

CMPSC 465: LECTURE XVII

Shortest Path with Negative Weights

Ke Chen

October 08, 2025

Negative edge weights

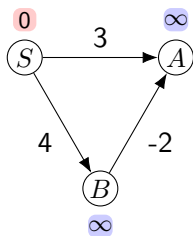
- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.

Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?

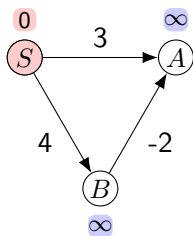
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



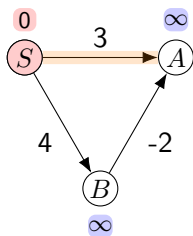
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



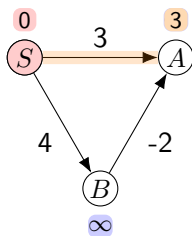
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



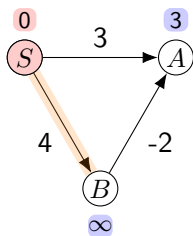
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



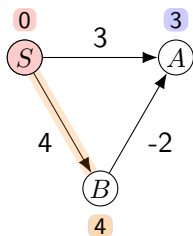
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



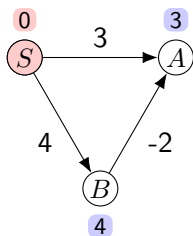
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



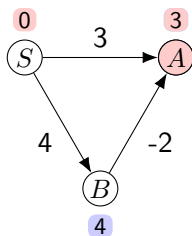
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



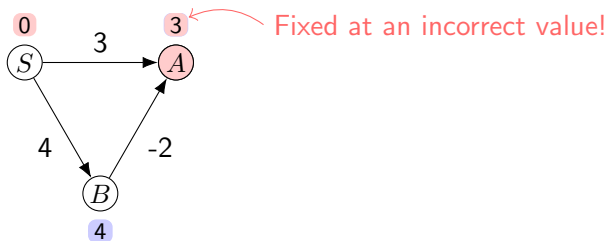
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



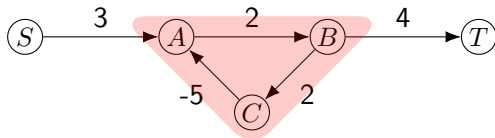
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?



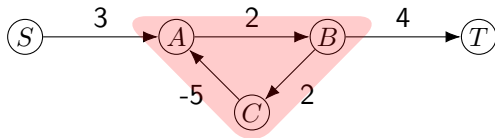
Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?
- ▶ Even worse, if there are **negative cycles**, the “shortest distance” is not well-defined.



Negative edge weights

- ▶ Recall that the correctness of Dijkstra's algorithm relies on all edge weights being nonnegative.
- ▶ What happens if there are negative edges?
- ▶ Even worse, if there are **negative cycles**, the “shortest distance” is not well-defined.



- ▶ Note that in directed graphs, negative edges \neq negative cycles; however, in undirected graphs, a negative edge = a negative cycle. (Why?)

Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

- ▶ The shortest distance from S to any node can be correctly computed by a sequence of Update calls along a shortest path.

Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

- The shortest distance from S to any node can be correctly computed by a sequence of Update calls along a shortest path. Remains valid with negative edges.

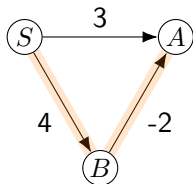
Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

- ▶ The shortest distance from S to any node can be correctly computed by a sequence of Update calls along a shortest path. **Remains valid with negative edges.**



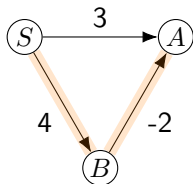
Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

- ▶ The shortest distance from S to any node can be correctly computed by a sequence of Update calls along a shortest path. **Remains valid with negative edges.**
- ▶ Having additional Update calls doesn't hurt.



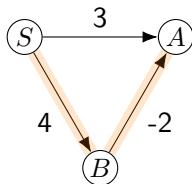
Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

- ▶ The shortest distance from S to any node can be correctly computed by a sequence of Update calls along a shortest path. **Remains valid with negative edges.**
- ▶ Having additional Update calls doesn't hurt.
- ▶ Dijkstra applies a **smart sequence of only $O(|E|)$** Update calls that's guaranteed to include the required sequence for each node if no negative weights.



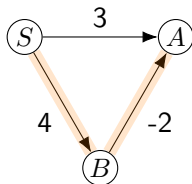
Update is fine with negative edges

Recall the **Update** operation:

$\text{Update}((v, w) \in E)$

if $\text{dist}[w] > \text{dist}[v] + \ell(v, w)$ **then**
 $\text{dist}[w] = \text{dist}[v] + \ell(v, w)$

- ▶ The shortest distance from S to any node can be correctly computed by a sequence of Update calls along a shortest path. **Remains valid with negative edges.**
- ▶ Having additional Update calls doesn't hurt.
- ▶ Dijkstra applies a **smart sequence of only $O(|E|)$** Update calls that's guaranteed to include the required sequence for each node if no negative weights. **It may fail with negative edges.**



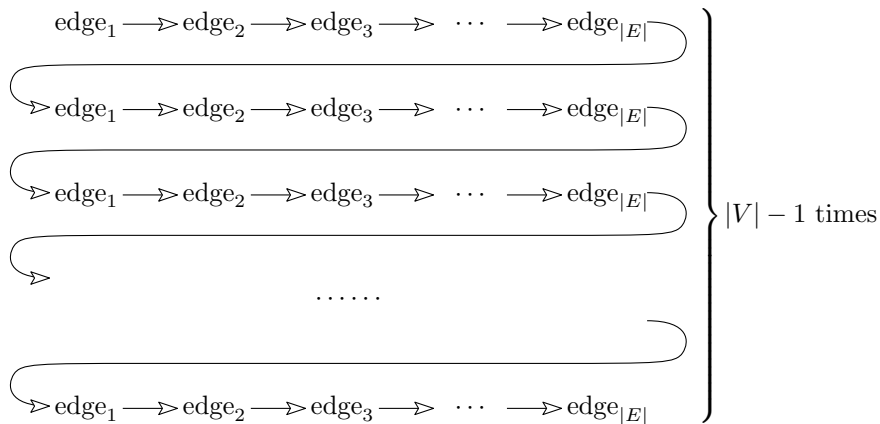
One sequence to rule them all

Can we find a sequence of Update calls that **always** work?

