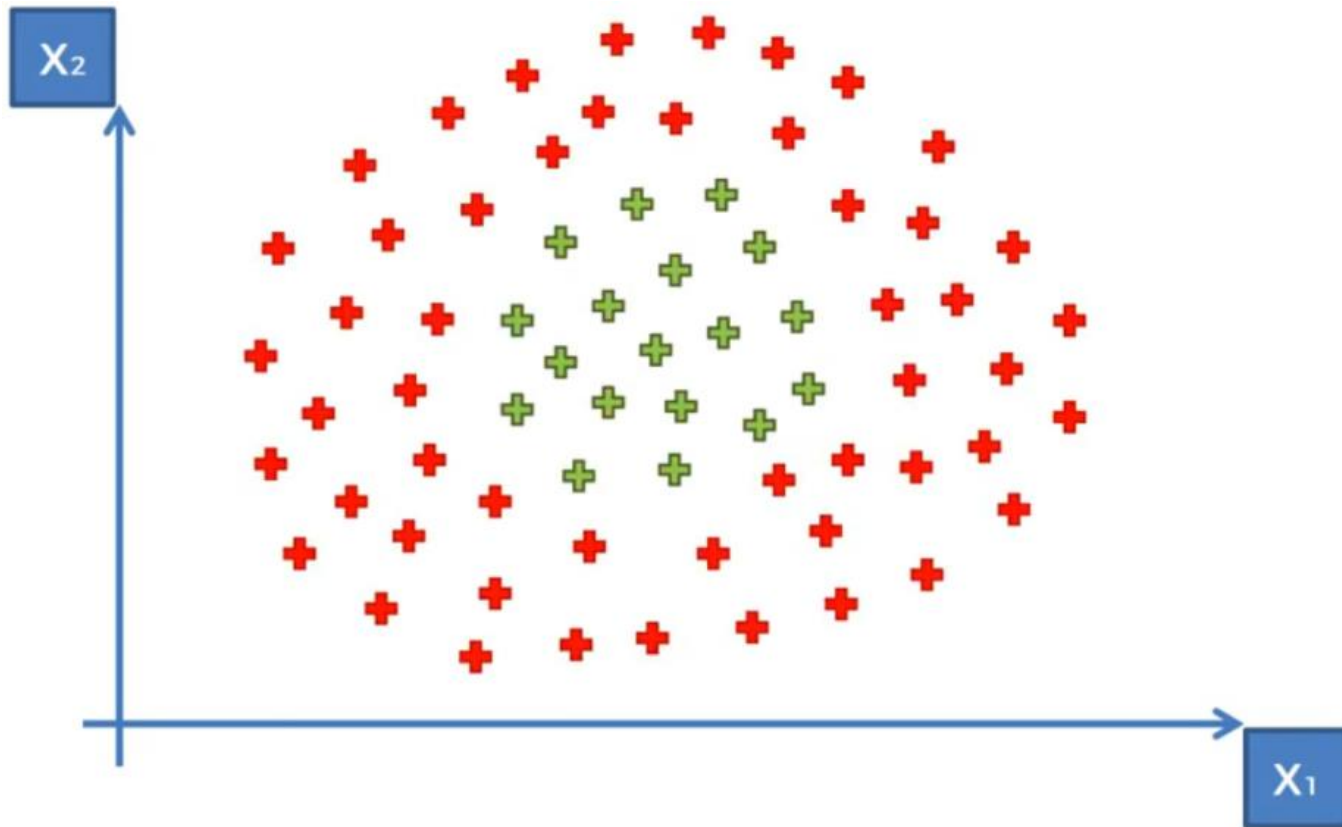


# Mapping to a higher dimension

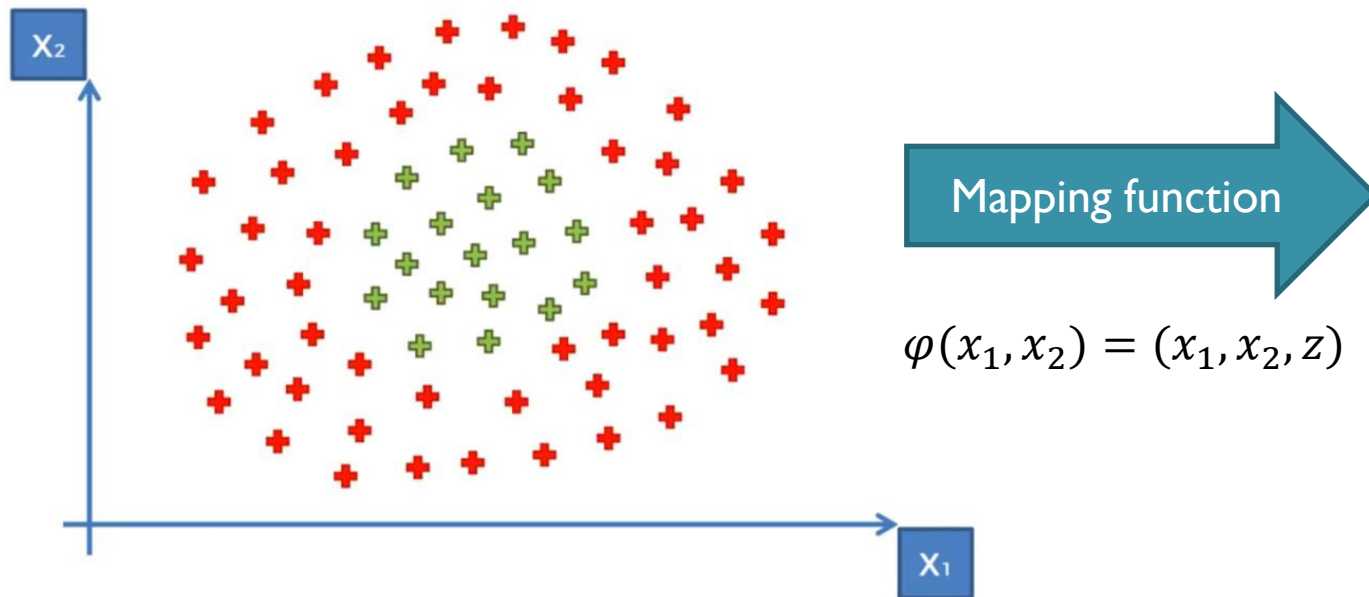


Finally we see  
that we can  
separate it

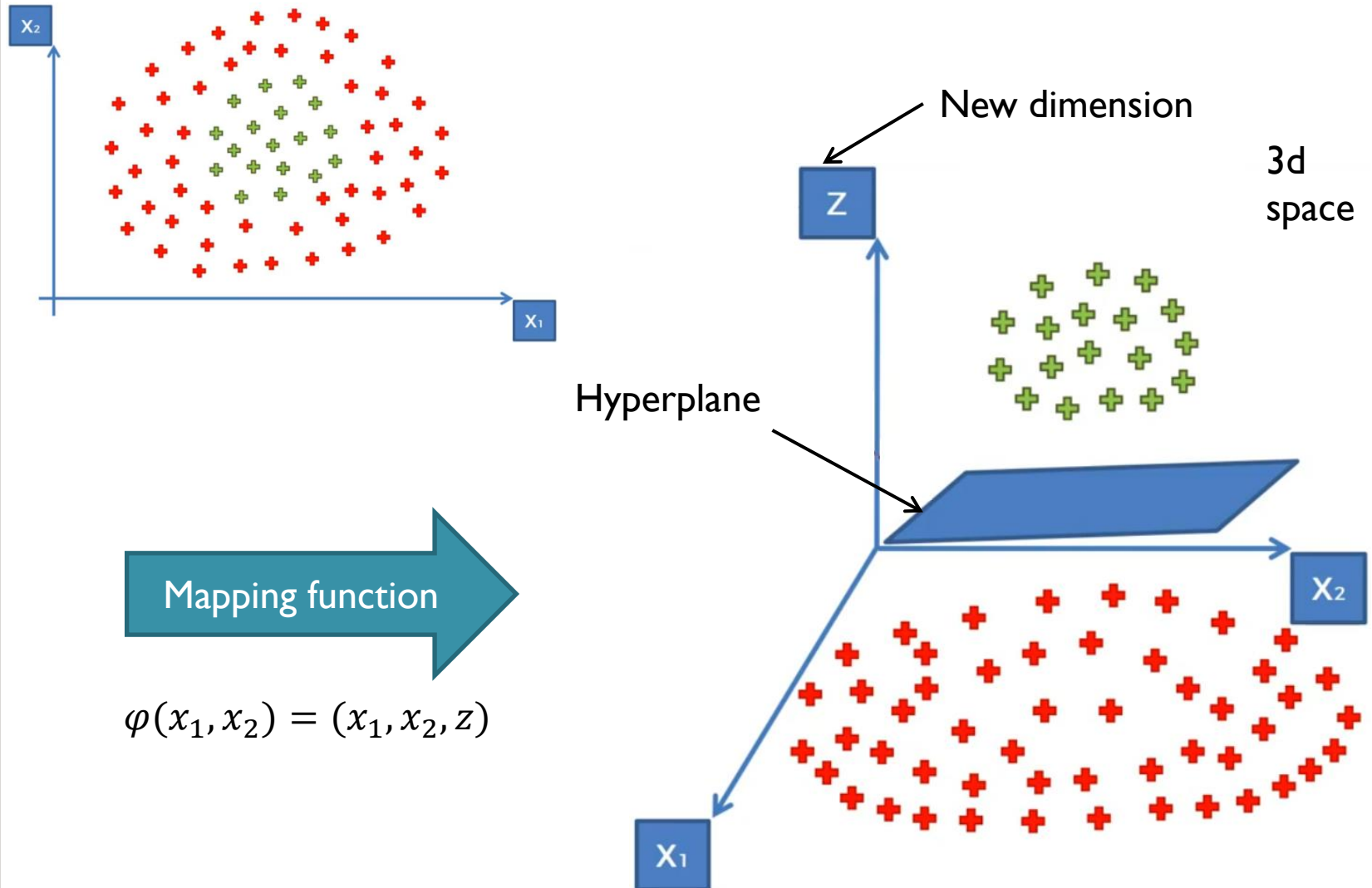
# Mapping to a higher dimension



