

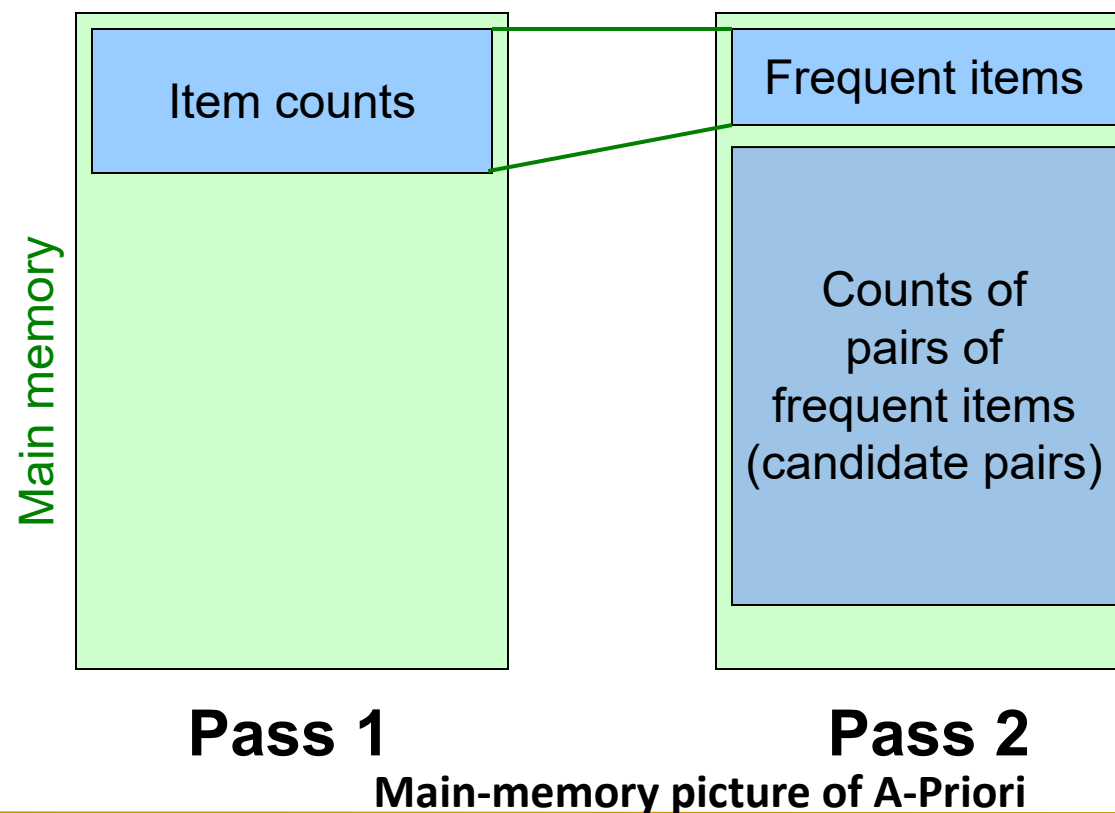
Section 3.5: PCY Algorithm

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- 1 PCY Algorithm – First Pass
- 2 PCY Algorithm – Between Passes
- 3 PCY Algorithm – Pass Two
- 4 Main-Memory in PCY Algorithm

3.5.1 PCY Algorithm – First Pass

- ❑ **Observation:** In pass 1 of A-Priori, most memory is idle
- We store only individual item counts
 - **Can we use the idle memory to reduce memory required in pass 2?**



3.5.1 PCY Algorithm – First Pass

- ❑ **Observation:** In pass 1 of A-Priori, most memory is idle
 - We store only individual item counts
 - **Can we use the idle memory to reduce memory required in pass 2?**
- ❑ **Pass 1 of PCY (Park-Chen-Yu) Algorithm:** In addition to item counts, maintain **a hash table** with as many buckets as fit in memory (桶计数哈希表)
 - Keep a **count** for each bucket into which **pairs** of items are hashed
 - For each bucket just keep the count, **not the actual pairs** that hash to the bucket!

