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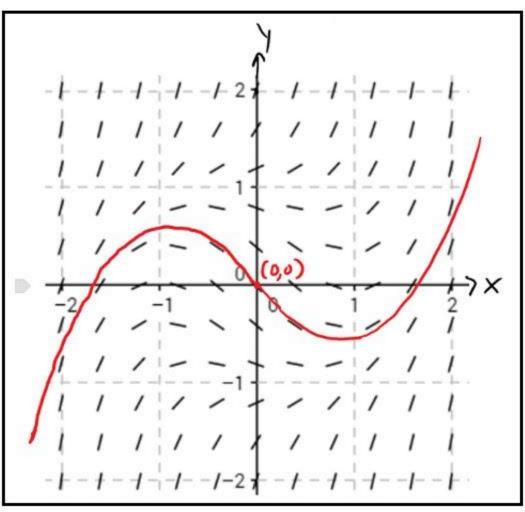
Лекция 7. Решение обыкновенных дифференциальных уравнений и задачи Коши

Вычислительна математика

Весенний семестр 2022

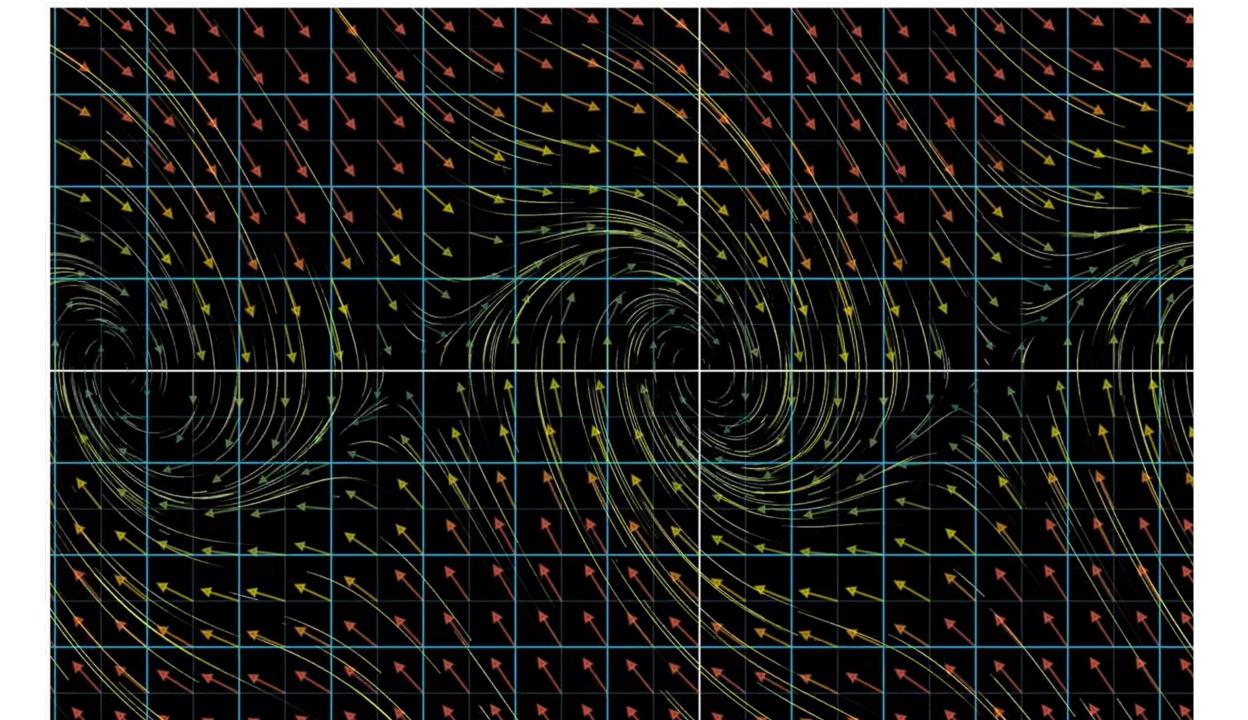
Ольга Вячеславовна Перл

Differential Equations: Direction Fields: Example 1

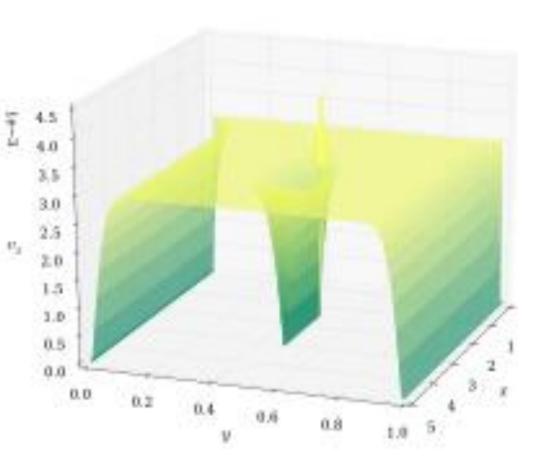


