

# EECS 545: Machine Learning

## Lecture 2. Linear Regression

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1/10/2022



# Announcement

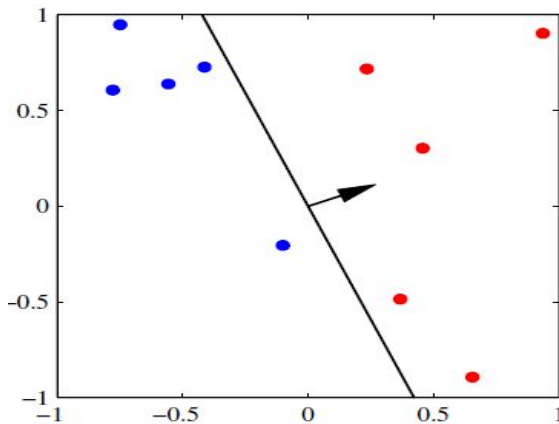
- Homework #1 is due 11:55 pm, Jan. 25 (**hard deadline with no late days allowed**)
  - Form a study group and start early.
- Honor code
  - Collaboration and discussion is strongly encouraged, but you should write your own solution independently.
  - **Do not** refer to or copy solutions from any other people or other resources. In addition, please do not let other people copy your solution.

# Announcement

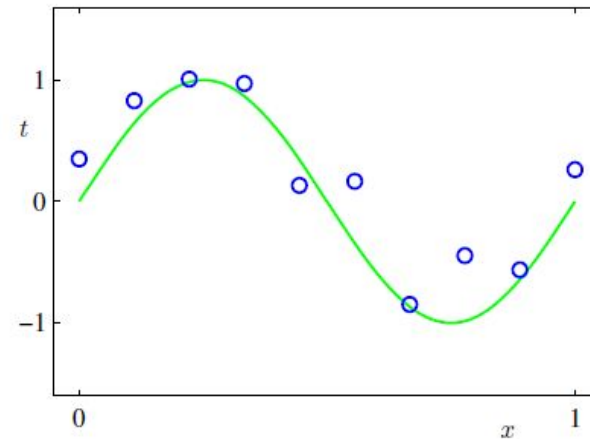
- Tutorial/review sessions this week (optional)
  - Linear Algebra (available at Canvas, by Sudeep)
  - Probability (1/11 Tue 2-3PM, by Aabhaas)
  - Python (1/14 Fri 4-5PM, by Kevin)
- Please check out the [schedule](#) and [calendar](#)
- Questions?

# Supervised Learning

- Goal:
  - Given data  $X$  in feature space and the labels  $Y$
  - Learn to predict  $Y$  from  $X$
- Labels could be discrete or continuous
  - Discrete-valued labels: classification
  - Continuous-valued labels: regression (today's topic)



classification



regression

# Overview of Topics

- Linear Regression
  - Objective function
  - Vectorization
  - Computing gradient
  - Batch gradient vs. Stochastic Gradient
  - Closed form solution

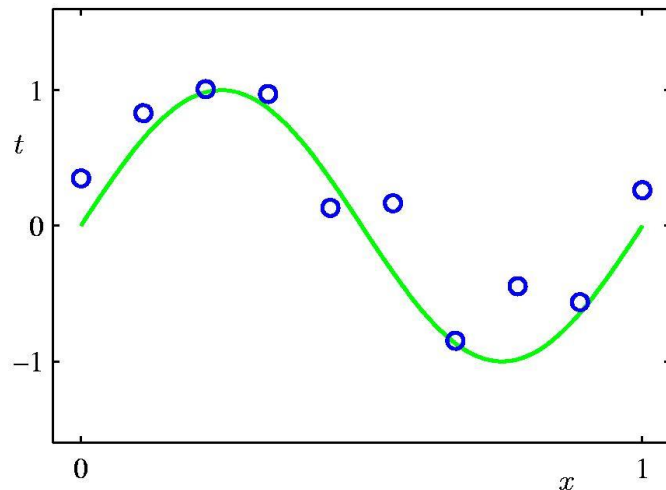
# Notation

In this lecture, we will use the following notation:

- $\mathbf{x} \in \mathbb{R}^D$  : data (scalar or vector)
- $\phi(\mathbf{x}) \in \mathbb{R}^M$  : features for  $\mathbf{x}$  (vector)
- $\phi_j(\mathbf{x}) \in \mathbb{R}$  : j-th feature for  $\mathbf{x}$  (scalar)
- $y \in \mathbb{R}$  : continuous-valued label (i.e., target value)
  
- $\mathbf{x}^{(n)}$  : denotes the n-th training example.
- $y^{(n)}$  : denotes the n-th training label.

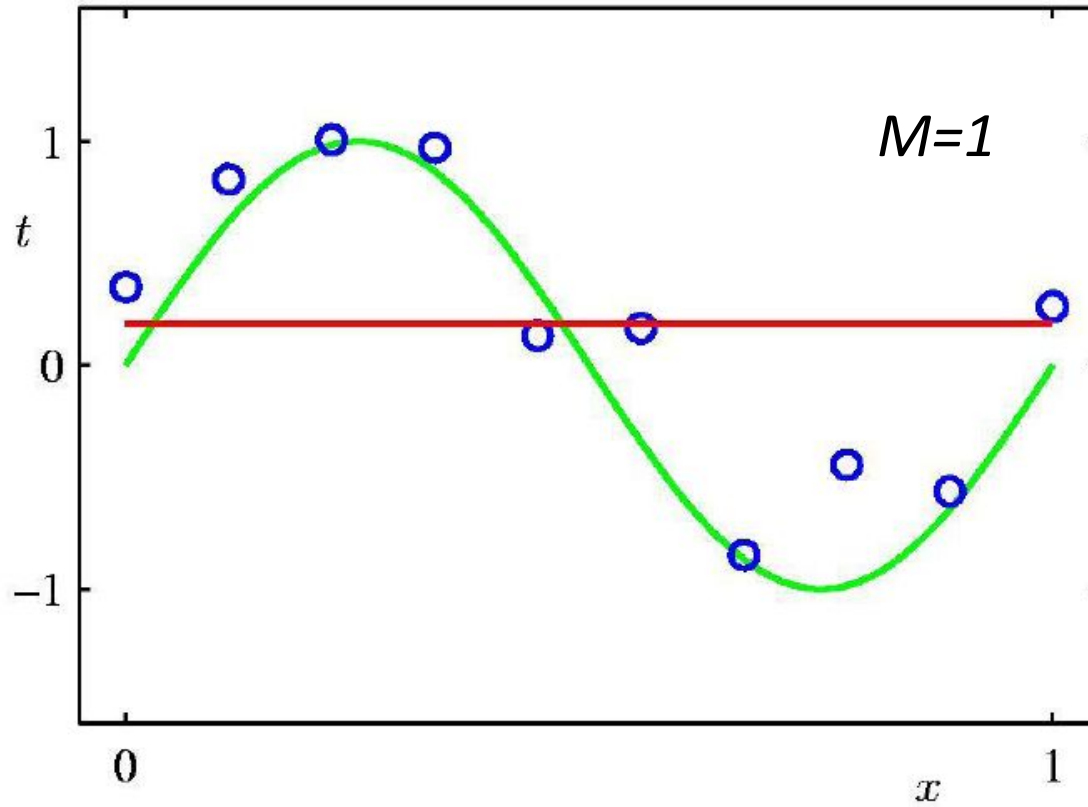
# Linear regression (with 1d inputs)

