

# 3D Renderer of Implicit Surfaces

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# Signed Distance Functions : Distance Surfaces

From “*Sphere tracing: a geometric method for antialiased ray tracing of implicit surfaces*” an implicit surface is defined by a function that, given a point in space, indicates whether the point is inside, on or outside the surface.

## Definition (Distance Surface)

A distance surface is implicitly defined by a function  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  that characterizes  $A \subset \mathbb{R}^3$ , set of points that are on or inside the implicit surface:

$$A = \{x : f(x) \leq 0\}$$

The surface can be also defined with  $f^{-1}(0)$ , which gives exactly the points on the surface.

# Signed Distance Functions : Point-To-Set Distance

We can define the surface from the outside using a *point-to-set* distance:

$$d(x, A) = \min_{y \in A} \|x - y\|$$

Thus  $d(x, A)$ , given a point  $x \in \mathbb{R}^3$ , returns the shortest distance to the surface defined by  $A$ .

We can interchange  $d(x, A)$  with  $d(x, f^{-1}(0))$  even if they are slightly different, because here we'll handle points that aren't in surfaces interiors.

# Signed Distance Functions : Bound and SDF

## Definition (Signed Distance Bound)

We say that  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  is a signed distance bound of its implicit surface  $f^{-1}(0)$  if and only if

$$|f(x)| \leq d(x, f^{-1}(0)) \quad (1)$$

## Definition (Signed Distance Function)

We say that  $f$  is a signed distance function (SDF) when holds

$$|f(x)| = d(x, f^{-1}(0)) \quad (2)$$

The first definition says that a signed distance bound is always at least as cautious as the true distance function  $d(x, f^{-1}(0))$  or the SDF.

# Signed Distance Functions : DUFs and DIFs

Two other names for the concepts of the previous slide are *distance underestimate (implicit) functions* (DUFs) and *distance implicit functions* (DIFs).

Remembering that  $DUF(x) \leq DIF(x)$  for every DUFs and DIFs respecting the definitions above.

We will interchange Signed Distance Bound with DUF and SDF with DIF, because they express the same concepts.

# Signed Distance Functions : Lipschitz

## Definition (Lipschitz Function)

We say that a function  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  is Lipschitz over a domain  $D$  if and only if there is a positive, finite, constant  $\lambda$  such that

$$|f(x) - f(y)| \leq \lambda \|x - y\| \quad (3)$$

Such  $\lambda$  is called the Lipschitz constant.

There is no upper limit to  $\lambda$ , but there is a lower bound. Let  $Lip(f)$  be the function returning such minimum value.

# Signed Distance Functions : Lipschitz

Manipulating 3 we can observe that

$$\begin{aligned}\lambda &\geq \frac{|f(x) - f(y)|}{\|x - y\|} \\ \lambda &\geq \frac{f(x) - f(y)}{\|x - y\|} \\ \lambda &\geq \lim_{\|x - y\| \rightarrow 0} \frac{f(x) - f(y)}{x - y} = f'(x)\end{aligned}$$

the last step, given the continuity of  $f$ , permits us to estimate a safe lower bound for the Lipschitz constant.

## Theorem

*Let  $f$  be Lipschitz with Lipschitz constant  $\lambda$ . Then the function  $f/\lambda$  is a SDF of its implicit surface.*

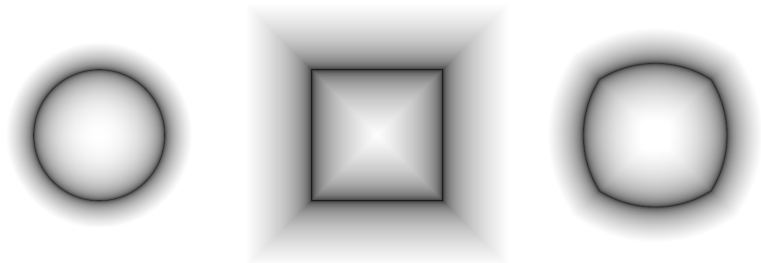
## Proof.

In the assignment.





## Signed Distance Functions : Examples



The images can be seen as 2D section of 3D objects done with a yz-aligned plane passing through the origin.

circle :  $x^2 + y^2 - 1$

square :  $\max(|x|, |y|) - 1$

squircle :  $k * (\max(|x|, |y|) - 1) + (1 - k) * (x^2 + y^2 - 1)$

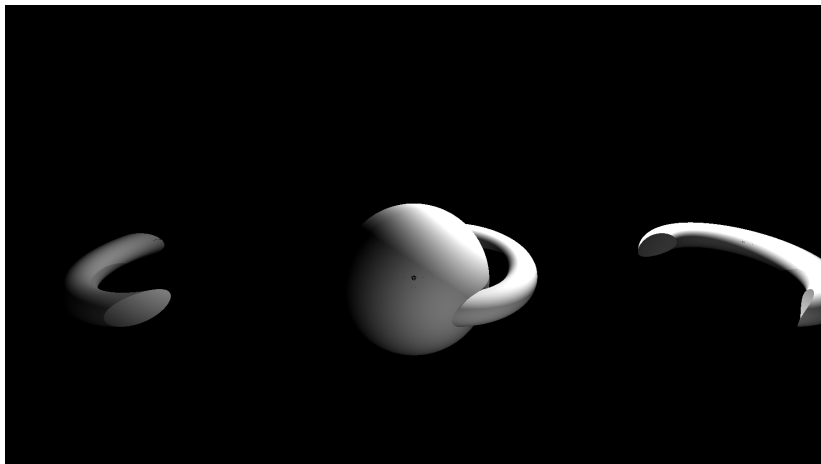
where  $k \in [0, 1]$

# Signed Distance Functions : Constructive Solid Geometry

SDFs make easy to create complex shapes from few simple primitives. This technique it known as Constructive Solid Geometry (CSG).

- ▶ union  $\min(f_1, f_2)$
- ▶ intersection  $\max(f_1, f_2)$
- ▶ subtraction  $\max(f_1, -f_2)$
- ▶ mixing  $k * f_1 + (1 - k) * f_2$  with  $k \in [0, 1]$

# Signed Distance Functions : Constructive Solid Geometry



From left to right: intersection, union and subtraction of a sphere and a torus.

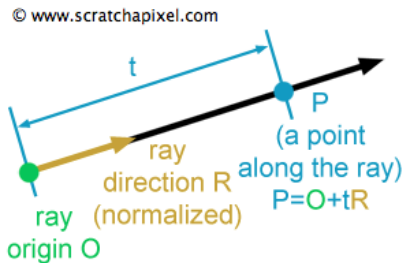
# Ray Tracing : Rays and Cameras

A ray is defined as a point and a direction in formulas:

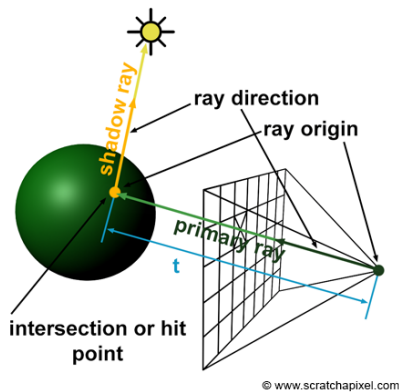
$$r(t) = O + tR$$

where  $O, R \in \mathbb{R}^3$  and  $R$  is a unit vector.

At each time  $t$  we can compute a point position on the ray.



# Ray Tracing : Rays and Cameras



A pinhole camera inside a scene with a sphere and a light source.

# Ray Tracing : Sphere Tracing

Ray Marching proceeds along the rays with a fixed step, with sphere tracing an adaptive step is used.