

2022机器学习期末大作业

基于VAE的手写数字生成

- 姓名：刘伟 张朝阳 边笛
- 学号：2013029 2011746 2012668

实验内容

1. 基本要求：利用 pytorch 神经网络框架编程实现变分自编码器 (VAE)；分别采用交叉熵损失 (Cross Entropy Loss) 和L2损失 (MSE Loss) 构建损失函数生成新的手写数字,分析结果并展示生成的手写数字
2. 中级要求：实现VAE的变分推导，描述VAE的由来以及优缺点
3. 高级要求：实现对VAE进行改进或创新，有VAE的变种——CVAE、 β -VAE的实现，可视化方法创新——隐变量输出的实现

成员贡献

- 共同部分：学习了解VAE变分自编码器的框架结构，掌握基本的理论前提。
- 刘伟：pytorch构建基本的Dense全连接层VAE；可视化的创新——隐变量层的输出展示；变种——CVAE条件变分自编码器
- 张朝阳：pytorch构建结合Conv卷积层的VAE结构；深入学习VAE的理论推导——复现VAE的变分推导
- 边笛：VAE的变种创新—— β -VAE，全面分析 β 对整个VAE结构的影响并结合隐变量层的学习成果深入分析

初级要求

利用 pytorch 神经网络框架编程实现变分自编码器 (VAE)

库函数与训练数据的加载

```
In [ ]: # 导入实验所需的相关库函数
import torch
import torch.utils.data as Data
import torch.nn as nn
import torch.nn.functional as F
from torchvision import transforms
from torchvision.datasets import MNIST
from torchvision.utils import save_image
from torchsummary import summary
import matplotlib.pyplot as plt
from PIL import Image
import numpy as np
```

```
import warnings
warnings.filterwarnings('ignore')
```

```
In [ ]: # 下载实验所需的MNIST数据集
train_dataset = MNIST(
    root='MNIST',
    train=True,
    transform=transforms.ToTensor(),
    download=True
)

# 查看mnist数据
print(train_dataset)

# 查看是否支持cuda GPU训练
print(torch.cuda.is_available())

# 数据集切分
batch_size = 128
dataIter = Data.DataLoader(train_dataset, batch_size=batch_size, shuffle=True)
```

```
Dataset MNIST
... Number of datapoints: 60000
... Root location: MNIST
... Split: Train
... StandardTransform
Transform: ToTensor()
True
```

代价损失函数：通过两种不同的方式构建损失函数

```
In [ ]: # 展平：多维数据展平成低维数据
def flatten(x):
    N = x.shape[0] # read in N, C, H, W
    return x.view(N, -1) # torch.Size([128, 784])

# L2损失 (MSE Loss) 构建损失函数
def vae_loss_mse(x, gen_x, mean, log_var):
    # 重构项损失
    mse_loss = torch.nn.MSELoss(reduction='sum')
    loss1 = mse_loss(gen_x, x)

    # 最小化 q(z|x) 和 p(z) 的距离
    KL_loss = 0.5 * torch.sum(torch.exp(log_var) + torch.pow(mean, 2) - log_var - 1)

    return loss1 + KL_loss

# 交叉熵损失 (Cross Entropy Loss) 构建损失函数
def vae_loss_cross(x, gen_x, mean, log_var):
    # 重构项损失
    loss1 = F.binary_cross_entropy(gen_x, x, reduction='sum')

    # 最小化 q(z|x) 和 p(z) 的距离
    KL_loss = 0.5 * torch.sum(torch.exp(log_var) + torch.pow(mean, 2) - log_var - 1)

    return loss1 + KL_loss
```

构造网络模型

- 采用全连接Dense(Linear)设计网络架构
- 采用卷积层Conv+Dense设计网络架构

全连接层——VAE网络

```
In [ ]: class VariationalAutoEncoder_Dense(nn.Module):
    def __init__(self,
                 image_shape=(1, 28, 28),
                 dense_size=(784, 256, 128),
                 z_dim=20):
        super(VariationalAutoEncoder_Dense, self).__init__()

        # 激活函数
        self.relu = nn.ReLU()
        self.sigmoid = nn.Sigmoid()

        # encoder全连接层
        self.enDense0 = nn.Linear(dense_size[0], dense_size[1])
        self.enDense1 = nn.Linear(dense_size[1], dense_size[2])

        # 隐变量层
        self.latent_mean = nn.Linear(dense_size[-1], z_dim)
        self.latent_log_var = nn.Linear(dense_size[-1], z_dim)

        # decoder全连接层
        self.deDense0 = nn.Linear(z_dim, dense_size[-1])
        self.deDense1 = nn.Linear(dense_size[-1], dense_size[-2])
        self.deDense2 = nn.Linear(dense_size[-2], dense_size[-3])

        # decoder reshape
        self.dec_reshape = transforms.Lambda(
            lambda x: torch.reshape(x, (x.shape[0], 1, int(image_shape[1]), int(image_shape[2]))))

    # 编码
    def encode(self, x):
        # 展平
        out = flatten(x)
        # 全连接层
        out = self.relu(self.enDense0(out))
        out = self.relu(self.enDense1(out))

        # 均值 mean
        latent_mean = self.latent_mean(out)
        # log方差 log_var
        latent_log_var = self.latent_log_var(out)

        return latent_mean, latent_log_var

    # 重参数化生成隐变量
    def re_parameterize(self, mu, log_var):
        var = torch.exp(0.5 * log_var)
        epsilon = torch.randn_like(var)
        return mu + torch.mul(var, epsilon)

    # 解码
    def decode(self, z):
        # 全连接层
        out = self.relu(self.deDense0(z))
        out = self.relu(self.deDense1(out))
        out = self.sigmoid(self.deDense2(out))

        # 重构shape
```

```

        out = self.dec_reshape(out)

    return out

# 整个前向传播过程: 编码 --> 解码
def forward(self, x):
    latent_mean, latent_log_var = self.encode(x)
    sampled_Z = self.re_parameterize(latent_mean, latent_log_var)
    Gen_X = self.decode(sampled_Z)
    return latent_mean, latent_log_var, Gen_X

```

卷积层——VAE网络

```

In [ ]: class VariationalAutoEncoder_Conv(nn.Module):
    def __init__(self,
                 image_shape=(1, 28, 28),
                 conv_size=(1, 6, 16, 4),
                 dense_size=(784, 128),
                 kernel=3,
                 z_dim=20):
        super(VariationalAutoEncoder_Conv, self).__init__()

        # 激活函数
        self.relu = nn.ReLU()
        self.sigmoid = nn.Sigmoid()

        # encoder卷积层
        # 输入 (128, 1, 28, 28) 输出 (128, 6, 28, 28)
        self.enConv0 = nn.Conv2d(conv_size[0], conv_size[1], kernel, padding=1, stride=1)
        # 输入 (128, 6, 28, 28) 输出 (128, 16, 14, 14)
        self.enConv1 = nn.Conv2d(conv_size[1], conv_size[2], kernel, stride=2, padding=1)
        # 输入 (128, 16, 14, 14) 输出 (128, 4, 14, 14)
        self.enConv2 = nn.Conv2d(conv_size[2], conv_size[3], kernel, padding=1, stride=2)

        # encoder全连接层
        self.enDense0 = nn.Linear(dense_size[0], dense_size[1])

        # 隐变量层
        self.latent_mean = nn.Linear(dense_size[-1], z_dim)
        self.latent_log_var = nn.Linear(dense_size[-1], z_dim)

        # decoder全连接层
        self.deDense0 = nn.Linear(z_dim, dense_size[-1])
        self.deDense1 = nn.Linear(dense_size[-1], dense_size[-2])
        self.deDense2 = nn.Linear(dense_size[-2], int(np.prod(image_shape)))

        # 需要对 全连接层输出的一维结果数据 进行 reshape
        self.dec_reshape = transforms.Lambda(
            lambda x: torch.reshape(x, (x.shape[0], 1, int(image_shape[1]), int(image_shape[2]))))

    # 编码
    def encode(self, x):
        # 卷积层
        out = self.relu(self.enConv0(x))
        out = self.relu(self.enConv1(out))
        out = self.relu(self.enConv2(out))

        # 展平
        out = flatten(out)

        # 全连接层
        out = self.relu(self.enDense0(out))

```

```

# 均值 mean
latent_mean = self.latent_mean(out)
# log方差 log_var
latent_log_var = self.latent_log_var(out)

return latent_mean, latent_log_var

# 重参数化生成隐变量
def re_parameterize(self, mu, log_var):
    var = torch.exp(0.5 * log_var)
    epsilon = torch.randn_like(var)
    return mu + torch.mul(var, epsilon)

# 解码
def decode(self, z):
    # 全连接层
    out = self.relu(self.deDense0(z))
    out = self.relu(self.deDense1(out))
    out = self.sigmoid(self.deDense2(out))

    # 重构shape
    out = self.dec_reshape(out)

    return out

# 整个前向传播过程: 编码 --> 解码
def forward(self, x):
    latent_mean, latent_log_var = self.encode(x)
    sampled_Z = self.re_parameterize(latent_mean, latent_log_var)
    Gen_X = self.decode(sampled_Z)
    return latent_mean, latent_log_var, Gen_X

```

查看网络结构

```

In [ ]: # 网络训练设备: 建议使用cuda
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
print(device)

# 利用summary函数查看网络的层次结构
print("-----VAE(Dense) 网络结构-----")
model_Dense = VariationalAutoEncoder_Dense()
model_Dense.to(device)
summary(model_Dense, input_size=(1, 28, 28))
print("-----VAE(Conv) 网络结构-----")
model_Conv = VariationalAutoEncoder_Conv()
model_Conv.to(device)
summary(model_Conv, input_size=(1, 28, 28))

```

cuda

=====VAE(Dense) 网络结构=====

Layer (type)	Output Shape	Param #
Linear-1	[-1, 256]	200,960
ReLU-2	[-1, 256]	0
Linear-3	[-1, 128]	32,896
ReLU-4	[-1, 128]	0
Linear-5	[-1, 20]	2,580
Linear-6	[-1, 20]	2,580
Linear-7	[-1, 128]	2,688
ReLU-8	[-1, 128]	0
Linear-9	[-1, 256]	33,024
ReLU-10	[-1, 256]	0
Linear-11	[-1, 784]	201,488
Sigmoid-12	[-1, 784]	0

Total params: 476,216

Trainable params: 476,216

Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.02

Params size (MB): 1.82

Estimated Total Size (MB): 1.84

=====VAE(Conv) 网络结构=====

Layer (type)	Output Shape	Param #
Conv2d-1	[-1, 6, 28, 28]	60
ReLU-2	[-1, 6, 28, 28]	0
Conv2d-3	[-1, 16, 14, 14]	880
ReLU-4	[-1, 16, 14, 14]	0
Conv2d-5	[-1, 4, 14, 14]	580
ReLU-6	[-1, 4, 14, 14]	0
Linear-7	[-1, 128]	100,480
ReLU-8	[-1, 128]	0
Linear-9	[-1, 20]	2,580
Linear-10	[-1, 20]	2,580
Linear-11	[-1, 128]	2,688
ReLU-12	[-1, 128]	0
Linear-13	[-1, 784]	101,136
ReLU-14	[-1, 784]	0
Linear-15	[-1, 784]	615,440
Sigmoid-16	[-1, 784]	0

Total params: 826,424

Trainable params: 826,424

Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.16

Params size (MB): 3.15

Estimated Total Size (MB): 3.32

设定模型参数

```
In [ ]: # 训练模型参数  
learning_rate = 1e-3 # 学习率
```

```

epoches = 20 # 迭代次数

# 实例化模型 二选一 即可
model = model_Conv
# model = model_Dense

# 创建优化器
optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)