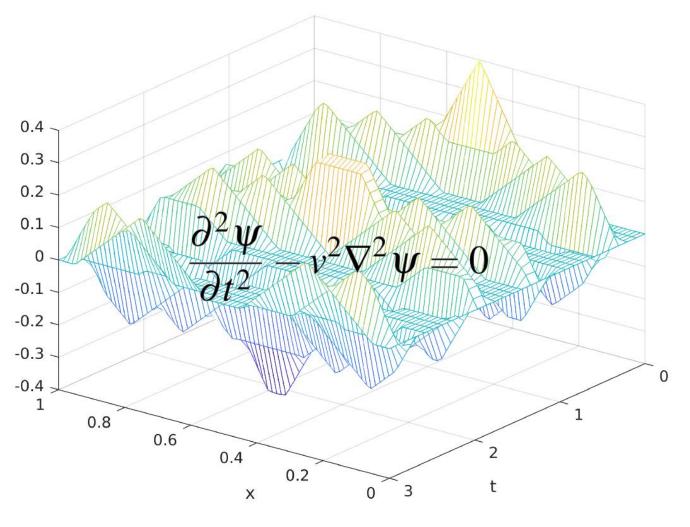
$$y' = x^2 + y^2 - 1$$

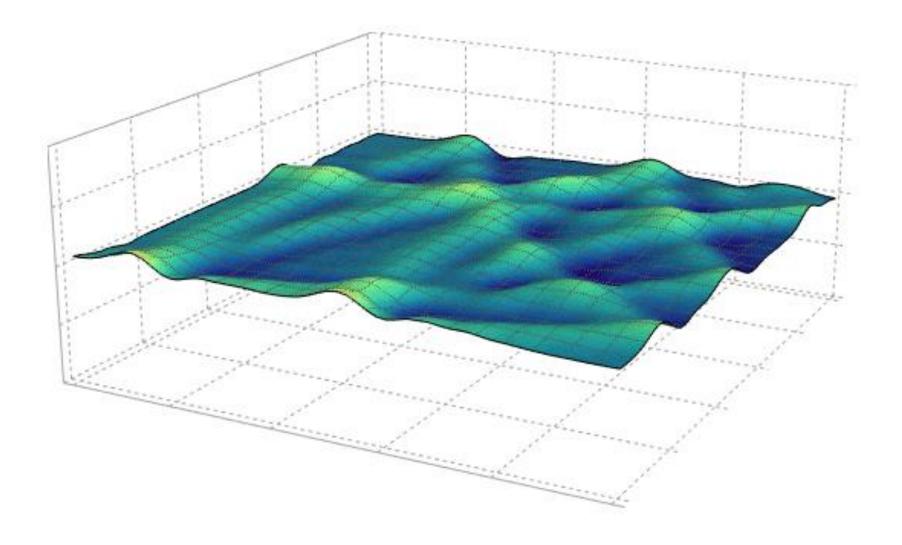
| Points | y'= slope |
|--------|--------------------------|
| (0,0) | y'= 0+0-1 = -1 |
| (0,1) | $y' = 0 + 1^2 - 1 = 0$ |
| (1,0) | $y' = 1^2 + 0 - 1 = 0$ |
| (0,2) | $y' = 0^2 + 2^2 - 1 = 3$ |
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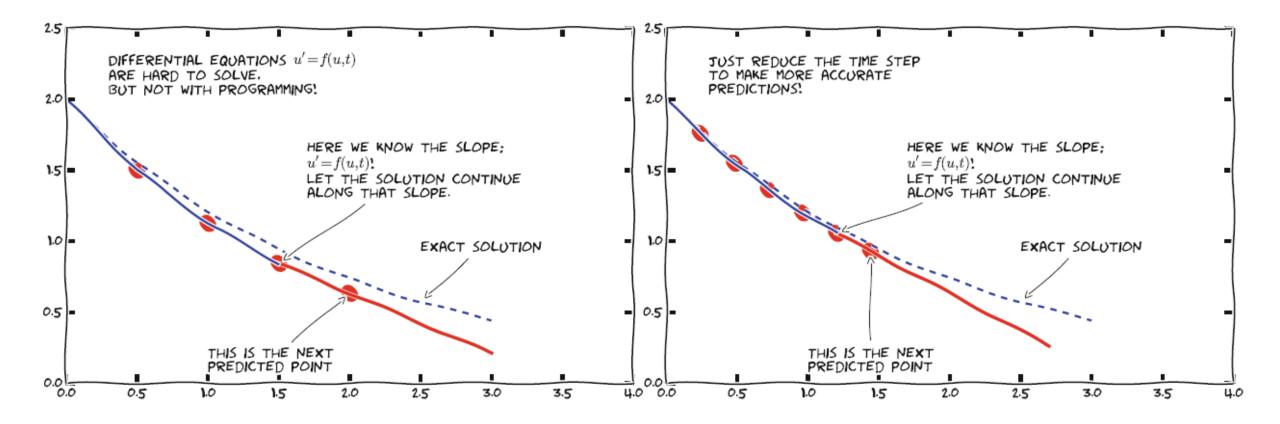






