

Classification as a QUBO problem

+
Nurali Bibolat

Introduction

- + Representing the search for optimal parameters (w, b) to construct the best for the decision boundary

$$(w^T x + b = 0)$$

for classifying the dataset, as a Quadratic Unconstrained Binary Optimization Problem

- + Use Grover's Adaptive Search with Phase Encoding algorithm to find the bit-string used for figuring out the optimal values

Classification

- m training data points $x^{(i)}$

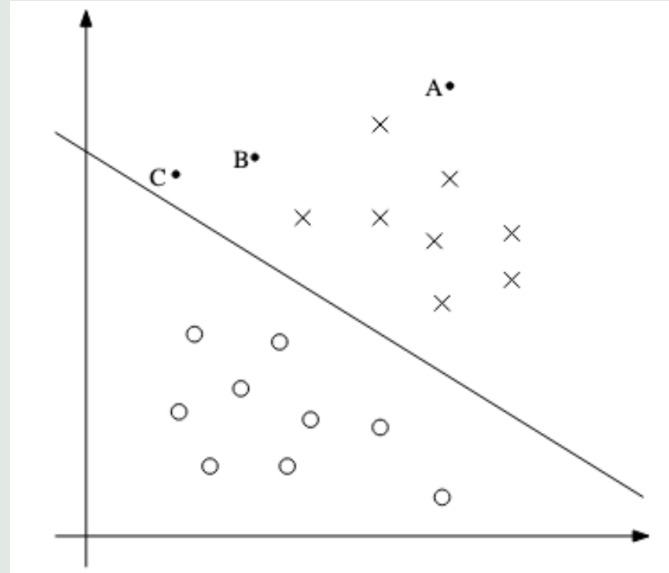
$$\begin{bmatrix} x_1^i \\ x_2^i \\ x_3^i \\ \vdots \\ x_n^i \end{bmatrix}$$

- associated output data points $y^{(i)}$
- either -1 or 1

- A classifier function, $g(w^T x + b)$ maps input data points to the output data points, by finding the optimal weights and constant

$$w = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ \vdots \\ w_n \end{bmatrix}, \text{ and optimal } b \text{ constant.}$$

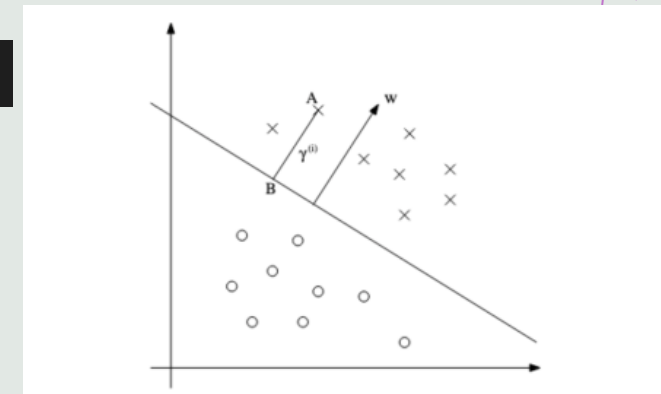
- Once the optimal weights and constants are found, a decision boundary is formed: $w^T x + b = 0$



- $w^T x + b \gg 0$
- confident that the $g(w^T x + b) = 1$

- Functional margin: $\hat{\gamma} = y^{(i)}(w^T x + b)$

- Geometric margin: $\gamma^{(i)} = \hat{\gamma}^{(i)} / ||w||$



Optimization problem

- + Largest distance between data points and decision boundary
- Further == more confident in prediction

$$\begin{aligned} \max_{\gamma, w, b} \quad & \gamma \\ \text{s.t.} \quad & y^{(i)}(w^T x^{(i)} + b) \geq \gamma, \quad i = 1, \dots, m \\ & \|w\| = 1. \end{aligned}$$

$$\begin{aligned} \max_{\gamma, w, b} \quad & \frac{\hat{\gamma}}{\|w\|} \\ \text{s.t.} \quad & y^{(i)}(w^T x^{(i)} + b) \geq \hat{\gamma}, \quad i = 1, \dots, m \end{aligned}$$

$$\hat{\gamma} = 1. \quad (\text{scale } w, b)$$

$$\begin{aligned} \min_{\gamma, w, b} \quad & \frac{1}{2} \|w\|^2 \\ \text{s.t.} \quad & y^{(i)}(w^T x^{(i)} + b) \geq 1, \quad i = 1, \dots, m \end{aligned}$$