- Consider 1d case (e.g.  $D=1$ )
- Given a set of observation  $\{x^{(1)} \dots x^{(N)}\}$
- and corresponding target values  $\{y^{(1)} \dots y^{(N)}\}$
- We want to learn a function  $h(x, \mathbf{w}) \approx y$  to predict future values



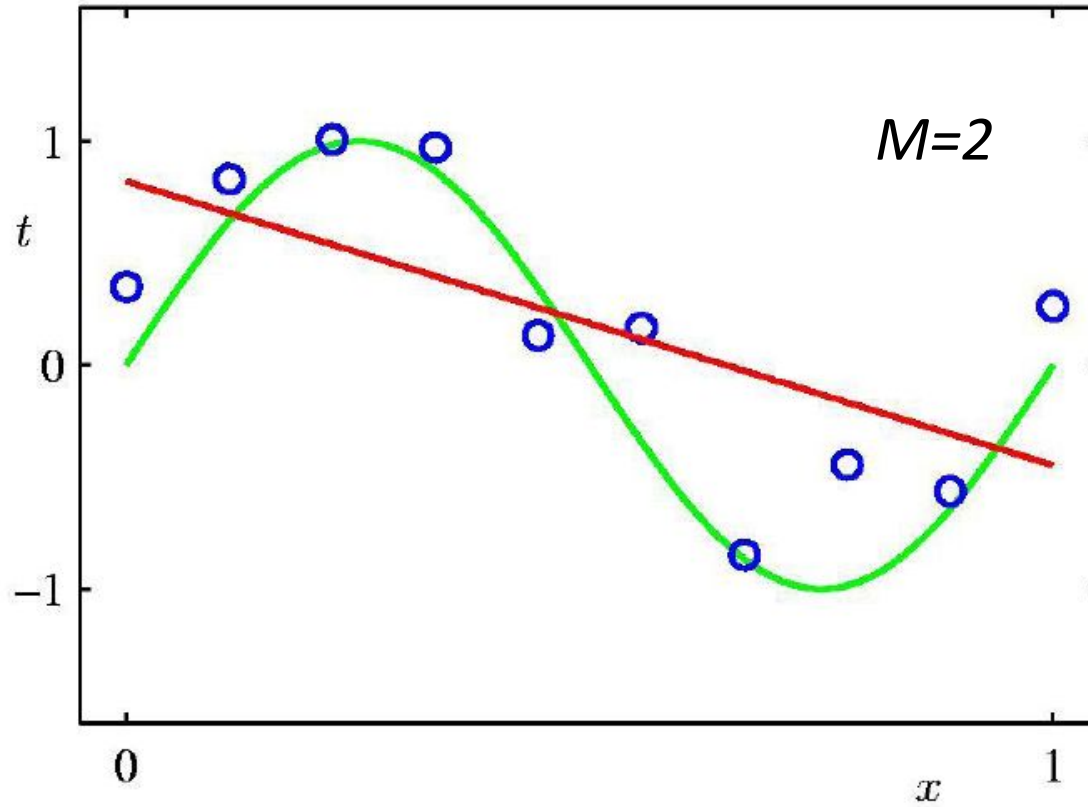
$$y(x, \mathbf{w}) = w_0 + w_1x + w_2x^2 + \dots + w_{M-1}x^{M-1} = \sum_{j=0}^{M-1} w_j x^j$$

# 0<sup>th</sup> Order Polynomial

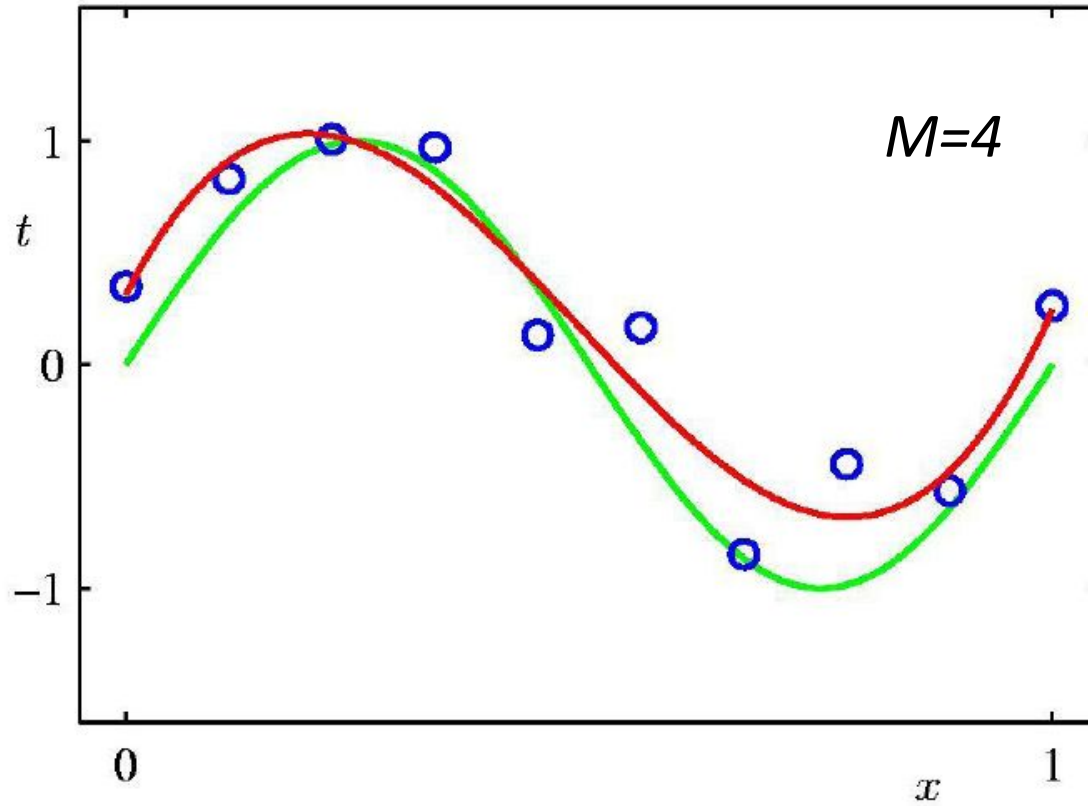




# 1<sup>st</sup> Order Polynomial



# 3<sup>rd</sup> Order Polynomial



# Linear Regression (general case)

$$h(\mathbf{x}, \mathbf{w}) = w_0 + \sum_{j=1}^{M-1} w_j \phi_j(\mathbf{x})$$

- The function  $h(\mathbf{x}, \mathbf{w})$  is linear in parameters  $\mathbf{w}$ .
  - Goal: find the best value for the weights,  $\mathbf{w}$ .
- For simplicity, add a *bias term (constant function)*:

$$h(\mathbf{x}, \mathbf{w}) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x})$$

$$\phi_0(\mathbf{x}) = 1$$

where  $\mathbf{w} = (w_0, \dots, w_{M-1})^T$

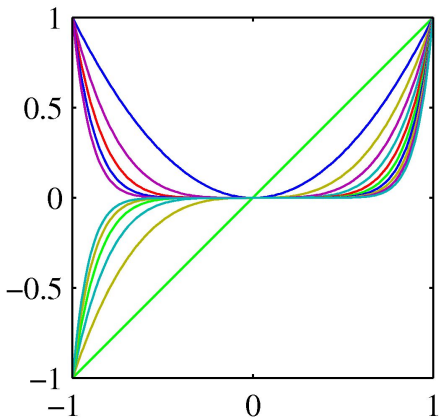
$$\phi(\mathbf{x}) = (\phi_0(\mathbf{x}), \dots, \phi_{M-1}(\mathbf{x}))^T$$