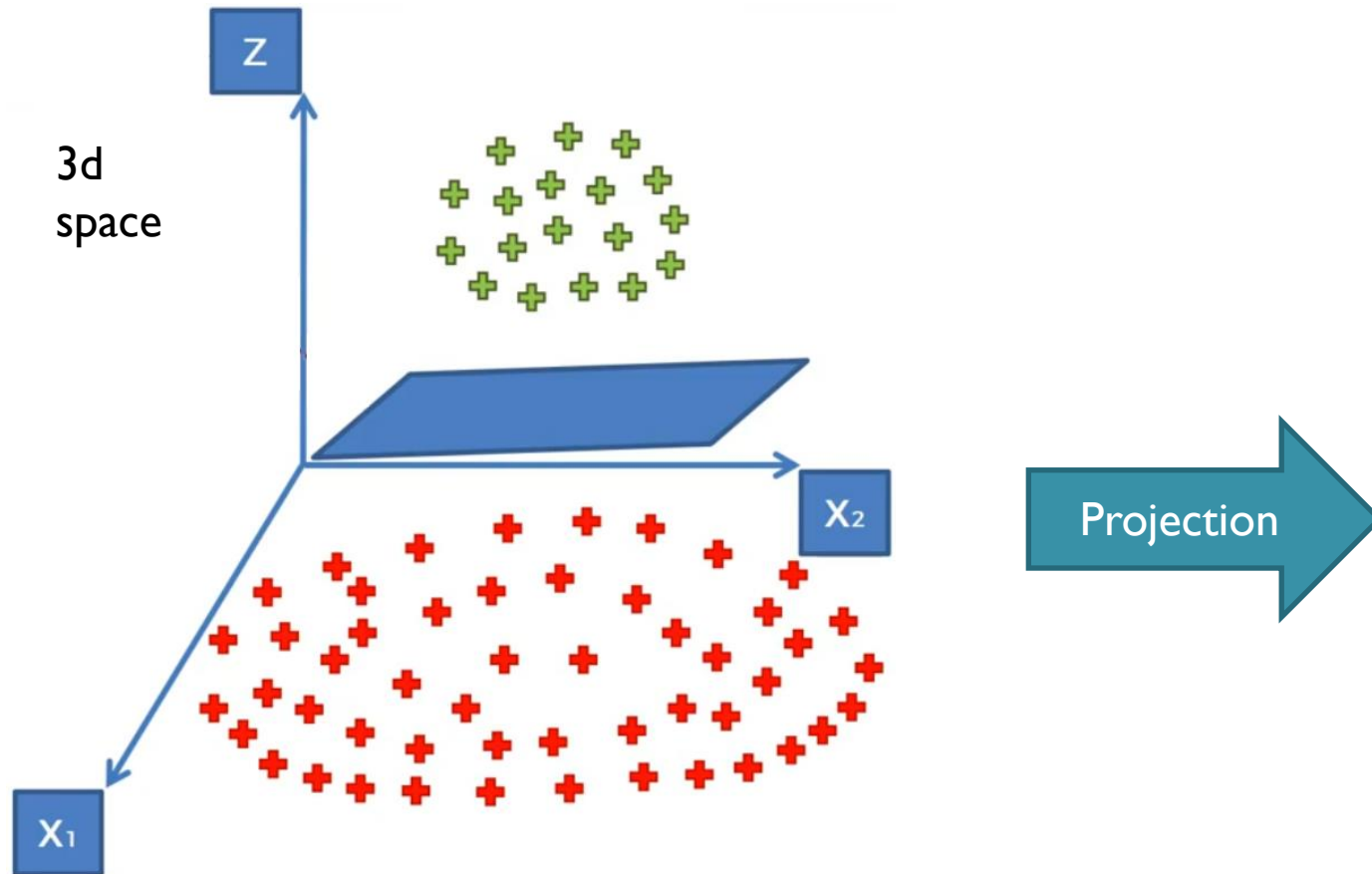
# Mapping to a higher dimension



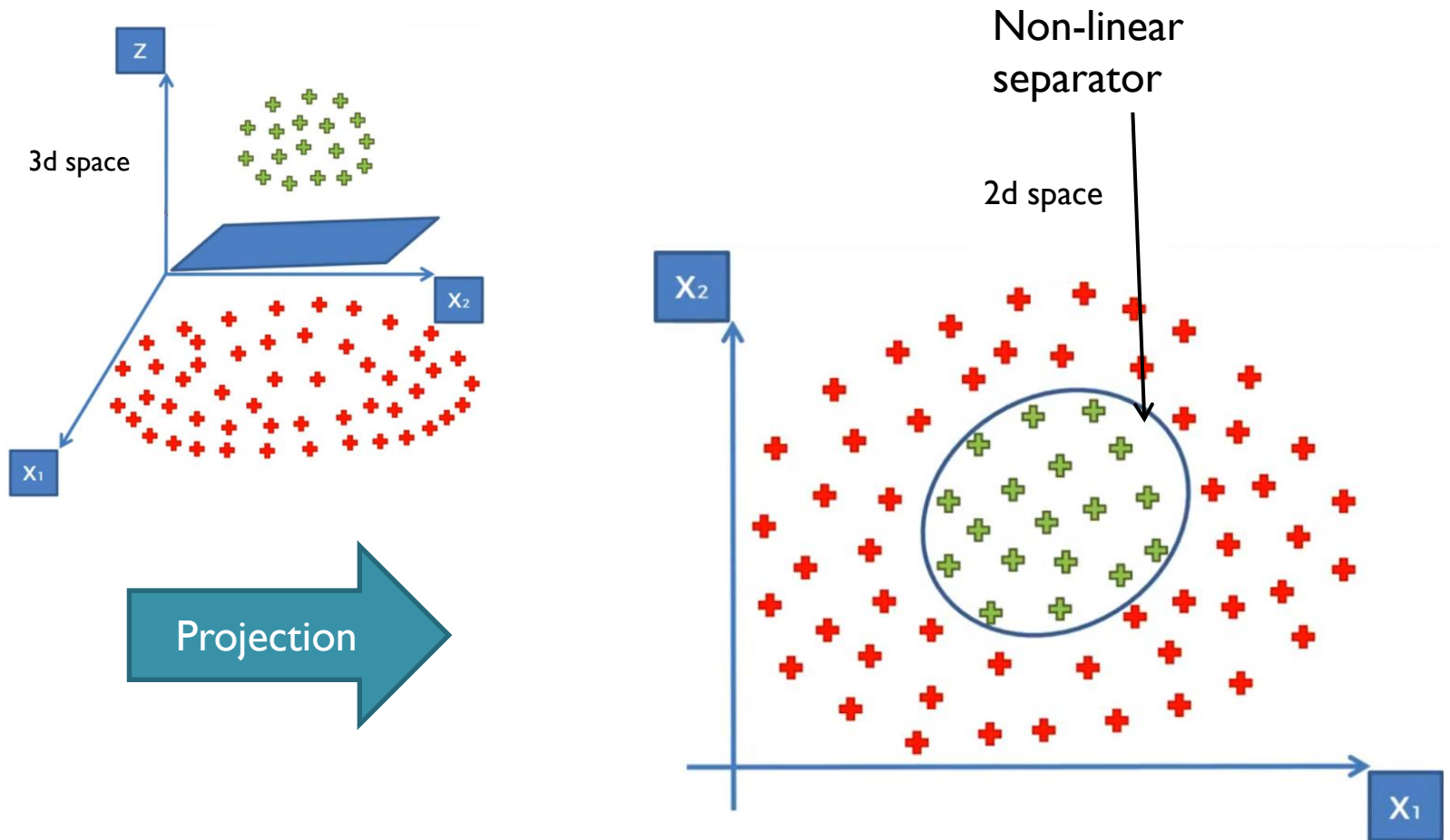
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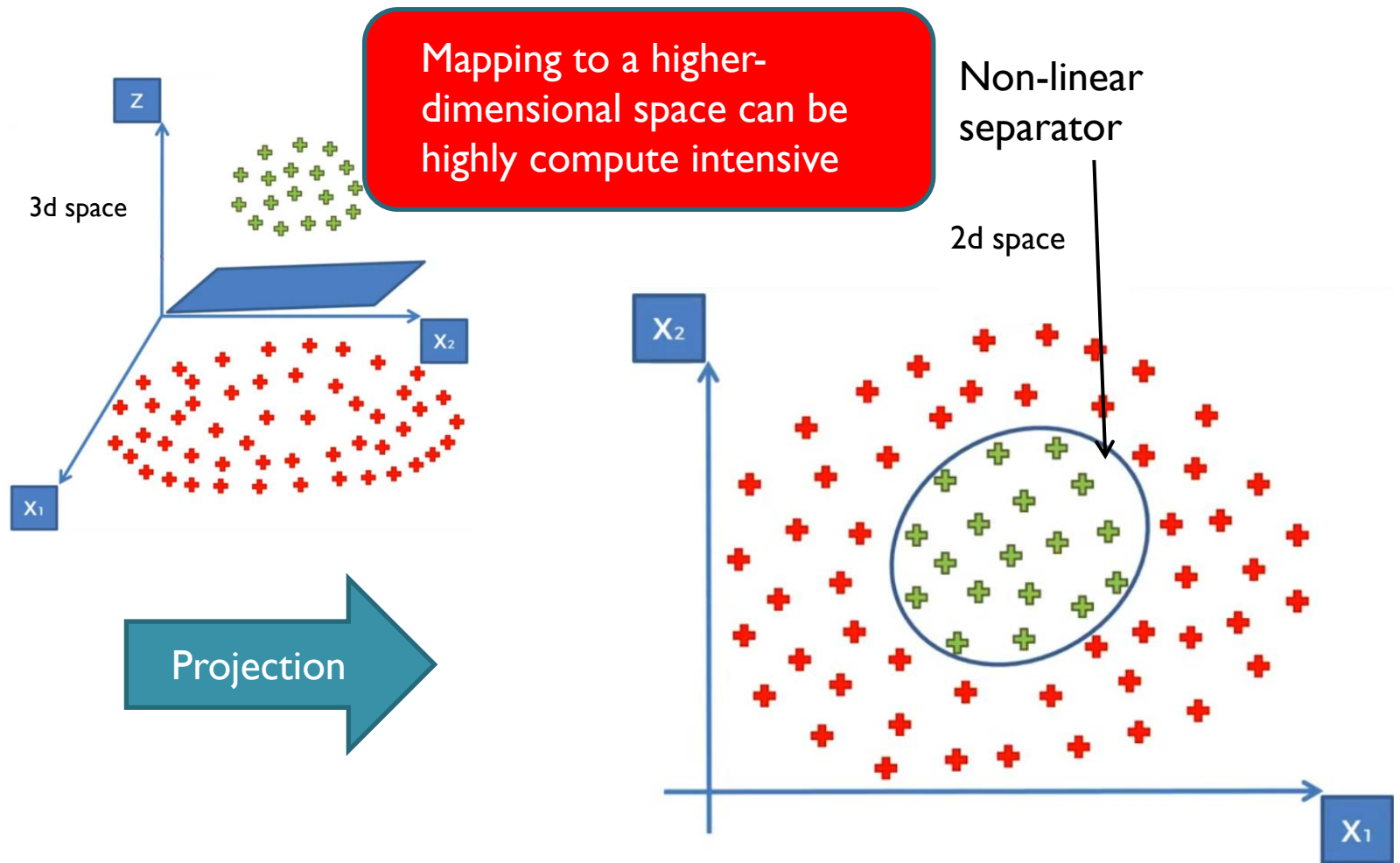
# Mapping to a higher dimension