Note: Bucket ≠ Basket

3.5.1 PCY Algorithm – First Pass

FOR (each basket) :

FOR (each item in the basket) :

add 1 to item's count;

New
in
PCY

FOR (each pair of items) :
hash the pair to a bucket;
add 1 to the count for that bucket;

□ Few things to note:

- Pairs of items need to be generated from the input file; they are not present in the file
- We are not just interested in the presence of a pair, but we need to see whether it is present at least s (support) times

3.5.2 PCY Algorithm – Between Passes

- ❑ **Observation:** If a bucket contains a frequent pair, then the bucket is surely frequent (called frequent bucket, 频繁桶)
- ❑ However, even without any frequent pair, a bucket can still be frequent 😞
 - So, we cannot use the hash to eliminate any member (pair) of a “frequent” bucket
- ❑ **But, for a bucket with total count less than s (called infrequent bucket, 非频繁桶), none of its pairs can be frequent 😊**
 - Pairs that hash to this bucket can be eliminated as candidates (even if the pair consists of 2 frequent items)
- ❑ **Pass 2:** Only count pairs that hash to frequent buckets

3.5.2 PCY Algorithm – Between Passes

- ❑ **Replace the buckets by a bit-vector (位图):**
 - **1** means the bucket count exceeded the support s (call it a **frequent bucket**); **0** means it did not
- ❑ **4-byte integer counts are replaced by bits, so the bit-vector requires 1/32 of memory**
- ❑ Also, decide which items are frequent and list them for the second pass

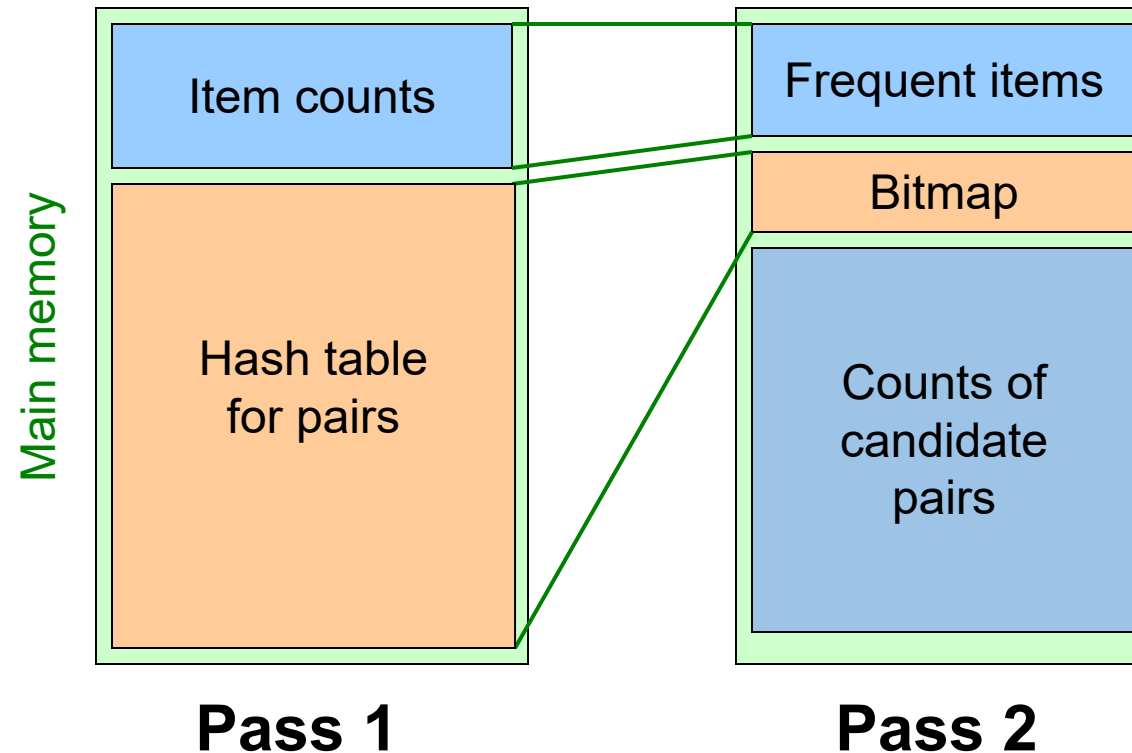
3.5.3 PCY Algorithm – Pass Two

- ❑ Count all pairs $\{i, j\}$ that meet the conditions for being a **candidate pair**:
 - 1) Both i and j are frequent items
 - 2) The pair $\{i, j\}$ hashes to a bucket whose bit in the bit vector is 1 (i.e., a frequent bucket)

