

Lecture 2:
The classic paradigm
VS
the predictive paradigm
Big Data and Machine Learning for Applied Economics
Econ 4676

Ignacio Sarmiento-Barbieri

Universidad de los Andes

August 13, 2020

Agenda

- 1 Motivation
- 2 The Classic Paradigm
- 3 Statistical Decision Theory
- 4 Reducible and Irreducible Error
- 5 Recap
- 6 If there's time left

Recap Last Class

Motivation

- ▶ We discussed the examples of Google Flu and Facebook face detection
 - ▶ Take away, the success was driven by an empiric approach
 - ▶ Given data estimate a function $f(x)$ that predicts y from x
- ▶ This is basically what we do as economists everyday so:
 - ▶ Are these algorithms merely applying standard techniques to novel and large datasets?
 - ▶ If there are fundamentally new empirical tools, how do they fit with what we know?
 - ▶ As empirical economists, how can we use them?

The Classic Paradigm

$$Y = f(X) + u \quad (1)$$

- ▶ Interest lies on inference
- ▶ "Correct" $f()$ to understand how Y is affected by X
- ▶ Model: Theory, experiment
- ▶ Hypothesis testing (std. err., tests)

Example: OLS and the classical model

Set

$$f(X) = X\beta \quad (2)$$

- ▶ $Y = X\beta + u$
- ▶ Interest in β
- ▶ The model is given.
- ▶ Problem: how to estimate β in the given model?
- ▶ Minimize SSR

$$\hat{\beta} = (X'X)^{-1}X'y \quad (3)$$

- ▶ Gauss-Markov: under the classical assumptions it is BLUE
- ▶ Classical assumptions: how they affect properties (omitted variables, endogeneity, heteroscedasticity, etc.)

The Predictive Paradigm

$$Y = f(X) + u \quad (4)$$

- ▶ Interest on predicting Y
- ▶ "Correct" $f()$ to be able to predict (no inference!)
- ▶ Model?

Statistical Decision Theory: A bit of theory

- ▶ We need a bit of theory to give us a framework for choosing f
- ▶ A decision theory approach involves an **action space** \mathcal{A}
- ▶ The **action space** \mathcal{A} specify the possible "actions we might take"
- ▶ Some examples

Table 1: Action Spaces

Inference	Action Space
Estimation $\theta, g(\theta)$	$\mathcal{A} = \Theta$
Prediction	$\mathcal{A} = \text{space of } X_{n+1}$
Model Selection	$\mathcal{A} = \{\text{Model I, Model II, ...}\}$
Hyp. Testing	$\mathcal{A} = \{\text{Reject} \text{Accept } H_0\}$

Statistical Decision Theory: A bit of theory

- ▶ After the data $X = x$ is observed, where $X \sim f(X|\theta)$, $\theta \in \Theta$
- ▶ A decision is made
- ▶ The set of allowable decisions is the action space (\mathcal{A})
- ▶ The loss function in an estimation problem reflects the fact that if an action a is close to θ ,
 - ▶ then the decision a is reasonable and little loss is incurred.
 - ▶ if it is far then a large loss is incurred

$$L : \mathcal{A} \rightarrow [0, \infty] \quad (5)$$

Statistical Decision Theory: A bit of theory

Loss Function

- ▶ If θ is real valued, two of the most common loss functions are
 - ▶ Squared Error Loss:

$$L(a, \theta) = (a - \theta)^2 \quad (6)$$

- ▶ Absolute Error Loss:

$$L(a, \theta) = |a - \theta| \quad (7)$$

- ▶ These two are symmetric functions. However, there's no restriction. For example in hypothesis testing a "0-1" Loss is common.
- ▶ Loss is minimum if the action is correct

Statistical Decision Theory: A bit of theory

Risk Function

In a decision theoretic analysis, the quality of an estimator is quantified by its risk function, that is, for an estimator $\delta(x)$ of θ , the risk function is

$$R(\theta, \delta) = E_{\theta}L(\theta, \delta(X)) \quad (8)$$

at a given θ , the risk function is the average loss that will be incurred if the estimator $\delta(X)$ is used