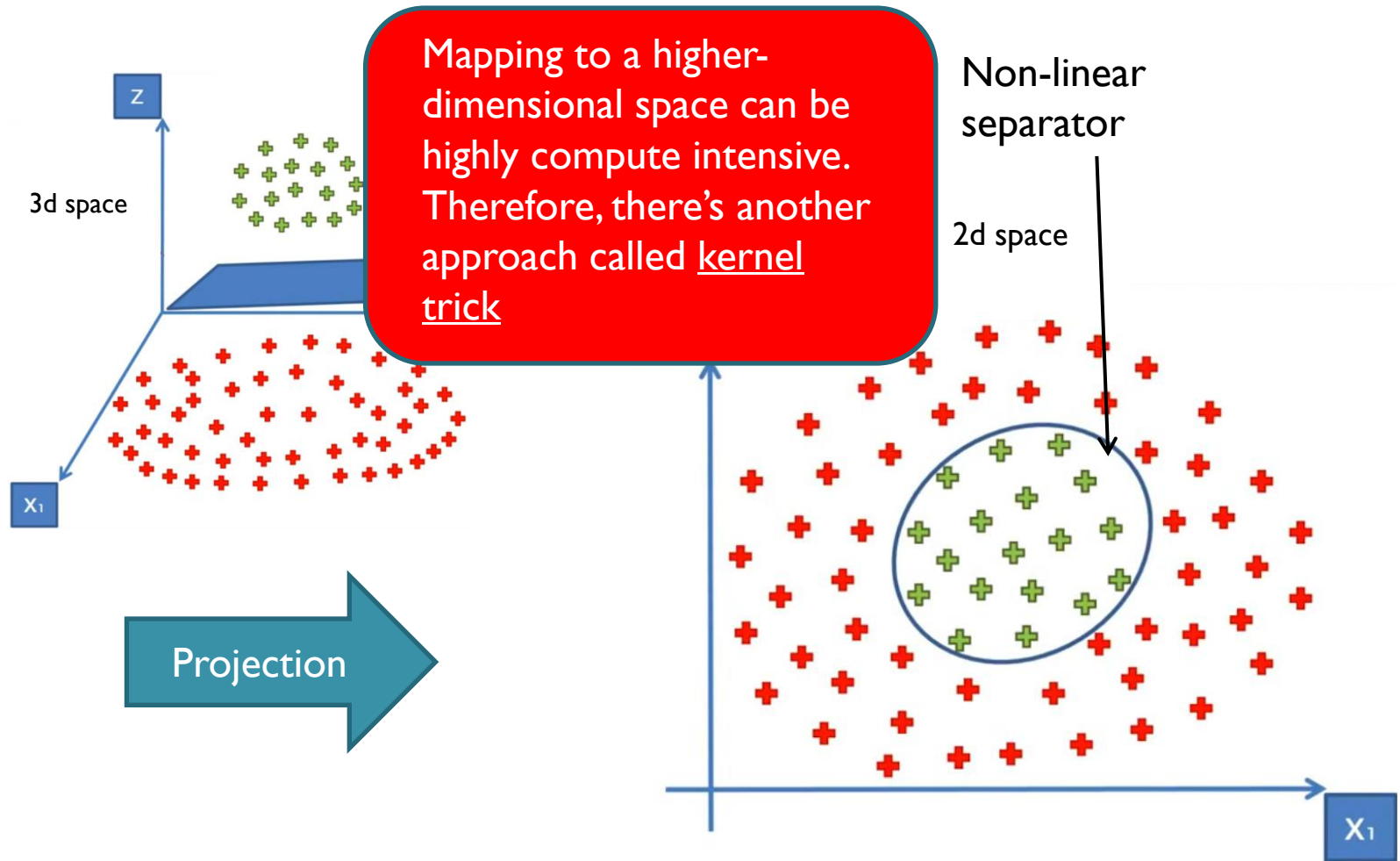
# Mapping to a higher dimension



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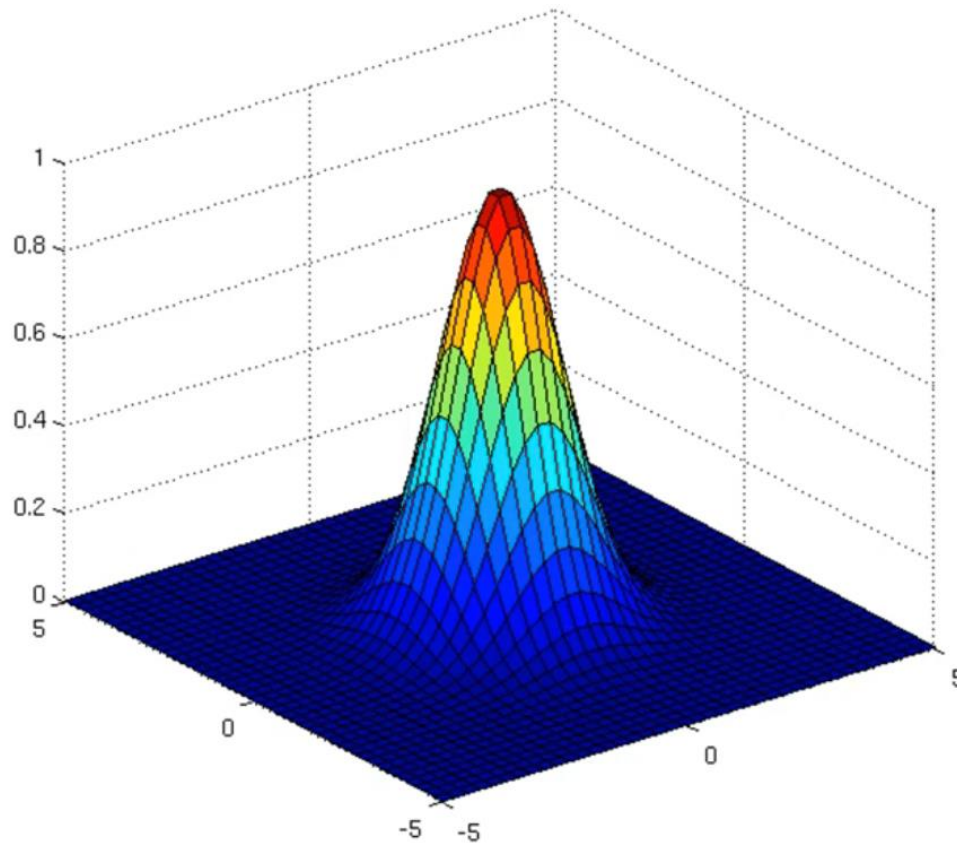