Lagrange multipliers + KKT

Given the following optimization problem:

$$\begin{aligned} \min_w \quad & f(w) \\ \text{s.t.} \quad & h_i(w) = 0, \quad i = 1, \dots, l. \end{aligned}$$

$$\mathcal{L}(w, \beta) = f(w) + \sum_{i=1}^l \beta_i h_i(w)$$

Karush-Kuhn-Tucker (KKT) conditions, which are as follows:

$$\begin{aligned} \frac{\partial}{\partial w_i} \mathcal{L}(w^*, \alpha^*, \beta^*) &= 0, \quad i = 1, \dots, n \\ \frac{\partial}{\partial \beta_i} \mathcal{L}(w^*, \alpha^*, \beta^*) &= 0, \quad i = 1, \dots, l \\ \alpha_i^* g_i(w^*) &= 0, \quad i = 1, \dots, k \\ g_i(w^*) &\leq 0, \quad i = 1, \dots, k \\ \alpha^* &\geq 0, \quad i = 1, \dots, k \end{aligned}$$

Maximize by varying alpha

$$\mathcal{L}(w, b, \alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m y^{(i)} y^{(j)} \alpha_i \alpha_j (x^{(i)})^T x^{(j)}.$$

$$\begin{aligned} \text{s.t.} \quad & \alpha_i \geq 0, \quad i = 1, \dots, m \\ & \sum_{i=1}^m \alpha_i y^{(i)} = 0, \end{aligned}$$

Minimize:

$$\sum_{i,j=1}^m y^{(i)} y^{(j)} \alpha_i \alpha_j (x^{(i)})^T x^{(j)}$$

$$\min_{\alpha} \sum_{i,j=1}^m \alpha_i \alpha_j q_{i,j}$$

this problem is an NP-hard problem that takes the form of

$$x = \min_{x \in X} \sum_{i,j=0}^{2^n-1} q_{ij} x_i x_j$$

Converting to a QUBO problem

$$\min_{\alpha} \sum_{i,j=1}^m \alpha_i \alpha_j q_{i,j}$$

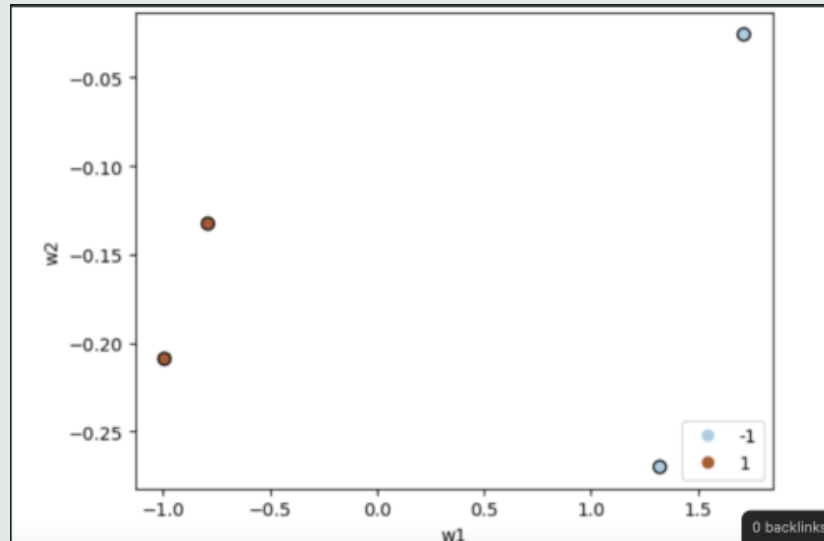
$$x = \min_{x \in X} \sum_{i,j=0}^{2^n-1} q_{ij} x_i x_j$$

$$\alpha_i = \sum_{k=1}^n x_{i,k} 2^{k-1}$$
$$\alpha_j = \sum_{l=1}^n x_{j,l} 2^{l-1}$$

$$\min_x f(x)$$
$$f(x) = \sum_{i,j=1}^m (\sum_{k=1}^n x_{i,k} 2^{k-1}) * (\sum_{l=1}^n x_{j,l} 2^{l-1}) * q_{i,j}$$

