

CMPSC 465: LECTURE XI

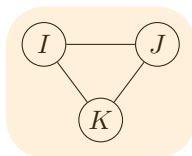
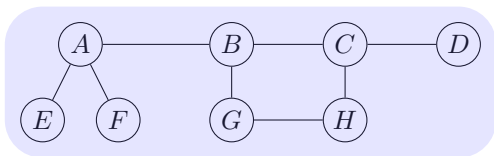
DFS on Undirected Graphs

Ke Chen

September 24, 2025

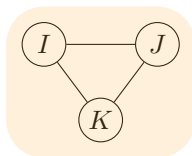
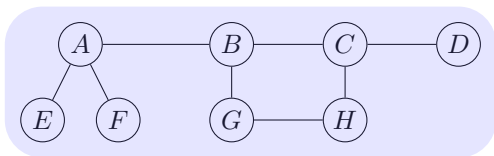
Connected component

Recall that the **connected component** of an undirected graph is defined as a maximal set of connected vertices.



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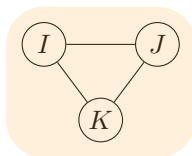
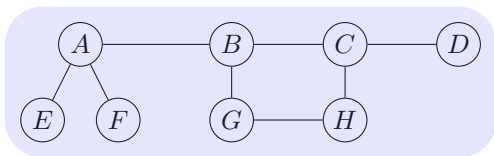
Recall that the **connected component** of an undirected graph is defined as a maximal set of connected vertices.



- Finding the connected components helps answer queries like “is node v connected to node w ?”.

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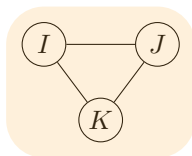
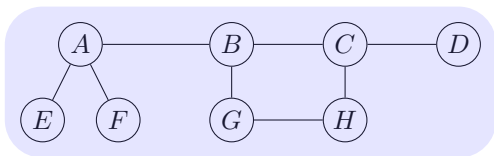
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- ▶ Finding the connected components helps answer queries like “is node v connected to node w ?”.
- ▶ How?

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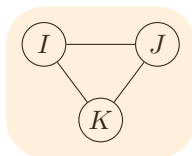
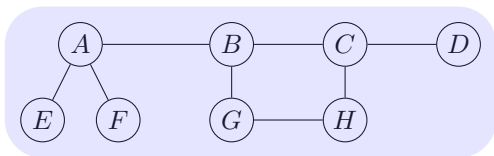
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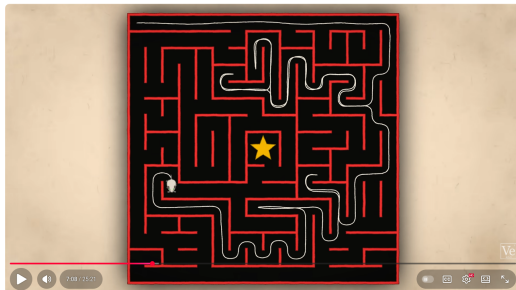
Recall that the **connected component** of an undirected graph is defined as a maximal set of connected vertices.



- ▶ Finding the connected components helps answer queries like “is node v connected to node w ?”.
- ▶ **How?** Just explore!

Explore by Depth First Search (DFS)

Intuition Explore a maze with a chalk and a string.



The Fastest Maze-Solving Competition On Earth by Veritasium

Explore by Depth First Search (DFS)

DFS on a graph follows the same idea:

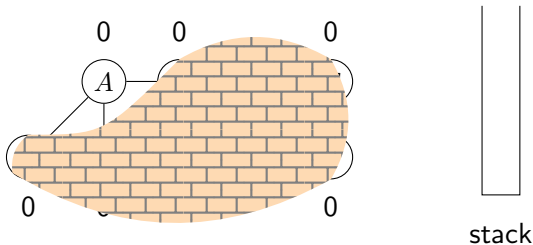
- ▶ The graph is the maze, with vertices corresponding to intersections.
- ▶ Integer array (one int per vertex) as the colored cyber-chalk.
- ▶ String can be modeled by a stack, to backtrack we pop from the stack.

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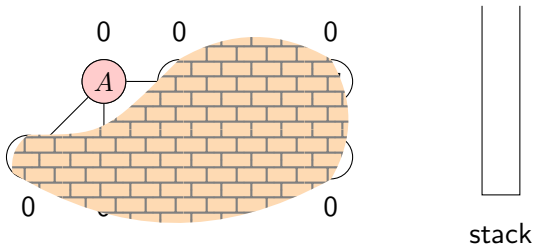


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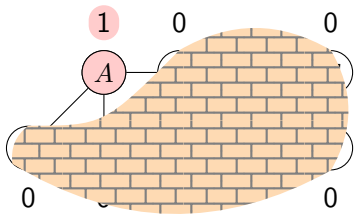