Численная устойчивость Numerical stability

- In the mathematical subfield of numerical analysis, numerical stability is a generally desirable property of numerical algorithms.
- The precise definition of stability depends on the context.
- One is numerical linear algebra and the other is algorithms for solving ordinary and partial differential equations by discrete approximation.
- In numerical linear algebra the principal concern is instabilities caused by proximity to singularities of various kinds, such as very small or nearly colliding eigenvalues.
- On the other hand, in numerical algorithms for differential equations the concern is the growth of round-off errors and/or small fluctuations in initial data which might cause a large deviation of final answer from the exact solution.



Ordinary differential equations VS Cauchy problem

TO SOLVE ORDINARY DIFFERENTIAL EQUATIONS

To solve ordinary differential equations, for example:

$$y' = \frac{xy}{2}$$

Means to find set (family) of functions, which have different constant.

TO SOLVE CAUCHY PROBLEM

- To solve ordinary differential equations by <u>initial</u> condition, for example: $y' = \frac{xy}{2}$ if y(0) = 1
- Means to find only one function (with constant value), which passing through a given point.

Численные методы



Улучшенный метод Эйлера

Метод Эйлера

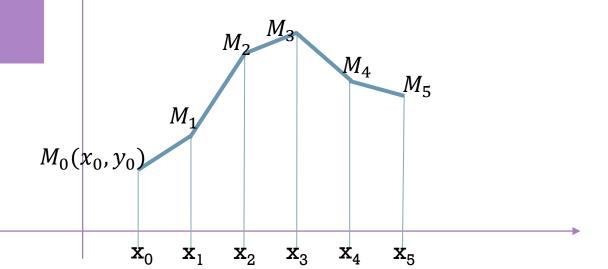
Let we have ordinary differential equation: y' = f(x, y) with initial condition $y(x_0) = y_0$. And let choose any small step h, then we may build system of equidistant points:

$$x_i = x_0 + ih (i = 0, 1, 2, ...)$$

■ Then we may replace correct integral line y = y(x), which passing through a point $M_0(x_0, y_0)$, by polyline $M_0M_1M_2$... with vertices $M_i(x_i, y_i)(i = 0, 1, 2, ...)$, where segments M_iM_{i+1} are straight line between $x = x_i, x = x_{i+1}$ and have ascent:

$$\frac{y_{i+1} - y_i}{h} = f(x_i, y_i)$$

It is named <u>Euler's polyline</u>.