- ❑ **Both conditions are necessary for the pair to have a chance of being frequent**

3.5.4 Main-Memory in PCY Algorithm

□ Main-memory picture of PCY:



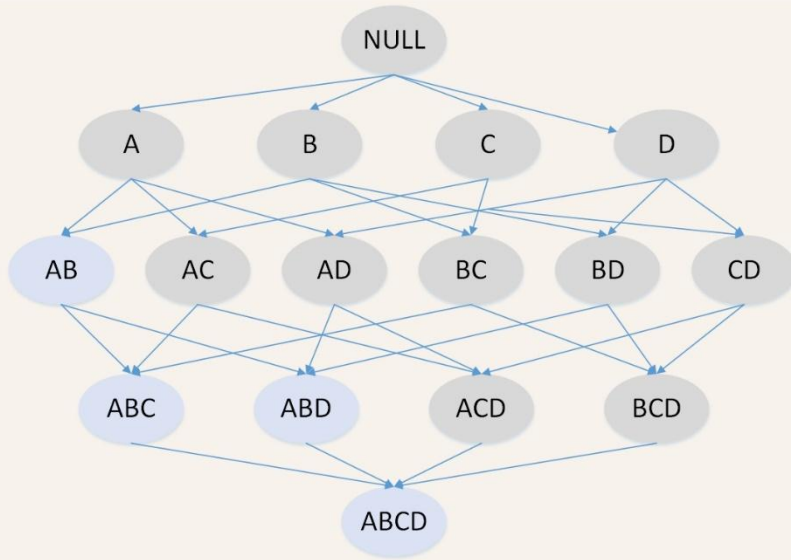
3.5.4 Main-Memory in PCY Algorithm

□ Buckets require a few bytes each:

- **Note:** we do not have to count past s
- #buckets is $O(\text{main-memory size})$

□ On second pass, a table of (item, item, count) triples (三元组方法) is essential (we cannot use triangular matrix approach, why?)

- Thus, hash table must eliminate approx. 2/3 of the candidate pairs for PCY to beat A-Priori



Section 3.6: Two Refinement Algorithms

Content

- 1 Multistage Algorithm
- 2 Multihash Algorithm
- 3 Summary for PCY extensions

3.6.1 Multistage Algorithm

❑ Limit the number of candidates to be counted

- **Remember:** Memory is the bottleneck
- Still need to generate all the itemsets but we only want to count/keep track of the ones that are frequent

❑ **Key idea** for **multistage algorithm** (多阶段算法): After Pass 1 of PCY, rehash only those pairs that **qualify** for Pass 2 of PCY

- 1) i and j are frequent, and
- 2) $\{i, j\}$ hashes to a frequent bucket from **Pass 1**

❑ On middle pass, fewer pairs contribute to buckets, so fewer **false positives** (伪阳性、伪正性、假阳性)

