BLP Simulation

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Ensemble/pooling Methods

TLP

Traditional linear pool finds optimal weights that maximmizes the likelihood of $f(y) = \sum_{i=1}^{k} w_i f_i(y)$.

BLP

BLP finds α , β , and weights that maximize the likelihood of

$$g_{\alpha,\beta} = \left(\sum_{i=1}^{k} w_i f_i(y)\right) b_{\alpha,\beta} \left(\sum_{i=1}^{k} w_i F_i(y)\right).$$

BLP Example: To obtain α , β , and the weights for all component models, train the BLP model on half of the data. Then, use α , β , and the weights from training to apply to the data held out for testing.

Bias-corrected TLP (bcTLP)

This method corrects for bias of the component models, and then use the traditional method to generate the ensemble. The difference between this and the traditional TLP is that the component models inputted in bcTLP are bias-corrected. The bias correction method used is simple linear regression (Raftery, 2005). By regressing y against the forecast output, we obtain the intercept and coefficient of each component,

$$g_i(y) = \alpha_i + \beta_i f_i(y)$$

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and the final ensemble is

$$g(y) = \sum_{i=1}^{k} w_i g_i(y)$$

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Bias-corrected BLP (bcBLP)

This method also corrects for bias of the component models using linear regression, and then use the BLP method to generate the ensemble. The final ensemble is

$$g_{\alpha,\beta} = (\sum_{i=1}^k w_i g_i) b_{\alpha,\beta} (\sum_{i=1}^k w_i G_i(y)).$$

BLP with Non-central Parameter(nBLP)

nBLP finds α , β , non-central parameter λ , and weights that maximize the likelihood of

$$g_{\alpha,\beta,\lambda} = (\sum_{i=1}^k w_i f_i(y)) b_{\alpha,\beta} (\sum_{i=1}^k w_i F_i(y)).$$

nBLP process: To obtain α , β , λ , and the weights for all component models, train the nBLP model on half of the data. Then, use α , β , λ , and the weights from training to apply to the data held out for testing.

Component-wise BLP (cBLP)

This is the extension of the traditional BLP. We beta-transform each of the cumulative distribution functions of the component models. This is done by finding α and β that maximize the likelihood of

$$G_{i,\alpha_i,\beta_i} = B_{\alpha_i,\beta_i}[F_i(y)]$$

$$g_{i,\alpha_i,\beta_i} = f_i(y) \times b_{\alpha_i,\beta_i}[F_i(y)]$$

Then, to obtain α , β , and the weights for 21 models, we apply BLP on the beta-transformed components:

$$G_{\alpha,\beta} = B_{\alpha,\beta} \left[\sum_{i=1}^{k} w_i B_{\alpha_i,\beta_i}(F_i(y)) \right]$$

$$g_{\alpha,\beta} = \left(\sum_{i=1}^{k} w_i b_{i,\alpha_i,\beta_i}(F_i(y)) f_i(y) \right) b_{\alpha,\beta} \left(\sum_{i=1}^{k} w_i B_{i,\alpha_i,\beta_i}(F_i(y)) \right)$$

cBLP - Part 1: For each component model, train over all observations to get α_i and β_i . Then, apply α_i and β_i to beta-transform the CDF. This ends the component-wise part.

cBLP Part 2: Apply the usual BLP process on the beta-transformed component models to get the BLP ensemble.

Componentwise Bias-Corrected & Componentwise Recalibrated BLP (cbcBLP)

This method corrects for bias of the component models and also recalibrate them using beta transform. Then the BLP method is used to generate the ensemble.

Simulation studies

The data generating process for the observation Y in the regression model is

$$Y = X_0 + a_1 X_1 + a_2 X_2 + a_3 X_3 + \epsilon, \epsilon \sim (0, 1)$$

where a_1, a_2 , and a_3 are real constants that vary across different simulation studies, and X_0, X_1, X_2, X_3 , and ϵ are independent, standard normal random variables. The individual predictive densities have partial access of the above set of covariates. f_1 has access to only X_0 and X_1 , f_2 has access to only X_0 and X_2 , and f_3 has access to only X_0 and X_3 . We want to combine f_1, f_2 , and f_3 to predict Y. In this setup, X_0 represent shared information, while other covariates represent information unique to each individual model.