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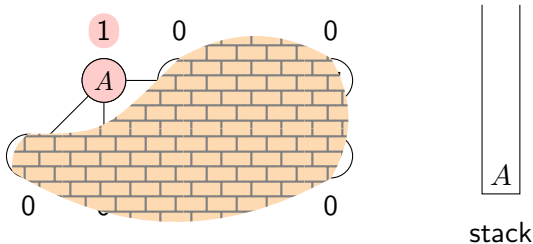
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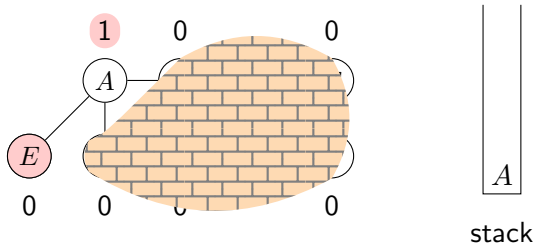


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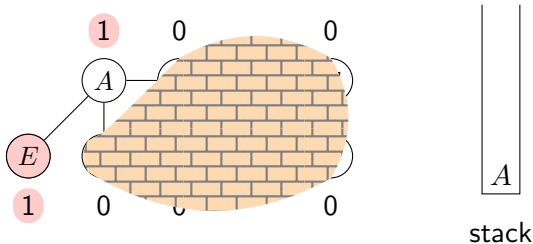


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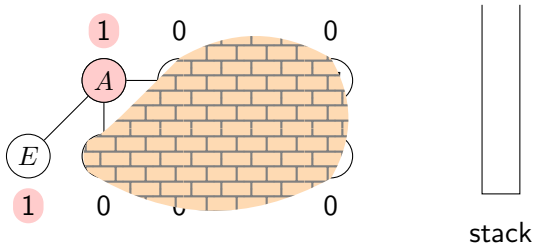


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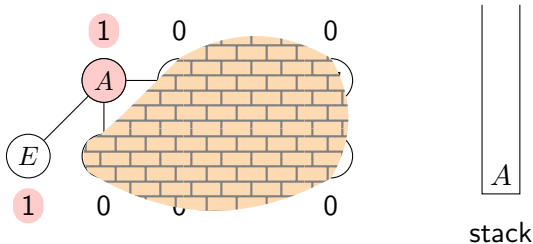


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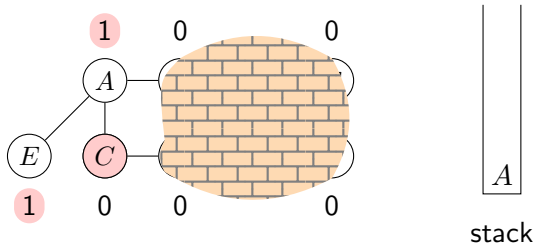


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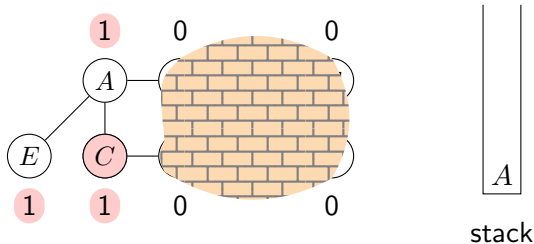


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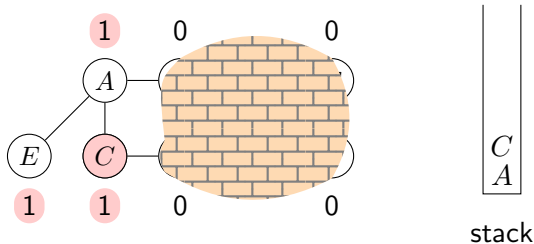


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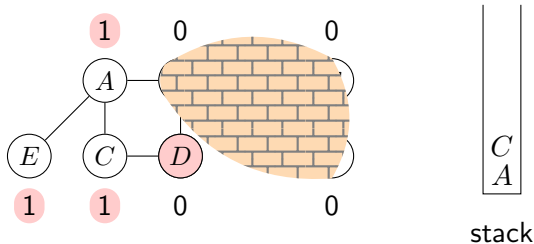


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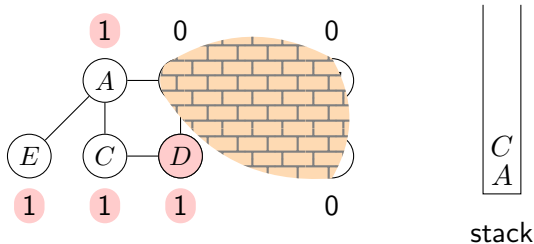


