Zichao Hu

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Research Interest

- o Machine perception and tracking, navigation and planning, map building
- Locomotion, exoskeleton, bio-inspired robotics
- o Robot swarms, multi-robot cooperations

Education

University of Virginia (UVA)

Charlottesville, VA

B.S. Computer Engineering, GPA: 3.95, Major GPA: 4.0

Expected Graduation: May, 2022

Publication

o Hanzhi Zhou*, **Zichao Hu***, Sihang Liu, and Samira Khan, "Efficient Graph SLAM For Sparse Sensing," in *IEEE International Conference on Robotics and Automation (ICRA) (under review)*, 2022.

Research Experience

Efficient Graph SLAM For Sparse Sensing

January 2021 - October 2021

- o Formulated a novel graph frontend using both raw odometry measurements and observation measurements to tackle the problem of data sparsity and correct robot pose trajectories
- o Implemented line feature extraction using split and merge method with hierarchical clustering
- Adapted the Cartographer's implementations of the real-time correlative scan matching algorithm to the proposed system, and extended with a approximate matching heuristic to address the sparse sensing problem
- o Performed experiments on the established Radish Dataset and evaluated metrics to compare with previous works

Secure Multiparty Computation (MPC) Cryptography

January 2020 - August 2021

- o Studied secure MPC protocols based on replicated secret sharing and Beaver Triple
- o Studied efficient pseudorandom correlation generator based upon LPN-assumption and bilinear function
- Performed crytanalysis on the distributed point functions (DPF) using information-theoretic security and reduction to private information retrieval (PIR)

Dynamic Computation Offloading for Nanodrone Swarms

September 2021 - Present

o Perform experiments using various microcontrollers, such as raspberry pi and STM32F405, on SLAM benchmarks to profile performance and understand the differences between a microcontroller and a real desktop server.

Work Experience

Scanoptix Inc., Fullstack Web Developer Intern

October 2019 - August 2020

- o Developed the Scanoptix's medical imaging Website with Angular 9, AWS S3/Lambdas, and GraphQL
- Implemented a image processing pipeline to achieve zooming, rotating, cropping, tuning functionalities and filter out noises using gamma correction
- o Set up a dockerized localstack and used Postman API to emulate the AWS workflow
- Used OAuth 2.0 as the protocol to perform authentication and authorization

Projects

Plannable.org https://plannable.org/

March 2019 - December 2019

- Co-founded a free class scheduling website that has served over 2000 students
- o Built the website with Vue.js, Typescript.js, and Webassembly
- o Conducted market research through various pitches, on/offline surveys, and analysis of the exisiting solutions

Signature Replication Machine Capstone

September 2021 - December 2021 (expected)

- o Programmed the TI's MSP432 microcontroller to control motors drivers and switch sensors
- o Designed PCB schematic using Multisim and Ultiboard, and cutomized a boosterpack to interface with the MSP432
- o Processed image using OpenCV such as denoising and line thinning and converted into voltage outputs

OpenStatics Attps://openstatics.github.io/

September 2019 - September 2020

- Involved in developing instructional modules for the UVa MAE 2300/2310 courses to accelerate student comprehension through clean UI designs and intuitive user-controlled animations
- o Utilized the JSXGraph library for the 2D/3D equation visualizations and animations
- Set up devops toolchains to enable effective collaborations among contributors

Skills

- o Prolificient in Python, C++, Familiar with Matlab, Window WSL, Linux
- o Experience with ROS, G2O, NI Multisim, TI's MSP microcontroller, Solidworks, AWS, Javascript Frontend Frameworks, Express.js
- o Fluent in English, Chinese, Upper-intermediate in Spanish

AWARDS AND ACHIEVEMENTS

- o Best Beginner Hacks at HooHacks UVa, March 2019
- o ICPC Regional Qualifier Ranking at 36/160, October, 2019