One sequence to rule them all

Can we find a sequence of Update calls that **always** work?

Yes! The following sequence contains **ALL** possible sequences of Update calls of length at most $|V| - 1$:



One sequence to rule them all

Idea Call Update on each edge, and repeat $|V| - 1$ times.

► Why $|V| - 1$?

One sequence to rule them all

Idea Call Update on each edge, and repeat $|V| - 1$ times.

- ▶ Why $|V| - 1$? A shortest path contains at most $|V| - 1$ edges.

One sequence to rule them all

Idea Call Update on each edge, and repeat $|V| - 1$ times.

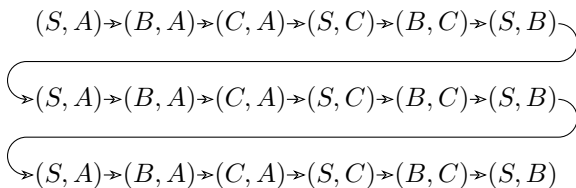
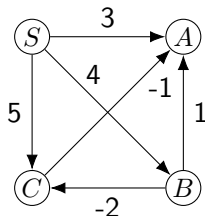
- ▶ Why $|V| - 1$? A shortest path contains at most $|V| - 1$ edges.
- ▶ The order of edges doesn't matter.

One sequence to rule them all

Idea Call Update on each edge, and repeat $|V| - 1$ times.

- ▶ Why $|V| - 1$? A shortest path contains at most $|V| - 1$ edges.
- ▶ The order of edges doesn't matter.

Example

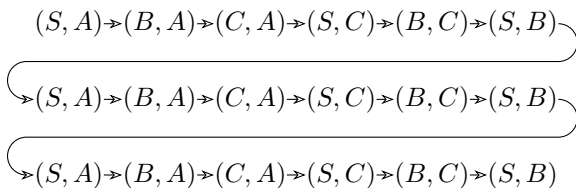
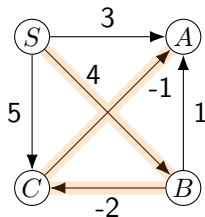


One sequence to rule them all

Idea Call Update on each edge, and repeat $|V| - 1$ times.

- ▶ Why $|V| - 1$? A shortest path contains at most $|V| - 1$ edges.
- ▶ The order of edges doesn't matter.

Example

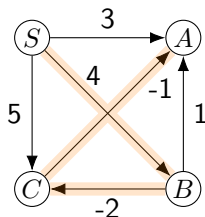


One sequence to rule them all

Idea Call Update on each edge, and repeat $|V| - 1$ times.

- ▶ Why $|V| - 1$? A shortest path contains at most $|V| - 1$ edges.
- ▶ The order of edges doesn't matter.

Example



$(S, A) \rightarrow (B, A) \rightarrow (C, A) \rightarrow (S, C) \rightarrow (B, C) \rightarrow (S, B)$

$(S, A) \rightarrow (B, A) \rightarrow (C, A) \rightarrow (S, C) \rightarrow (B, C) \rightarrow (S, B)$

$(S, A) \rightarrow (B, A) \rightarrow (C, A) \rightarrow (S, C) \rightarrow (B, C) \rightarrow (S, B)$

Bellman-Ford algorithm

Input: Graph $G = (V, E, \ell)$, starting vertex s

Output: Shortest path from s to any other vertex

Bellman-Ford(G, s)

// dist stores distances from s

foreach $v \in V$ **do**

$dist[v] = \infty$

$dist[s] = 0$

repeat $|V| - 1$ *times* **do**

foreach $e \in E$ **do**

 Update(e)

Bellman-Ford algorithm

Input: Graph $G = (V, E, \ell)$, starting vertex s

Output: Shortest path from s to any other vertex

Bellman-Ford(G, s)

```
// dist stores distances from  $s$ 
```

```
foreach  $v \in V$  do
```

```
└  $dist[v] = \infty$ 
```

```
 $dist[s] = 0$ 
```

```
repeat  $|V| - 1$  times do
```

```
└ foreach  $e \in E$  do
```

```
└ └ Update( $e$ )
```

Time complexity?