( $\mathbf{w}$  and  $\phi(\mathbf{x})$  are column vectors)

# Basis Functions

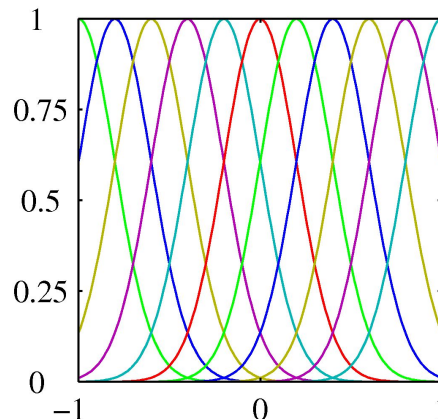
- The basis functions  $\phi_j(\mathbf{x})$  doesn't need to be linear

$$\phi_j(x) = x^j$$



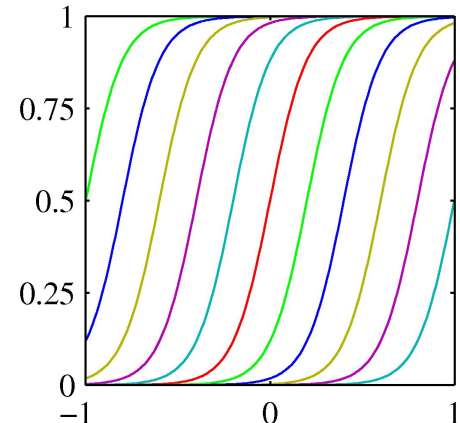
polynomial

$$\phi_j(x) = \exp \left\{ -\frac{(x - \mu_j)^2}{2s^2} \right\}$$



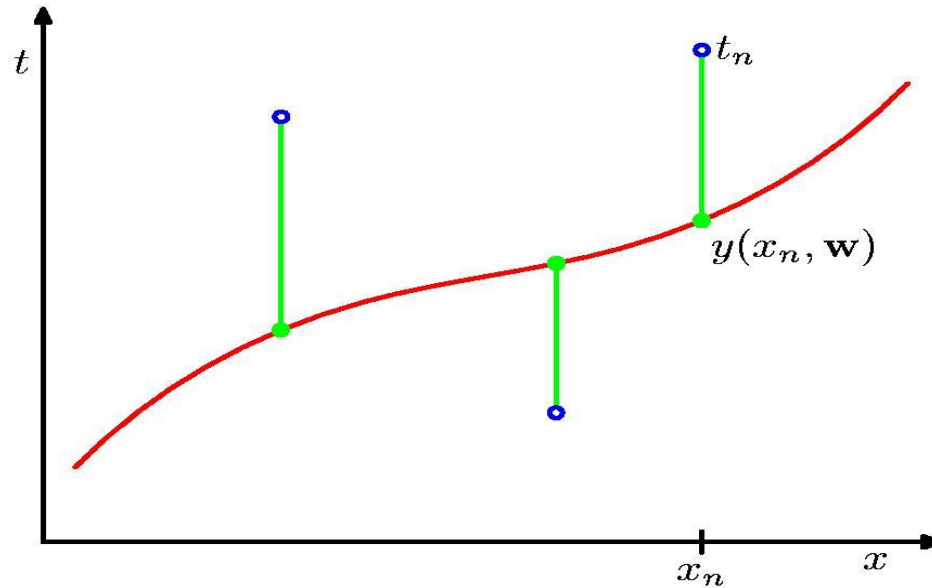
Gaussian

$$\phi_j(x) = \sigma \left( \frac{x - \mu_j}{s} \right)$$
$$\sigma(a) = \frac{1}{1 + \exp(-a)}$$



Sigmoid

# Objective: Sum-of-Squares Error Function

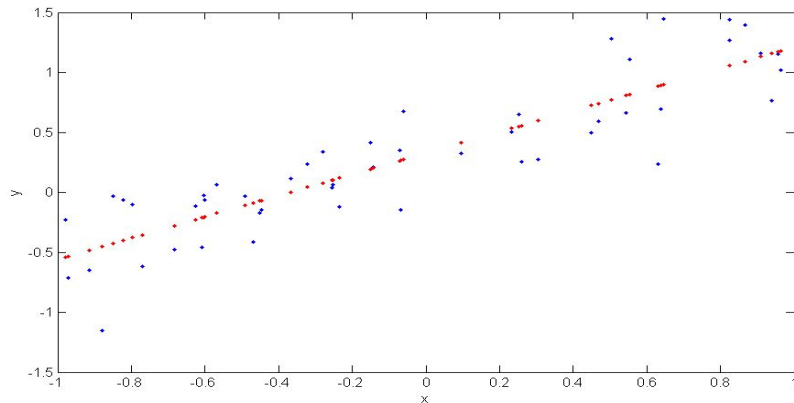


$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left\{ h(\mathbf{x}^{(n)}, \mathbf{w}) - y^{(n)} \right\}^2$$

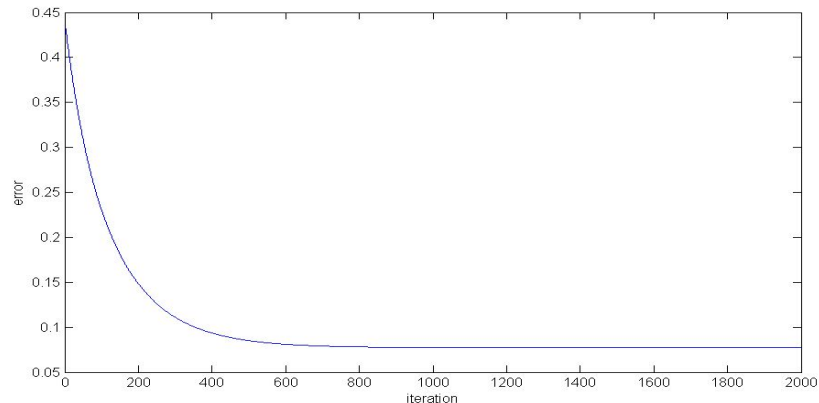
We want to find  $\mathbf{w}$  that minimizes  $E(\mathbf{w})$  over the training data.