- ▶ since θ is unknown we would like to use an estimator that has a small value of $R(\theta, \delta)$ for all values θ
- ▶ Loss is minimum if the action is correct
- ▶ If we need to compare two estimators (δ_1 and δ_2) then we will compare their risk functions
- ▶ If $R(\delta_1, \theta) < R(\delta_2, \theta)$ for all $\theta \in \Theta$, then δ_1 is preferred because it performs better for all θ

How to choose f for prediction

- ▶ In a prediction problem we want to predict Y from $f(X)$ in such a way that the loss is minimum
- ▶ Assume also that $X \in \mathbb{R}^p$ and $Y \in \mathbb{R}$ with joint distribution $Pr(X, Y)$

$$R(Y, f(X)) = E[(Y - f(X))^2] \quad (9)$$

$$= \int (y - f(x))^2 Pr(dx, dy) \quad (10)$$

conditioning on X we have that

$$R(Y, f(X)|X) = E_X E_{Y|X}[(Y - f(X))^2|X] \quad (11)$$

this risk is also known as the **mean squared (prediction) error** $Err(f)$

Mean square error

It suffices to minimize the $Err(f)$ point wise so

$$f(x) = \operatorname{argmin}_m E_{Y|X}[(Y - m)^2 | X = x] \quad (12)$$

Y a random variable and m a constant (predictor)

$$\min_m E(Y - m)^2 = \int (y - m)^2 f(y) dy \quad (13)$$

Result: The best prediction of Y at any point $X = x$ is the conditional mean, when best is measured by mean squared error.

Mean square error

Proof

FOC

$$\int -2(y - m)f(y)dy = 0 \quad (14)$$

Divided by -2 and clearing

$$m \int f(y)dy = \int yf(y)dz = 0 \quad (15)$$

$$m = E(Y|X = x) \quad (16)$$

The best prediction of Y at any point $X = x$ is the conditional mean, when best is measured by mean squared error.

Reducible and Irreducible Error

$$Y = f(X) + u \quad (17)$$

- ▶ If f were known and X were observable, the problem comes down to predicting u
- ▶ Given that u is not observable, the best prediction in MSE is its expectation. u is the irreducible error
- ▶ When $f(\cdot)$ is also unknown, the prediction problem is reduced to knowing $f(\cdot)$
- ▶ The 'reducible' error refers to the discrepancy between $\hat{f}(\cdot)$ and $f(\cdot)$

Reducible and irreducible error

- ▶ Let's think about our usual problem $f(\cdot)$ is unknown
- ▶ Consider a given estimate \hat{f} and a set of predictors
- ▶ this predictors yield $\hat{Y} = \hat{f}(x)$.
- ▶ For now assume \hat{f} and X are fixed (Hastie et al. make this assumption any idea why?)
- ▶ Then we can show that the mean square error

$$E(Y - \hat{Y})^2 = E(f(X) + u - \hat{f}(X))^2 \quad (18)$$

$$= \underbrace{[f(X) - \hat{f}(X)]^2}_{\text{Reducible}} + \underbrace{\text{Var}(u)}_{\text{Irreducible}} \quad (19)$$

Reducible and irreducible error

$$E(Y - \hat{Y})^2 = \underbrace{[f(X) - \hat{f}(X)]^2}_{\text{Reducible}} + \underbrace{\text{Var}(u)}_{\text{Irreducible}} \quad (20)$$

- ▶ The focus is on techniques for estimating f with the aim of minimizing the reducible error
- ▶ It is important to keep in mind that the irreducible error will always provide an upper bound on the accuracy of our prediction for Y
- ▶ This bound is almost always unknown in practice

Variance Decomposition/ Bias

Remember

- ▶ $Bias(\hat{f}(X)) = E(\hat{f}(X)) - f = E(\hat{f}(X) - f(X))$
- ▶ $Var(\hat{f}) = E(\hat{f} - E(\hat{f}))^2$