Bellman-Ford algorithm

Input: Graph $G = (V, E, \ell)$, starting vertex s

Output: Shortest path from s to any other vertex

Bellman-Ford(G, s)

```
// dist stores distances from  $s$ 
```

```
foreach  $v \in V$  do
```

```
└  $dist[v] = \infty$ 
```

```
 $dist[s] = 0$ 
```

```
repeat  $|V| - 1$  times do
```

```
└ foreach  $e \in E$  do
```

```
└ └ Update( $e$ )
```

Time complexity? $O(|V| \cdot |E|)$

Bellman-Ford algorithm

Input: Graph $G = (V, E, \ell)$, starting vertex s

Output: Shortest path from s to any other vertex

Bellman-Ford(G, s)

```
// dist stores distances from  $s$ 
```

```
foreach  $v \in V$  do
```

```
└  $dist[v] = \infty$ 
```

```
 $dist[s] = 0$ 
```

```
repeat  $|V| - 1$  times do
```

```
└ foreach  $e \in E$  do
```

```
└ └ Update( $e$ )
```

Time complexity? $O(|V| \cdot |E|)$

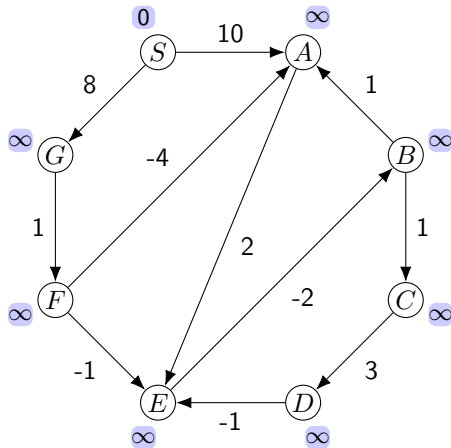
Can we do better?

Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round:

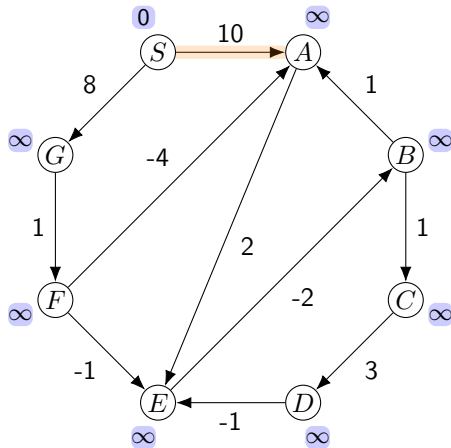


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

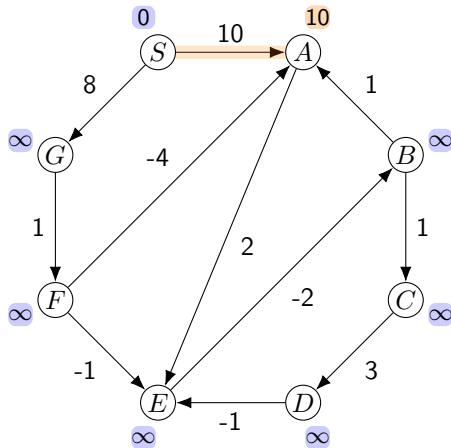


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

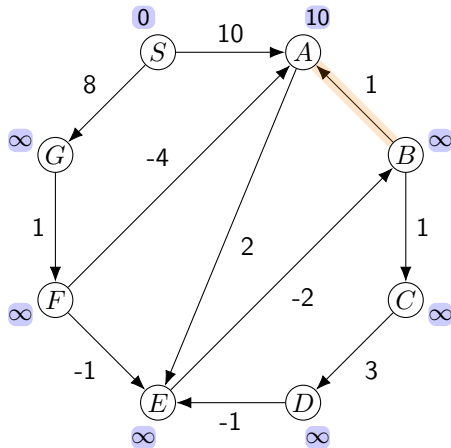


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

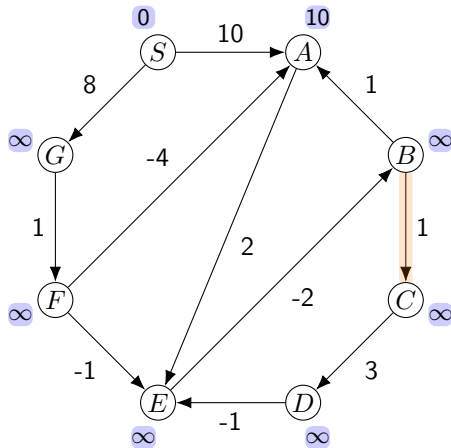


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

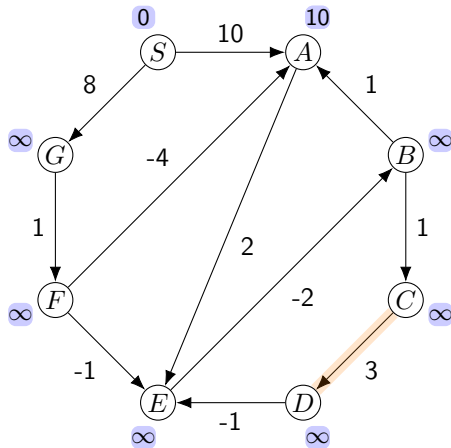


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

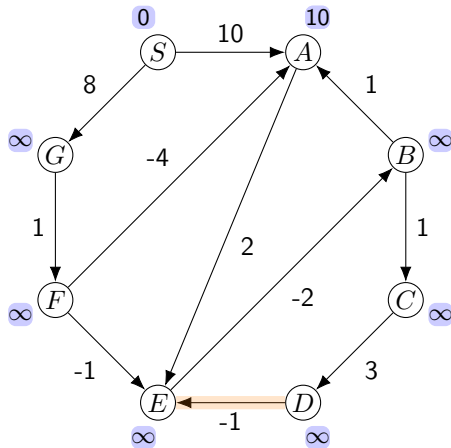


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

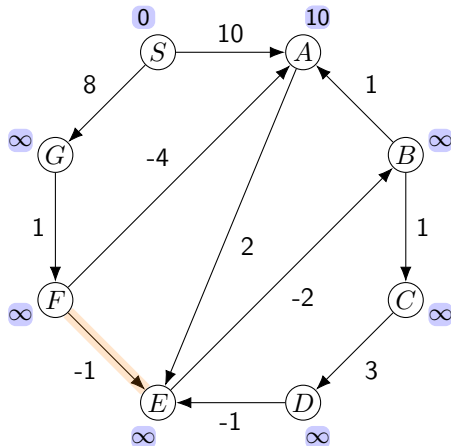


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

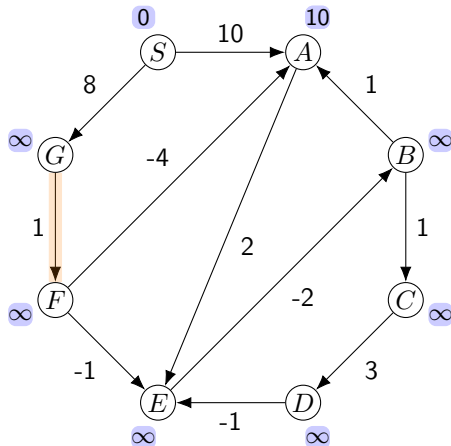


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

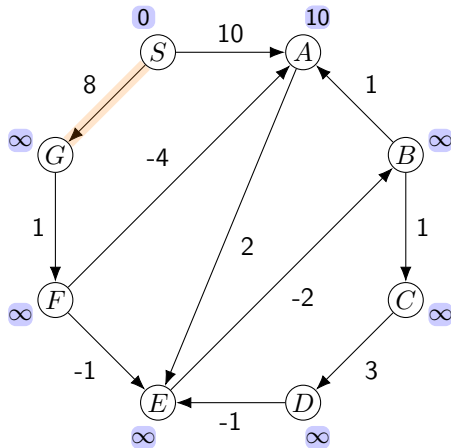


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

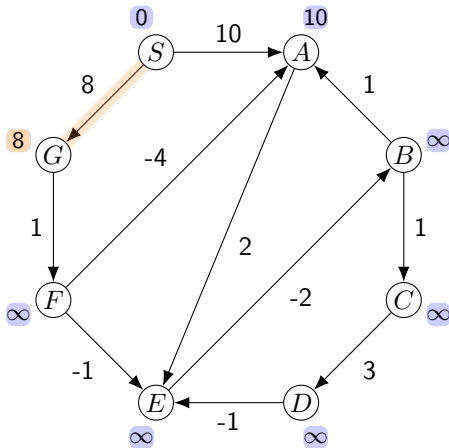