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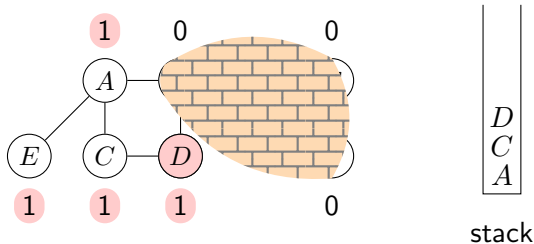


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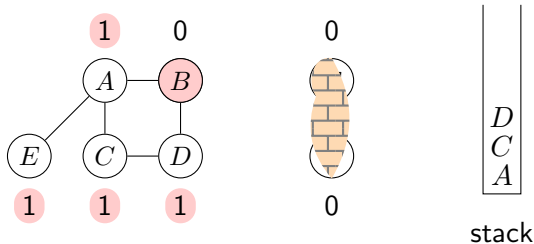


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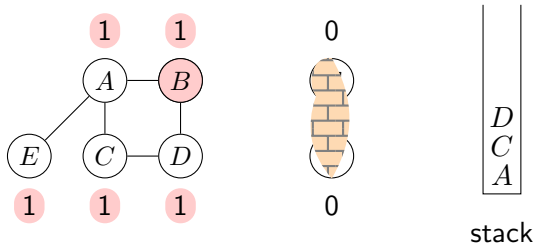


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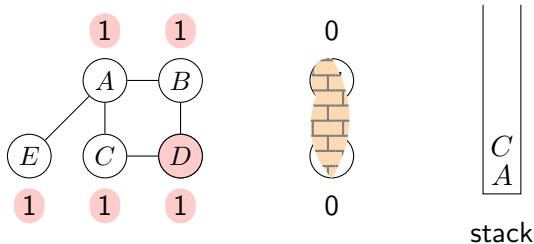


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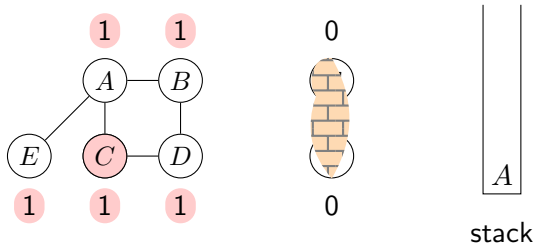


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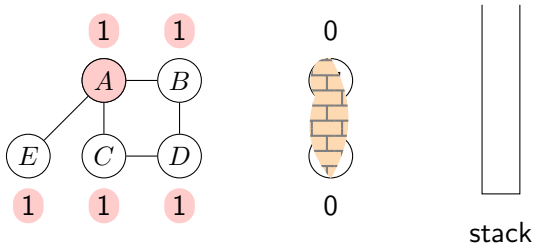


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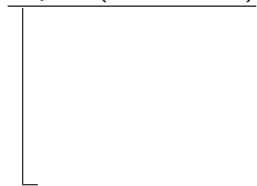


Explore by Depth First Search (DFS)

Input: Graph $G = (V, E)$, starting vertex s , chalk $color$

Output: Mark all nodes reachable from s with $color$

Explore($G, s, color$)




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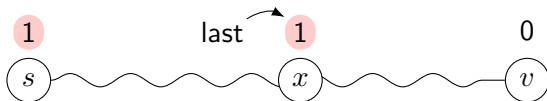
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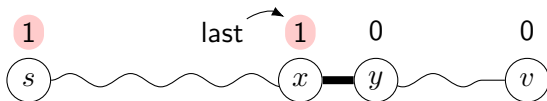
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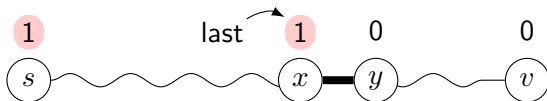
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DFS($G = (V, E)$)

visited is an array of length $|V|$, filled with 0's

color = 1

foreach $s \in V$ **do**

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 Explore($G, s, color$)

color = *color* + 1

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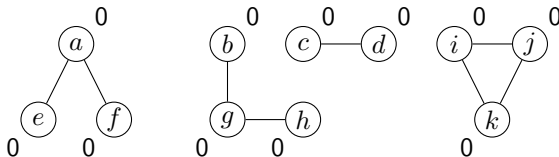
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Example



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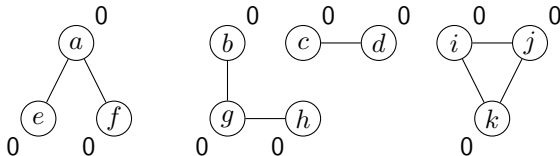
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Example Explore($G, a, 1$)



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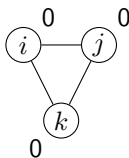
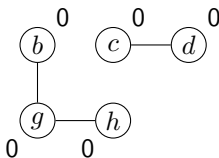
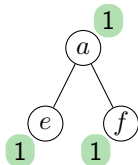
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Example Explore($G, a, 1$)