```

模型训练

```

In [ ]: train_loss = [] # 保存每个epoch的训练误差
number = len(dataIter.dataset)
result_dir = './VAEResult' # 保存生成图片的目录
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        # 前向传播
        mean, log_var, gen_x = model(x)

        # 计算损失函数 二选一 即可
        loss = vae_loss_mse(x, gen_x, mean, log_var)
        # loss = vae_loss_cross(x, gen_x, mean, log_var)
        batch_loss.append(loss.item())

        # 反向传播和优化
        optimizer.zero_grad() # 每一次循环之前，将梯度清零
        loss.backward() # 反向传播
        optimizer.step() # 梯度下降

        # 输出batch信息
        # if i % 100 == 0 and i > 0:
        #     print("epoch : {} | batch : {} | batch average loss: {}"
        #           .format(epoch + 1, i, loss.item() / x.shape[0]))

        # 保存 各个epoch下 VAE的生成效果图
        if i == 0:
            x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)],
                                  dim=3) #torch.Size([128, 1, 28, 56])
        #     save_image(x_concatD, './%s/reconstructed-%d.png' % (result_dir, epoch))

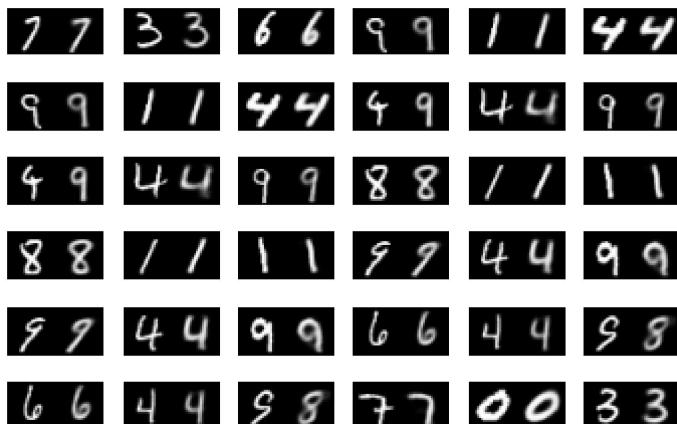
        # 输出epoch信息
        train_loss.append(np.sum(batch_loss) / number)
print("epoch[{} / {}] | loss: {}"
      .format(epoch + 1, epoches, train_loss[epoch]))

```

```
epoch[1/20] | loss:52.37612461751302
epoch[2/20] | loss:38.15426111653646
epoch[3/20] | loss:33.8532580485026
epoch[4/20] | loss:32.30478760986328
epoch[5/20] | loss:31.240277282714842
epoch[6/20] | loss:30.621502152506512
epoch[7/20] | loss:30.20562481689453
epoch[8/20] | loss:29.88453271077474
epoch[9/20] | loss:29.626651607259113
epoch[10/20] | loss:29.438368599446616
epoch[11/20] | loss:29.267931953938803
epoch[12/20] | loss:29.087553869628906
epoch[13/20] | loss:28.97938673502604
epoch[14/20] | loss:28.863276033528646
epoch[15/20] | loss:28.741947403971356
epoch[16/20] | loss:28.638105383300783
epoch[17/20] | loss:28.515713920084636
epoch[18/20] | loss:28.441164237467447
epoch[19/20] | loss:28.351834224446616
epoch[20/20] | loss:28.28068007405599
```

展示最终迭代训练后：VAE生成图片与原始图片的对比

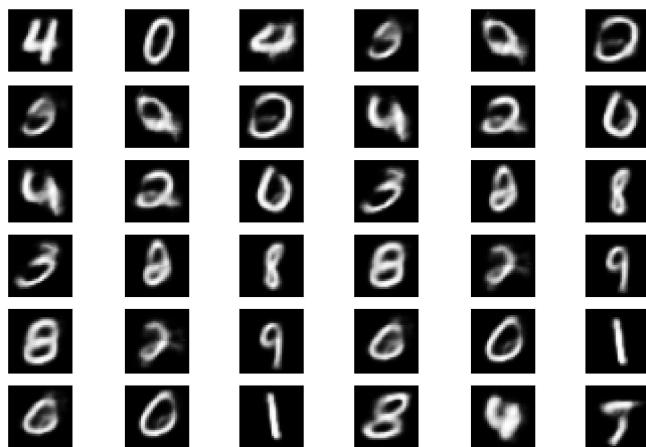
```
In [ ]: # 展示最终迭代训练后：VAE生成图片与原始图片的对比
x_s = x_concatD.view(128, 28, 28).detach().cpu().numpy() * 255.
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_s[i * 3 + j], cmap='gray')
plt.show()
```



evaluation 测试生成效果

```
In [ ]: # 从正态分布随机采样z
z = torch.randn(batch_size, 20).to(device)
logits = model.decode(z) # 仅通过解码器生成图片
x_hat = torch.sigmoid(logits) # 转换为像素范围
x_hat = x_hat.view(128, 28, 28).detach().cpu().numpy() * 255.
# 展示图片
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
```

```
    axes[i][j].imshow(x_hat[i * 3 + j], cmap='gray')
plt.show()
```



中级要求

实现VAE的变分推导

有一批数据样本 $\{x_1, x_2, \dots, x_n\}$, x 的分布 $p(x)$ 未知

z: 隐变量 q: 隐变量 z 的近似分布

散度定义: $KL(a||b) = \sum_x a(x) \log \frac{a(x)}{b(x)}$, KL 越大说明 a, b 两分布差异越大, 且 $KL \geq 0$

我们的目的是最大化 $p(x)$, 采用最大似然的方法, 即最大化 $\sum_x \log p(x)$.

[标红处为用到的公式或定理]

解: 已知 $\int_z q(z|x) dz = 1$,

两边同乘 $\log p(x)$ 得: $\log p(x) = \int_z q(z|x) \cdot \log p(x) dz$

将 $p(x) = \frac{P(x|z)}{P(z|x)} = \frac{P(x,z)}{q(z|x)} \cdot \frac{q(z|x)}{P(z|x)}$ 代入等式右端: $[P(x,y) = P(x|y) \cdot P(y)]$

$$\begin{aligned} \log p(x) &= \int_z q(z|x) \cdot \log \left[\frac{P(x,z)}{q(z|x)} \cdot \frac{q(z|x)}{P(z|x)} \right] dz \\ &= \int_z q(z|x) \cdot \log \frac{P(x,z)}{q(z|x)} dz + \int_z q(z|x) \cdot \log \frac{q(z|x)}{P(z|x)} dz \end{aligned}$$

可以看出第二项为 $q(z|x)$ 和 $P(z|x)$ 的散度, 即:

$$\log p(x) = \int_z q(z|x) \cdot \log \frac{P(x,z)}{q(z|x)} dz + KL(q(z|x) || p(z|x)) \quad \dots \quad ①$$

接下来对①式分析。①式共两项, 我们的目的让①式整体尽可能大, 但第二项, 即 q 和 P 之间的散度应尽可能小, 即 $q(z|x)$ 和 $P(z|x)$ 两分布应尽可能接近。在 $p(x)$ 值不变的情况下。

第一项和第二项之间的大小关系呈反相关, 因此我们下边的工作是让第一项尽可能大。

记第一项为 L , 代入 $[P(x,z) = p(x|z) \cdot P(z)]$

$$L = \int_z q(z|x) \cdot \log \frac{P(z)}{q(z|x)} dz + \int_z q(z|x) \cdot \log p(x|z) dz \quad \dots \quad ②$$

分析②式得第一项为 $q(z|x)$ 和 $P(z)$ 散度的相反数, 第二项可看作是 $\log p(x|z)$ 在 $q(z|x)$ 分布上的期望
[对函数 $Y = g(x)$, 在分布 $f(x)$ 上, 有 $E(g(x)) = \int_X f(x) \cdot g(x) dx$]

$$\text{即 } ELBO = L = E_{q(z|x)} \log p(x|z) - KL(q(z|x) || p(z))$$

第一项称为重构损失项, 是要最大化对数据似然函数; 第二项则是要最小化 $q(z|x)$ 和 $P(z)$ 的距离

$$\text{Loss} = -ELBO = KL(q(z|x) || p(z)) - E_{q(z|x)} \log p(x|z)$$

下面对损失函数进行化简：

第一项：已知 $q(z|x) \sim N(\mu, \sigma^2)$ $p(z) \sim N(0, 1)$,

在一元正态分布的情况下，

$$\begin{aligned} KL(q(z|x)||p(z)) &= \int_{\mathbb{R}} q(z|x) \cdot \log \frac{q(z|x)}{p(z)} dz \\ &= \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \cdot \log \frac{\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}}{\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}} dx \\ &= \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \cdot \log \left\{ \frac{1}{\sigma} \cdot e^{[\frac{x^2}{2} - \frac{(x-\mu)^2}{2\sigma^2}]} \right\} dx \\ &= \frac{1}{2} \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \cdot (x^2 - \frac{(x-\mu)^2}{\sigma^2} - \log \sigma^2) dx \end{aligned}$$

拆开算三项：

$$(1) \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \cdot x^2 dx = E(x^2) = D(x) + E(x)^2 = \sigma^2 + \mu^2$$

[对函数 $Y = g(x)$, 在分布 $f(x)$ 上, 有 $E(g(x)) = \int_X f(x) \cdot g(x) dx$]

$$\begin{aligned} (2) \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \cdot \frac{(x-\mu)^2}{\sigma^2} dx &= E\left[\frac{(x-\mu)^2}{\sigma^2}\right] \\ &= \frac{1}{\sigma^2}[E(x^2) - 2\mu E(x) + \mu^2] \\ &= \frac{1}{\sigma^2}[\sigma^2 + \mu^2 - 2\mu^2 + \mu^2] = 1 \end{aligned}$$

$$(3) \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \cdot \log \sigma^2 dx = \log \sigma^2 \cdot \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx = \log \sigma^2$$

\therefore 第一项为 $\frac{1}{2}(\sigma^2 + \mu^2 - 1 - \log \sigma^2)$

当是多元正态分布时 (d 维度) 为,

$$\sum_{i=1}^d \frac{\partial}{\partial z_i} (\sigma^2 + \mu^2 - 1 - \log \sigma^2)$$

第二项：当样本数为 n 时, $[E(x) = \frac{1}{n} \sum_{i=1}^n x_i]$

$$E_{q(z|x)} \log p(x|z) = \frac{1}{n} \sum_{i=1}^n \log p(x_i|z_i)$$

$$\text{综上: Loss} = \frac{1}{2} \sum_{i=1}^d (\sigma^2 + \mu^2 - 1 - \log \sigma^2) - \frac{1}{n} \sum_{i=1}^n \log p(x_i|z_i)$$

VAE的由来以及优缺点

自编码器 (Auto-Encoder, AE) 是一种无监督的神经网络，一般由编码器和解码器两部分构成。其过程为：编码器处理输入的数据进行编码，解码器根据编码内容来解码，从而还原出原始输入数据。简单来说，就是输入即为输出。这样的过程当然存在一定的问题：

- 容易受噪声数据干扰
- 对于没见过的输入，会给出意料之外的输出
- 以原输入再生成出原输入，在实际操作中，并无太大用处。

为了克服上述缺点，人们提出了一些AE模型的变种方案，VAE就是一种AE的变种。

变分自编码器 (Variational AutoEncoder, VAE) , 是一个根据输入的数据的分布, 类型, 来模拟生成类似于输入数据的数据生成模型。VAE结合贝叶斯理论, 不再认为整个样本空间只服从一个可观测的概率分布, 而认为存在一个隐变量 z , 控制着每个样本的概率分布。在隐变量 z 的作用下, VAE的输出不再与输入相同, 而是成为了输入的一个近似, 存在更多的不确定性。这样的结果是一把双刃剑:

- 优点: VAE采用分布的形式使得输出更加多样化, 且不同的输出结果之间连接比较平滑。可以处理各种类型的数据, 序列的和非序列的, 连续的或离散的, 甚至有标签的或无标签的, 这使得它成为非常强大的生成工具。
- 缺点: 生成的输出比较模糊, 甚至可能偏离输入内容较远。不适用于对结果精确度有较高要求的情景。