# Kernel trick

$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

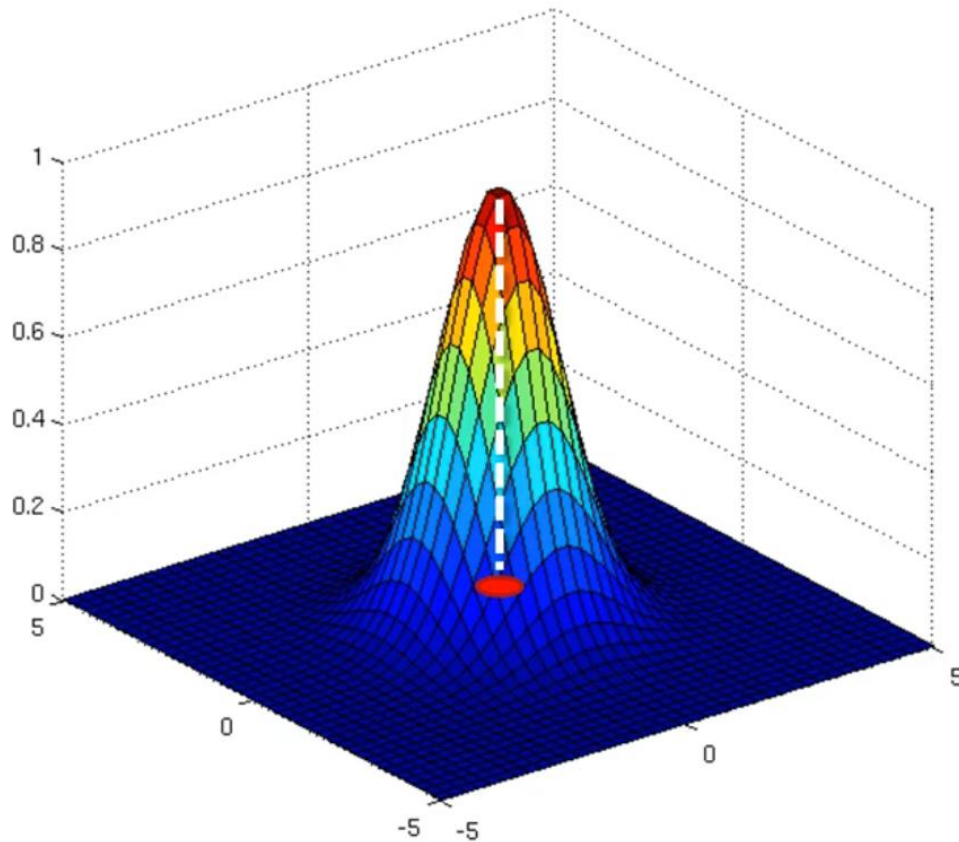
# Kernel trick



Gaussian  
Radial basis  
function (RBF)

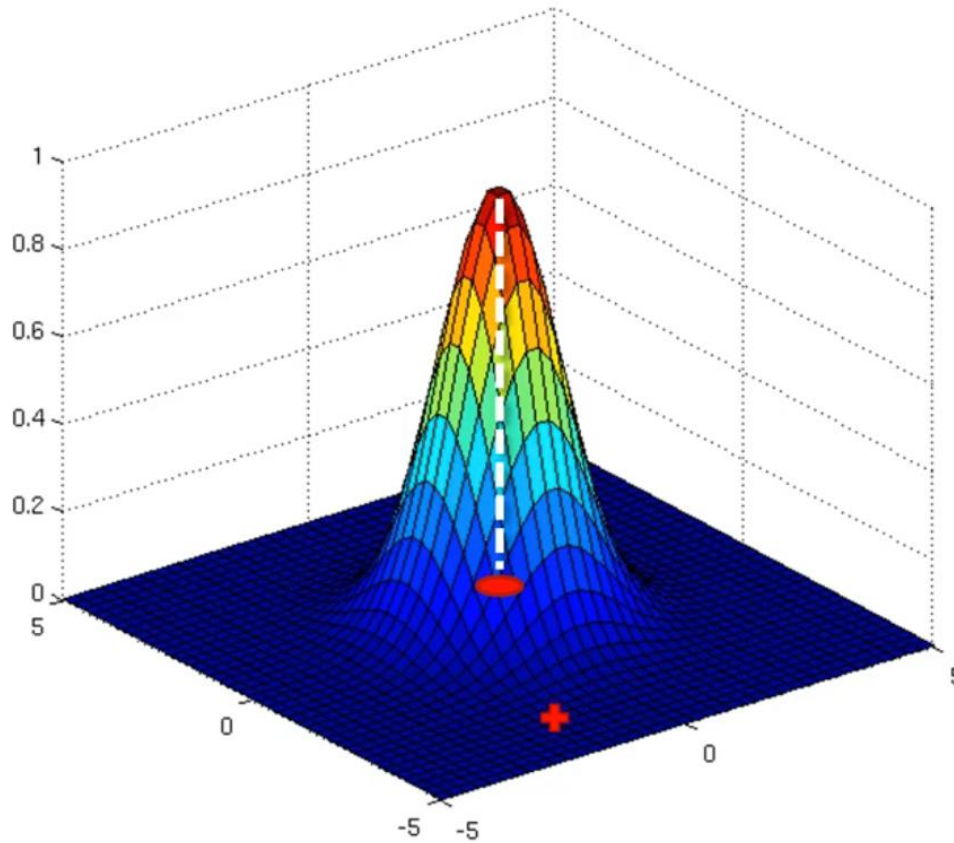
$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

# Kernel trick



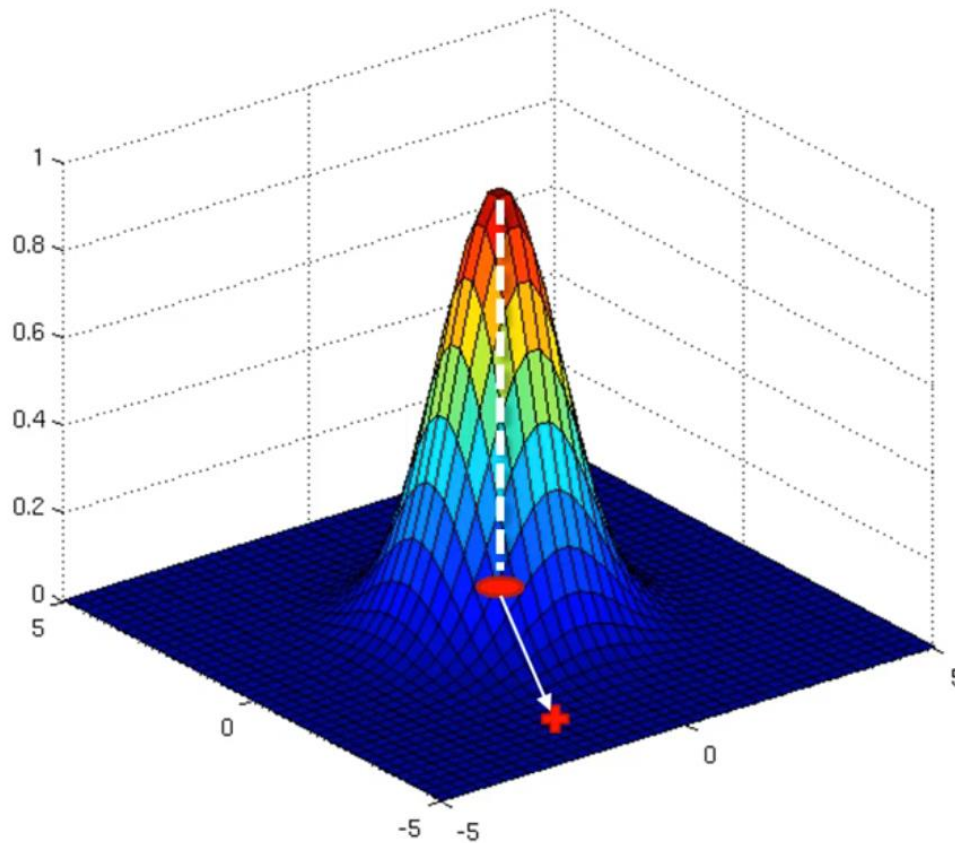
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# Kernel trick