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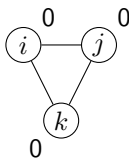
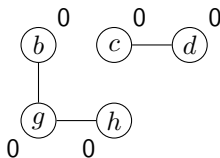
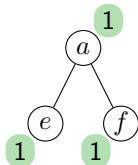
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 Explore(G, s, color)

color = *color* + 1

Example Explore($G, b, 2$)



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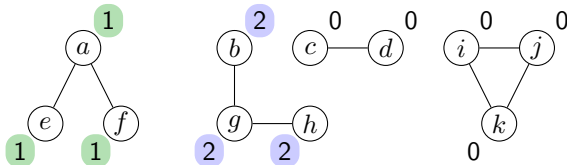
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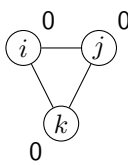
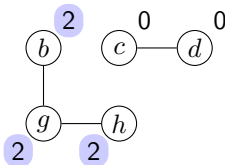
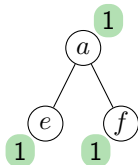
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Example Explore($G, c, 3$)



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- ▶ The Explore procedure reveals **one** connected component.
- ▶ DFS works by repeatedly calling Explore.

$\text{DFS}(G = (V, E))$

visited is an array of length $|V|$, filled with 0's

color = 1

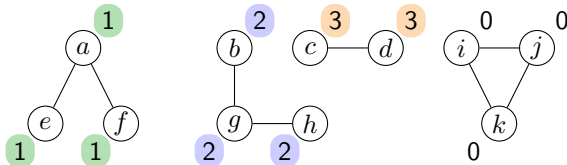
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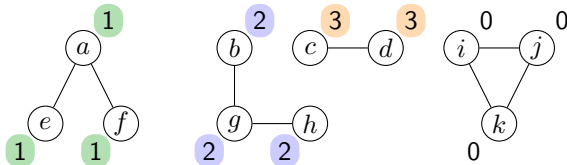
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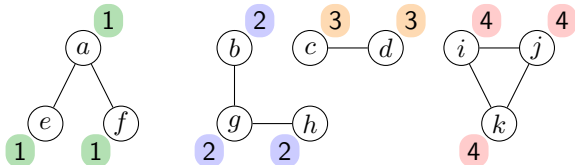
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$O(|V|^2)$

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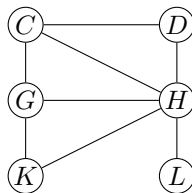
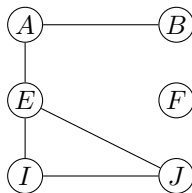
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Can we do better?

$O(|V| + |E|)$ is the best possible, since we need to read the graph.

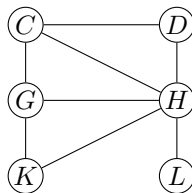
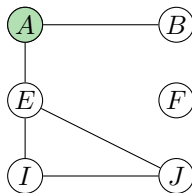
Edge types in DFS forest (undirected)

Example Suppose nodes are visited in lexicographical



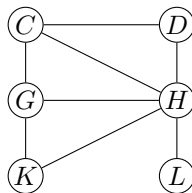
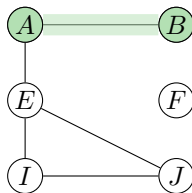
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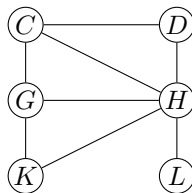
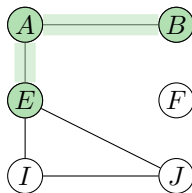
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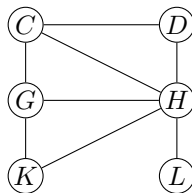
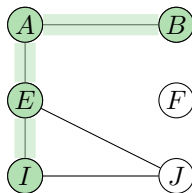
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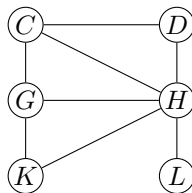
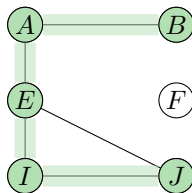
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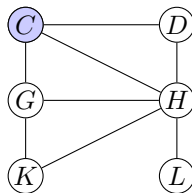
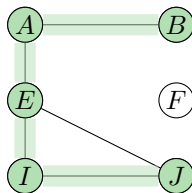
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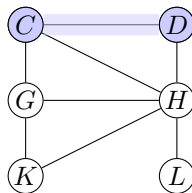
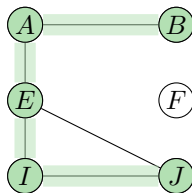
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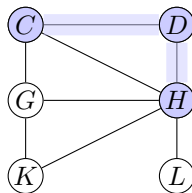
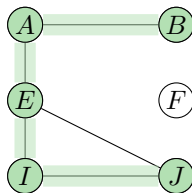
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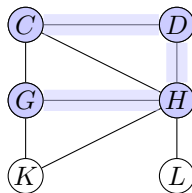
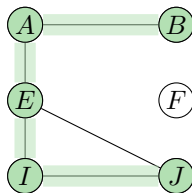
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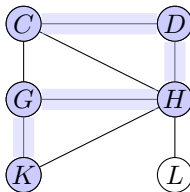
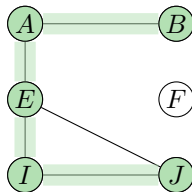
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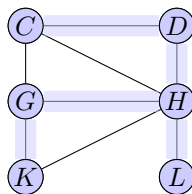
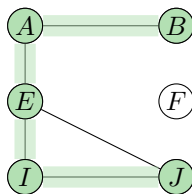
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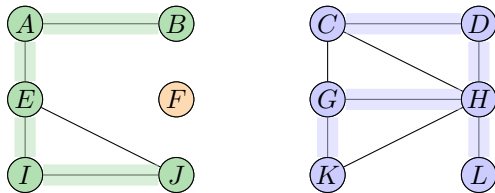
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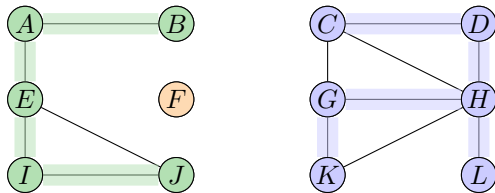
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► This is a DFS forest.