高级要求

隐变量输出展示

为了便于得知隐变量的学习内容, 将 z_dim 改成2维, 进行训练学习, 观察隐变量采样

```
In [ ]: import os
from scipy.stats import norm

# 生成隐空间内的采样
# 训练时Z_dim设定为20, 这里仅观察隐空间前俩维度表示特征
model = VariationalAutoEncoder_Conv(z_dim=2)
model.to(device)
epoches = 20
optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)
train_loss = [] # 保存每个epoch的训练误差
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        # 前向传播
        mean, log_var, gen_x = model(x)

        # 计算损失函数 二选一 即可
        loss = vae_loss_mse(x, gen_x, mean, log_var)
        batch_loss.append(loss.item())

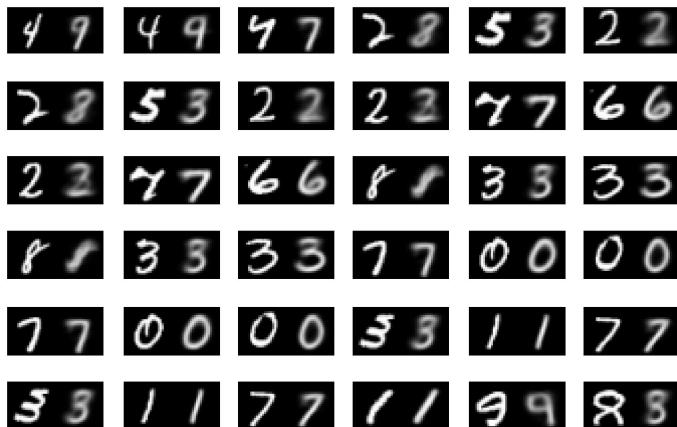
        # 反向传播和优化
        optimizer.zero_grad() # 每一次循环之前, 将梯度清零
        loss.backward() # 反向传播
        optimizer.step() # 梯度下降

        if i == 0:
            x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)], dim=3) #torch.Size([128, 1, 28, 56])

    # 输出epoch信息
    train_loss.append(np.sum(batch_loss) / number)
    print("epoch[{}]/{} | loss:{}"
          .format(epoch + 1, epoches, train_loss[epoch]))
```

```
# 展示最终迭代训练后：VAE生成图片与原始图片的对比
x_s = x_concatD.view(128, 28, 56).detach().cpu().numpy() * 255.
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_s[i * 3 + j], cmap='gray')
plt.show()
```

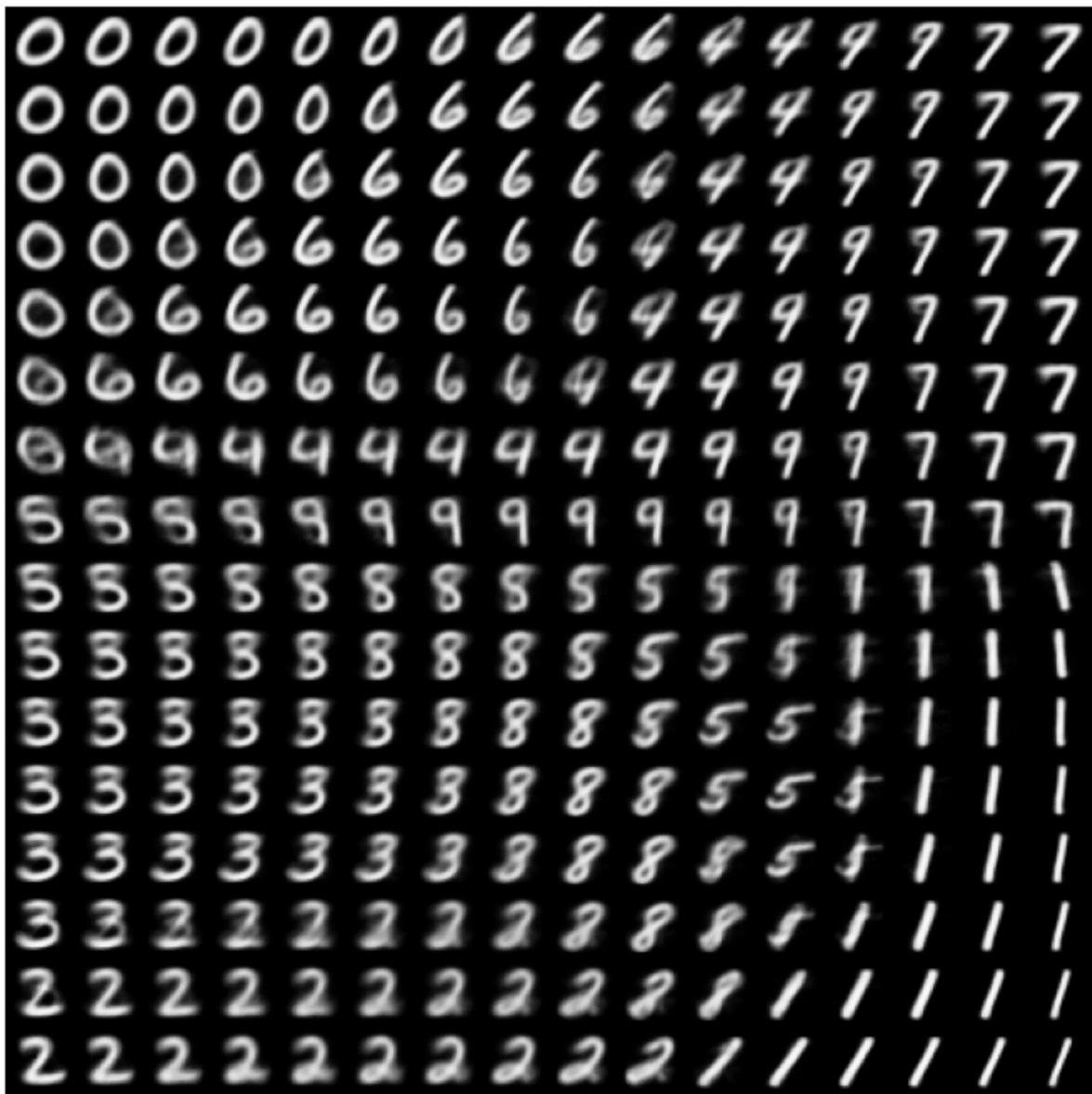
```
epoch[1/20] | loss:54.73777405598958
epoch[2/20] | loss:48.60477434082031
epoch[3/20] | loss:41.396358451334635
epoch[4/20] | loss:39.77705034586589
epoch[5/20] | loss:38.7182927734375
epoch[6/20] | loss:38.03185735270182
epoch[7/20] | loss:37.55494031575521
epoch[8/20] | loss:37.23315347086589
epoch[9/20] | loss:36.958701883951825
epoch[10/20] | loss:36.75901299641927
epoch[11/20] | loss:36.58999401041667
epoch[12/20] | loss:36.450571240234375
epoch[13/20] | loss:36.328932267252604
epoch[14/20] | loss:36.19714766438802
epoch[15/20] | loss:36.11057159423828
epoch[16/20] | loss:35.986125130208336
epoch[17/20] | loss:35.932440087890626
epoch[18/20] | loss:35.844634948730466
epoch[19/20] | loss:35.799882779947914
epoch[20/20] | loss:35.727352176920576
```



```
In [ ]: num_per_row, num_per_col = 16, 16
digit_size = 28
figure = np.zeros((digit_size * num_per_row, digit_size * num_per_col))
grid_x = norm.ppf(np.linspace(0.05, 0.95, num_per_row))
grid_y = norm.ppf(np.linspace(0.05, 0.95, num_per_col))

for i, yi in enumerate(grid_x):
    for j, xi in enumerate(grid_y):
        z_sample = np.array([[xi, yi]])
        z_sample = torch.tensor(np.tile(z_sample, batch_size)).reshape(batch_size, 2)
        x_decoded = model.decode(z_sample)
        digit = x_decoded[0].reshape(digit_size, digit_size)
        digit = torch.sigmoid(digit)
        figure[i * digit_size: (i + 1) * digit_size,
               j * digit_size: (j + 1) * digit_size] = digit.detach().cpu().numpy() * 255.

plt.figure(figsize=(12, 12))
plt.axis("off")
plt.imshow(figure, cmap='Greys_r')
plt.show()
```



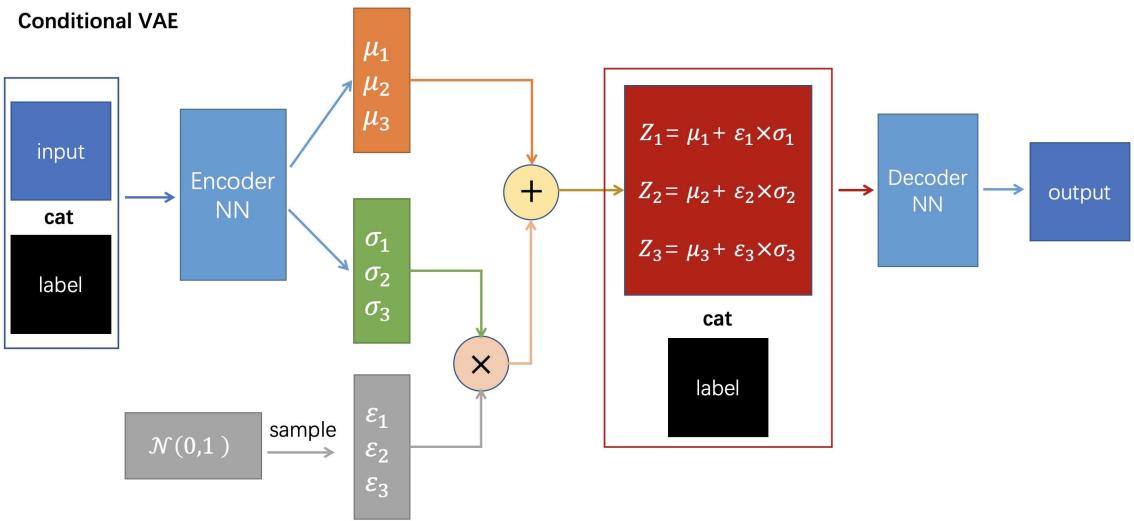
从上图中可以看出，VAE学到的二维隐变量Z：

- 第一维度（水平维度）主要控制 数字的形状，字体的斜度改变幅度不大
- 第二维度（竖直维度）主要控制数字的 倾斜 和 形状（低于第一维度的影响）

CVAE

先介绍AE和VAE的优缺点：

- AE适合数据压缩与还原，不适合生成未见过的数据
- VAE适合生成未见过的数据，但不能控制生成内容。### CVAE (Conditional VAE) 可以在生成数据时通过指定其标签来生成想生成的数据



In []:

```
# 条件变分自编码器
class CVAE(nn.Module):

    def __init__(self, feature_size, class_size, latent_size):
        super(CVAE, self).__init__()

        self.fc1 = nn.Linear(feature_size + class_size, 200)
        self.fc2_mu = nn.Linear(200, latent_size)
        self.fc2_log_std = nn.Linear(200, latent_size)
        self.fc3 = nn.Linear(latent_size + class_size, 200)
        self.fc4 = nn.Linear(200, feature_size)

    def encode(self, x, y):
        h1 = F.relu(self.fc1(torch.cat([x, y], dim=1))) # 连接特征和标签
        mu = self.fc2_mu(h1)
        log_std = self.fc2_log_std(h1)
        return mu, log_std

    def decode(self, z, y):
        h3 = F.relu(self.fc3(torch.cat([z, y], dim=1))) # 连接标签和latent隐变量
        recon = torch.sigmoid(self.fc4(h3))
        return recon

    def reparametrize(self, mu, log_std):
        std = torch.exp(0.5 * log_std)
        eps = torch.randn_like(std)
        z = mu + eps * std
        return z

    def forward(self, x, y):
        mu, log_std = self.encode(x, y)
        z = self.reparametrize(mu, log_std)
        recon = self.decode(z, y)
        return recon, mu, log_std

    def loss_function(self, recon, x, mu, log_std) -> torch.Tensor:
        recon_loss = F.mse_loss(recon, x, reduction="sum")
        k1_loss = -0.5 * (1 + 2 * log_std - mu.pow(2) - torch.exp(2 * log_std))
        k1_loss = torch.sum(k1_loss)
        loss = recon_loss + k1_loss
        return loss
```

In []:

```
cvae = CVAE(feature_size=784, class_size=10, latent_size=20)
optimizer = torch.optim.Adam(cvae.parameters(), lr=1e-3)
result_dir = '.\\VAEResult\\CVAE'
```

```
train_loss = []
epoches = 40
for epoch in range(epoches):

    batch_loss = []
    for i, data in enumerate(dataIter):
        img, label = data
        img.to(device)
        inputs = img.view(img.shape[0], -1)
        y = torch.nn.functional.one_hot(label, num_classes=10)
        # print(inputs.shape)
        # print(y.shape)
        y.to(device)

        recon, mu, log_std = cvae(inputs, y)
        loss = cvae.loss_function(recon, inputs, mu, log_std)
        batch_loss.append(loss.item())

        optimizer.zero_grad()
        loss.backward()
        optimizer.step()

    # 输出batch信息
    if i % 100 == 0 and i > 0:
        print("epoch : {} | batch : {} | batch average loss: {}".format(epoch + 1, i, loss.item() / img.shape[0]))
    if i == 0:
        x_concatD = torch.cat([img.view(-1, 1, 28, 28), recon.view(-1, 1, 28, 28)])
        save_image(x_concatD, '%s\\reconstructed-%d.png' % (result_dir, epoch + 1))

    # 输出epoch信息
    train_loss.append(np.sum(batch_loss) / number)
    print("epoch[{} / {}] | loss: {}".format(epoch + 1, epoches, train_loss[epoch]))
```