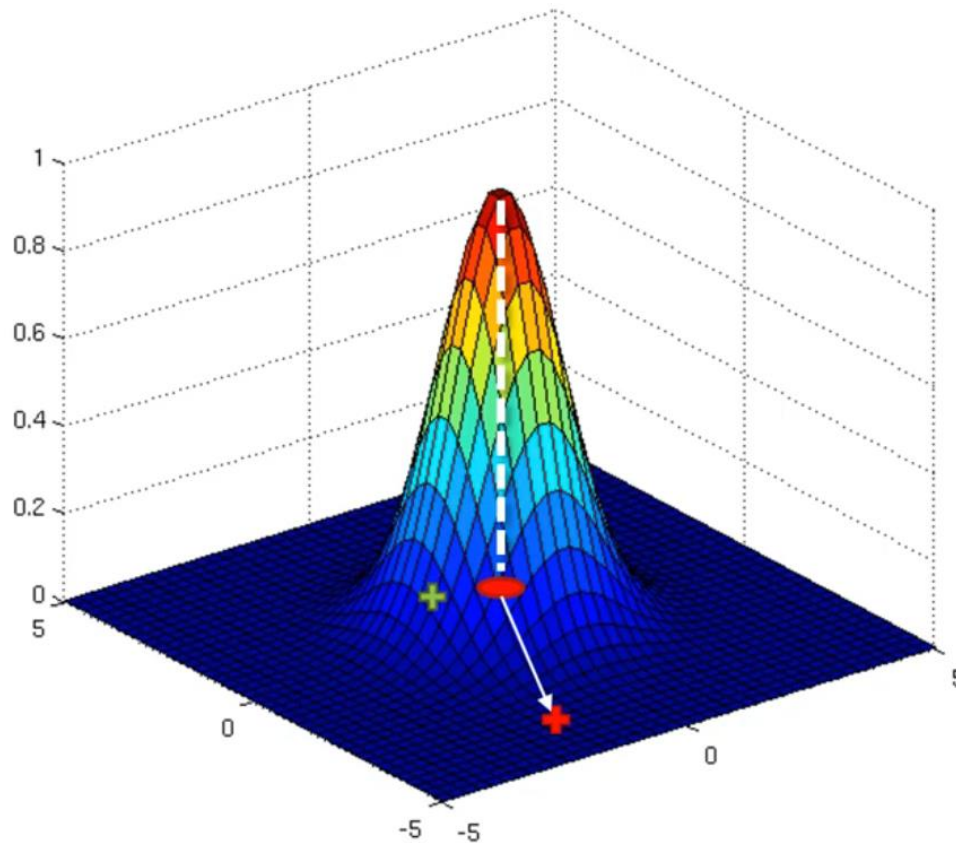
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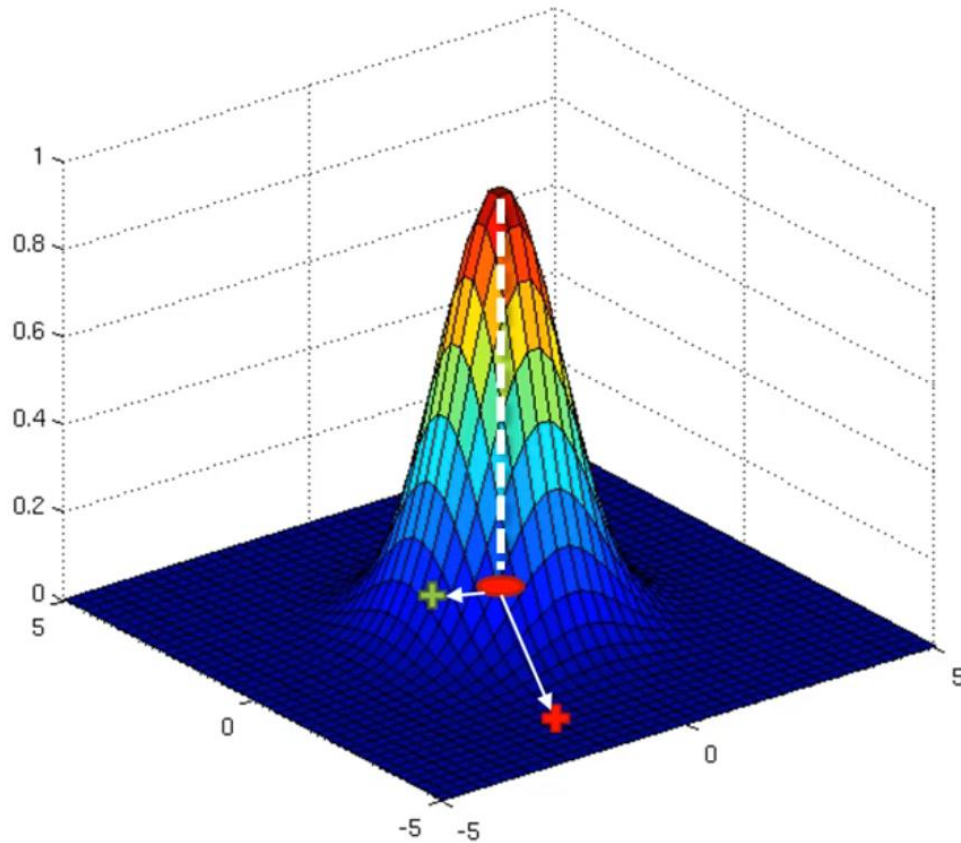
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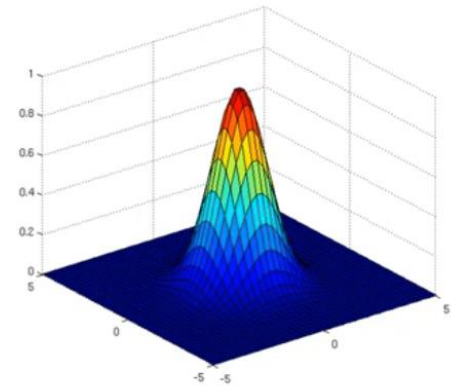
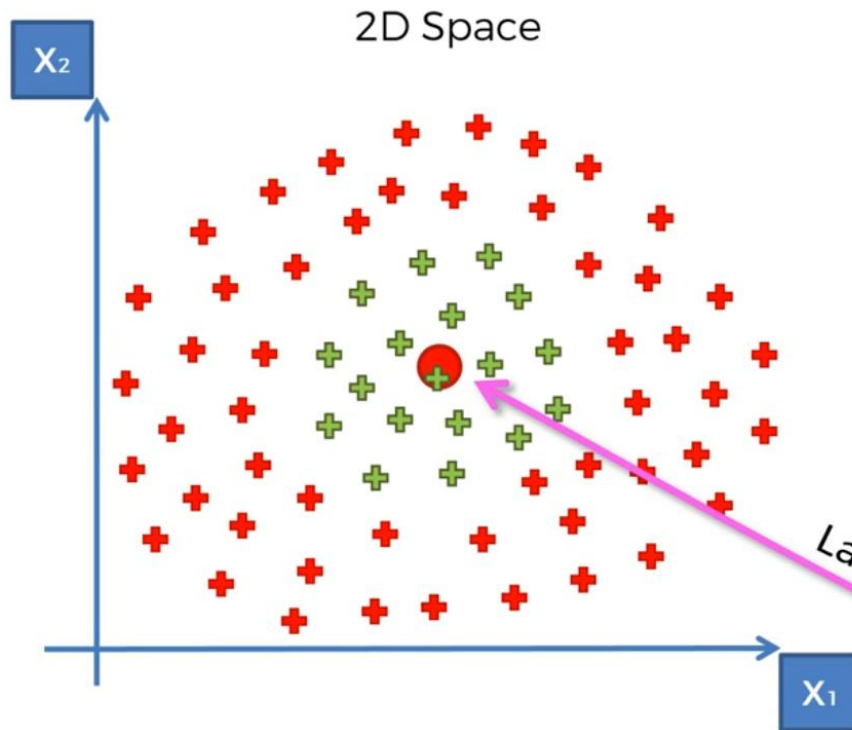


# Kernel trick



$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

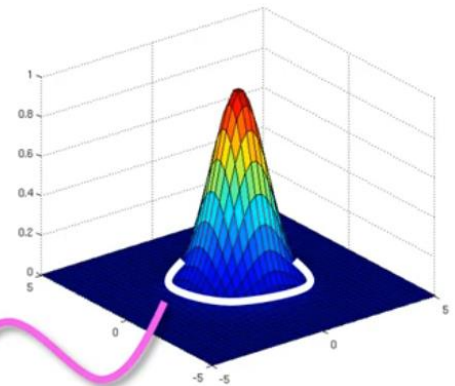
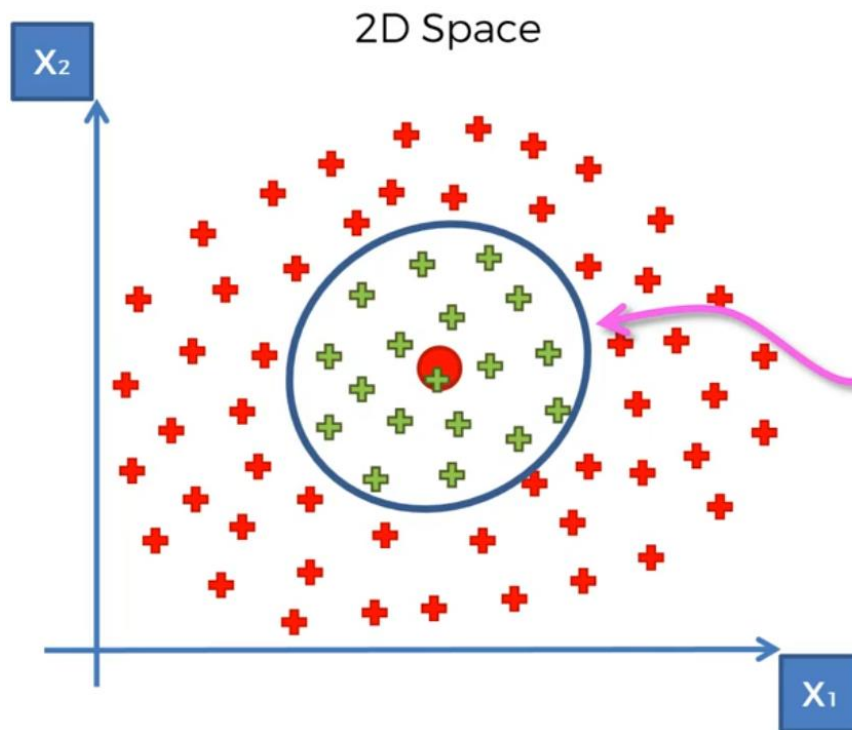
# Kernel trick