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

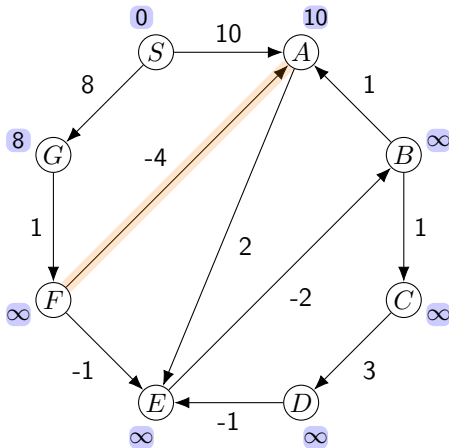


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

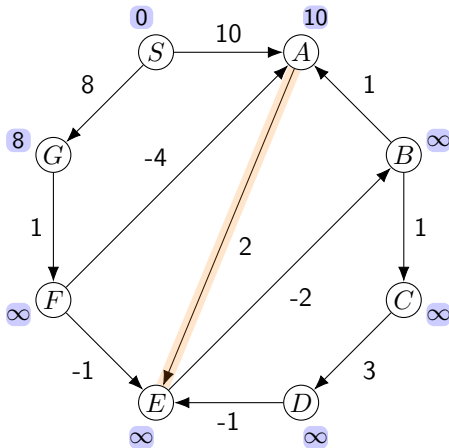


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

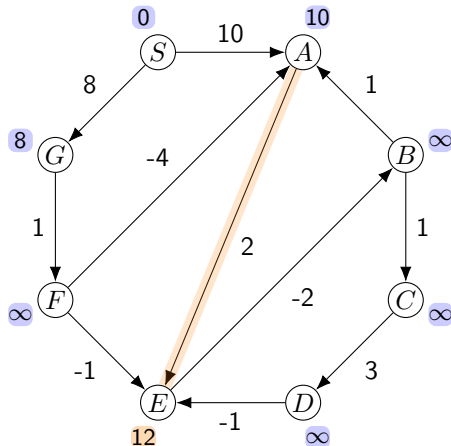


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

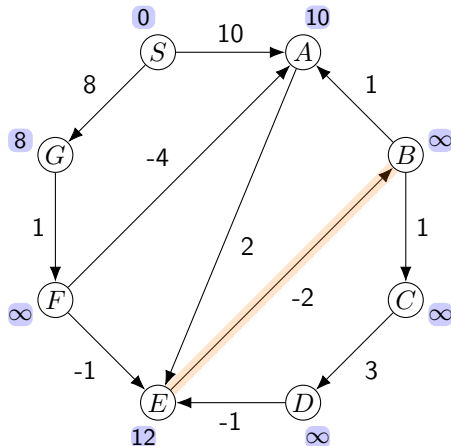


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

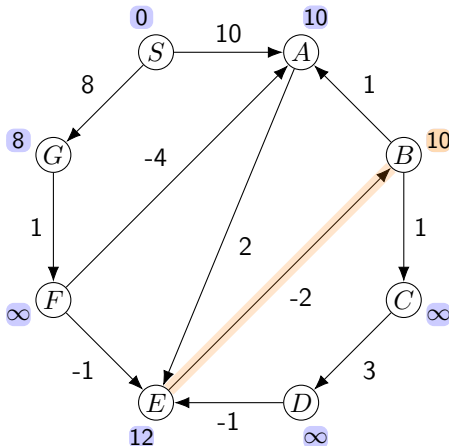


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 1

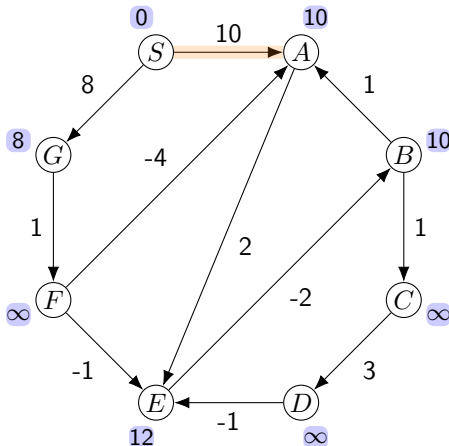


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

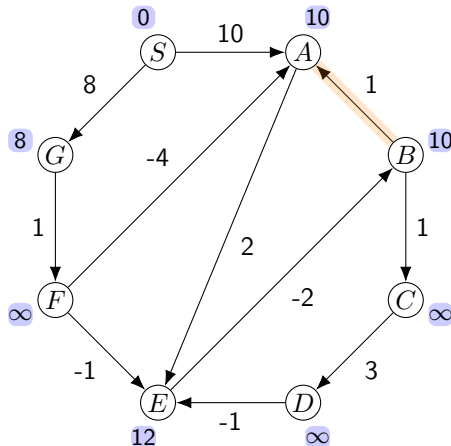


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

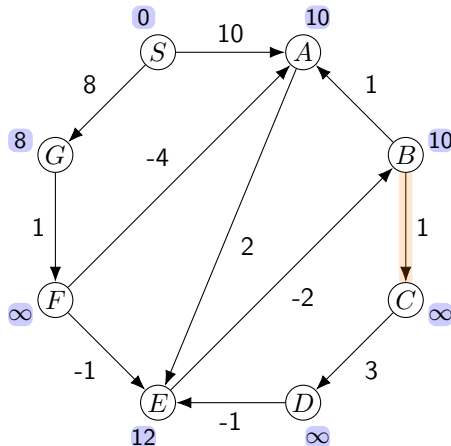


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

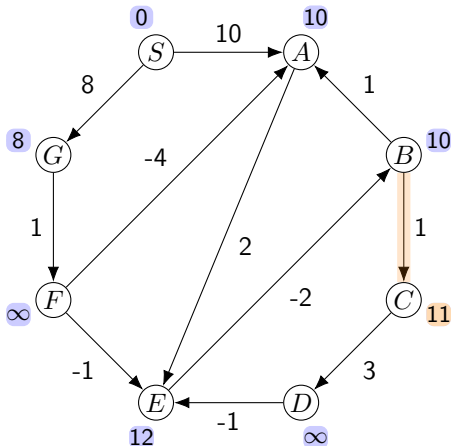


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