❑ **Drawback:** Requires 3 passes over the data

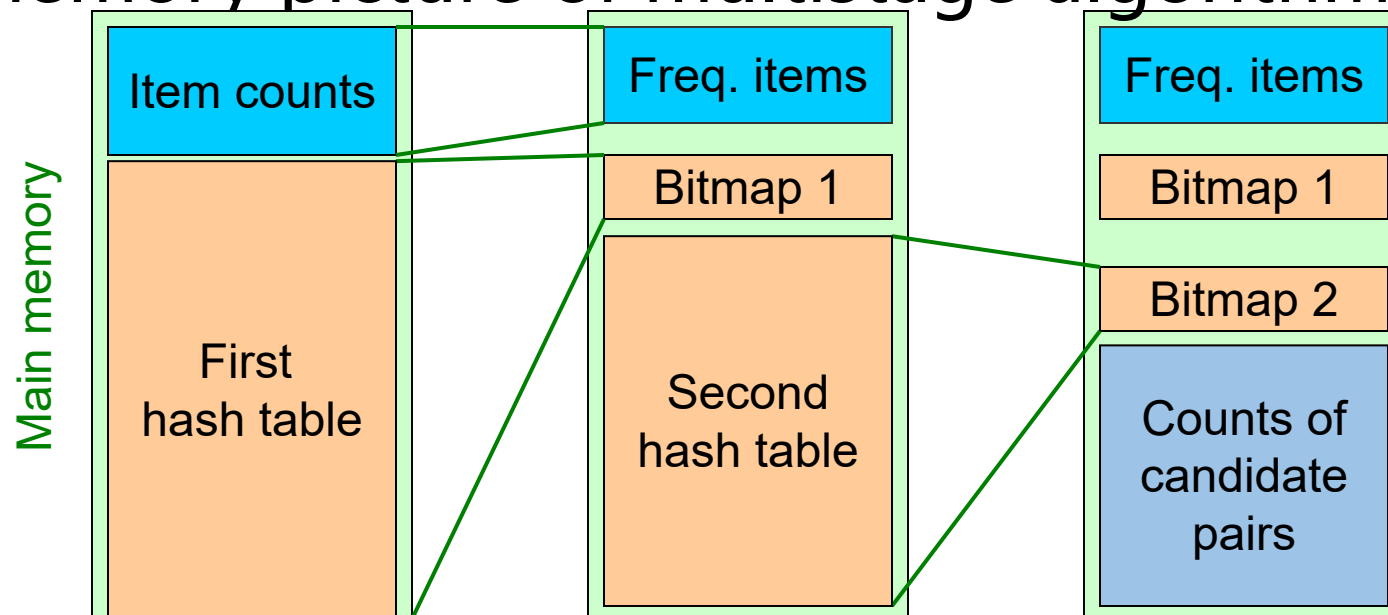
假阳性:测试结果呈阳性, 但事实上却没有

3.6.1 Multistage Algorithm

- Pass 3 of Multistage Algorithm: Count only those pairs $\{i, j\}$ that satisfy these **candidate pair conditions**:
- 1) Both i and j are frequent items
 - 2) Using the first hash function, the pair hashes to a bucket whose bit in **the first bit-vector is 1**
 - 3) Using the second hash function, the pair hashes to a bucket whose bit in **the second bit-vector is 1**

3.6.1 Multistage Algorithm

□ Main-memory picture of multistage algorithm:



Pass 1

Count items
Hash pairs $\{i,j\}$

Pass 2

Hash pairs $\{i,j\}$
into Hash2 iff:
1) i,j are frequent,
2) $\{i,j\}$ hashes to
freq. bucket in B1

Pass 3

Count pairs $\{i,j\}$ iff:
1) i,j are frequent,
2) $\{i,j\}$ hashes to freq. bucket in B1
3) $\{i,j\}$ hashes to freq. bucket in B2

3.6.1 Multistage Algorithm

□ **Important points** in multistage algorithm:

1. The two hash functions have to be independent

2. We need to check both hashes on the third pass

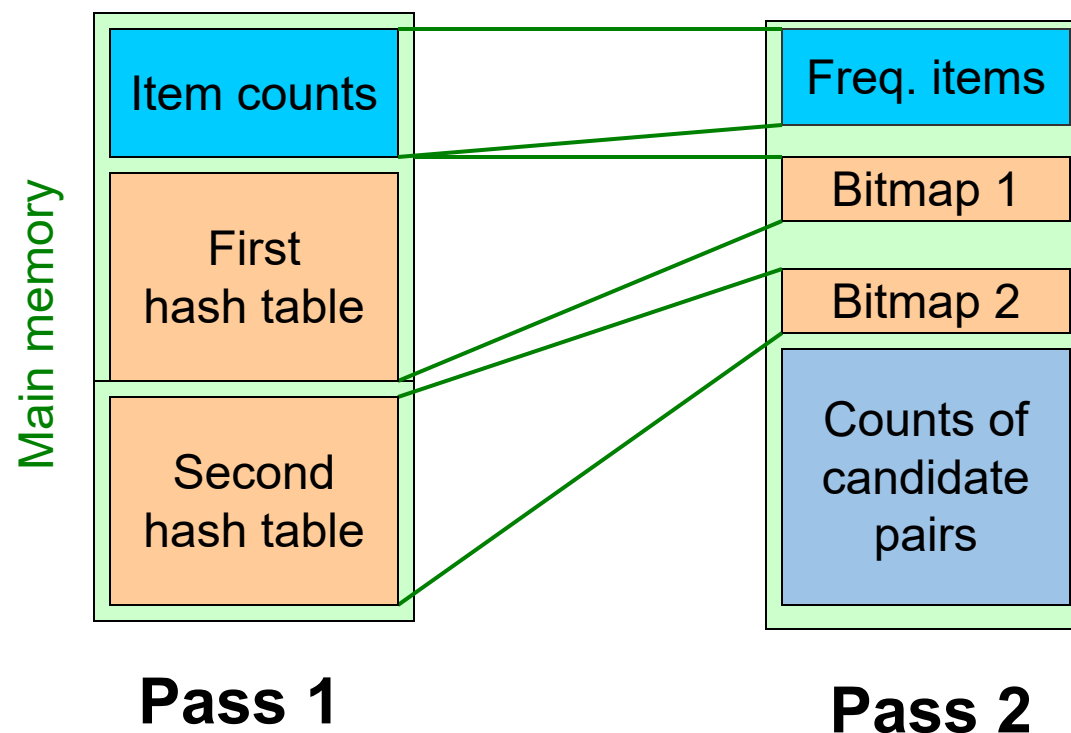
- If not, we would end up counting pairs of frequent items that hashed first to an infrequent bucket but happened to hash second to a frequent bucket

3.6.2 Multihash Algorithm

- ❑ **Multihash algorithm(多哈希算法)** **key idea:** Use **several independent hash tables** on the **first pass**
- ❑ **Risk:** Halving the number of buckets doubles the average count
 - We have to be sure most buckets will still not reach count s
- ❑ If so, we can get a benefit like multistage, but in only 2 passes

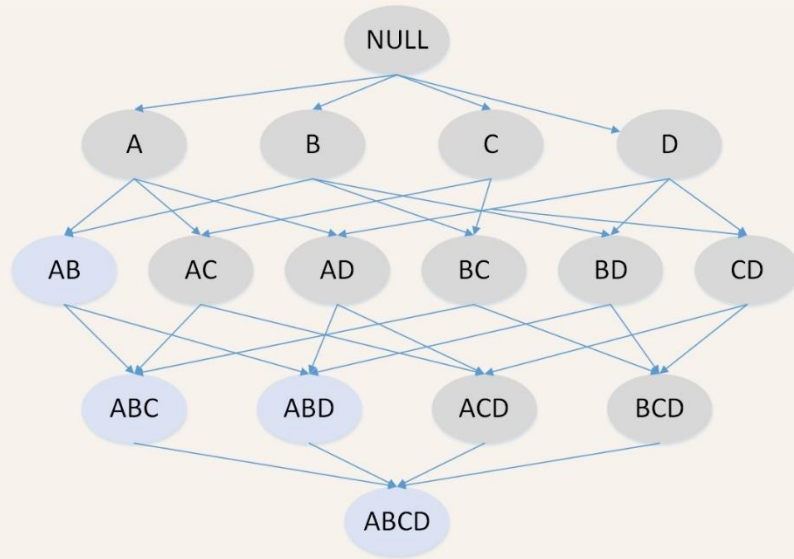
3.6.2 Multihash Algorithm

□ Main-memory picture of multihash algorithm:



3.6.3 Summary for PCY extensions

- Either **multistage** or **multihash** can use more than two hash functions
 - In **multistage**, there is a point of diminishing returns, since the bit-vectors eventually consume all of main memory
 - For **multihash**, the bit-vectors occupy exactly what one PCY bitmap does, but too many hash functions makes all counts $> s$



Section 3.7: Frequent Itemsets in ≤ 2 Passes

Random sampling
& SON & Toivonen

Content

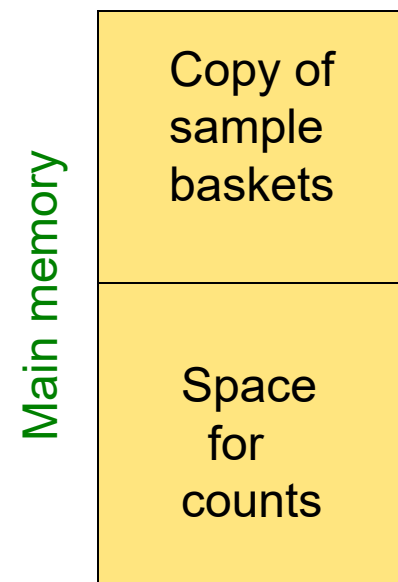
- 1 Random sampling
- 2 SON Algorithm
- 3 Toivonen Algorithm

3.7 Frequent Itemsets in ≤ 2 Passes

- ❑ A-Priori, PCY, etc., take k passes to find frequent itemsets of size k . **Can we use fewer passes?**
- ❑ Use 2 or fewer passes for all sizes, but **may miss** some frequent itemsets
 - **3.7.1: Random sampling**
 - **3.7.2: SON (Savasere, Omiecinski, and Navathe)**
 - **3.7.3: Toivonen (托伊沃宁算法)**

3.7.1 Random Sampling – (1)

- ❑ Take a random sample of the market baskets
- ❑ Run a-priori or one of its improvements in main memory
 - So we don't pay for disk I/O each time we increase the size of itemsets
 - Reduce support threshold proportionally to match the sample size



3.7.1 Random Sampling – (2)

- ❑ But you don't catch sets frequent in the whole but not in the sample
 - Smaller threshold, e.g., $s/125$, helps catch more truly frequent itemsets. But requires more space
- ❑ Problem for random sampling:
 - **False positive(伪正例)**: 某个项集在整个数据集上是不频繁的, 但它在抽样样本中频繁
 - **False negative(伪反例)**: 某个项集在整个数据集上是频繁的, 但它在抽样样本中不频繁
- ❑ Optionally, verify that the candidate pairs are truly frequent in the entire data set by a second pass (avoid **false positives**)
- ❑ But we cannot avoid **false negatives**

3.7.2 SON Algorithm – (1)

- ❑ To avoid false negative (伪反例) and false positive(伪正例), **SON (Savasere, Omiecinski, and Navathe) algorithm** is designed, using two passes.
- ❑ **Key “monotonicity” idea:** an itemset cannot be frequent in the entire set of baskets unless it is frequent in at least one subset.

3.7.2 SON Algorithm – (2)

- ❑ On a first pass, **repeatedly** read **small subsets** of the baskets into main memory and run an in-memory algorithm to find all frequent itemsets
 - Note: we are not sampling, but processing the entire file in memory-sized chunks
 - An itemset becomes a **candidate** if it is found to be frequent in *any* one or more subsets of the baskets.

- ❑ On a second pass, **SON algorithm** counts all the candidate itemsets and determines which are frequent in the entire set

3.7.2 SON – Distributed Version

- ❑ SON lends itself to distributed data mining
- ❑ Baskets distributed among many nodes
 - Compute frequent itemsets at each node
 - Distribute candidates to all nodes
 - Accumulate the counts of all candidates
- ❑ **Phase 1:** Find candidate itemsets
 - Map?
 - Reduce?
- ❑ **Phase 2:** Find true frequent itemsets
 - Map?
 - Reduce?