$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

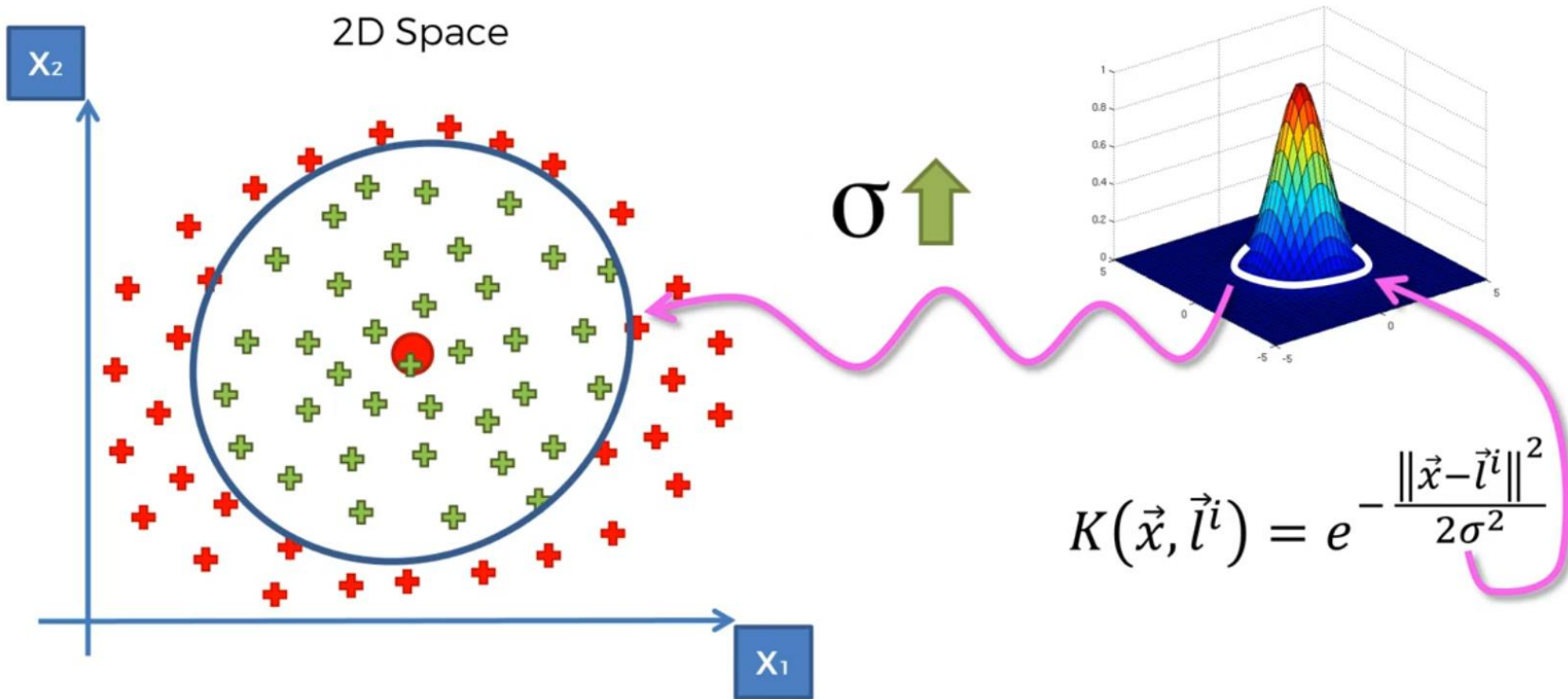


# Kernel trick

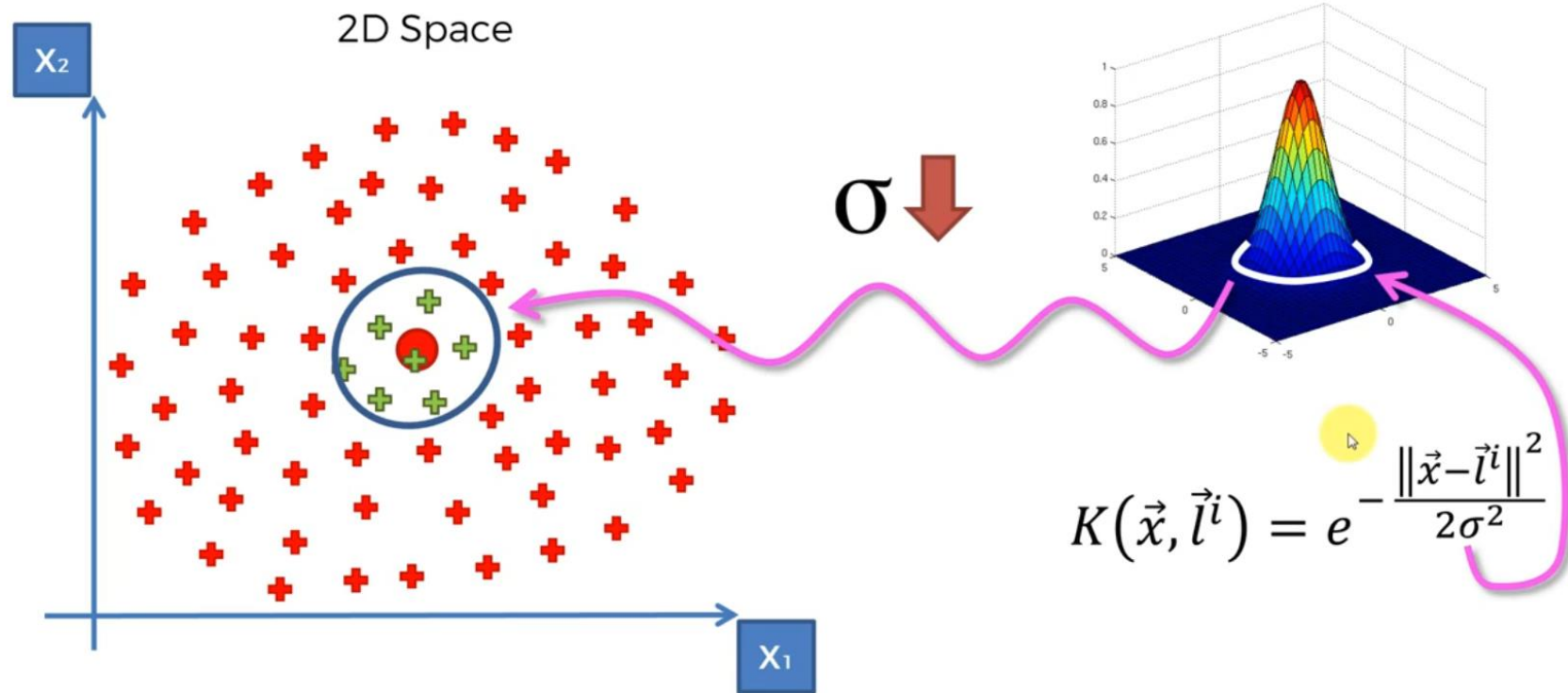


$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

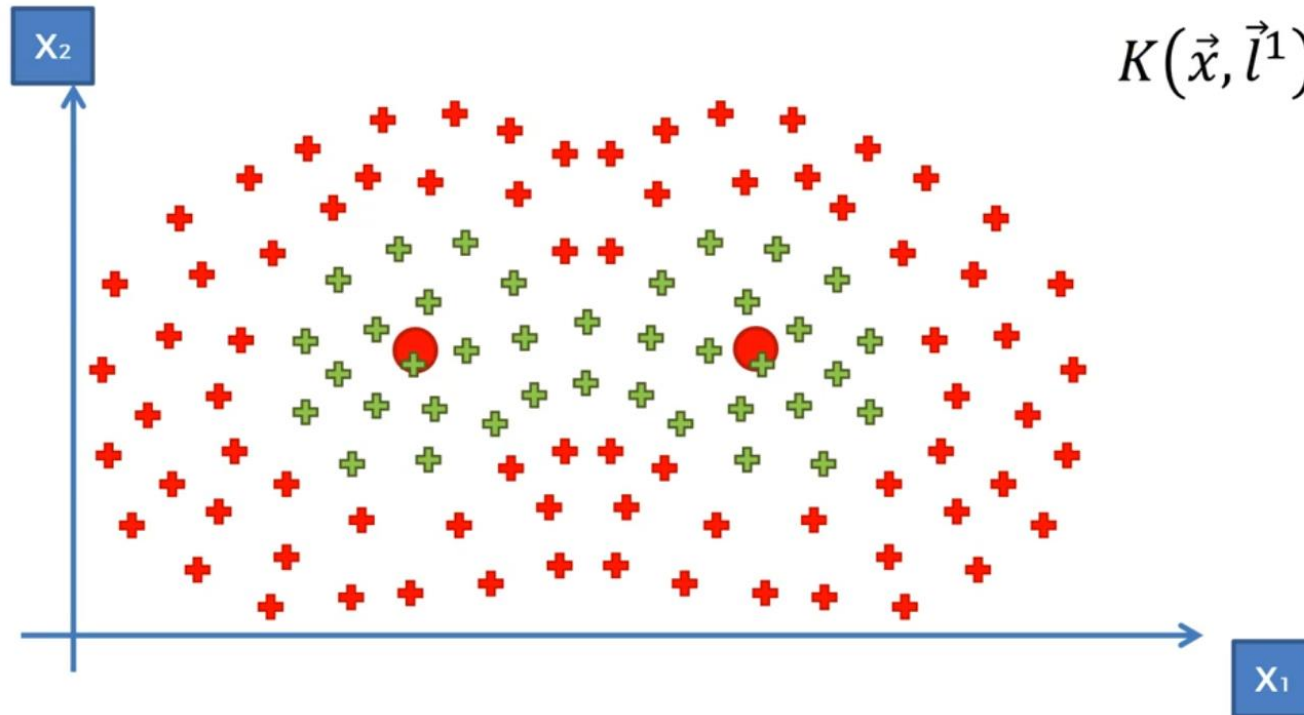
# Kernel trick



# Kernel trick



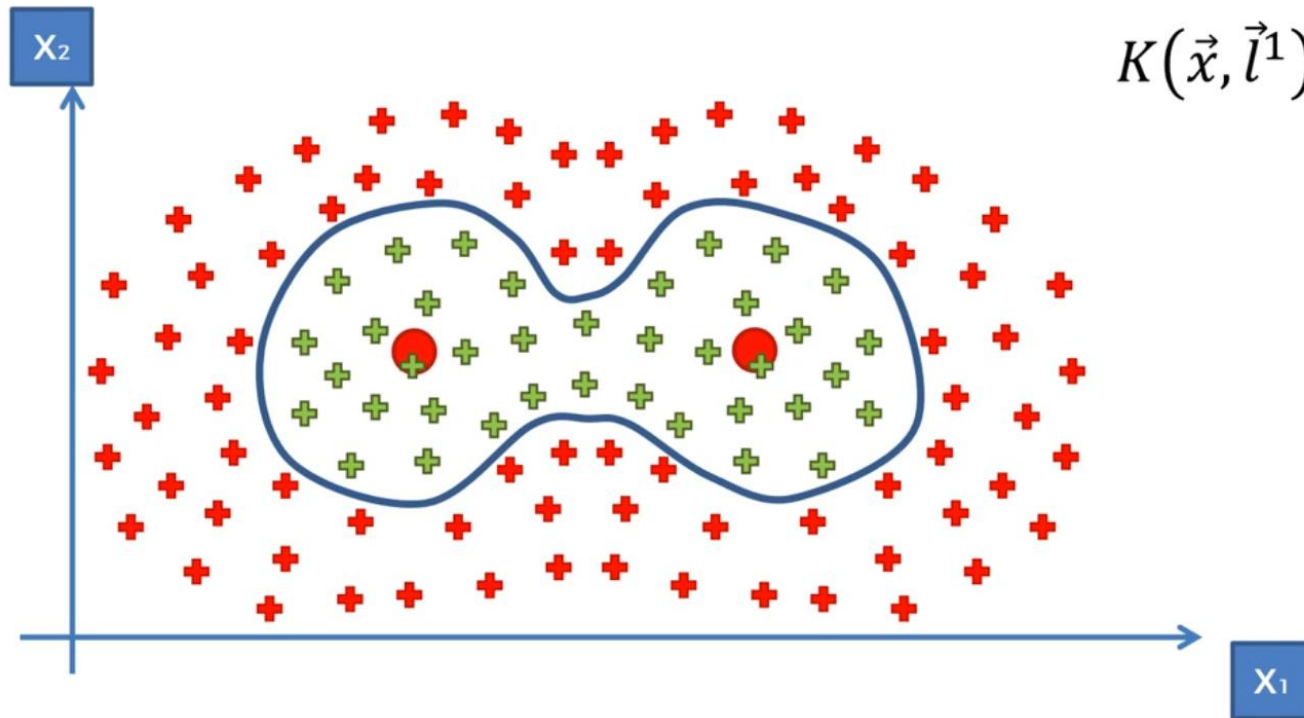
