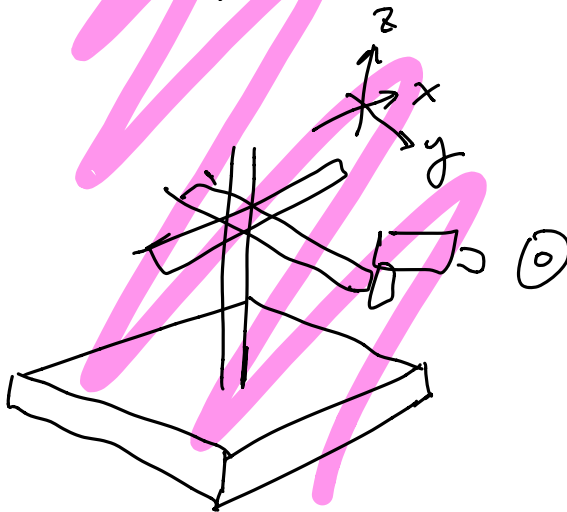


Divergence :

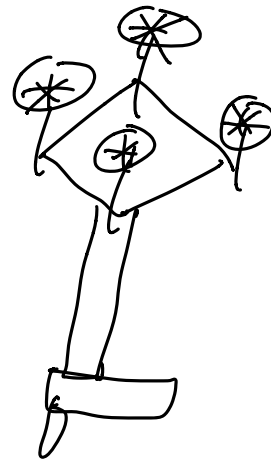
Moveable Base .



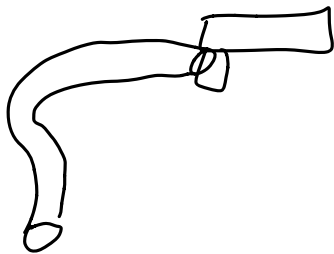
Track



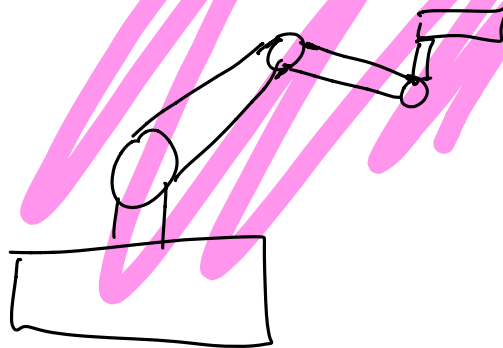
Drone .



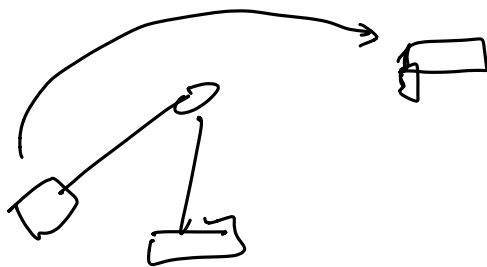
Soft Robo Arm



Traditional Robo Arm.



Projectile

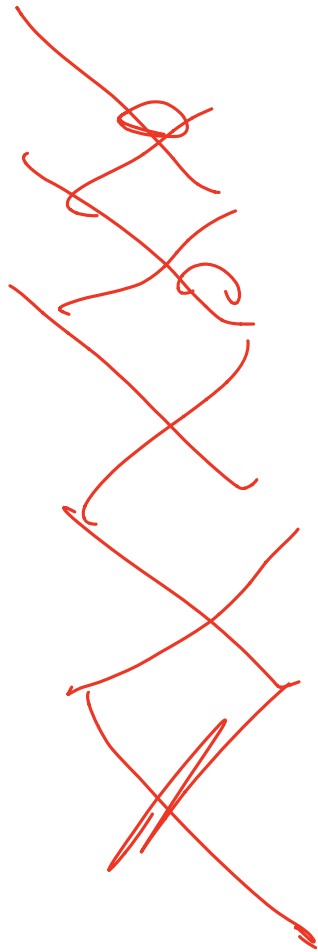


Matrix

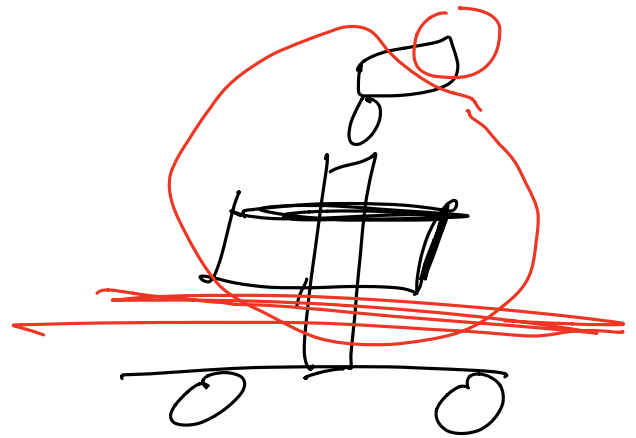
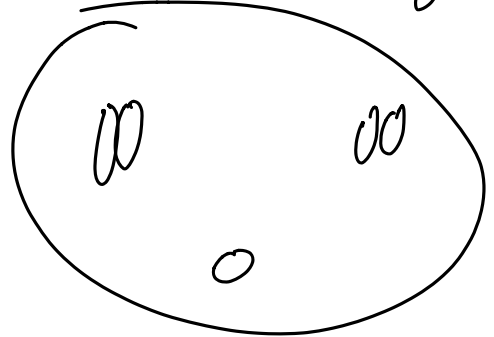
- Cost estimate
- ease of control
- stability / repeatable

3 votes/person.

- durability



house cleaning robot



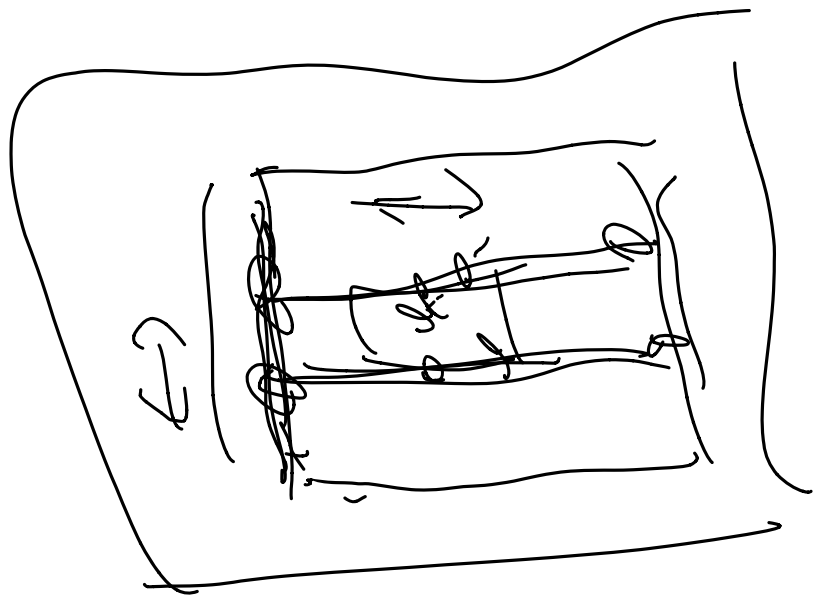
Week 5 Finish Component Selection/Research/Buy

6 Test Component performance

Reading Start assembly, Finish Base

7 Buy additional products, finish upper

- 8 Assembly gripper
- 9 Human Control Plug in
- 10 Detect & Plug in
- 11 Calibrate
- 12 Final
- 13 Report



Richard : Base

Leo : Charger movement & track }

Mengin : Image detect  
Sensor Camera

Thursday Night