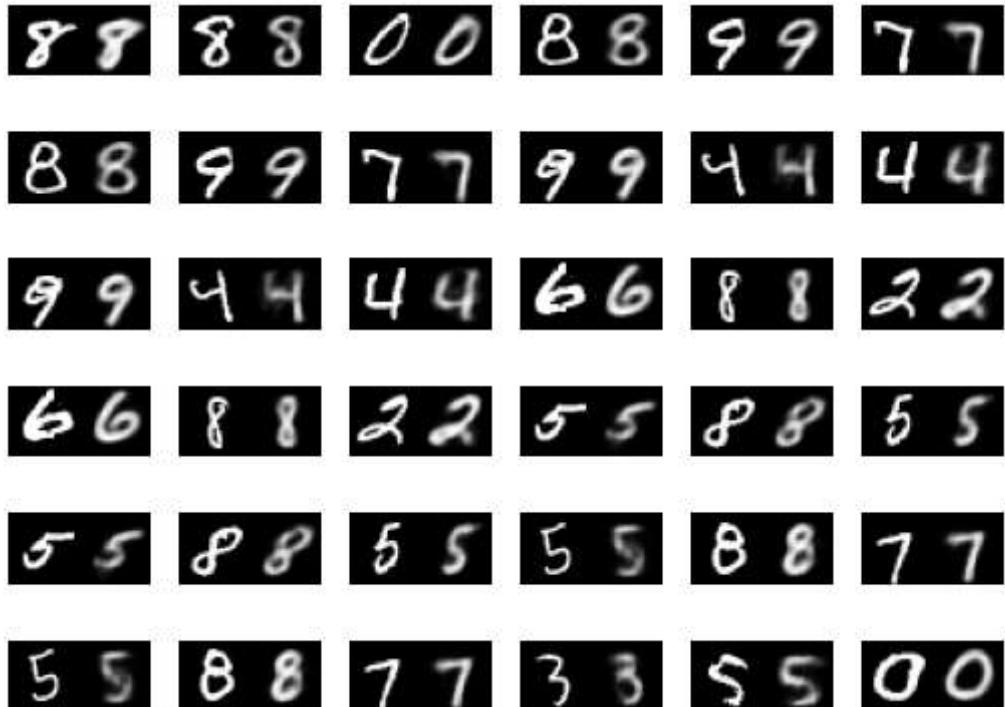
epoch : 1 | batch : 100 | batch average loss: 51.963008880615234
epoch : 1 | batch : 200 | batch average loss: 45.13134002685547
epoch : 1 | batch : 300 | batch average loss: 40.94240188598633
epoch : 1 | batch : 400 | batch average loss: 38.570213317871094
epoch[1/40] | loss:48.95314457194011
epoch : 2 | batch : 100 | batch average loss: 38.26136016845703
epoch : 2 | batch : 200 | batch average loss: 37.370811462402344
epoch : 2 | batch : 300 | batch average loss: 35.45708084106445
epoch : 2 | batch : 400 | batch average loss: 35.08346176147461
epoch[2/40] | loss:36.59286827799479
epoch : 3 | batch : 100 | batch average loss: 36.25738525390625
epoch : 3 | batch : 200 | batch average loss: 33.35258865356445
epoch : 3 | batch : 300 | batch average loss: 32.806697845458984
epoch : 3 | batch : 400 | batch average loss: 33.62622833251953
epoch[3/40] | loss:34.4992719523112
epoch : 4 | batch : 100 | batch average loss: 34.40482711791992
epoch : 4 | batch : 200 | batch average loss: 34.585147857666016
epoch : 4 | batch : 300 | batch average loss: 32.33565139770508
epoch : 4 | batch : 400 | batch average loss: 31.76677131652832
epoch[4/40] | loss:33.41451225992839
epoch : 5 | batch : 100 | batch average loss: 33.434326171875
epoch : 5 | batch : 200 | batch average loss: 34.187599182128906
epoch : 5 | batch : 300 | batch average loss: 32.80463790893555
epoch : 5 | batch : 400 | batch average loss: 31.56391143798828
epoch[5/40] | loss:32.67819062093099
epoch : 6 | batch : 100 | batch average loss: 33.56522750854492
epoch : 6 | batch : 200 | batch average loss: 31.77747917175293
epoch : 6 | batch : 300 | batch average loss: 31.043067932128906
epoch : 6 | batch : 400 | batch average loss: 33.22935485839844
epoch[6/40] | loss:32.212308577473955
epoch : 7 | batch : 100 | batch average loss: 33.25436019897461
epoch : 7 | batch : 200 | batch average loss: 30.396987915039062
epoch : 7 | batch : 300 | batch average loss: 29.83347511291504
epoch : 7 | batch : 400 | batch average loss: 30.063520431518555
epoch[7/40] | loss:31.85576857096354
epoch : 8 | batch : 100 | batch average loss: 31.95095443725586
epoch : 8 | batch : 200 | batch average loss: 30.38056182861328
epoch : 8 | batch : 300 | batch average loss: 33.28582763671875
epoch : 8 | batch : 400 | batch average loss: 30.283403396606445
epoch[8/40] | loss:31.6026166015625
epoch : 9 | batch : 100 | batch average loss: 29.716054916381836
epoch : 9 | batch : 200 | batch average loss: 31.252925872802734
epoch : 9 | batch : 300 | batch average loss: 30.440357208251953
epoch : 9 | batch : 400 | batch average loss: 34.86772537231445
epoch[9/40] | loss:31.36993547363281
epoch : 10 | batch : 100 | batch average loss: 33.55823516845703
epoch : 10 | batch : 200 | batch average loss: 29.30370330810547
epoch : 10 | batch : 300 | batch average loss: 31.13372230529785
epoch : 10 | batch : 400 | batch average loss: 30.678951263427734
epoch[10/40] | loss:31.19885840657552
epoch : 11 | batch : 100 | batch average loss: 31.896329879760742
epoch : 11 | batch : 200 | batch average loss: 31.10787010192871
epoch : 11 | batch : 300 | batch average loss: 30.818161010742188
epoch : 11 | batch : 400 | batch average loss: 30.791887283325195
epoch[11/40] | loss:31.03942110188802
epoch : 12 | batch : 100 | batch average loss: 32.36382293701172
epoch : 12 | batch : 200 | batch average loss: 31.722469329833984
epoch : 12 | batch : 300 | batch average loss: 30.01117515563965
epoch : 12 | batch : 400 | batch average loss: 30.601226806640625
epoch[12/40] | loss:30.90047344156901
epoch : 13 | batch : 100 | batch average loss: 29.797889709472656
epoch : 13 | batch : 200 | batch average loss: 30.809833526611328
epoch : 13 | batch : 300 | batch average loss: 31.6361083984375
epoch : 13 | batch : 400 | batch average loss: 30.772850036621094

epoch[13/40] | loss:30.824939388020834
epoch : 14 | batch : 100 | batch average loss: 29.731353759765625
epoch : 14 | batch : 200 | batch average loss: 31.06955337524414
epoch : 14 | batch : 300 | batch average loss: 31.559471130371094
epoch : 14 | batch : 400 | batch average loss: 30.52155303955078
epoch[14/40] | loss:30.73059589029948
epoch : 15 | batch : 100 | batch average loss: 30.45916748046875
epoch : 15 | batch : 200 | batch average loss: 30.16378402709961
epoch : 15 | batch : 300 | batch average loss: 31.088815689086914
epoch : 15 | batch : 400 | batch average loss: 32.014007568359375
epoch[15/40] | loss:30.675125561523437
epoch : 16 | batch : 100 | batch average loss: 31.838071823120117
epoch : 16 | batch : 200 | batch average loss: 30.342453002929688
epoch : 16 | batch : 300 | batch average loss: 30.87862777709961
epoch : 16 | batch : 400 | batch average loss: 29.179012298583984
epoch[16/40] | loss:30.59822233072917
epoch : 17 | batch : 100 | batch average loss: 29.511093139648438
epoch : 17 | batch : 200 | batch average loss: 30.699844360351562
epoch : 17 | batch : 300 | batch average loss: 32.082977294921875
epoch : 17 | batch : 400 | batch average loss: 30.24424934387207
epoch[17/40] | loss:30.530924995930988
epoch : 18 | batch : 100 | batch average loss: 30.295574188232422
epoch : 18 | batch : 200 | batch average loss: 30.765518188476562
epoch : 18 | batch : 300 | batch average loss: 30.426048278808594
epoch : 18 | batch : 400 | batch average loss: 30.835126876831055
epoch[18/40] | loss:30.472196333821614
epoch : 19 | batch : 100 | batch average loss: 30.74138832092285
epoch : 19 | batch : 200 | batch average loss: 30.207359313964844
epoch : 19 | batch : 300 | batch average loss: 30.918550491333008
epoch : 19 | batch : 400 | batch average loss: 28.2825870513916
epoch[19/40] | loss:30.369287532552082
epoch : 20 | batch : 100 | batch average loss: 30.907062530517578
epoch : 20 | batch : 200 | batch average loss: 29.95197296142578
epoch : 20 | batch : 300 | batch average loss: 30.51449966430664
epoch : 20 | batch : 400 | batch average loss: 30.24428939819336
epoch[20/40] | loss:30.36614881591797
epoch : 21 | batch : 100 | batch average loss: 29.085006713867188
epoch : 21 | batch : 200 | batch average loss: 28.42890739440918
epoch : 21 | batch : 300 | batch average loss: 28.805042266845703
epoch : 21 | batch : 400 | batch average loss: 28.745967864990234
epoch[21/40] | loss:30.30871149088542
epoch : 22 | batch : 100 | batch average loss: 31.5228214263916
epoch : 22 | batch : 200 | batch average loss: 30.416906356811523
epoch : 22 | batch : 300 | batch average loss: 29.9090576171875
epoch : 22 | batch : 400 | batch average loss: 30.389057159423828
epoch[22/40] | loss:30.278405017089845
epoch : 23 | batch : 100 | batch average loss: 29.83504867553711
epoch : 23 | batch : 200 | batch average loss: 28.420379638671875
epoch : 23 | batch : 300 | batch average loss: 29.209976196289062
epoch : 23 | batch : 400 | batch average loss: 32.416481018066406
epoch[23/40] | loss:30.226935026041666
epoch : 24 | batch : 100 | batch average loss: 29.19626235961914
epoch : 24 | batch : 200 | batch average loss: 29.717859268188477
epoch : 24 | batch : 300 | batch average loss: 29.214136123657227
epoch : 24 | batch : 400 | batch average loss: 30.004039764404297
epoch[24/40] | loss:30.199798457845052
epoch : 25 | batch : 100 | batch average loss: 31.328393936157227
epoch : 25 | batch : 200 | batch average loss: 30.36971664428711
epoch : 25 | batch : 300 | batch average loss: 30.22542381286621
epoch : 25 | batch : 400 | batch average loss: 30.190940856933594
epoch[25/40] | loss:30.12611864827474
epoch : 26 | batch : 100 | batch average loss: 28.886539459228516
epoch : 26 | batch : 200 | batch average loss: 28.849742889404297
epoch : 26 | batch : 300 | batch average loss: 30.608139038085938