# Linear regression via gradient descent (illustration)

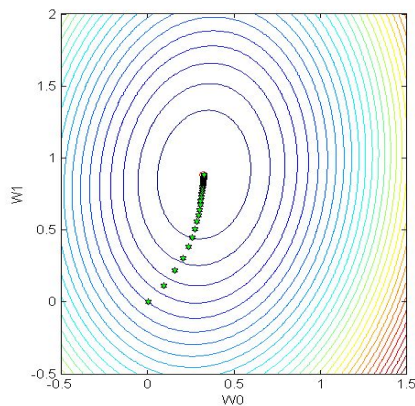
Training data (blue) vs. prediction (red)



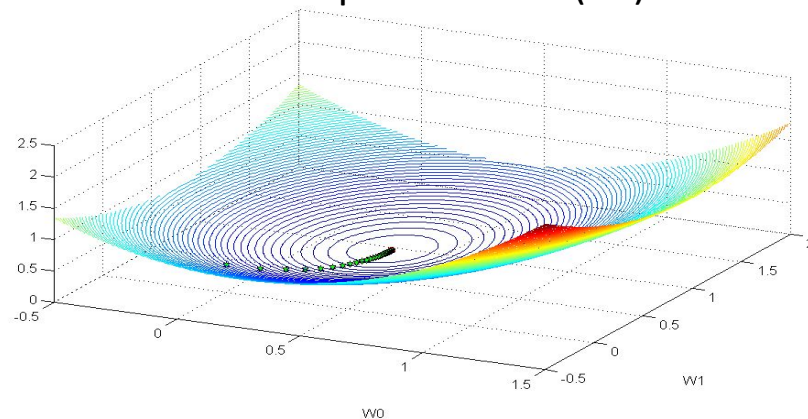
Error curve vs. training epoch



Contour plot of error



Contour plot of error (3d)



# Least squares problem

- Objective function

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

- Gradient

$$\frac{\partial E(w)}{\partial w_k} = \frac{\partial}{\partial w_k} \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

# Least squares problem

- Objective function

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

- Gradient

$$\begin{aligned} \frac{\partial E(w)}{\partial w_k} &= \frac{\partial}{\partial w_k} \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \sum_{n=1}^N \left[ \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \frac{\partial}{\partial w_k} \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \right] \end{aligned}$$



# Least squares problem

- Objective function

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

- Gradient

$$\begin{aligned} \frac{\partial E(w)}{\partial w_k} &= \frac{\partial}{\partial w_k} \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \sum_{n=1}^N \left[ \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \frac{\partial}{\partial w_k} \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \right] \\ &= \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi_k(\mathbf{x}^{(n)}) \end{aligned}$$

Concatenate each component of the gradient:

$$\frac{\partial E(w)}{\partial w_k} = \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi_k(\mathbf{x}^{(n)})$$

We get a vectorized form of the gradient:

$$\nabla_{\mathbf{w}} E(\mathbf{w}) = \begin{bmatrix} \frac{\partial}{\partial w_0} E(\mathbf{w}) \\ \frac{\partial}{\partial w_1} E(\mathbf{w}) \\ \vdots \\ \frac{\partial}{\partial w_{M-1}} E(\mathbf{w}) \end{bmatrix}$$

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Concatenate each component of the gradient:

$$\frac{\partial E(w)}{\partial w_k} = \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi_k(\mathbf{x}^{(n)})$$

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# Batch Gradient Descent

- Given data  $(\mathbf{x}, y)$ , initial  $\mathbf{w}$ 
  - Repeat until convergence

$$\mathbf{w} := \mathbf{w} - \eta \nabla_{\mathbf{w}} E(\mathbf{w})$$

where

$$\begin{aligned} \nabla_{\mathbf{w}} E(\mathbf{w}) &= \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi(\mathbf{x}^{(n)}) \\ &= \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}) - y^{(n)}) \phi(\mathbf{x}^{(n)}) \end{aligned}$$

# Stochastic Gradient Descent

- Main idea: instead of computing batch gradient (over entire training data), just compute gradient for individual example and update

- Repeat until convergence

– for  $n=1, \dots, N$

$$\mathbf{w} := \mathbf{w} - \eta \nabla_{\mathbf{w}} E(\mathbf{w} | \mathbf{x}^{(n)})$$

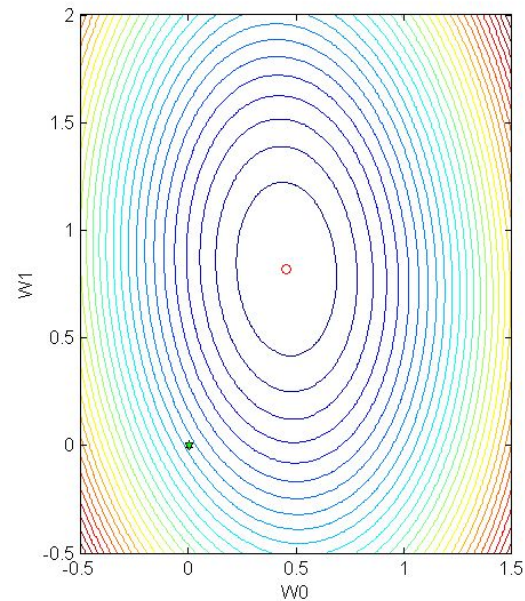
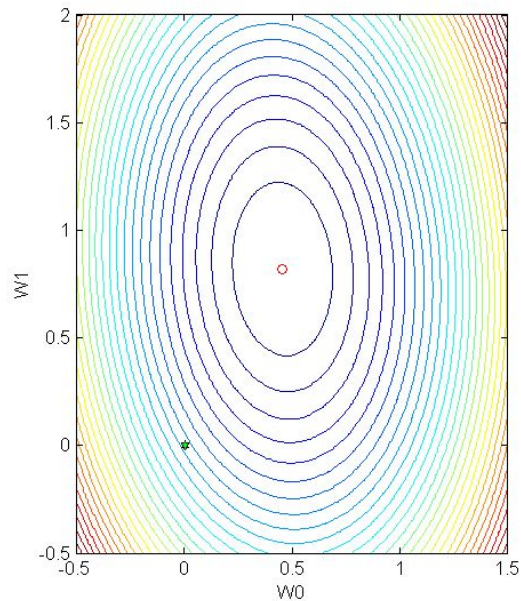
where

$$\begin{aligned} \nabla_{\mathbf{w}} E(\mathbf{w} | \mathbf{x}^{(n)}) &= \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi(\mathbf{x}^{(n)}) \\ &= \left( \mathbf{w}^T \phi(\mathbf{x}^{(n)}) - y^{(n)} \right) \phi(\mathbf{x}^{(n)}) \end{aligned}$$

Note: Typically the learning rate is gradually decreased as training time ( $t$ ) goes on:

e.g.,  $\eta_t \propto \frac{1}{t}$

# Batch gradient vs. Stochastic gradient





# Closed form solution

- Main idea:
  - Compute gradient and set gradient to 0. (condition for optimal solution)
  - Solve the equation in a closed form

- Objective function:

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

- We will derive the gradient from matrix calculus

# Closed form solution

- Objective function:

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# Closed form solution

- Objective function:

$$\begin{aligned} E(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \frac{1}{2} \sum_{n=1}^N \left( \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \end{aligned}$$

# Closed form solution

- Objective function:

$$\begin{aligned} E(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}) - y^{(n)})^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}))^2 - \sum_{n=1}^N y^{(n)} \mathbf{w}^T \phi(\mathbf{x}^{(n)}) + \frac{1}{2} \sum_{n=1}^N y^{(n)2} \end{aligned}$$