We estimate the pooling/combination formulas on a random sample $(f_{1i}, f_{2i}, f_{3i}, Y_i) : i = 1, ..., n$ of size n = 50,000 and evaluate on an independent test sample of the same size.

Scenario 1: calibrated components (Baseline scenario).

In this scenario, $a_1 = a_2 = 1$ and $a_3 = 1.1$, so that f_3 is a more concentrated, sharper density forecast than f_1 and f_2 (Gneiting and Ranjan (2013)) and they are defined as follows:

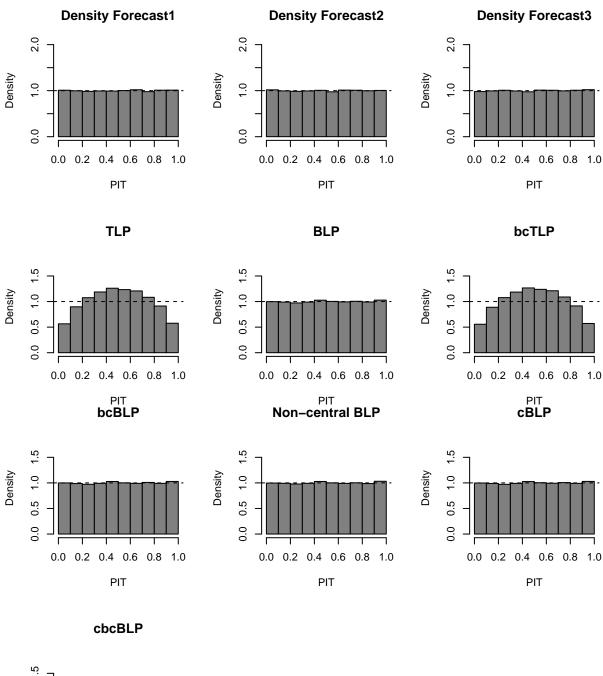
$$f_1 = N(X_0 + a_1 X_1, 1 + a_2^2 + a_3^2)$$

$$f_2 = N(X_0 + a_2 X_2, 1 + a_1^2 + a_3^2)$$

$$f_3 = N(X_0 + a_3 X_3, 1 + a_1^2 + a_2^2)$$

Table 1: Model Parameters and Log Score

	w1	w2	w3	alpha	beta	ncp		Training	Test
TLP	0.271	0.264	0.465	NA	NA	NA	f1	-1.998	-2.004
BLP	0.301	0.295	0.404	1.465	1.469	NA	f2	-1.999	-2.006
bcTLP	0.272	0.264	0.464	NA	NA	NA	f3	-1.965	-1.969
bcBLP	0.301	0.296	0.403	1.477	1.477	NA	TLP	-1.907	-1.912
nBLP	0.301	0.295	0.404	1.452	1.483	0.076	BLP	-1.864	-1.872
cBLP	0.300	0.296	0.405	1.459	1.460	NA	bcTLP	-1.906	-1.911
cbcBLP	0.301	0.296	0.403	1.469	1.469	NA	bcBLP	-1.861	-1.870
							nBLP	-1.864	-1.872
							cBLP	-1.864	-1.872
							cbcBLP	-1.862	-1.870



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Scenario 2: Biased forecast scenario