epoch : 26 | batch : 400 | batch average loss: 30.700090408325195
epoch[26/40] | loss:30.143408459472656
epoch : 27 | batch : 100 | batch average loss: 30.710426330566406
epoch : 27 | batch : 200 | batch average loss: 29.411388397216797
epoch : 27 | batch : 300 | batch average loss: 28.671241760253906
epoch : 27 | batch : 400 | batch average loss: 32.32023239135742
epoch[27/40] | loss:30.078115478515624
epoch : 28 | batch : 100 | batch average loss: 29.604829788208008
epoch : 28 | batch : 200 | batch average loss: 30.363327026367188
epoch : 28 | batch : 300 | batch average loss: 30.298006057739258
epoch : 28 | batch : 400 | batch average loss: 28.877004623413086
epoch[28/40] | loss:30.047482482910155
epoch : 29 | batch : 100 | batch average loss: 29.092262268066406
epoch : 29 | batch : 200 | batch average loss: 30.497058868408203
epoch : 29 | batch : 300 | batch average loss: 29.675079345703125
epoch : 29 | batch : 400 | batch average loss: 29.023897171020508
epoch[29/40] | loss:30.00537834065755
epoch : 30 | batch : 100 | batch average loss: 30.67474937438965
epoch : 30 | batch : 200 | batch average loss: 30.208881378173828
epoch : 30 | batch : 300 | batch average loss: 28.00241470336914
epoch : 30 | batch : 400 | batch average loss: 28.121036529541016
epoch[30/40] | loss:30.008169958496094
epoch : 31 | batch : 100 | batch average loss: 30.705406188964844
epoch : 31 | batch : 200 | batch average loss: 30.130264282226562
epoch : 31 | batch : 300 | batch average loss: 30.544179916381836
epoch : 31 | batch : 400 | batch average loss: 29.273479461669922
epoch[31/40] | loss:29.990759016927083
epoch : 32 | batch : 100 | batch average loss: 31.866615295410156
epoch : 32 | batch : 200 | batch average loss: 28.473804473876953
epoch : 32 | batch : 300 | batch average loss: 30.587295532226562
epoch : 32 | batch : 400 | batch average loss: 31.260520935058594
epoch[32/40] | loss:29.96353927001953
epoch : 33 | batch : 100 | batch average loss: 28.99738883972168
epoch : 33 | batch : 200 | batch average loss: 28.271421432495117
epoch : 33 | batch : 300 | batch average loss: 28.6134033203125
epoch : 33 | batch : 400 | batch average loss: 28.58405303955078
epoch[33/40] | loss:29.90408229166667
epoch : 34 | batch : 100 | batch average loss: 29.95927619934082
epoch : 34 | batch : 200 | batch average loss: 29.22492790222168
epoch : 34 | batch : 300 | batch average loss: 28.661806106567383
epoch : 34 | batch : 400 | batch average loss: 28.675168991088867
epoch[34/40] | loss:29.940753666178384
epoch : 35 | batch : 100 | batch average loss: 28.52299690246582
epoch : 35 | batch : 200 | batch average loss: 31.263370513916016
epoch : 35 | batch : 300 | batch average loss: 30.374156951904297
epoch : 35 | batch : 400 | batch average loss: 29.15502166748047
epoch[35/40] | loss:29.90136706542969
epoch : 36 | batch : 100 | batch average loss: 29.628070831298828
epoch : 36 | batch : 200 | batch average loss: 29.055295944213867
epoch : 36 | batch : 300 | batch average loss: 30.4556941986084
epoch : 36 | batch : 400 | batch average loss: 31.521160125732422
epoch[36/40] | loss:29.854595438639322
epoch : 37 | batch : 100 | batch average loss: 29.48159408569336
epoch : 37 | batch : 200 | batch average loss: 28.464279174804688
epoch : 37 | batch : 300 | batch average loss: 28.795665740966797
epoch : 37 | batch : 400 | batch average loss: 30.136043548583984
epoch[37/40] | loss:29.827265291341146
epoch : 38 | batch : 100 | batch average loss: 29.85831069946289
epoch : 38 | batch : 200 | batch average loss: 27.91811752319336
epoch : 38 | batch : 300 | batch average loss: 30.69519805908203
epoch : 38 | batch : 400 | batch average loss: 29.865501403808594
epoch[38/40] | loss:29.818939029947916
epoch : 39 | batch : 100 | batch average loss: 29.2919921875
epoch : 39 | batch : 200 | batch average loss: 32.69929504394531

```
epoch : 39 | batch : 300 | batch average loss: 29.28822135925293
epoch : 39 | batch : 400 | batch average loss: 31.737045288085938
epoch[39/40] | loss: 29.8075778523763
epoch : 40 | batch : 100 | batch average loss: 30.906143188476562
epoch : 40 | batch : 200 | batch average loss: 29.92847442626953
epoch : 40 | batch : 300 | batch average loss: 30.740585327148438
epoch : 40 | batch : 400 | batch average loss: 29.669231414794922
epoch[40/40] | loss: 29.782788846842447
```

```
In [ ]: # 展示最终迭代训练后：VAE生成图片与原始图片的对比
x_s = x_concatD.view(128, 28, 28).detach().cpu().numpy() * 255.
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_s[i * 3 + j], cmap='gray')
plt.show()
```



```
In [ ]: # 利用CVAE生成特定label下的图片
label = 3
z = torch.randn(784, 20)
labels = torch.full(size=(784,), fill_value=label, dtype=torch.int64)
y = torch.nn.functional.one_hot(labels, num_classes=10)
recon = cvae.decode(z, y)

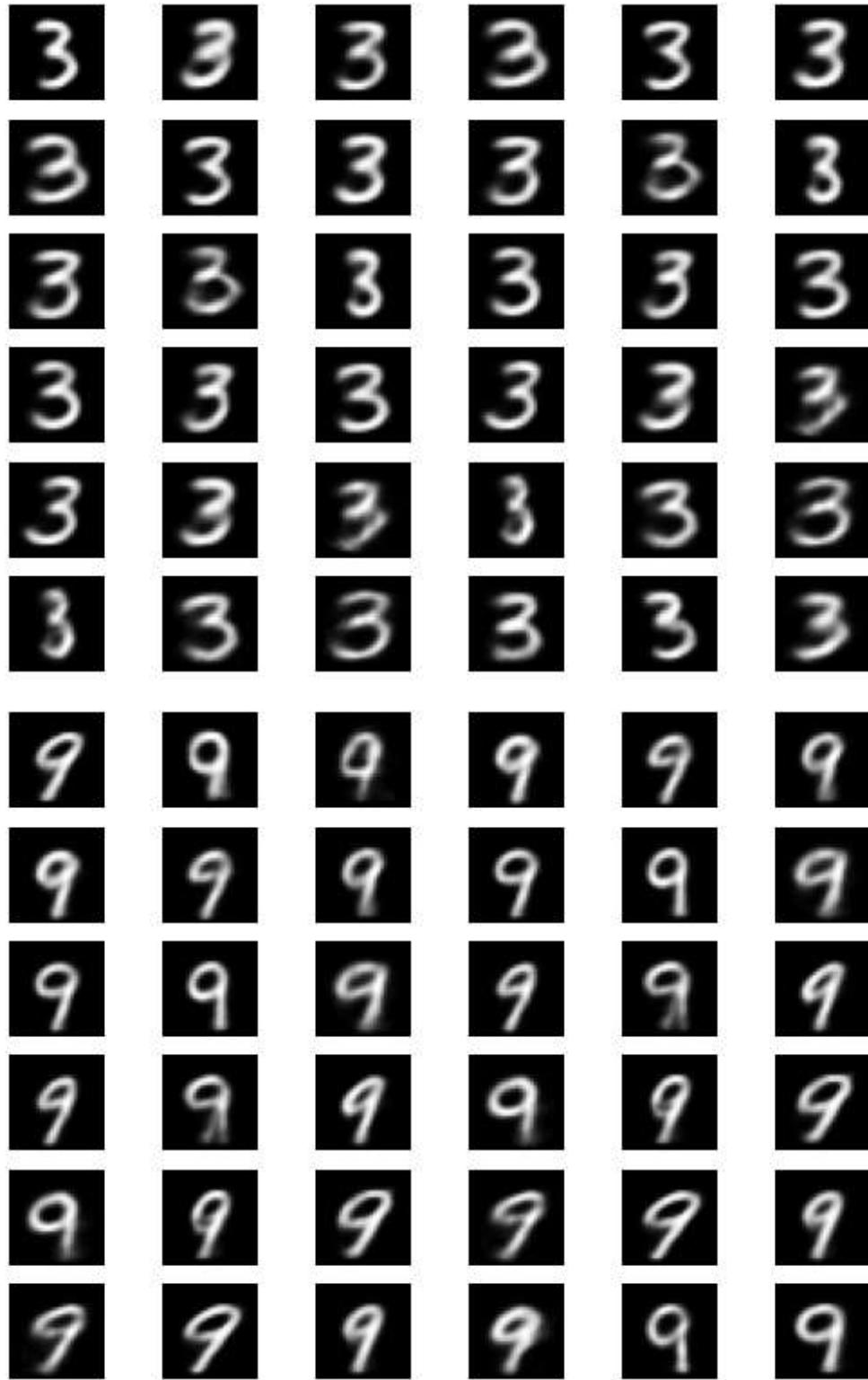
# 显示
img = recon.view(recon.shape[0], 28, 28).detach().cpu().numpy() * 255.
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(img[i * 3 + j], cmap='gray')
plt.show()

label = 9
z = torch.randn(784, 20)
labels = torch.full(size=(784,), fill_value=label, dtype=torch.int64)
y = torch.nn.functional.one_hot(labels, num_classes=10)
recon = cvae.decode(z, y)
```

```

# 显示
img = recon.view(recon.shape[0], 28, 28).detach().cpu().numpy() * 255.
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(img[i * 3 + j], cmap='gray')
plt.show()

```



β -VAE

β -VAE是在传统VAE基础上对损失函数进行修改，为损失函数的

KL散度项加上一个超参数 β

VAE的损失函数由两部分组成，一部分是重构项，一部分是KL散度。VAE的整体过程可以粗略看成两步，第一步是编码，第二步是解码，两步由编码生成的隐变量连结。 β 的引入相当于为隐变量的信息增加了一个信息瓶颈。

重构项反映了输入与隐变量的互信息大小，KL部分反映了隐变量含有的信息量大小， β 的引入约束了隐变量的传递的信息量，在信息保存（重建成本作为正则化）和潜在信道容量限制（ $\beta > 1$ ）之间寻找平衡，增强了模型的解耦能力。

损失函数引入超参数 β

```
In [ ]: # L2损失 (MSE Loss) 构建损失函数
def beta_vae_loss_mse(x, gen_x, mean, log_var, beta):
    # 重构项损失
    mse_loss = torch.nn.MSELoss(reduction='sum')
    loss1 = mse_loss(gen_x, x)

    # 最小化  $q(z|x)$  和  $p(z)$  的距离
    KL_loss = 0.5 * torch.sum(torch.exp(log_var) + torch.pow(mean, 2) - log_var - 1)

    return loss1 + beta*KL_loss

# 交叉熵损失 (Cross Entropy Loss) 构建损失函数
def beta_vae_loss_cross(x, gen_x, mean, log_var, beta):
    # 重构项损失
    loss1 = F.binary_cross_entropy(gen_x, x, reduction='sum')

    # 最小化  $q(z|x)$  和  $p(z)$  的距离
    KL_loss = 0.5 * torch.sum(torch.exp(log_var) + torch.pow(mean, 2) - log_var - 1)

    return loss1 + beta*KL_loss
```

```
In [ ]: test_z = torch.randn((batch_size, 20)).to(device)
```