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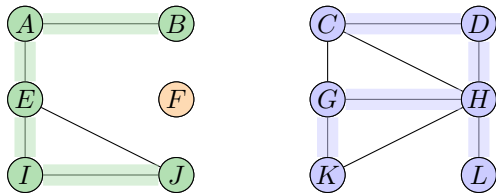
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- ▶ This is a DFS forest.
- ▶ Colored edges are called **tree edges**.

Edge types in DFS forest (undirected)

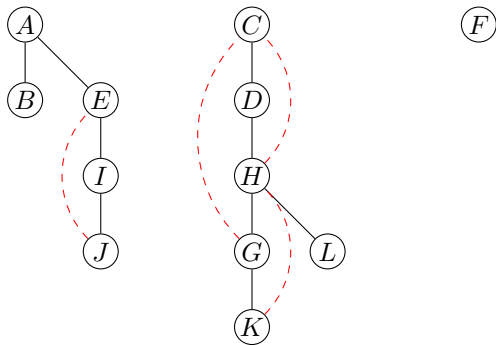
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- ▶ This is a DFS forest.
- ▶ Colored edges are called **tree edges**.
- ▶ Unused edges are called **back edges**.

Edge types in DFS forest (undirected)

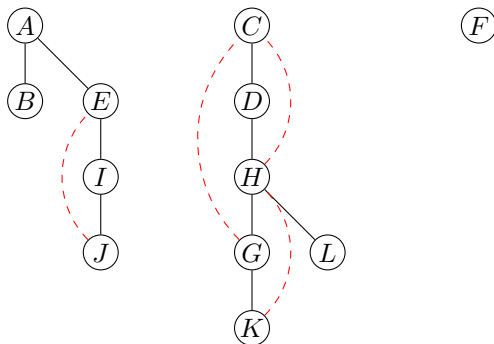
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- ▶ This is a DFS forest.
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Edge types in DFS forest (undirected)

Example Suppose nodes are visited in lexicographical



- ▶ This is a DFS forest.
- ▶ Solid edges are called **tree edges**.
- ▶ Dashed edges are called **back edges**.
- ▶ Back edges correspond to **cycles**.

Cycle detection (undirected)

To find cycles, it is sufficient to find back edges, which can be done with a simple modification to the Explore procedure.

Explore($G, s, color, previous$)

$visited[s] = color$

foreach edge $\{s, v\} \in E$ **do**

if $visited[v] == 0$ **then**

 Explore($G, v, color, s$)

if $visited[v] \neq 0$ **and** $v \neq previous$ **then**

 Output $\{v, s\}$ is a back edge or “found cycle”

Pre- and post-visit timestamps (undirected)

We can collect more information during Explore by keeping a global clock that ticks every time we:

- ▶ visit a node for the first time, and
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```
// pre and post are integer arrays of size  $|V|$   
// clock is an integer counter starting at 1  
Explore( $G, s, color$ )
```