Example

	flavanoids	malic_acid	target
0	1.321944	-0.270148	-1
1	1.714484	-0.025601	-1
2	-0.992685	-0.209012	1
3	-0.789647	-0.132590	1



- 12 + 13 = 25 qubits
- Transpile(qc, backend) doesn't work for more than 29
- See whether a sensible boundary is constructed
 - (not horizontal)

Example

- Use the Grover's Adaptive Search with Phase Encoding algorithm

$f(x) =$

```
'x_ik(1, 1, 0)*x_jl(1, 1, 0) *1.820516541074912 + 2*x_ik(1, 1, 0)*x_jl(1, 2, 1) *1.820516541074912 + 4*x_ik(1, 1, 0)*x_jl(1, 3, 2) *1.820516541074912 + x_ik(1, 1, 0)*x_jl(2, 1, 3) *2.273367695306561 + 2*x_ik(1, 1, 0)*x_jl(2, 2, 4) *2.273367695306561 + 4*x_ik(1, 1, 0)*x_jl(2, 3, 5) *2.273367695306561 + x_ik(1, 1, 0)*x_jl(3, 1, 6) *1.2558098032447949 + 2*x_ik(1, 1, 0)*x_jl(3, 2, 7) *1.2558098032447949 + 4*x_ik(1, 1, 0)*x_jl(3, 3, 8) *1.2558098032447949 + x_ik(1, 1, 0)*x_jl(4, 1, 9) *1.0080504032334583 + 2*x_ik(1, 1, 0)*x_jl(4, 2, 10) *1.0080504032334583 + 4*x_ik(1, 1, 0)*x_jl(4, 3, 11) *1.0080504032334583 + 2*x_ik(1, 2, 1)*x_jl(1, 1, 0) *1.820516541074912 + 4*x_ik(1, 2, 1)*x_jl(1, 2, 1) *1.820516541074912 + 8*x_ik(1, 2, 1)*x_jl(1, 3, 2) *1.820516541074912 + 2*x_ik(1, 2, 1)*x_jl(2, 1, 3) *2.273367695306561 + 4*x_ik(1, 2, 1)*x_jl(2, 2, 4) *2.273367695306561 + 8*x_ik(1, 2, 1)*x_jl(2, 3, 5) *2.273367695306561 + 2*x_ik(1, 2, 1)*x_jl(3, 1, 6) *1.2558098032447949 + 4*x_ik(1, 2, 1)*x_jl(3, 2, 7) *1.2558098032447949 + 8*x_ik(1, 2, 1)*x_jl(3, 3, 8) *1.2558098032447949 + 2*x_ik(1, 2, 1)*x_jl(4, 1, 9) *1.0080504032334583 + 4*x_ik(1, 2, 1)*x_jl(4, 2, 10) *1.0080504032334583 + 8*x_ik(1, 2, 1)*x_jl(4, 3, 11) *1.0080504032334583
```

```
def Grover1(xlist, couplings, y, r):  
    n = 12  
    m = 13  
    qi = QuantumRegister(n, name='input')  
    qo = QuantumRegister(m, name='output')  
    c = ClassicalRegister(m)  
    d = ClassicalRegister(n)  
    qc = QuantumCircuit(qi, qo, c, d)  
  
    qc.h(qi)  
  
    print('y_init=', y)  
    coeffs = couplings.copy()  
    coeffs.append(y)  
  
    AOperator(qc, qi, qo, xlist, coeffs)  
    qc.barrier()  
  
    for i in range(r):  
        qc.z(qo[m-1])  
        qc.barrier()  
  
        Adagger(qc, qi, qo, xlist, coeffs)  
  
        qc.barrier()  
        qc.h(qi)  
        qc.x(qi)  
        qc.mcp(np.pi, qi[1:], qi[0])  
        qc.x(qi)  
        qc.h(qi)  
        qc.barrier()  
  
        AOperator(qc, qi, qo, xlist, coeffs)  
  
    qc.barrier()  
    qc.measure(qo, c)  
    qc.measure(qi, d)  
  
    backend = Aer.get_backend('qasm_simulator')  
    circ = transpile(qc, backend)  
    counts = backend.run(circ, shots=1024).result().get_counts(circ)  
    return counts, qc
```

```
maxiter=1000  
score=764  
y=-score  
bestx=0  
r=1  
cutoff = -4  
  
for i in range(maxiter):  
    print('r=', r)  
    counts, q = Grover1(xlist, couplings, y, r)  
  
    x = max(counts, key=lambda key: counts[key])  
    print('x =', x)  
  
    ##### f x #####  
  
    expandedd = str(expanded)  
  
    for key, value in dct.items():  
        expandedd = expandedd.replace(f'{key}', f'{x[value]}')  
    fx = eval(expandedd)  
  
    ##### f x #####  
  
    print('f(x) =', fx)  
    xx = [int(str(x[3:6]), 2), int(str(x[6:9]), 2), int(str(x[9:12]), 2)]  
    print((-1 * xx[0]) + (-1 * xx[1]) + xx[2] + xx[3])  
    if fx < score: #Is the function value better than the best so far?  
        r=1 #If so, update the variables  
        y=fx  
        score=fx  
        bestx=x  
        if score < cutoff:  
            break  
    else:  
        if r < 3: #If the value isn't better, try again with a new number of iterations  
            r+=1  
        else: #Or just move on  
            r=1  
            y+=1  
    print('best x=', bestx, ' with a score of ', score)  
  
r= 1  
y_init= -764  
x = 011111000101 0000011001110
```