经测试 $\beta = 3$ 时有较好的生成效果

```
In [ ]: # 训练模型参数
learning_rate = 1e-3 # 学习率
epoches = 10 # 迭代次数

# 实例化模型
beta_vae = VariationalAutoEncoder_Conv()
beta_vae.to(device)
beta_model = beta_vae

# 超参数
beta = 3

# 创建优化器
beta_optimizer = torch.optim.Adam(beta_model.parameters(), lr=learning_rate)

train_loss = [] # 保存每个epoch的训练误差
result_dir = '.\VAEResult\bata-VAE' # 保存生成图片的目录
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
```

```

for i, (x, y) in enumerate(dataIter):
    x = x.to(device) # gpu训练

    mean, log_var, gen_x = beta_model(x)
    loss = beta_vae_loss_mse(x, gen_x, mean, log_var, beta)
    batch_loss.append(loss.item())

    # 反向传播和优化
    beta_optimizer.zero_grad() # 每一次循环之前，将梯度清零
    loss.backward() # 反向传播
    beta_optimizer.step() # 梯度下降

    # 保存 各个epoch下 VAE的生成效果图
    if i == 0:
        x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)])
    # 输出epoch信息
    train_loss.append(np.sum(batch_loss) / number)
    print("epoch[{} / {}] | loss:{}"
          .format(epoch + 1, epoches, train_loss[epoch]))

logits = beta_model.decode(test_z) # 仅通过解码器生成图片
x_hat = torch.sigmoid(logits) # 转换为像素范围
x_hat = x_hat.view(128, 28, 28).detach().cpu().numpy() * 255.

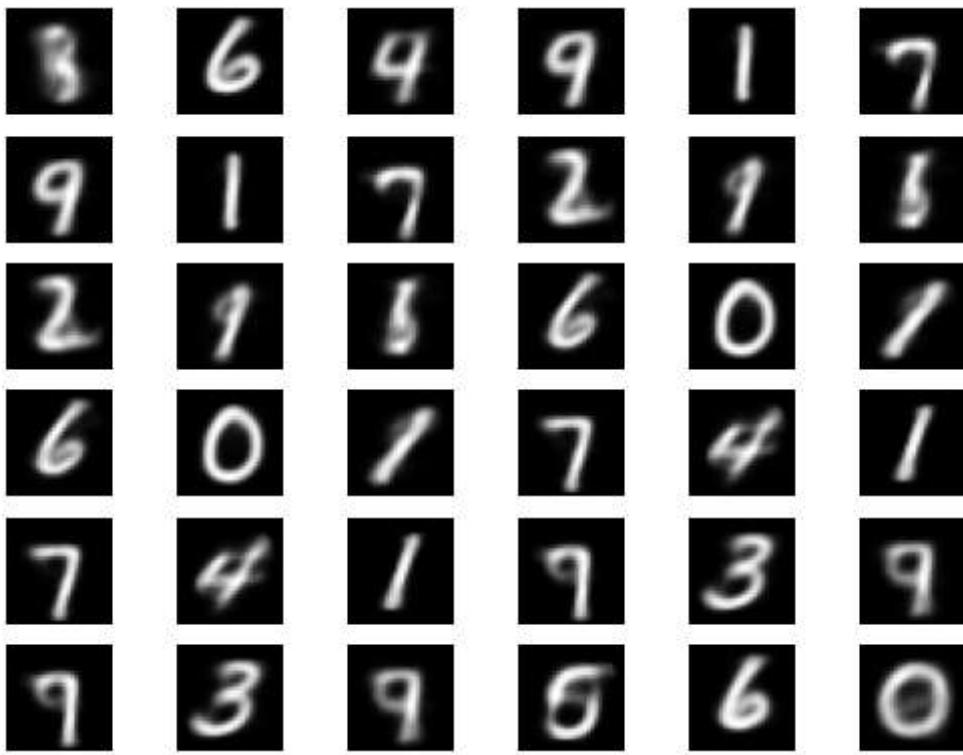
# 展示图片
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_hat[i * 3 + j], cmap='gray')
plt.show()

```

```

epoch[1/10] | loss:53.801485278320314
epoch[2/10] | loss:48.48496276855469
epoch[3/10] | loss:46.122619482421875
epoch[4/10] | loss:44.91053746744792
epoch[5/10] | loss:44.41830204264323
epoch[6/10] | loss:44.05171790364583
epoch[7/10] | loss:43.800046158854165
epoch[8/10] | loss:43.617858894856774
epoch[9/10] | loss:43.45289364420573
epoch[10/10] | loss:43.37656237792969

```



为进一步探究验证超参数 β 的作用，测试不同 β 值下的生成结果

$\beta = 1$ (VAE)

```
In [ ]: # 训练模型参数
learning_rate = 1e-3 # 学习率
epoches = 10 # 迭代次数

# 实例化模型
beta_vae1 = VariationalAutoEncoder_Conv()
beta_vae1.to(device)
beta_model = beta_vae1

#超参数
beta = 1

# 创建优化器
beta_optimizer = torch.optim.Adam(beta_model.parameters(), lr=learning_rate)

train_loss = [] # 保存每个epoch的训练误差
result_dir = '.\\VAEResult\\bata-VAE' # 保存生成图片的目录
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        mean, log_var, gen_x = beta_model(x)
        loss = beta_vae_loss_mse(x, gen_x, mean, log_var, beta)
        batch_loss.append(loss.item())

    # 反向传播和优化
    beta_optimizer.zero_grad() # 每一次循环之前，将梯度清零
    loss.backward() # 反向传播
    beta_optimizer.step() # 梯度下降
```

```

# 保存 各个epoch下 VAE的生成效果图
if i == 0:
    x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)])

# 输出epoch信息
train_loss.append(np.sum(batch_loss) / number)
print("epoch[{} / {}] | loss: {}"
      .format(epoch + 1, epoches, train_loss[epoch]))


logits = beta_model.decode(test_z) # 仅通过解码器生成图片
x_hat = torch.sigmoid(logits) # 转换为像素范围
x_hat = x_hat.view(128, 28, 28).detach().cpu().numpy() * 255.

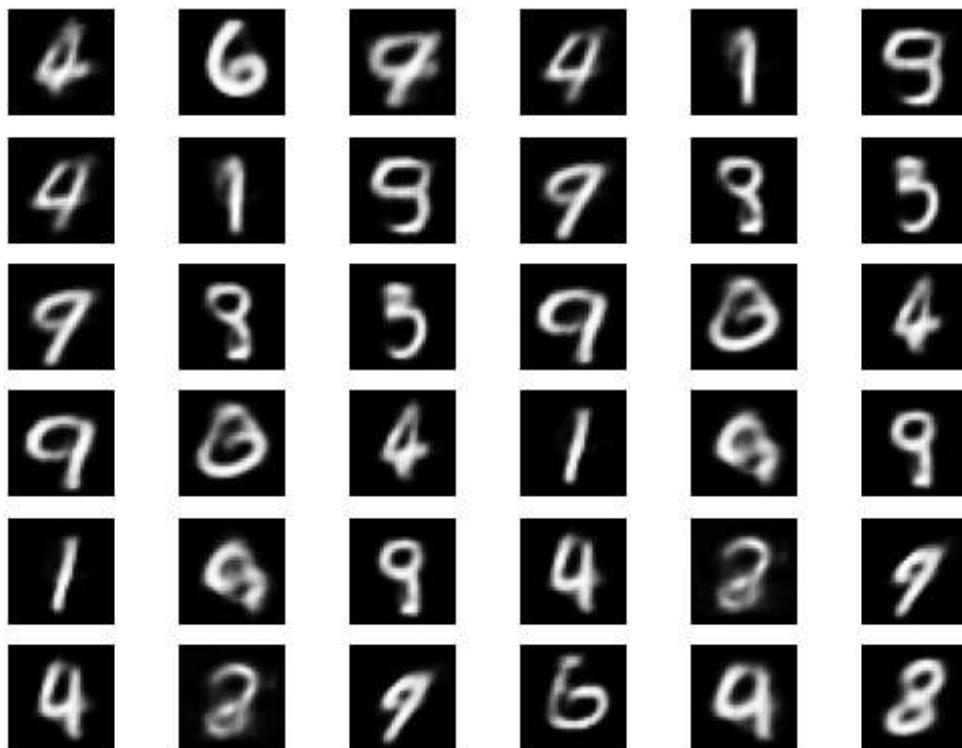
# 展示图片
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_hat[i * 3 + j], cmap='gray')
plt.show()

```

```

epoch[1/10] | loss:49.908536385091146
epoch[2/10] | loss:36.818755301920575
epoch[3/10] | loss:33.74037689208984
epoch[4/10] | loss:32.548841548665365
epoch[5/10] | loss:31.865619213867188
epoch[6/10] | loss:31.306879956054686
epoch[7/10] | loss:30.82028231608073
epoch[8/10] | loss:30.462920483398438
epoch[9/10] | loss:30.15816045735677
epoch[10/10] | loss:29.915357299804686

```



$$\beta = 8$$

```

In [ ]: # 训练模型参数
learning_rate = 1e-3 # 学习率
epoches = 10 # 迭代次数

```

```

# 实例化模型
beta_vae2 = VariationalAutoEncoder_Conv()
beta_vae2.to(device)
beta_model = beta_vae2

#超参数
beta = 8

# 创建优化器
beta_optimizer = torch.optim.Adam(beta_model.parameters(), lr=learning_rate)

train_loss = [] # 保存每个epoch的训练误差
result_dir = '.\\VAEResult\\bata-VAE' # 保存生成图片的目录
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        mean, log_var, gen_x = beta_model(x)
        loss = beta_vae_loss_mse(x, gen_x, mean, log_var, beta)
        batch_loss.append(loss.item())

    # 反向传播和优化
    beta_optimizer.zero_grad() # 每一次循环之前，将梯度清零
    loss.backward() # 反向传播
    beta_optimizer.step() # 梯度下降

    # 保存各个epoch下 VAE的生成效果图
    if i == 0:
        x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)])
    # 输出epoch信息
    train_loss.append(np.sum(batch_loss) / number)
    print("epoch[{} / {}] | loss:{}".format(epoch + 1, epoches, train_loss[epoch]))

```

```

logits = beta_model.decode(test_z) # 仅通过解码器生成图片
x_hat = torch.sigmoid(logits) # 转换为像素范围
x_hat = x_hat.view(128, 28, 28).detach().cpu().numpy() * 255.

```

```

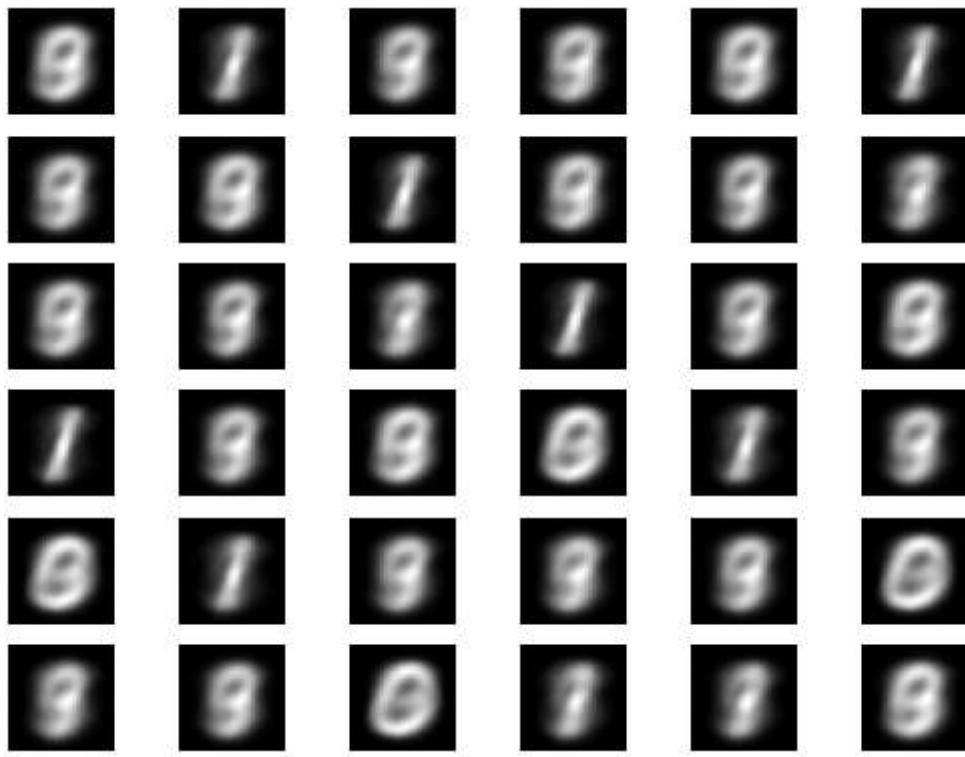
# 展示图片
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_hat[i * 3 + j], cmap='gray')
plt.show()

```

```

epoch[1/10] | loss:54.8489836344401
epoch[2/10] | loss:52.94638594563802
epoch[3/10] | loss:52.85733248697917
epoch[4/10] | loss:52.76279864095052
epoch[5/10] | loss:52.70004223632812
epoch[6/10] | loss:52.665559692382814
epoch[7/10] | loss:52.62776123046875
epoch[8/10] | loss:52.4991755859375
epoch[9/10] | loss:52.44217868652344
epoch[10/10] | loss:52.42447747395833