# Closed form solution

- Objective function:

$$\begin{aligned} E(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}) - y^{(n)})^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}))^2 - \sum_{n=1}^N y^{(n)} \mathbf{w}^T \phi(\mathbf{x}^{(n)}) + \frac{1}{2} \sum_{n=1}^N y^{(n)2} \\ &= \frac{1}{2} \mathbf{w}^T \Phi^T \Phi \mathbf{w} - \mathbf{w}^T \Phi^T \mathbf{y} + \frac{1}{2} \mathbf{y}^T \mathbf{y} \end{aligned}$$

- Trick: vectorization (by defining data matrix)

# The data matrix

- The design matrix is an  $N \times M$  matrix, applying
  - the  $M$  basis functions (columns)
  - to  $N$  data points (rows)

$$\Phi = \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix}$$

$$\Phi \mathbf{w} \approx \mathbf{y}$$

$$\Phi = \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix}$$

$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2$$

$$\Phi = \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix}$$

$$\begin{aligned} E(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}) - y^{(n)})^2 \end{aligned}$$



$$\Phi = \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix}$$

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$$\Phi = \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix}$$

$$\begin{aligned} E(\mathbf{w}) &= \frac{1}{2} \sum_{n=1}^N \left( \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}^{(n)}) - y^{(n)} \right)^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}) - y^{(n)})^2 \\ &= \frac{1}{2} \sum_{n=1}^N (\mathbf{w}^T \phi(\mathbf{x}^{(n)}))^2 - \sum_{n=1}^N y^{(n)} \mathbf{w}^T \phi(\mathbf{x}^{(n)}) + \frac{1}{2} \sum_{n=1}^N y^{(n)2} \\ &= \frac{1}{2} \mathbf{w}^T \Phi^T \Phi \mathbf{w} - \mathbf{w}^T \Phi^T \mathbf{y} + \frac{1}{2} \mathbf{y}^T \mathbf{y} \end{aligned}$$

# Useful trick: Matrix Calculus

- Idea so far:
  - Compute gradient and set gradient to 0.  
(condition for optimal solution)
  - Solve the equation in a closed form using matrix calculus
- Need to compute the first derivative in matrix form

# Matrix calculus: The Gradient

- Suppose that  $f : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$  is a function that takes as input a matrix  $A$  of size  $m \times n$  and returns a real value (scalar). Then the gradient of  $f$  (with respect to  $A \in \mathbb{R}^{m \times n}$ ) is the matrix of partial derivatives, defined as:

$$\nabla_A f(A) \in \mathbb{R}^{m \times n} = \begin{bmatrix} \frac{\partial f(A)}{\partial A_{11}} & \frac{\partial f(A)}{\partial A_{12}} & \cdots & \frac{\partial f(A)}{\partial A_{1n}} \\ \frac{\partial f(A)}{\partial A_{21}} & \frac{\partial f(A)}{\partial A_{22}} & \cdots & \frac{\partial f(A)}{\partial A_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f(A)}{\partial A_{m1}} & \frac{\partial f(A)}{\partial A_{m2}} & \cdots & \frac{\partial f(A)}{\partial A_{mn}} \end{bmatrix}$$

$$(\nabla_A f(A))_{ij} = \frac{\partial f(A)}{\partial A_{ij}}$$

# Matrix calculus: The Gradient

Note that the size of  $\nabla_A f(A)$  is always the same as the size of  $A$ . So if, in particular,  $A$  is just a vector  $x \in \mathbb{R}^n$ ,

$$\nabla_x f(x) = \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \\ \vdots \\ \frac{\partial f(x)}{\partial x_n} \end{bmatrix}.$$

- $\nabla_x (f(x) + g(x)) = \nabla_x f(x) + \nabla_x g(x)$ .
- For  $t \in \mathbb{R}$ ,  $\nabla_x (t f(x)) = t \nabla_x f(x)$ .

# Gradient of Linear Functions

- Linear function:  $f(\mathbf{x}) = \sum_{i=1}^n b_i x_i = \mathbf{b}^T \mathbf{x}$
- Gradient:  $\frac{\partial f(\mathbf{x})}{\partial x_k} = \frac{\partial}{\partial x_k} \sum_{i=1}^n b_i x_i = b_k$
- Compact form:  $\nabla_{\mathbf{x}} f(\mathbf{x}) = \mathbf{b}$

# Gradient of Quadratic Functions

- Linear function:  $f(\mathbf{x}) = \sum_{i,j=1}^n x_i A_{ij} x_j = \mathbf{x}^T \mathbf{A} \mathbf{x}$
- Gradient:  $\frac{\partial f(\mathbf{x})}{\partial x_k} = 2 \sum_{j=1}^n A_{kj} x_j = 2(\mathbf{A} \mathbf{x})_k$
- Compact form:  $\nabla_{\mathbf{x}} f(\mathbf{x}) = \mathbf{A} \mathbf{x}$

# Putting together: Solution via matrix calculus

- Compute gradient and set to zero

$$\begin{aligned}\nabla_{\mathbf{w}} E(\mathbf{w}) &= \nabla_{\mathbf{w}} \left( \frac{1}{2} \mathbf{w}^T \Phi^T \Phi \mathbf{w} - \mathbf{w}^T \Phi^T \mathbf{y} + \frac{1}{2} \mathbf{y}^T \mathbf{y} \right) \\ &= \Phi^T \Phi \mathbf{w} - \Phi^T \mathbf{y} \\ &= 0\end{aligned}$$

- Solve the resulting equation (normal equation)

$$\begin{aligned}\Phi^T \Phi \mathbf{w} &= \Phi^T \mathbf{y} \\ \mathbf{w}_{ML} &= (\Phi^T \Phi)^{-1} \Phi^T \mathbf{y}\end{aligned}$$

This is the *Moore-Penrose pseudo-inverse*:  $\Phi^\dagger = (\Phi^T \Phi)^{-1} \Phi^T$

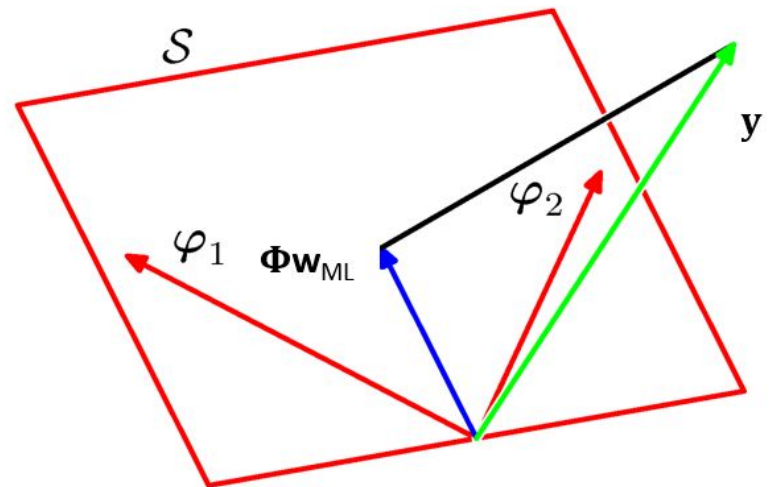
applied to:  $\Phi \mathbf{w} \approx \mathbf{y}$