```
    visited[ $s$ ] = color
```

```
    pre[ $s$ ] = clock
```

```
    clock = clock + 1
```

```
    foreach edge  $\{s, v\} \in E$  do
```

```
        if visited[ $v$ ] == 0 then
```

```
            Explore( $G, v, color$ )
```

```
    post[ $s$ ] = clock
```

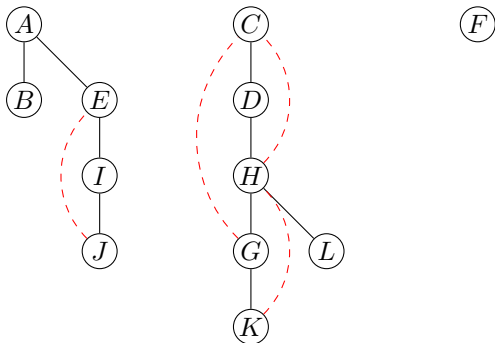
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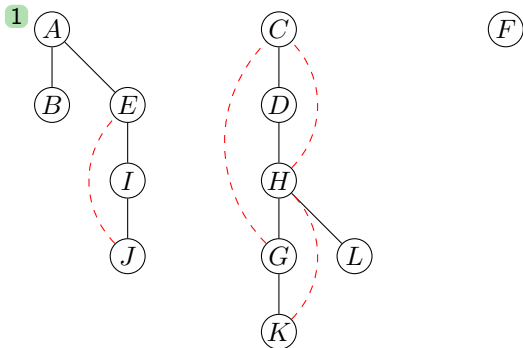


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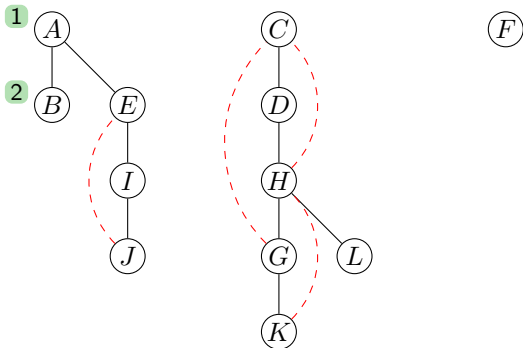


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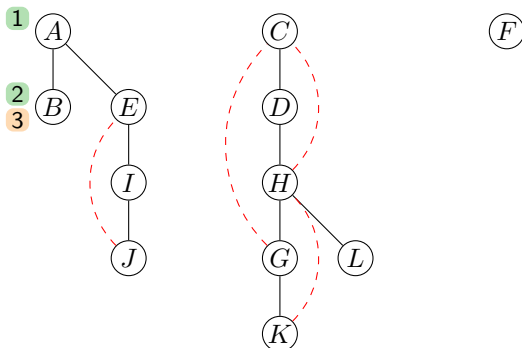


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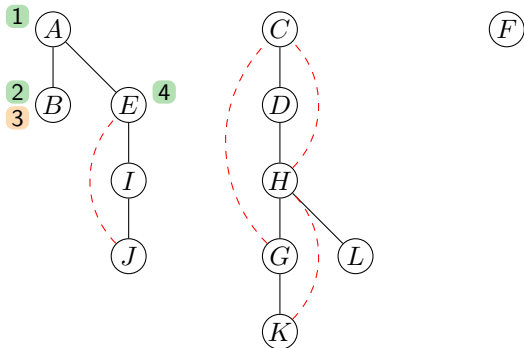


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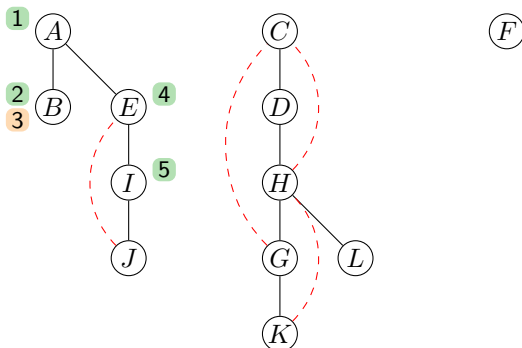


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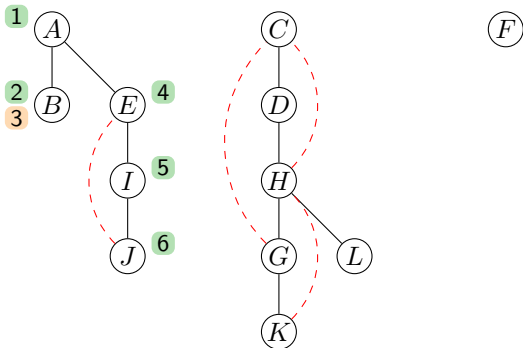