3.7.3 Toivonen Algorithm – (1)

- ❑ **Toivonen algorithm (托伊沃宁算法)**, using 2 passes, will give **neither false negatives (伪反例)** nor **false positives (伪正例)**, but there is a small yet nonzero probability that it will **fail to produce any answer at all**.

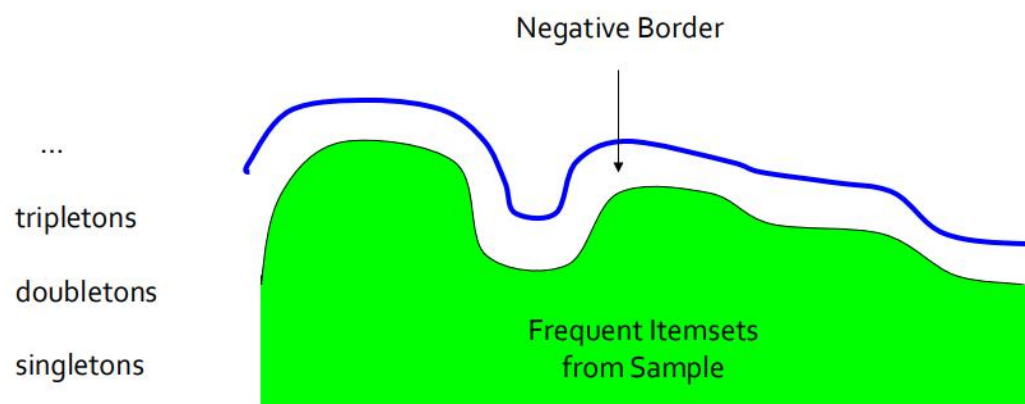
- ❑ **Step 1 in Pass 1:** Toivonen algorithm starts as in the simple algorithm, and also lowers the threshold slightly for the **sample data** to find **frequent itemsets**
 - Example: if the sample is 1% of the baskets, use **0.008s as the support threshold** rather than 0.01s.
 - Goal is to avoid missing any itemset that is frequent in the full set of baskets.

3.7.3 Toivonen Algorithm – (2)

□ **Step 2 in Pass 1:** Then, find the negative border (反例边界) in the **sample**.

➤ **反例边界:** An itemset is in the **negative border** if it is **not deemed frequent** in the sample, but all its **immediate subsets are frequent**.

□ **Example:** ABCD is in the negative border if and only if it is not frequent, but all of ABC, BCD, ACD, and ABD are.



备注:immediate subsets (直接子集),
删除集合中的一个元素构建的集合

3.7.3 Example

□ Example: Let items = {A,B,C,D,E,F} and there are frequent itemsets: {A}, {B}, {C}, {F}, {A,B}, {A,C}, {A,F}, {C,F}, {A,C,F}. Find whole negative border

□ Ans:

- {D}, {E}
- {B,C}, {B,F}

反例边界: 在数据上满足如下性质的非频繁项集组成, 即这些项集的直接子集都是频繁的

3.7.3 Toivonen Algorithm – (3)

- ❑ **Step 1 in Pass 2:** Make **a pass** through **the entire dataset**, counting all candidate frequent itemsets and the negative border (from the **sample data**).
 - **Case 1:** If **no itemset from the negative border turns out to be frequent**, then whichever candidates prove to be frequent in the whole data are exactly the frequent itemsets.
 - **Case 2:** Some itemsets from the negative border are frequent. Then how to deal with it?
 - **Ans:** We must start over again! We must repeat the algorithm with a **new random sample**.
 - **Note:** By choosing the **support threshold** for the sample wisely, we can **make the probability of failure low**, while still keeping the number of itemsets checked on step 3 low enough for main-memory.

- Frequent itemsets, Association rules
- 三角矩阵存储方法 Vs. 三元组存储方法
- Algorithms for finding frequent itemsets:
 - A-Priori algorithm
 - PCY algorithm
 - Multistage algorithm (多阶段算法)
 - Multihash algorithm (多哈希算法)
 - Random sampling
 - SON algorithm
 - Toivonen algorithm (托伊沃宁算法)