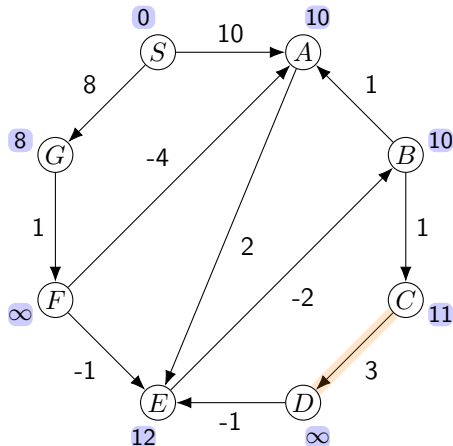


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

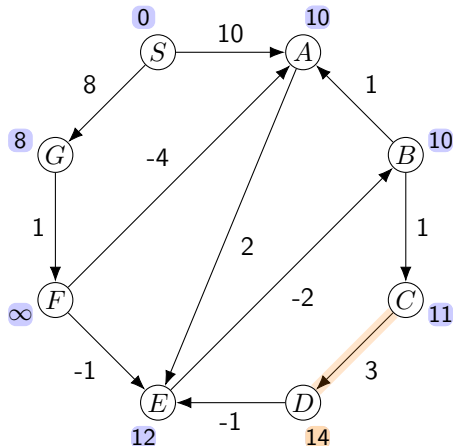


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

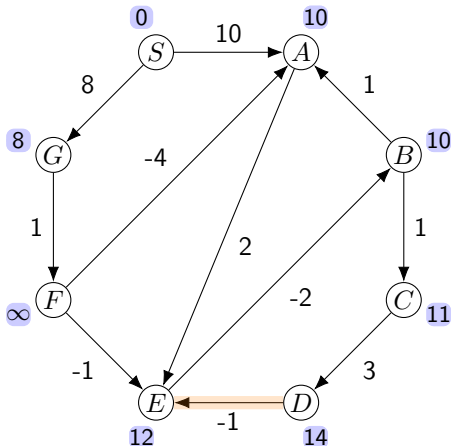


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

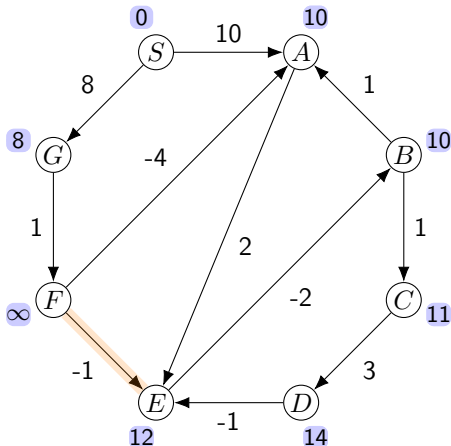


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

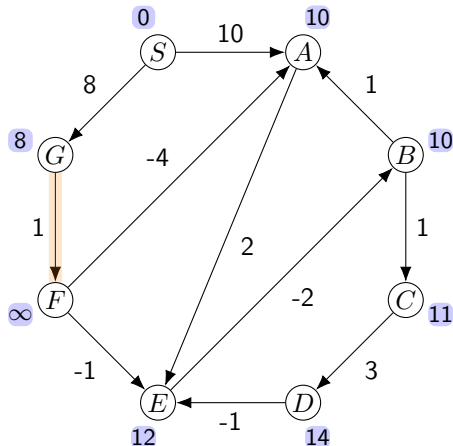


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

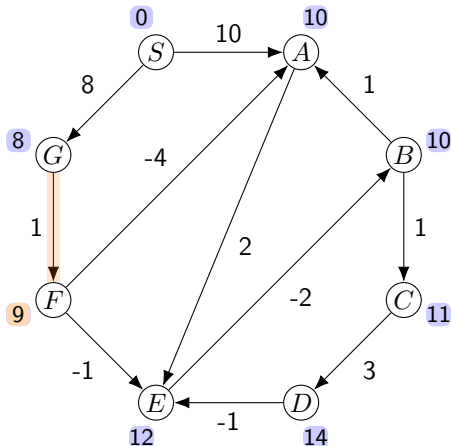


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

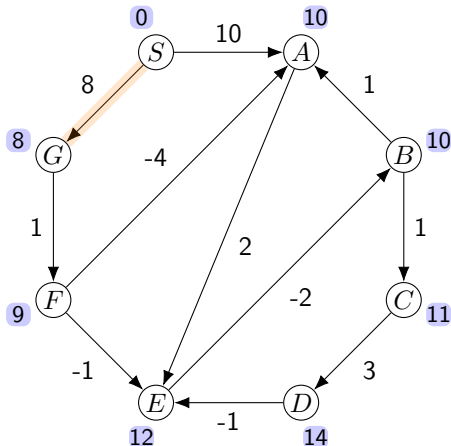


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

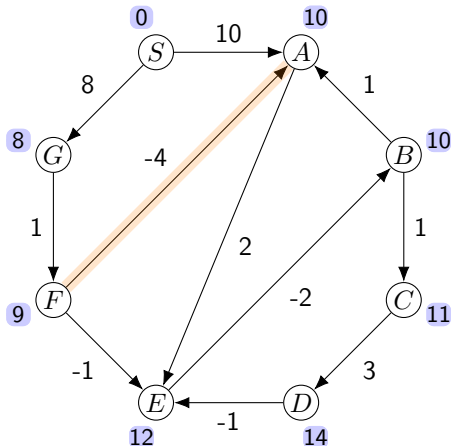


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

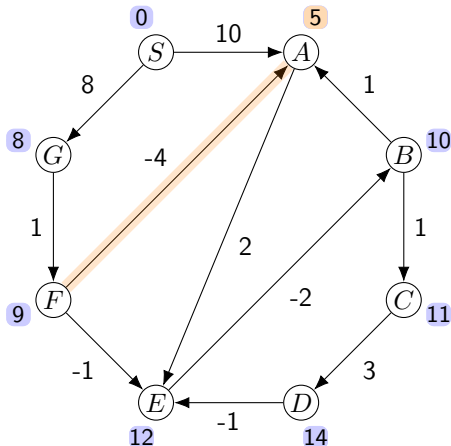


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

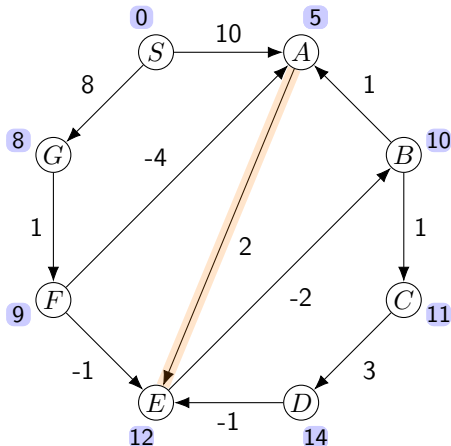


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