Result (very important!)

$$MSE = Bias^2(\hat{f}(X)) + V(\hat{f}(X)) \quad (21)$$

Proof: as an exercise

The econometric approach

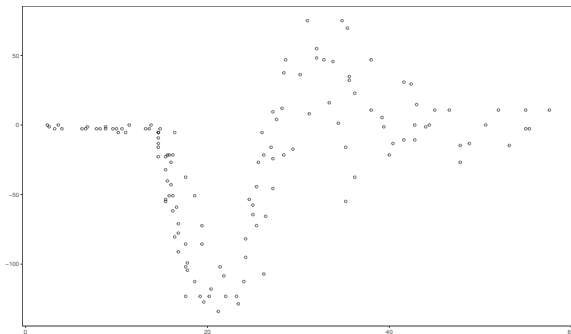
$$MSE = Bias^2(\hat{f}(X)) + V(\hat{f}(X)) \quad (22)$$

- ▶ When $\hat{f}(X)$ is unbiased, minimize MSE $\hat{f}(X)$ is reduced to minimize $V(\hat{f}(X))$
- ▶ The best kept secret: tolerating some bias is possible to reduce $V(\hat{f}(X))$ and lower MSE
- ▶ If the goal is to predict, it is not a problem to tolerate biased estimates
- ▶ It could be the case that the MSE is minimum for biased predictors

How to estimate $f()$

- ▶ Parametric methods \rightarrow assume the functional form \rightarrow from economic theory?

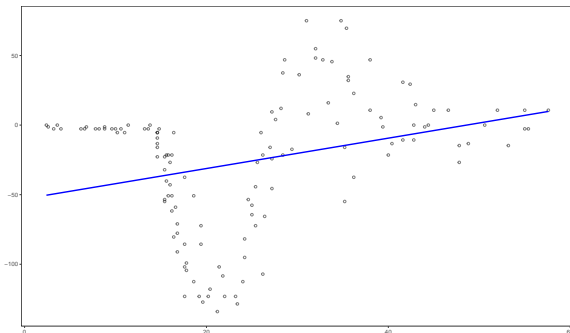
How to estimate $f(\cdot)$



Source: motorcycle data from <https://www.stata-press.com/data/r12/r.html>

How to estimate $f(\cdot)$

- Linear $f(X) = X\beta$



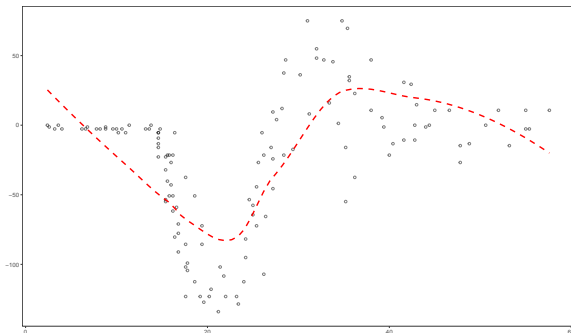
Source: motorcycle data from <https://www.stata-press.com/data/r12/r.html>

How to estimate $f()$

- ▶ Parametric methods → assume the functional form → from economic theory?
- ▶ Non-Parametric methods → no assumption about $f()$ let the data speak