# Geometric Interpretation

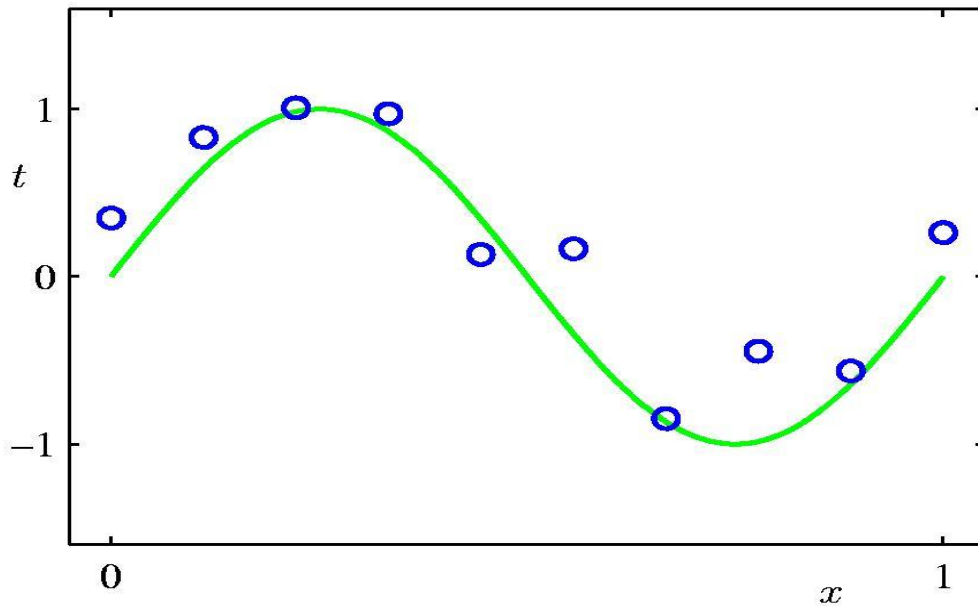
- Assuming many more observations (N) than the M basis functions  $\phi_j(x)$  ( $j=0,\dots,M-1$ )
- View the observed target values  $\mathbf{y} = \{y^{(1)}, \dots, y^{(N)}\}$  as a vector in an N-dim. space.
- The M basis functions  $\phi_j(x)$  span the N-dimensional subspace.
  - Where the N-dim vector for  $\phi_j$  is  $\{\phi_j(\mathbf{x}^{(1)}), \dots, \phi_j(\mathbf{x}^{(N)})\}$
- $\Phi\mathbf{w}_{\text{ML}}$  is the point in the subspace with minimal squared error from  $\mathbf{y}$ .
- It's the projection of  $\mathbf{y}$  onto that subspace.

$$\Phi = \begin{pmatrix} \phi_0(\mathbf{x}^{(1)}) & \phi_1(\mathbf{x}^{(1)}) & \dots & \phi_{M-1}(\mathbf{x}^{(1)}) \\ \phi_0(\mathbf{x}^{(2)}) & \phi_1(\mathbf{x}^{(2)}) & \dots & \phi_{M-1}(\mathbf{x}^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(\mathbf{x}^{(N)}) & \phi_1(\mathbf{x}^{(N)}) & \dots & \phi_{M-1}(\mathbf{x}^{(N)}) \end{pmatrix}$$