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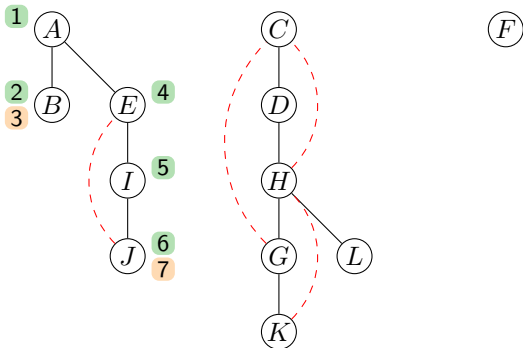


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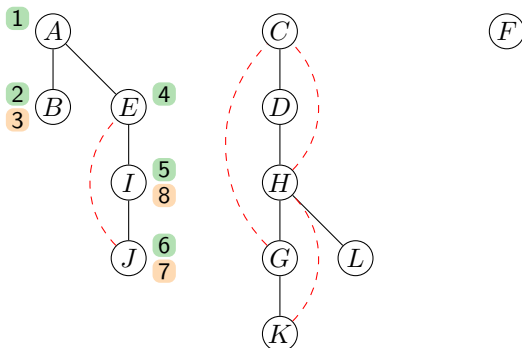


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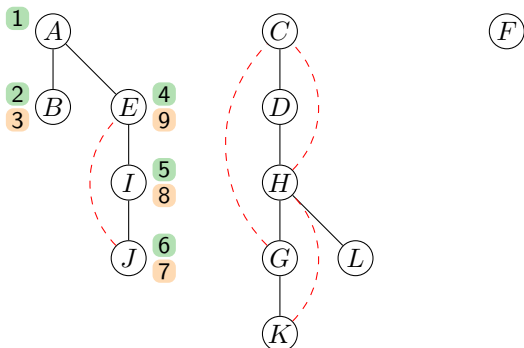


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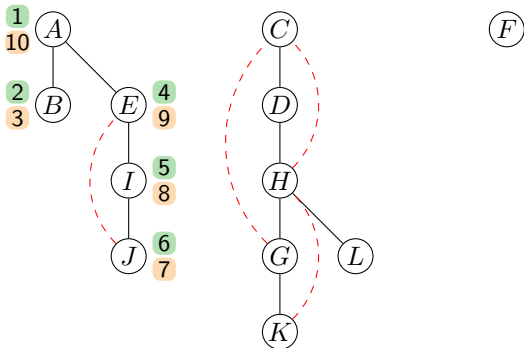


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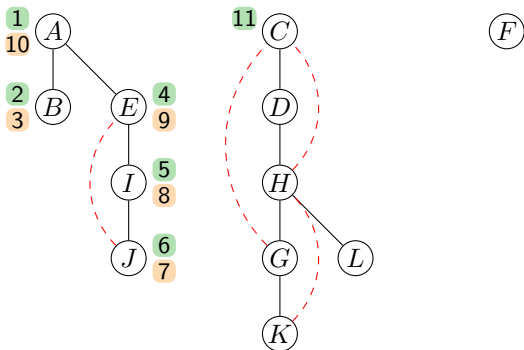


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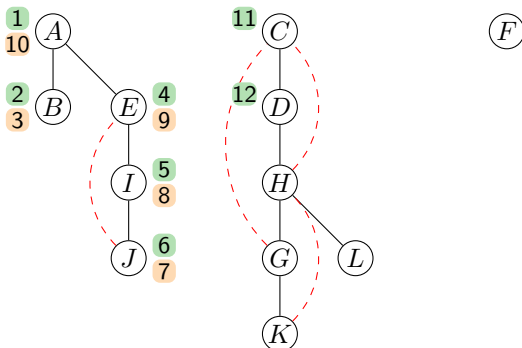


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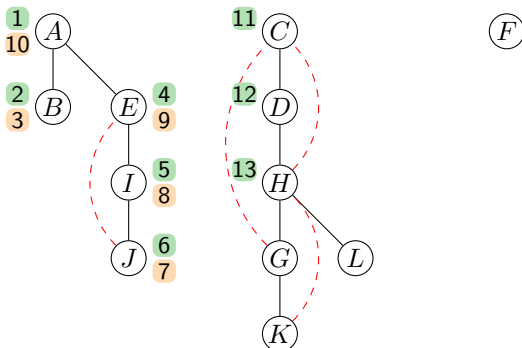


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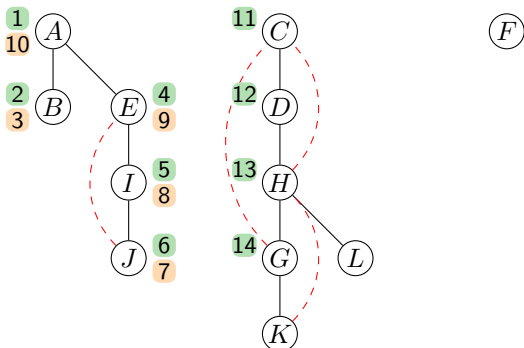


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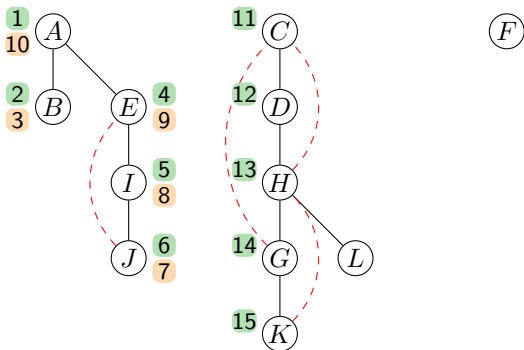