# Kernel trick



$$K(\vec{x}, \vec{l}^1) + K(\vec{x}, \vec{l}^2)$$

(Simplified Formula)

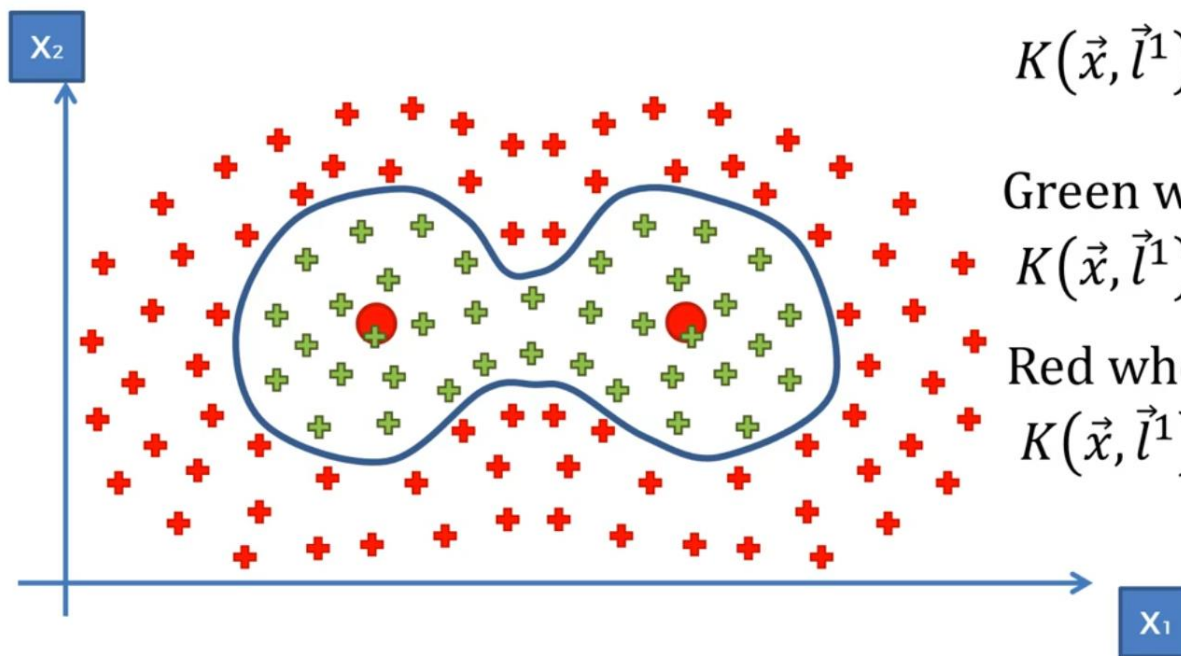
# Kernel trick



$$K(\vec{x}, \vec{l}^1) + K(\vec{x}, \vec{l}^2)$$

(Simplified Formula)

# Kernel trick



$$K(\vec{x}, \vec{l}^1) + K(\vec{x}, \vec{l}^2)$$

(Simplified Formula)