```



$\beta = 16$

```
In [ ]: # 训练模型参数
learning_rate = 1e-3 # 学习率
epoches = 10 # 迭代次数

# 实例化模型
beta_vae3 = VariationalAutoEncoder_Conv()
beta_vae3.to(device)
beta_model = beta_vae3

#超参数
beta = 16

# 创建优化器
beta_optimizer = torch.optim.Adam(beta_model.parameters(), lr=learning_rate)

train_loss = [] # 保存每个epoch的训练误差
result_dir = '.\\VAEResult\\bata-VAE' # 保存生成图片的目录
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        mean, log_var, gen_x = beta_model(x)
        loss = beta_vae_loss_mse(x, gen_x, mean, log_var, beta)
        batch_loss.append(loss.item())

    # 反向传播和优化
    beta_optimizer.zero_grad() # 每一次循环之前，将梯度清零
    loss.backward() # 反向传播
    beta_optimizer.step() # 梯度下降

    # 保存各个epoch下 VAE的生成效果图
    if i == 0:
```

```

x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)])
# 输出epoch信息
train_loss.append(np.sum(batch_loss) / number)
print("epoch[{}]/{} | loss:{}"
      .format(epoch + 1, epoches, train_loss[epoch]))

logits = beta_model.decode(test_z) # 仅通过解码器生成图片
x_hat = torch.sigmoid(logits) # 转换为像素范围
x_hat = x_hat.view(128, 28, 28).detach().cpu().numpy() * 255.

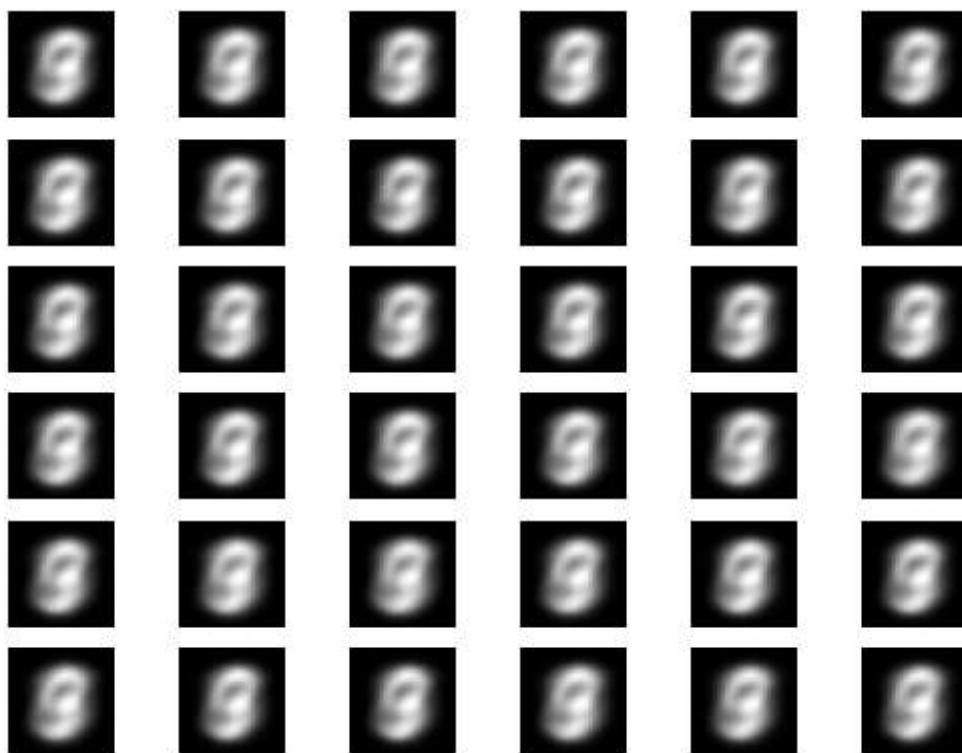
# 展示图片
_, axes = plt.subplots(6, 6)
for i in range(6):
    for j in range(6):
        axes[i][j].axis('off')
        axes[i][j].imshow(x_hat[i * 3 + j], cmap='gray')
plt.show()

```

```

epoch[1/10] | loss:54.87018264160156
epoch[2/10] | loss:52.99105546875
epoch[3/10] | loss:52.91904027506511
epoch[4/10] | loss:52.876090885416666
epoch[5/10] | loss:52.853292586263024
epoch[6/10] | loss:52.82928025716146
epoch[7/10] | loss:52.80811359049479
epoch[8/10] | loss:52.7967451578776
epoch[9/10] | loss:52.78326774902344
epoch[10/10] | loss:52.77977409667969

```



经过测试发现，随着 β 的增大生成的手写数字特征逐渐单一，可以推断出是由于隐变量信息保留的过少导致的。

为进一步验证，对于不同 β 下学习得到的隐变量进行观察

$$\beta = 3$$

```
In [ ]: import os
from scipy.stats import norm
```

```

# 生成隐空间内的采样
# 训练时Z_dim设定为20, 这里仅观察隐空间前俩维度表示特征
model = VariationalAutoEncoder_Conv(z_dim=2)
model.to(device)
epoches = 15
optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)
train_loss = [] # 保存每个epoch的训练误差
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        # 前向传播
        mean, log_var, gen_x = model(x)

        # 计算损失函数 二选一 即可
        loss = beta_vae_loss_mse(x, gen_x, mean, log_var, 3)
        batch_loss.append(loss.item())

        # 反向传播和优化
        optimizer.zero_grad() # 每一次循环之前, 将梯度清零
        loss.backward() # 反向传播
        optimizer.step() # 梯度下降

        if i == 0:
            x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)
                                  dim=3)] #torch.Size([128, 1, 28, 56])

    # 输出epoch信息
    train_loss.append(np.sum(batch_loss) / number)
    print("epoch[{} / {}] | loss: {}"
          .format(epoch + 1, epoches, train_loss[epoch]))

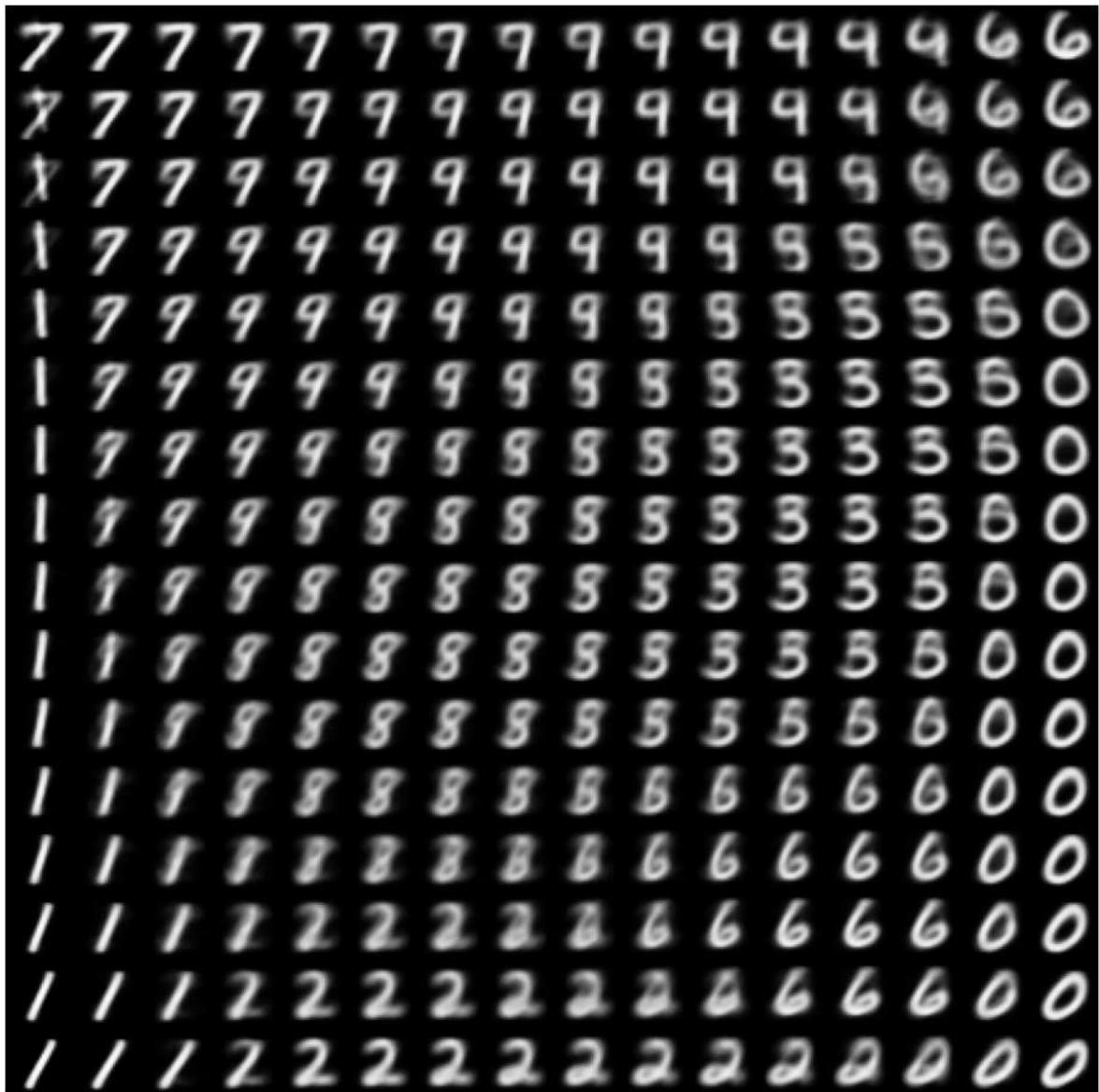
num_per_row, num_per_col = 16, 16
digit_size = 28
figure = np.zeros((digit_size * num_per_row, digit_size * num_per_col))
grid_x = norm.ppf(np.linspace(0.05, 0.95, num_per_row))
grid_y = norm.ppf(np.linspace(0.05, 0.95, num_per_col))

for i, yi in enumerate(grid_x):
    for j, xi in enumerate(grid_y):
        z_sample = np.array([[xi, yi]])
        z_sample = torch.tensor(np.tile(z_sample, batch_size)).reshape(batch_size, 2)
        x_decoded = model.decode(z_sample)
        digit = x_decoded[0].reshape(digit_size, digit_size)
        digit = torch.sigmoid(digit)
        figure[i * digit_size: (i + 1) * digit_size,
               j * digit_size: (j + 1) * digit_size] = digit.detach().cpu().numpy() * 255.

plt.figure(figsize=(12, 12))
plt.axis("off")
plt.imshow(figure, cmap='Greys_r')
plt.show()

```

```
epoch[1/15] | loss:53.993572607421875
epoch[2/15] | loss:48.99080161946615
epoch[3/15] | loss:47.26605036621094
epoch[4/15] | loss:46.69642425130208
epoch[5/15] | loss:46.279779052734376
epoch[6/15] | loss:45.92567962239583
epoch[7/15] | loss:45.71086240234375
epoch[8/15] | loss:45.59258842773438
epoch[9/15] | loss:45.46363501790365
epoch[10/15] | loss:45.325813842773435
epoch[11/15] | loss:45.29882972819011
epoch[12/15] | loss:45.17237499186198
epoch[13/15] | loss:45.110591959635414
epoch[14/15] | loss:45.02343063964844
epoch[15/15] | loss:45.03124555664063
```