Example

- + Given amount of training data points (m) = 4, n = 3 qubits per each alpha (alpha can take max value of 7)

```
y_init= -764
x = 010010001011 0000001001000
f(x) = 219.57387865924778
0
r= 2
y_init= -764
x = 111010011011 0000011100000
f(x) = 546.4754837280741
-3
r= 3
y_init= -764
x = 010110110111 0000100001010
f(x) = 266.33934231988127
5
r= 1
y_init= -763
x = 100000010010 0000000011101
f(x) = 24.049554652731366
0
r= 1
y_init= -763
```

- for each y_{init} , the algorithm takes about 3-3.5 minutes to output the x , $f(x)$, $\sum_{i=1}^m \alpha_i y_i$, and r
- Calculated x and $f(x)$ from -778 to -708
- Chose $x = 100000010010$ for which $f(x)$ is very low relative to all other $f(x)$, and satisfies other conditions

$$\alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \\ 2 \\ 2 \end{bmatrix}$$

Results

$$w = \sum_{i=1}^m \alpha_i y^{(i)} x^{(i)}$$

```
W = np.zeros(2)
alpha = [4, 0, 2, 2]
for i in range(len(w)):
    #print(v(i))
    #print(np.array(v(i)[0]))
    W += np.array(v(i)[0]) * y(i) * alpha[i]
```

W

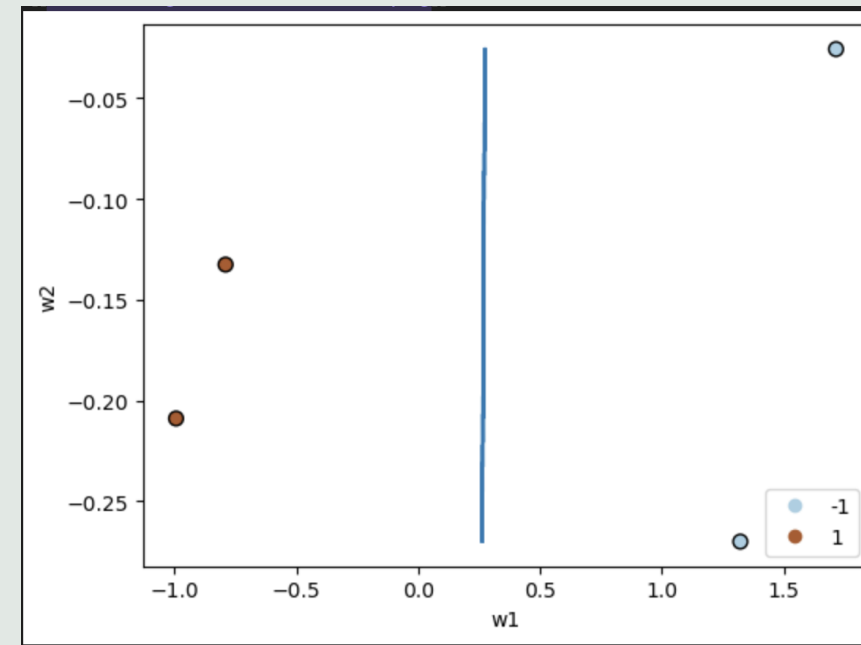
array([-8.85244 , 0.397388])