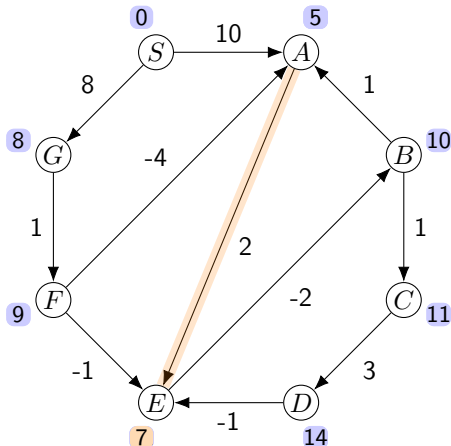


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

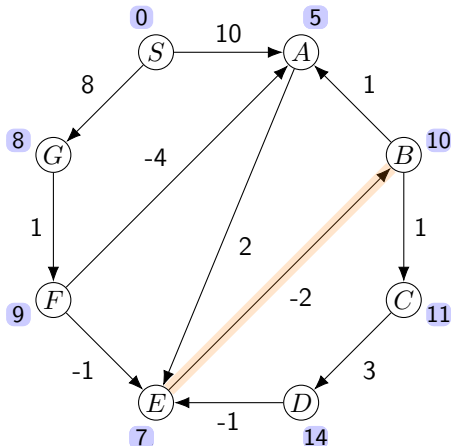


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

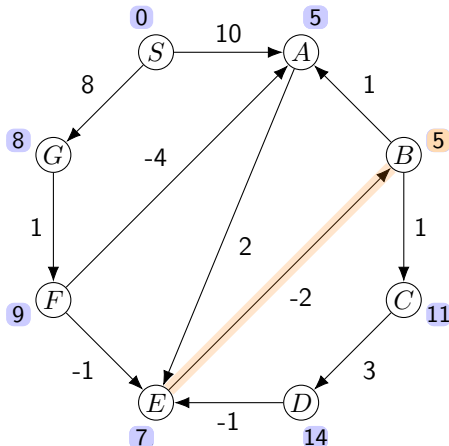


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 2

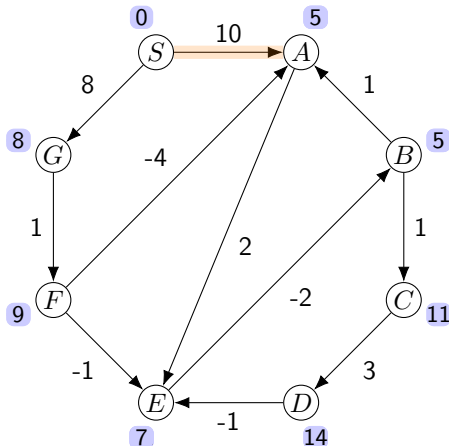


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

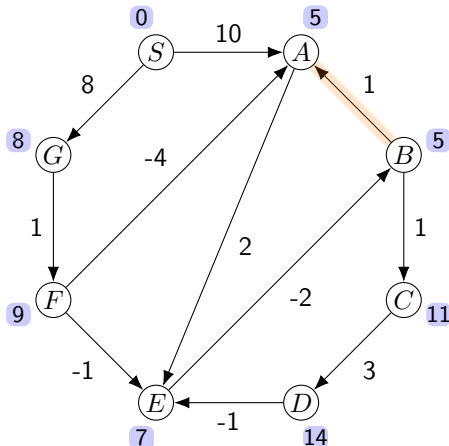


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

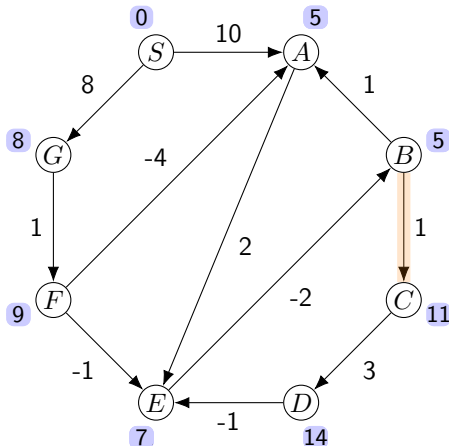


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

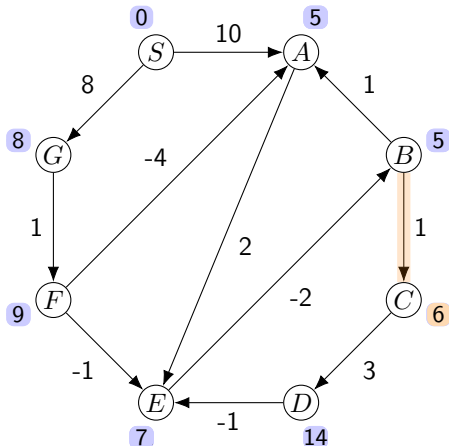


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

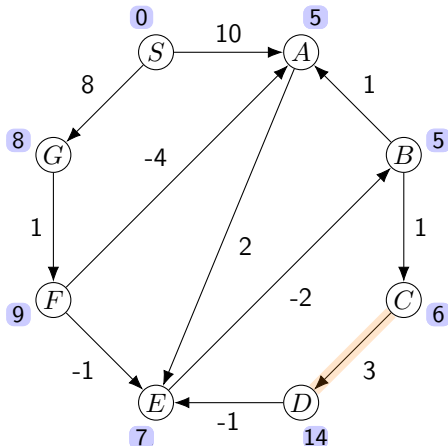


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

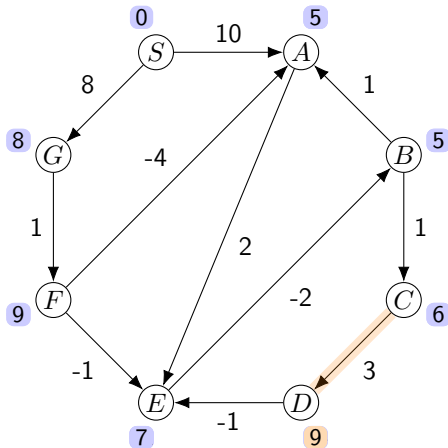


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

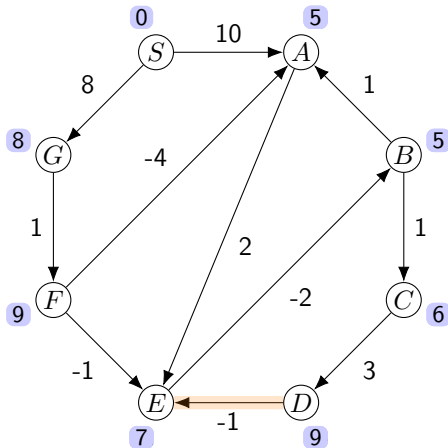