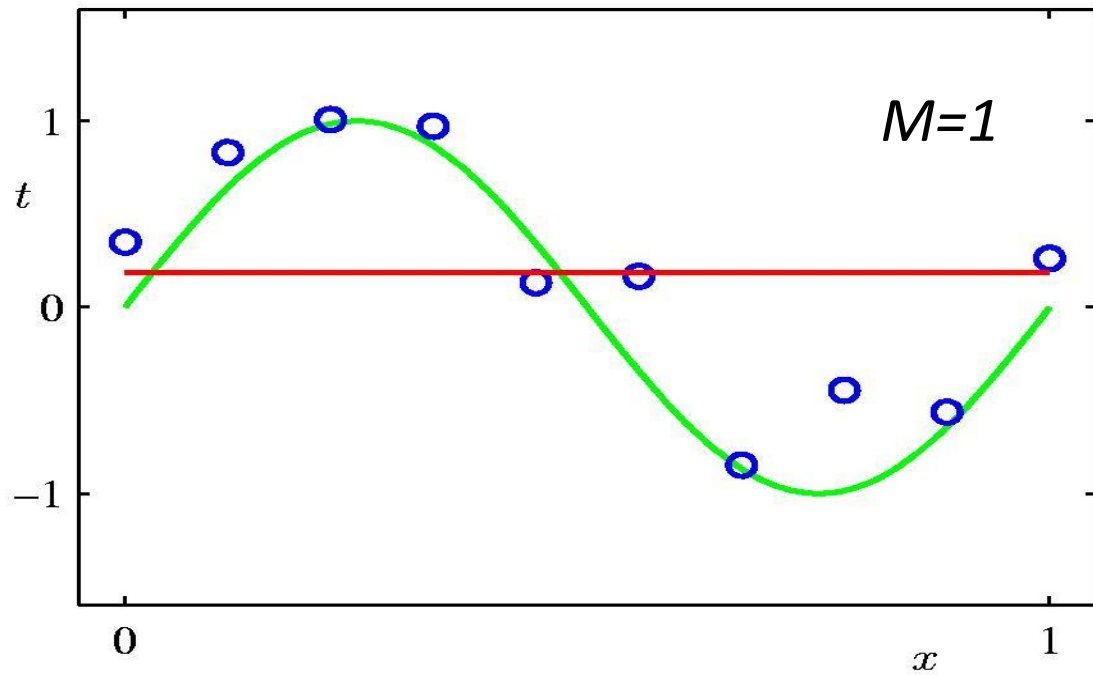
Back to curve-fitting examples

# Polynomial Curve Fitting

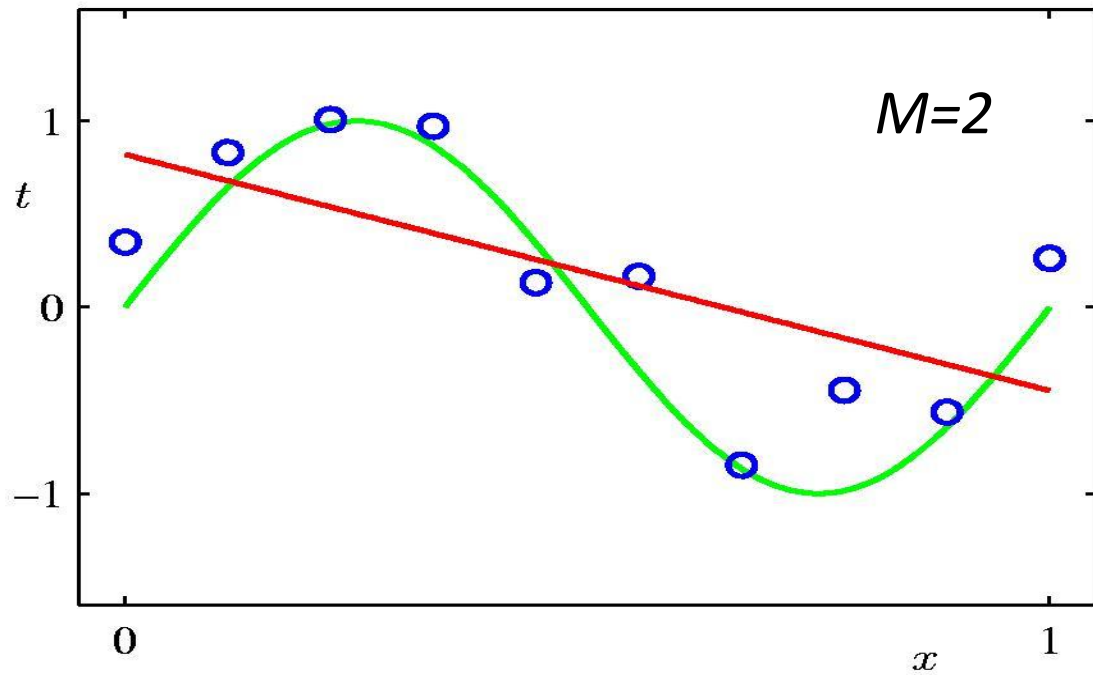


$$h(x, \mathbf{w}) = w_0 + w_1x + w_2x^2 + \dots + w_{M-1}x^{M-1} = \sum_{j=0}^{M-1} w_j x^j$$