Formula for Euler method:

$$y_{i+1} = y_i + \Delta y_i$$

 $\Delta y_i = hf(x_i) \ (i = 0, 1, 2, ...)$

- Method has low accuracy
- Method is not stable because systematically increase errors.
- Order of accuracy: $O(h^2)$

Метод Эйлера

correct solution

solution by Euler method

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At Euler method we should to calculate intermediate point:

$$x_{i+\frac{1}{2}} = x_i + \frac{h}{2}; \ y_{i+\frac{1}{2}} = y_i + \frac{h}{2}f_i;$$

Then:

$$f_{i+\frac{1}{2}} = f(x_{i+\frac{1}{2}}, y_{i+\frac{1}{2}})$$

 $y_{i+1} = y_i + h f_{i+\frac{1}{2}}$

And then we let:

$$\begin{array}{c|c} & y_{i+1} \\ & \text{arctg } f_{i+1/2} \\ & y_{i} \\ & y_{i+1/2} \\ & x_{i} \\ & x_{i+1/2} \end{array}$$

Улучшенный Метод Эйлера

Метод Рунге-Кутты (4-го порядка)

• Runge-Kutta change way to calculate Δy_i in formula $y_{i+1} = y_i + \Delta y_i$:

$$\Delta y_i = \frac{1}{6} \left(k_1^{(i)} + 2k_2^{(i)} + 2k_3^{(i)} + k_4^{(i)} \right) (i = 0, 1, 2, \dots)$$

where:

$$k_1^{(i)} = hf(x_i, y_i),$$

$$k_2^{(i)} = hf(x_i + \frac{h}{2}, y_i + \frac{k_1^{(i)}}{2})$$

$$k_3^{(i)} = hf(x_i + \frac{h}{2}, y_i + \frac{k_2^{(i)}}{2})$$

$$k_4^{(i)} = hf(x_i + h, y_i + k_3^{(i)})$$

- Method has good accuracy and well used. Method is applicable for changed step.
- Order of accuracy: $O(h^5)$

Метод Адамса

- For all multistep methods we need set on initial points. For Cauchy problem (when we have only 1 initial point) we may calculate <u>initial</u> <u>segment (acceleration points)</u> by any one-step methods (usually it is Runge-Kutta method).
- Adams method used Newton interpolation method to approximate solution of Cauchy problem with accuracy of 4th order:

$$y' = y'_{i} + q\Delta y'_{i-1} + \frac{q(q+1)}{2!}\Delta^{2}y'_{i-2} + \frac{q(q+1)(q+2)}{3!}\Delta^{2}y'_{i-3}$$

where $q = \frac{x - x_i}{h}$

Adams extrapolation formula:

$$\Delta y_i = hy'_i + \frac{1}{2}\Delta(hy'_{i-1}) + \frac{5}{12}\Delta^2(hy'_{i-2}) + \frac{3}{8}\Delta^3(hy'_{i-3})$$

Adams method:

$$y_{i+1} = y_i + \frac{h}{24} (55y'_i - 59y'_{i-1} + 37y'_{i-2} - 9y'_{i-3})(i = 4, 5, ...)$$

• Order of accuracy: $O(h^4)$

Метод Милна (предиктора и корректора)

- This method also based on Newton interpolation method.
- Prediction formula:

$$y_i = y_{i-4} + \frac{4h}{3} (2y'_{i-1} - y'_{i-2} + 2y'_{i-3})$$

Correction formula:

$$y_i = y_{i-2} + \frac{h}{3}(y'_i + 4y'_{i-1} + y'_{i-2})$$

Controlling formula for Milne method:

$$\varepsilon_i = \left| \varepsilon_i^{(2)} \right| = \frac{\left| y_i^{(1)} - y_i^{(2)} \right|}{29}$$

• Order of accuracy: $O(h^4)$

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Спасибо за внимание!

В случае вопросов по лекции задавайте их через форму:

https://forms.yandex.ru/u/61ffab0425b437e0e3410e9b/

Мы обязательно обсудим их на следующем занятии.