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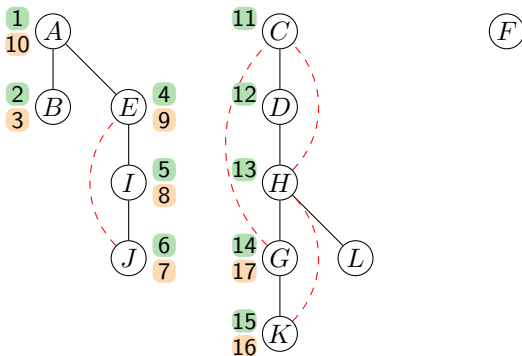


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Example

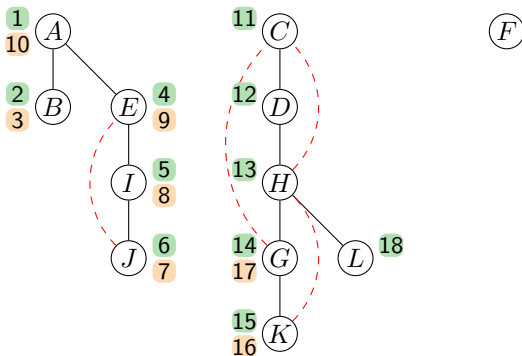


Pre- and post-visit timestamps (undirected)

We can collect more information during Explore by keeping a global clock that ticks every time we:

- ▶ visit a node for the first time, and
- ▶ leave a node for good.

Example

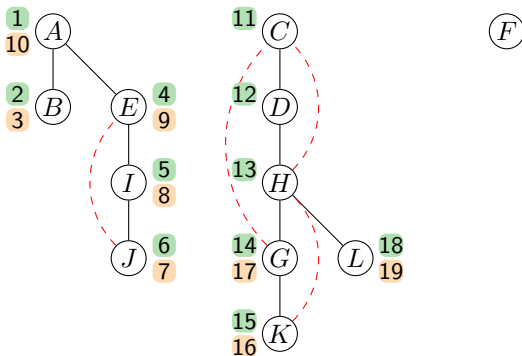


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Example

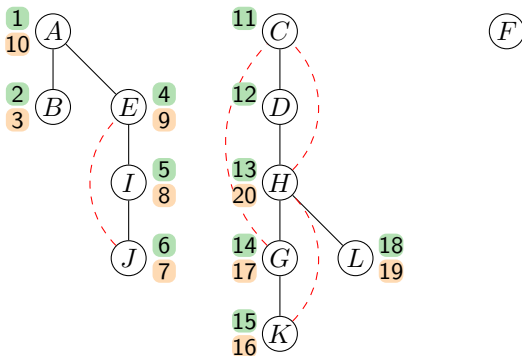


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Example

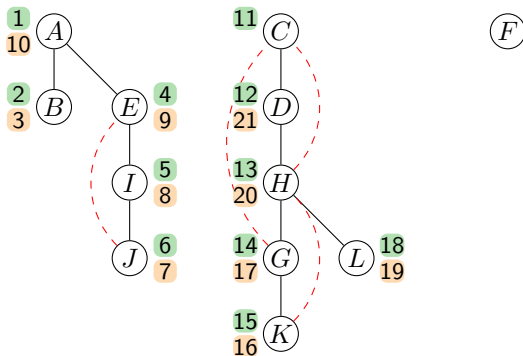


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Example

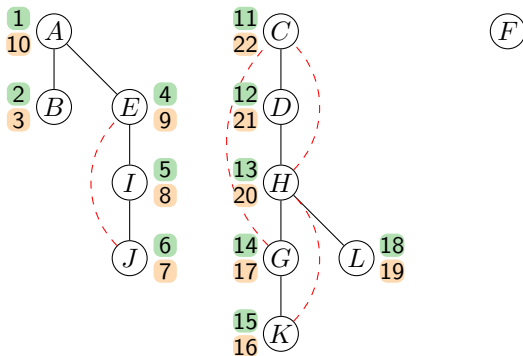


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Example

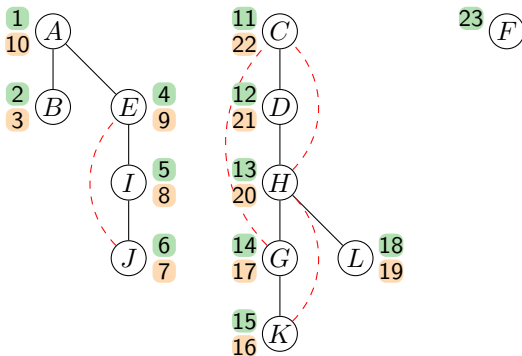


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