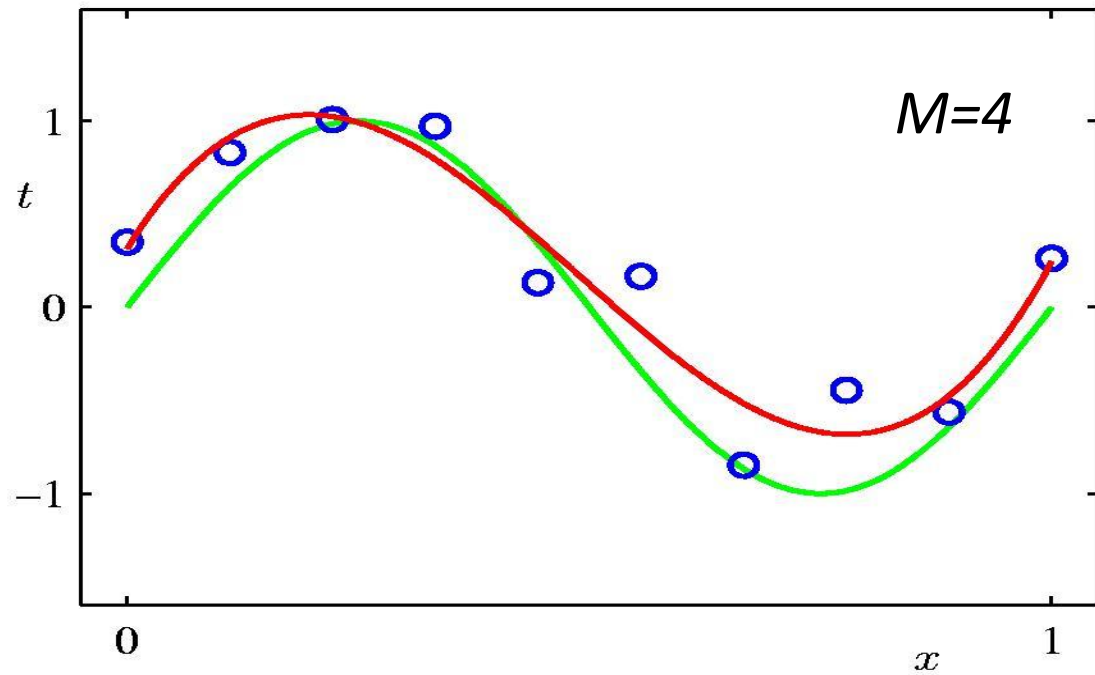
# 0<sup>th</sup> Order Polynomial



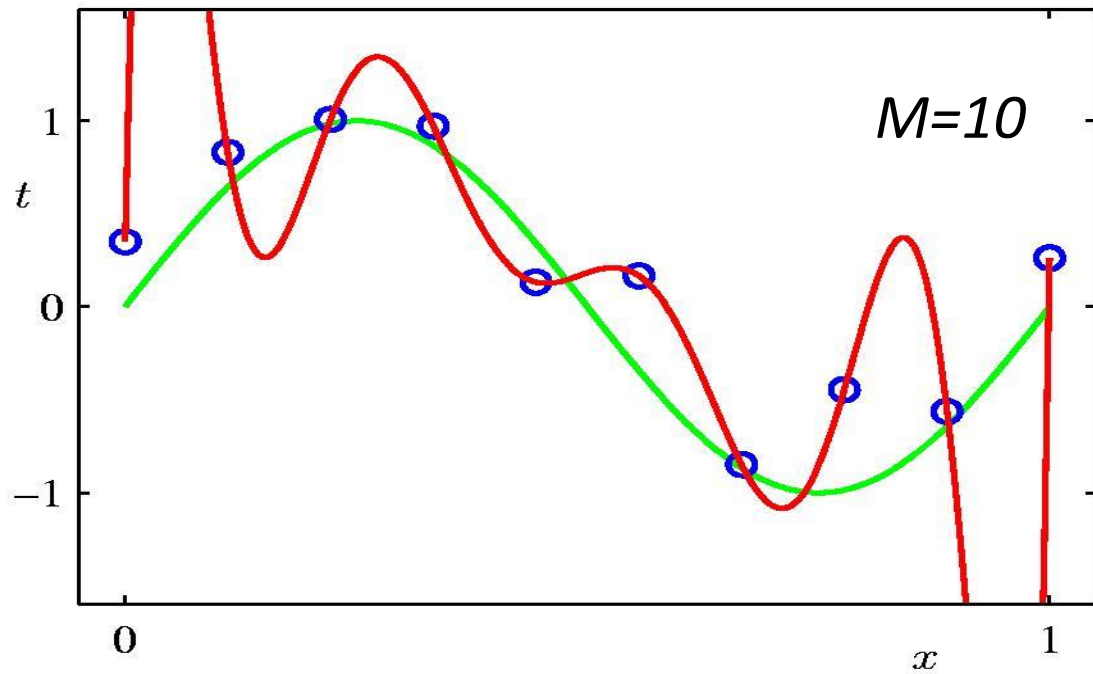
# 1<sup>st</sup> Order Polynomial



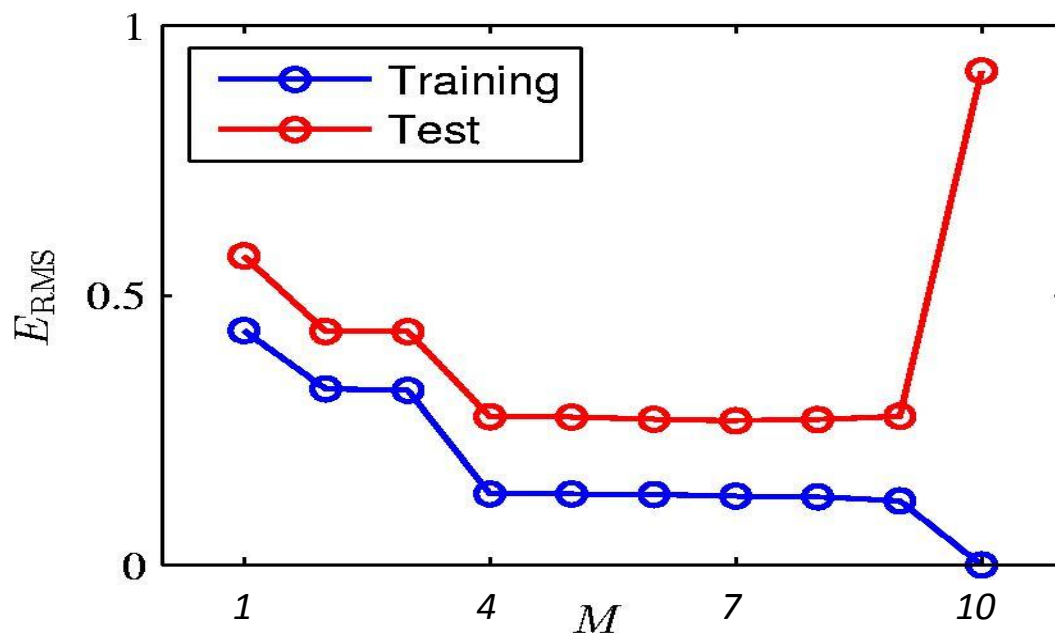
# 3<sup>rd</sup> Order Polynomial



# 9<sup>th</sup> Order Polynomial



# Over-fitting



Root-Mean-Square (RMS) Error:

$$E_{\text{RMS}} = \sqrt{2E(\mathbf{w}^*)/N}$$

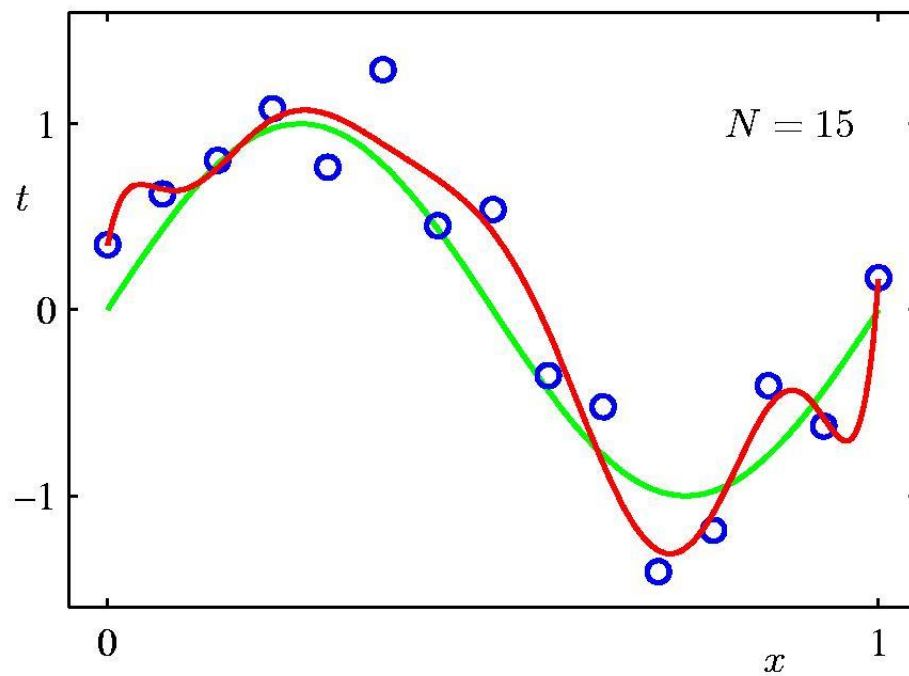


# Polynomial Coefficients

	$M=1$	$M=2$	$M=4$	$M=10$
$w_0^*$	0.19	0.82	0.31	0.35
$w_1^*$		-1.27	7.99	232.37
$w_2^*$			-25.43	-5321.83
$w_3^*$			17.37	48568.31
$w_4^*$				-231639.30
$w_5^*$				640042.26
$w_6^*$				-1061800.52
$w_7^*$				1042400.18
$w_8^*$				-557682.99
$w_9^*$				125201.43

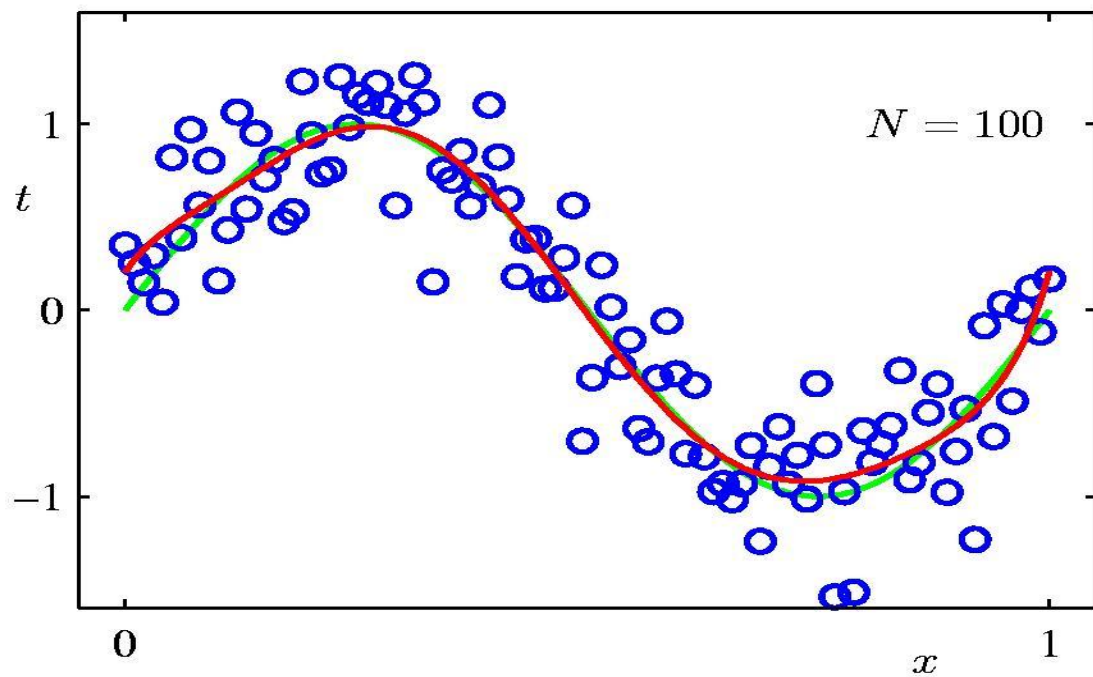
# Data Set Size: $N = 15$

## 9<sup>th</sup> Order Polynomial



Data Set Size:  $N = 100$

9<sup>th</sup> Order Polynomial



Q. How do we choose the degree of polynomial?

# Rule of thumb

- If you have a small number of data points, then you should use low order polynomial (small number of features).
  - Otherwise, your model will overfit
- As you obtain more data points, you can gradually increase the order of the polynomial (more features).
  - However, your model is still limited by the finite amount of the data available (i.e., the optimal model for finite data cannot be infinite dimensional polynomial).
- Controlling model complexity: **regularization**