How to estimate $f(\cdot)$

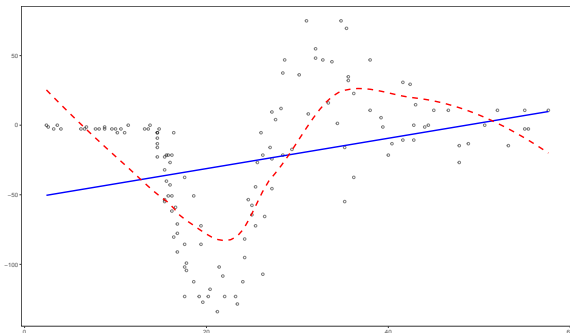
► Local Polynomial Regression



Source: motorcycle data from <https://www.stata-press.com/data/r12/r.html>

How to estimate $f(\cdot)$

► Linear vs Local Polynomial Regression



Source: motorcycle data from <https://www.stata-press.com/data/r12/r.html>

Accuracy, complexity and interpretability



Source: https://imgs.xkcd.com/comics/machine_learning.png

Accuracy, complexity and interpretability

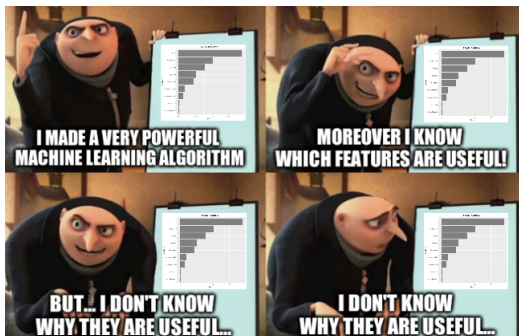
Recall the problem of interpretation in

$$Y = \beta_1 + \beta_2 X + \beta_3 X^2 + u \quad (23)$$

- ▶ We have lost the interpretation of β_2 as a marginal effect
- ▶ In a non-linear model the interpretations are no longer trivial
- ▶ Machine learning: we quickly lose interpretability in predictive quality post
- ▶ Is this a problem?

Accuracy, complexity and interpretability

- Is this a problem?

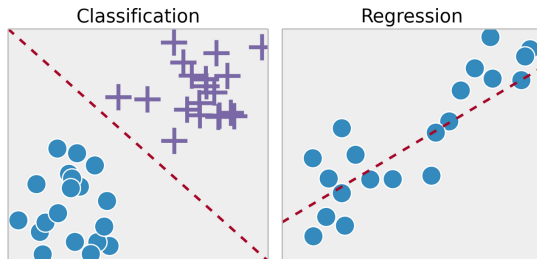


Source: shorturl1.at/gm013

Supervised vs Unsupervised

► Supervised Learning

- for each predictor x_i a 'response' is observed y_i .
- everything we have done in econometrics is supervised

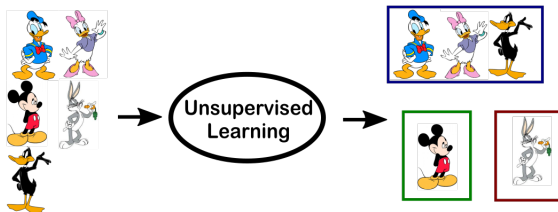


Source: shorturl.at/opqkT

Supervised vs Unsupervised

► Unsupervised Learning

- observed x_i but no response.
- example: cluster analysis



Source: shorturl.at/opqKT

Recap

- ▶ We start shifting paradigms
- ▶ Tools are not that different (so far)
- ▶ Decision Theory: Risk with square error loss \rightarrow MSE
- ▶ Objective minimize the reducible error
- ▶ Irreducible error our unknown bound
- ▶ Machine Learning best kept secret: some bias can help lower MSE

Next

- ▶ GitHub Demo
- ▶ Questions about software installation
 - ▶ R and RStudio
 - ▶ Conda?

Further Readings

- ▶ Casella, G., & Berger, R. L. (2002). Statistical inference (Vol. 2, pp. 337-472). Pacific Grove, CA: Duxbury.
- ▶ James, G., Witten, D., Hastie, T., & Tibshirani, R. (2013). An introduction to statistical learning (Vol. 112, p. 18). New York: springer.
- ▶ Friedman, J., Hastie, T., & Tibshirani, R. (2001). The elements of statistical learning (Vol. 1, No. 10). New York: Springer series in statistics.
- ▶ Mullainathan, S. and Spiess, J., 2017. Machine learning: an applied econometric approach. Journal of Economic Perspectives, 31(2), pp.87-106.