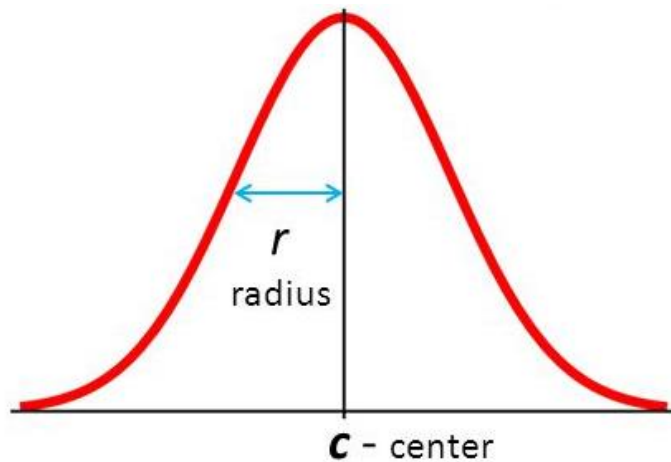
Green when:

$$K(\vec{x}, \vec{l}^1) + K(\vec{x}, \vec{l}^2) > 0$$

Red when:

$$K(\vec{x}, \vec{l}^1) + K(\vec{x}, \vec{l}^2) = 0$$

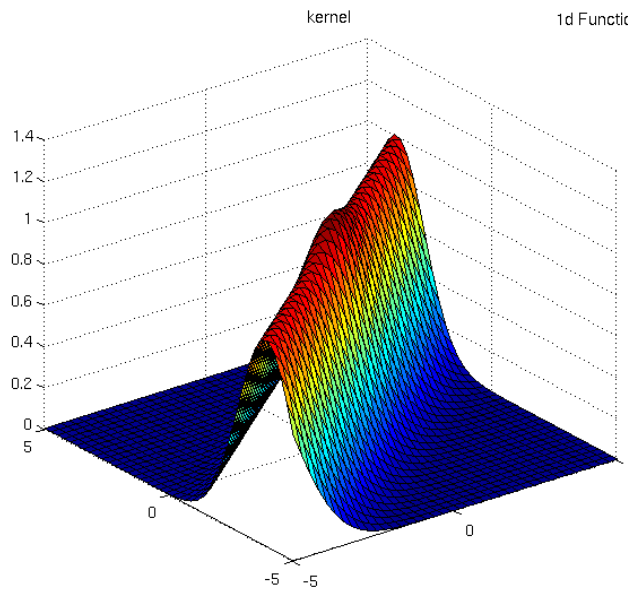
# Types of kernel functions



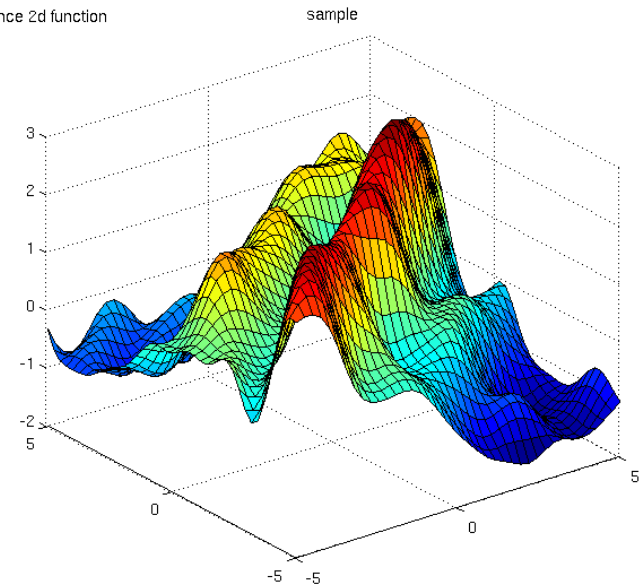
$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

Gaussian  
Radial basis  
function (RBF)

# Types of kernel functions

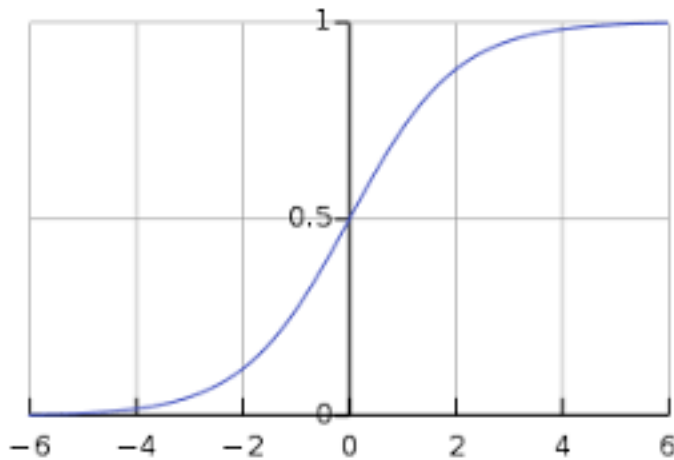


1d Function plus low-variance 2d function





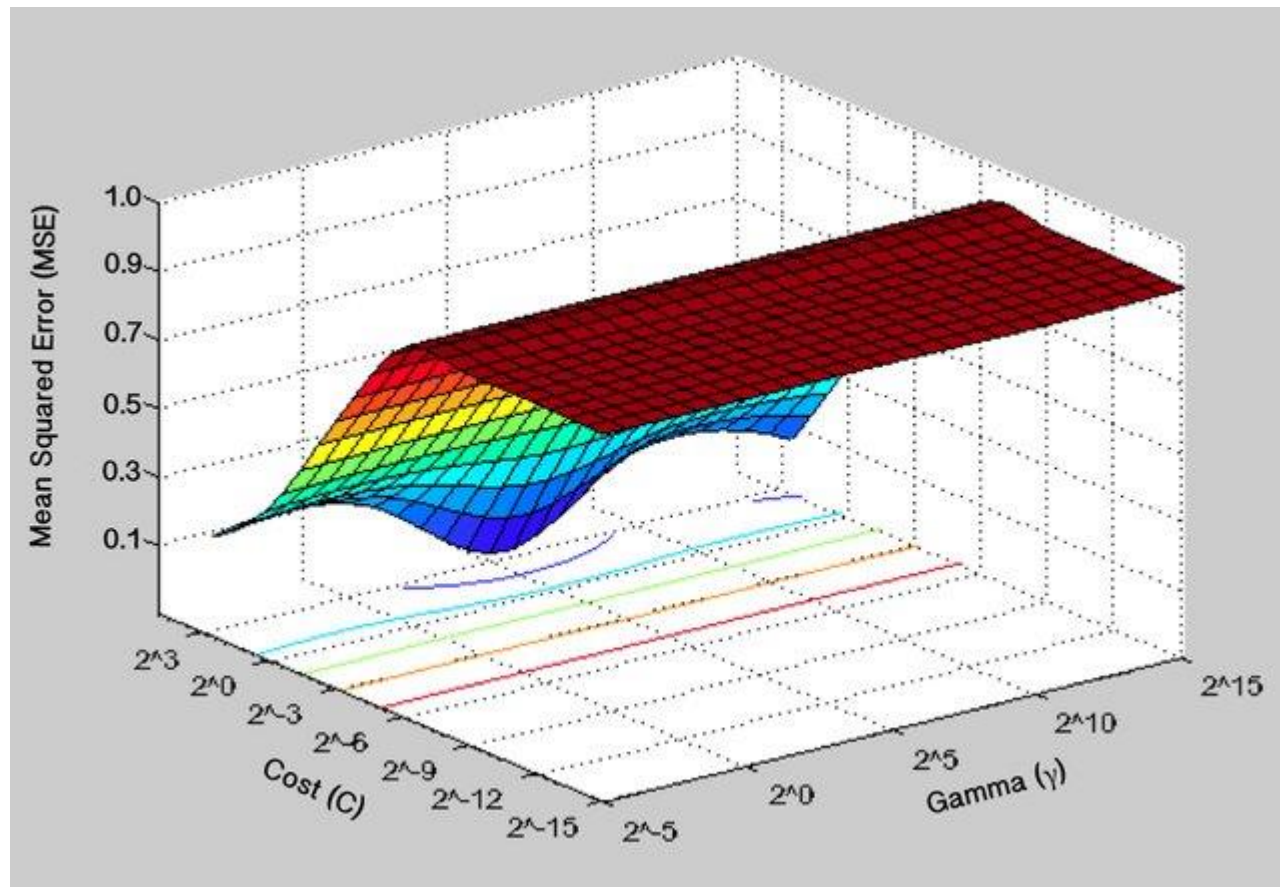
# Types of kernel functions



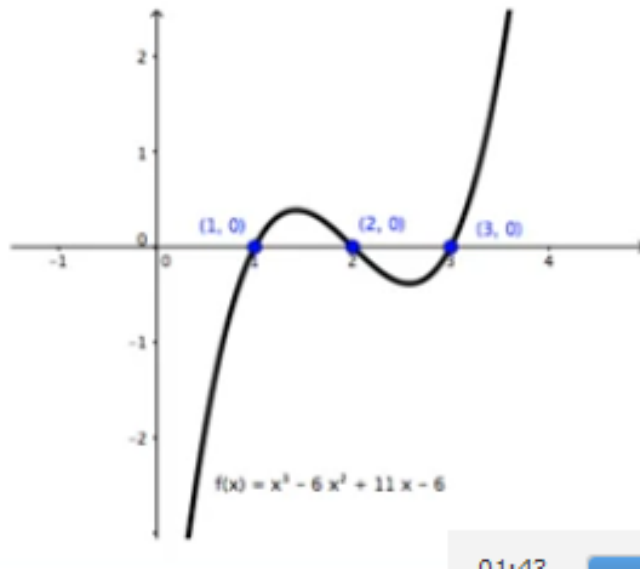
$$K(X, Y) = \tanh(\gamma \cdot X^T Y + r)$$

Sigmoid kernel

# Types of kernel functions



# Types of kernel functions



$$K(X, Y) = (\gamma \cdot X^T Y + r)^d, \gamma > 0$$

Polynomial kernel

# Additional readings

- <https://mlkernels.readthedocs.io/en/latest/index.html>
- [https://en.wikipedia.org/wiki/Radial\\_basis\\_function](https://en.wikipedia.org/wiki/Radial_basis_function)



**This is it ;-)**