$$b = -\frac{(\max_{i:y(i)=-1} w^T x^{(i)}) + (\min_{i:y(i)=1} w^T x^{(i)})}{2}$$

```
maxx = max([W.T @ np.array(v(i)[0]) for i in range(len(w)) if y(i) == -1])
minn = min([W.T @ np.array(v(i)[0]) for i in range(len(w)) if y(i) == 1])
```

```
#print(maxx, minn)
b = -(maxx + minn)/2
print(b)
```

2.4360852515120004

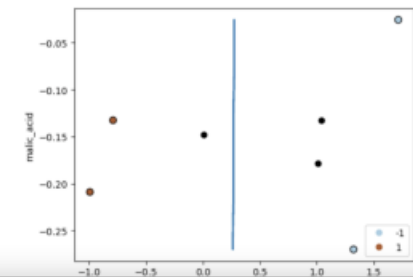


In [146]: testw.iloc[1:4]

Out[146]:

	flavanoids	malic_acid	target	predicted
1	1.010620	-0.178443	-1	-1
2	1.037691	-0.132590	-1	-1
3	0.008967	-0.147875	-1	1

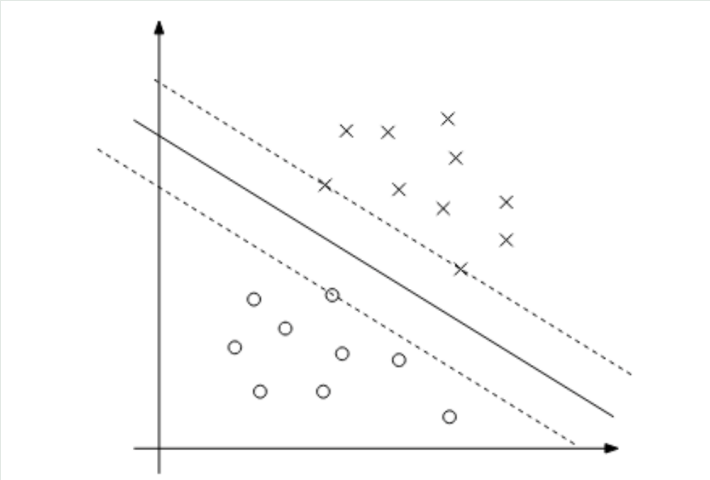
```
In [143]: plt.figure(1)
plot = plt.scatter(w['flavanoids'], w['malic_acid'], c=w['target'], edgecolor='k', s=50)
plt.xlabel('flavanoids')
plt.ylabel('malic_acid')
plt.plot(w1, w2)
plt.scatter(testw1[1:4], testw2[1:4], color='black')
plt.legend(handles=plot.legend_elements()[0], labels=['-1', '1'], loc='lower right')
plt.show()
```



• the performance is quite poor (2/3 success) due to the following limitations of the implementation

Errors

- Algorithm with lagrange multipliers works best if we use data points with functional margins = 1 during training
 - At the optimal solution, KKT duality complementary conditions states that
→ $\alpha_i > 0$ occurs only for training data points that have functional margin = 1
 - The implementation used data points with functional margins > 0 , due to lack of training data points



- The three data points used ($\hat{\gamma} = y^{(i)}(w^T x + b) = 1$) are the support vectors
 - used to create the optimal decision boundary for data points near it
 - QUBO Support Vector implementation would utilize only these datapoints when constructing $f(x)$

- Need more training data points
- Only applicable for linearly separable datasets (no intersections)
 - Non-separable → reformulate the optimization problem again → new algorithms + Kernels → Support Vector Machines learning in high-dimensional feature space → ???

Source:

<https://see.stanford.edu/materials/aimlcs229/cs229-notes3.pdf>

<https://see.stanford.edu/Course/CS229/37>

Thank you! +