$$\beta = 8$$

```
In [ ]: import os
from scipy.stats import norm

# 生成隐空间内的采样
# 训练时Z_dim设定为20, 这里仅观察隐空间前俩维度表示特征
model = VariationalAutoEncoder_Conv(z_dim=2)
model.to(device)
epoches = 15
optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)
```

```

train_loss = [] # 保存每个epoch的训练误差
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        # 前向传播
        mean, log_var, gen_x = model(x)

        # 计算损失函数 二选一 即可
        loss = beta_vae_loss_mse(x, gen_x, mean, log_var, 8)
        batch_loss.append(loss.item())

        # 反向传播和优化
        optimizer.zero_grad() # 每一次循环之前，将梯度清零
        loss.backward() # 反向传播
        optimizer.step() # 梯度下降

        if i == 0:
            x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)
                                  dim=3]) #torch.Size([128, 1, 28, 56])

        # 输出epoch信息
        train_loss.append(np.sum(batch_loss) / number)
        print("epoch[{}]/{} | loss:{}"
              .format(epoch + 1, epoches, train_loss[epoch]))

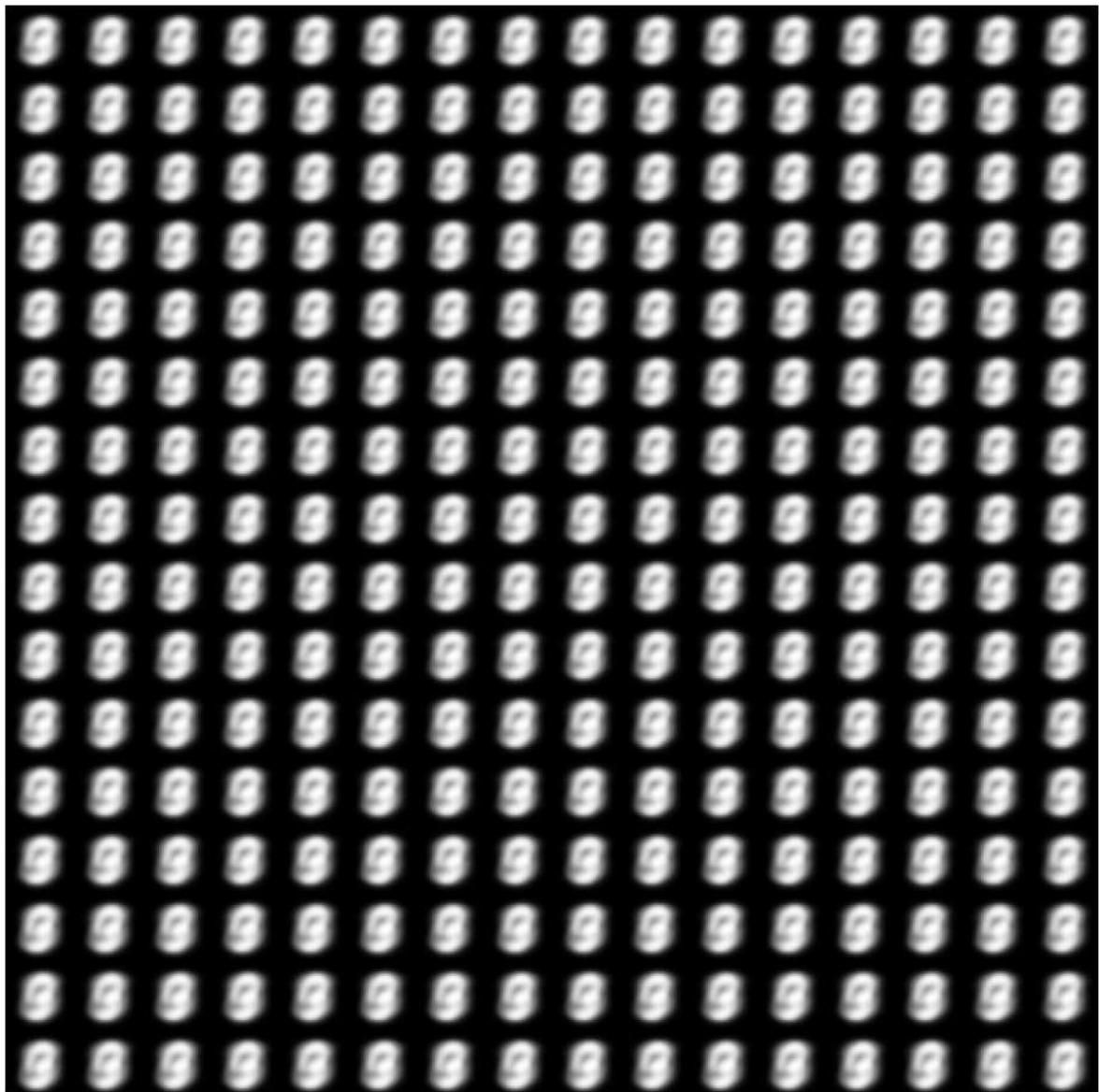
num_per_row, num_per_col = 16, 16
digit_size = 28
figure = np.zeros((digit_size * num_per_row, digit_size * num_per_col))
grid_x = norm.ppf(np.linspace(0.05, 0.95, num_per_row))
grid_y = norm.ppf(np.linspace(0.05, 0.95, num_per_col))

for i, yi in enumerate(grid_x):
    for j, xi in enumerate(grid_y):
        z_sample = np.array([[xi, yi]])
        z_sample = torch.tensor(np.tile(z_sample, batch_size)).reshape(batch_size, 2)
        x_decoded = model.decode(z_sample)
        digit = x_decoded[0].reshape(digit_size, digit_size)
        digit = torch.sigmoid(digit)
        figure[i * digit_size: (i + 1) * digit_size,
               j * digit_size: (j + 1) * digit_size] = digit.detach().cpu().numpy() * 255.

plt.figure(figsize=(12, 12))
plt.axis("off")
plt.imshow(figure, cmap='Greys_r')
plt.show()

```

```
epoch[1/15] | loss:54.59007465820312
epoch[2/15] | loss:52.874010213216145
epoch[3/15] | loss:52.84616063639323
epoch[4/15] | loss:52.82879040527344
epoch[5/15] | loss:52.81733885091146
epoch[6/15] | loss:52.79720810546875
epoch[7/15] | loss:52.792586328125
epoch[8/15] | loss:52.78499647623698
epoch[9/15] | loss:52.777526326497394
epoch[10/15] | loss:52.77128342285156
epoch[11/15] | loss:52.76522055664063
epoch[12/15] | loss:52.76194845377604
epoch[13/15] | loss:52.75534208984375
epoch[14/15] | loss:52.75855578613281
epoch[15/15] | loss:52.755916861979166
```



$$\beta = 16$$

```
In [ ]: import os
from scipy.stats import norm

# 生成隐空间内的采样
# 训练时Z_dim设定为20, 这里仅观察隐空间前俩维度表示特征
model = VariationalAutoEncoder_Conv(z_dim=2)
model.to(device)
epoches = 15
optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate)
```

```

train_loss = [] # 保存每个epoch的训练误差
x_concatD = torch.empty((128, 1, 28, 56))

for epoch in range(epoches):
    batch_loss = []
    for i, (x, y) in enumerate(dataIter):
        x = x.to(device) # gpu训练

        # 前向传播
        mean, log_var, gen_x = model(x)

        # 计算损失函数 二选一 即可
        loss = beta_vae_loss_mse(x, gen_x, mean, log_var, 16)
        batch_loss.append(loss.item())

        # 反向传播和优化
        optimizer.zero_grad() # 每一次循环之前，将梯度清零
        loss.backward() # 反向传播
        optimizer.step() # 梯度下降

        if i == 0:
            x_concatD = torch.cat([x.view(-1, 1, 28, 28), gen_x.view(-1, 1, 28, 28)
                                  dim=3]) #torch.Size([128, 1, 28, 56])

        # 输出epoch信息
        train_loss.append(np.sum(batch_loss) / number)
        print("epoch[{}]/{} | loss: {}"
              .format(epoch + 1, epoches, train_loss[epoch]))

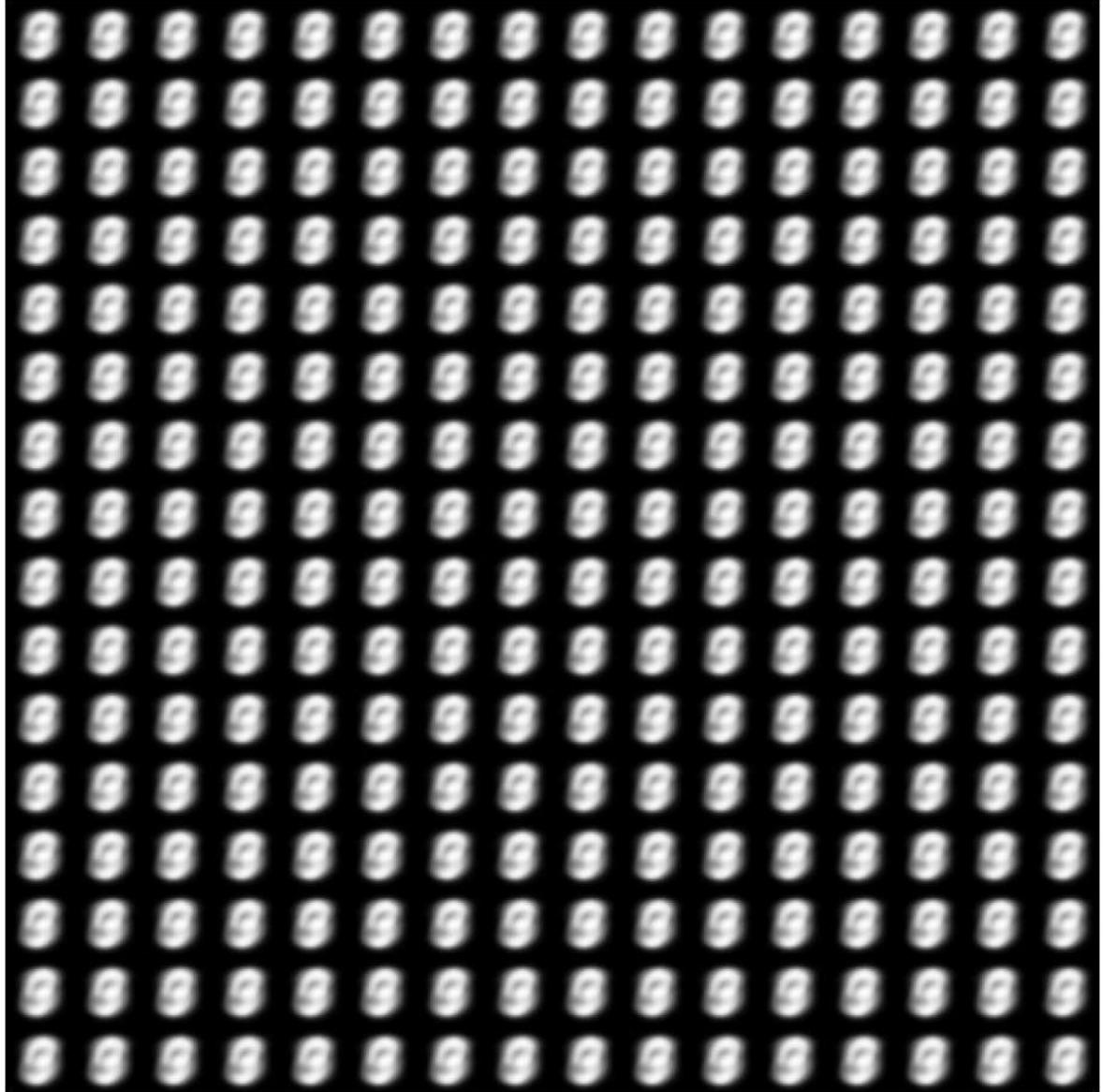
num_per_row, num_per_col = 16, 16
digit_size = 28
figure = np.zeros((digit_size * num_per_row, digit_size * num_per_col))
grid_x = norm.ppf(np.linspace(0.05, 0.95, num_per_row))
grid_y = norm.ppf(np.linspace(0.05, 0.95, num_per_col))

for i, yi in enumerate(grid_x):
    for j, xi in enumerate(grid_y):
        z_sample = np.array([[xi, yi]])
        z_sample = torch.tensor(np.tile(z_sample, batch_size)).reshape(batch_size, 2)
        x_decoded = model.decode(z_sample)
        digit = x_decoded[0].reshape(digit_size, digit_size)
        digit = torch.sigmoid(digit)
        figure[i * digit_size: (i + 1) * digit_size,
               j * digit_size: (j + 1) * digit_size] = digit.detach().cpu().numpy() * 255.

plt.figure(figsize=(12, 12))
plt.axis("off")
plt.imshow(figure, cmap='Greys_r')
plt.show()

```

```
epoch[1/15] | loss:54.63142722167969  
epoch[2/15] | loss:52.87429535319011  
epoch[3/15] | loss:52.84610010579427  
epoch[4/15] | loss:52.8118392171224  
epoch[5/15] | loss:52.809633618164064  
epoch[6/15] | loss:52.79538573404948  
epoch[7/15] | loss:52.79316895345052  
epoch[8/15] | loss:52.78191050618489  
epoch[9/15] | loss:52.766322029622394  
epoch[10/15] | loss:52.767954125976566  
epoch[11/15] | loss:52.767016292317706  
epoch[12/15] | loss:52.75978400065104  
epoch[13/15] | loss:52.756106754557294  
epoch[14/15] | loss:52.75557743326823  
epoch[15/15] | loss:52.749213810221356
```



很明显可以看到随着 β 的增大，隐变量所蕴含信息的减少，更加印证了 β 引入的作用。

将标准的VAE框架重新设计为具有强大潜在容量约束和独立先验压力的约束优化问题。通过用可调节此类压力强度的 β 系数增加下界公式，并因此提高模型所体现的定性性质， β -VAE能够一致而稳健地发现数据中更多的变异因素，并且它学习的表示形式涵盖了更广泛的因子值范围，并且比其他基准测试更清晰地进行了纠缠。