In this scenario, $a_1 = a_2 = 1$ and $a_3 = 1.1$, and we add N(2,1) to the mean of f_1 so that it is a biased forecast. The models are defined as follows:

$$f_1 = N(X_0 + a_1 X_1 + N(2, 1), 1 + a_2^2 + a_3^2)$$

$$f_2 = N(X_0 + a_2 X_2, 1 + a_1^2 + a_3^2)$$

$$f_3 = N(X_0 + a_3 X_3, 1 + a_1^2 + a_2^2)$$

Distribution of Differrences between Y and forecast means

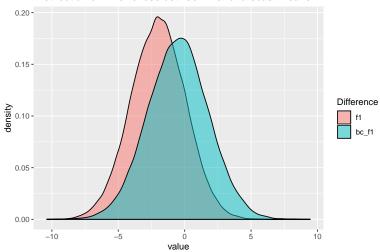
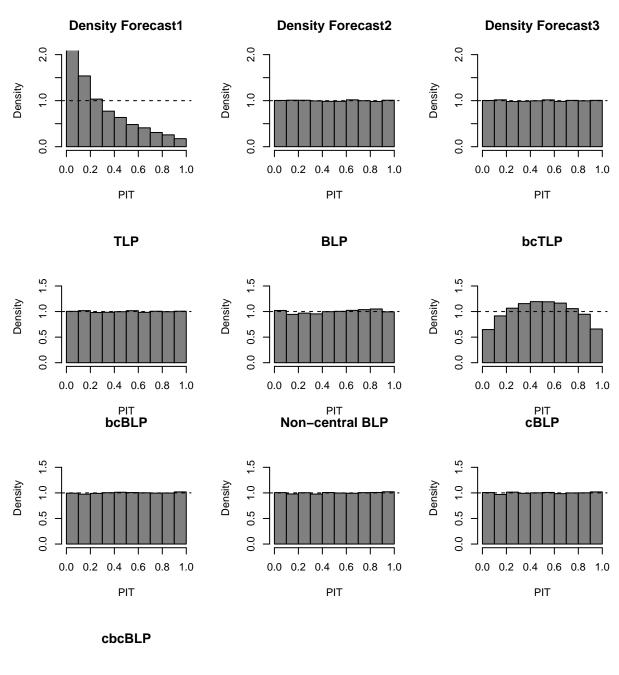
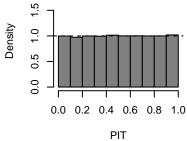


Table 2: Model Parameters and Log Score

	w1	w2	w3	alpha	beta	ncp		Training	Test
TLP	0.000	0.000	1.000	NA	NA	NA	f1	-2.788	-2.777
BLP	0.140	0.391	0.469	1.420	1.676	NA	f2	-1.998	-2.004
bcTLP	0.005	0.417	0.579	NA	NA	NA	f3	-1.965	-1.969
bcBLP	0.088	0.411	0.500	1.372	1.373	NA	TLP	-1.965	-1.969
nBLP	0.138	0.390	0.472	1.309	1.822	0.653	BLP	-1.884	-1.888
cBLP	0.183	0.381	0.436	1.510	1.518	NA	bcTLP	-1.917	-1.921
cbcBLP	0.133	0.386	0.481	1.398	1.399	NA	bcBLP	-1.888	-1.893
						_	nBLP	-1.883	-1.888
							cBLP	-1.967	-1.971
							cbcBLP	-1.895	-1.900





Scenario 3: Higher variance forecast scenario

We modified the standard deviation of the first density forecast by adding a constant of 2 as follows:

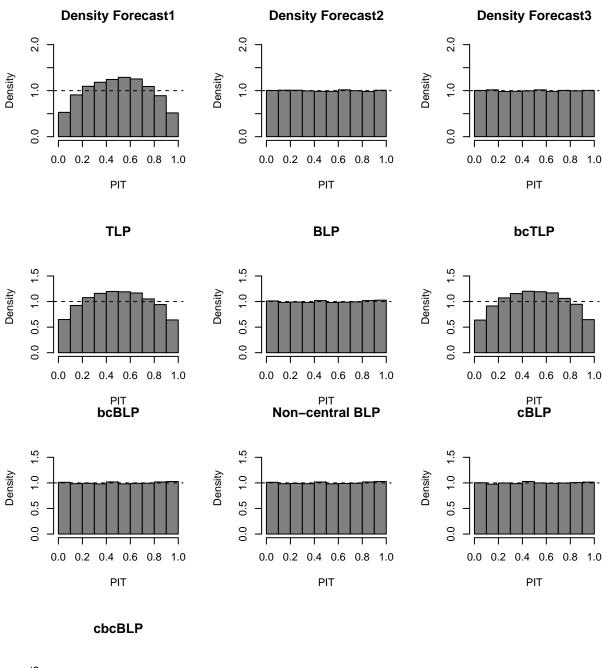
$$f_1 = N(X_0 + a_1X_1, 1 + a_2^2 + a_3^2 + 2)$$

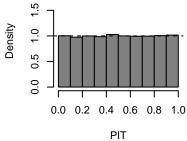
$$f_2 = N(X_0 + a_2X_2, 1 + a_1^2 + a_3^2)$$

$$f_3 = N(X_0 + a_3X_3, 1 + a_1^2 + a_2^2)$$

Table 3: Model Parameters and Log Score

	w1	w2	w3	alpha	beta	ncp		Training	Test
TLP	0.013	0.411	0.576	NA	NA	NA	f1	-2.051	-2.053
BLP	0.327	0.288	0.385	1.658	1.668	NA	f2	-1.998	-2.004
bcTLP	0.013	0.412	0.575	NA	NA	NA	f3	-1.965	-1.969
bcBLP	0.327	0.289	0.384	1.668	1.668	NA	TLP	-1.918	-1.921
nBLP	0.327	0.288	0.385	1.654	1.672	0.02	BLP	-1.864	-1.869
cBLP	0.204	0.357	0.439	1.443	1.444	NA	bcTLP	-1.917	-1.921
cbcBLP	0.204	0.357	0.439	1.448	1.448	NA	bcBLP	-1.863	-1.868
							nBLP	-1.864	-1.869
							cBLP	-1.866	-1.871
							cbcBLP	-1.865	-1.870





Scenario 4 Biased + higher variance forecast scenario

In this scenario, $a_1 = a_2 = 1$ and $a_3 = 1.1$, but we modified the standard deviation of the first and second density forecast as follows:

$$f_1 = N(X_0 + a_1X_1 + N(2, 1), 1 + a_2^2 + a_3^2)$$

$$f_2 = N(X_0 + a_2X_2, 1 + a_1^2 + a_3^2 + 2)$$

$$f_3 = N(X_0 + a_3X_3, 1 + a_1^2 + a_2^2)$$

Distribution of Differrences between Y and forecast means

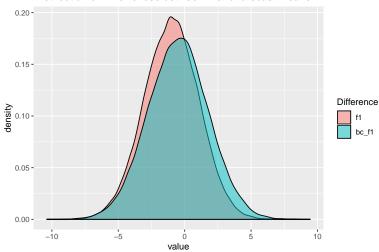


Table 4: Model Parameters and Log Score

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	w1	w2	w3	alpha	beta	ncp		Training	Test
TLP	0.000	0.000	1.000	NA	NA	NA	f1	-2.317	-2.310
BLP	0.161	0.414	0.425	1.660	1.832	NA	f2	-2.050	-2.054
bcTLP	0.130	0.150	0.720	NA	NA	NA	f3	-1.965	-1.969
bcBLP	0.085	0.453	0.461	1.639	1.639	NA	TLP	-1.965	-1.969
nBLP	0.160	0.414	0.426	1.648	1.846	0.068	BLP	-1.878	-1.882
cBLP	0.249	0.264	0.487	1.524	1.528	NA	bcTLP	-1.942	-1.945
cbcBLP	0.205	0.281	0.514	1.401	1.401	NA	bcBLP	-1.888	-1.893
							nBLP	-1.878	-1.882
							cBLP	-1.915	-1.920
							cbcBLP	-1.905	-1.910