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

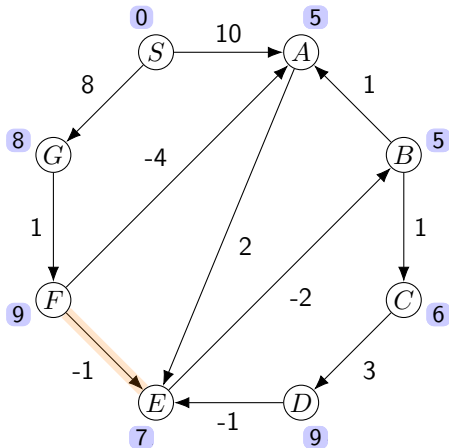


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

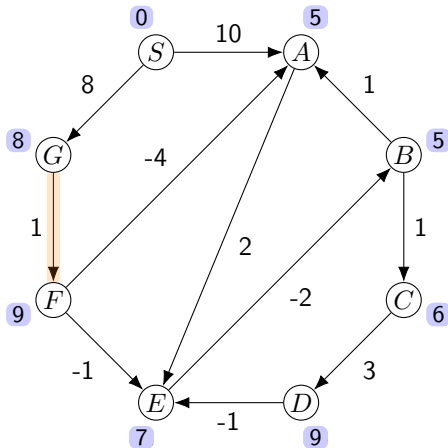


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

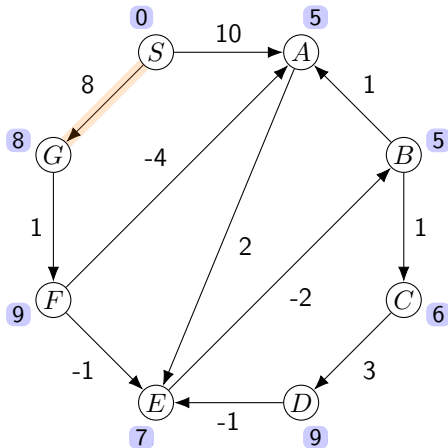


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

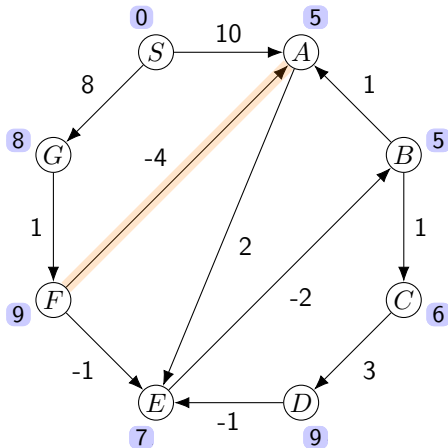


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

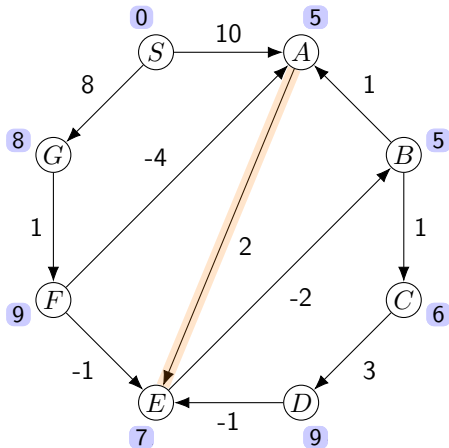


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

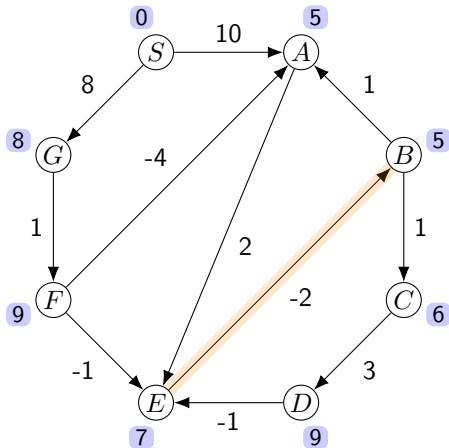


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 3

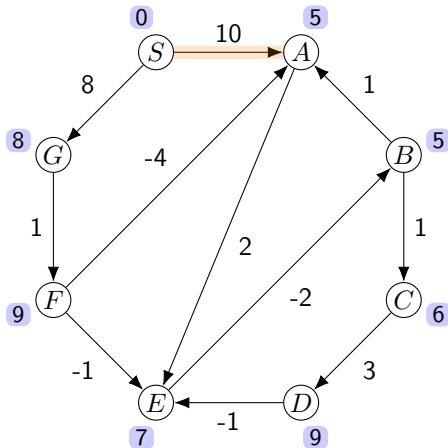


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

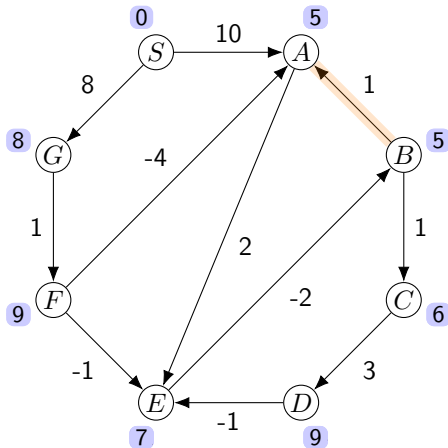


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

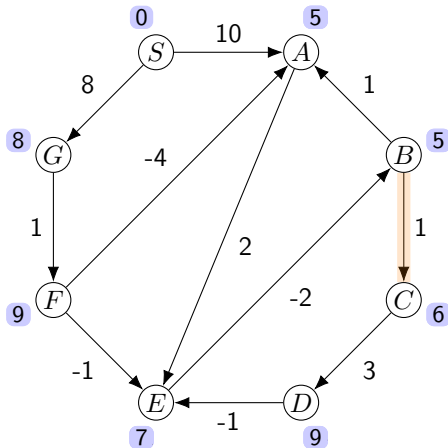


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

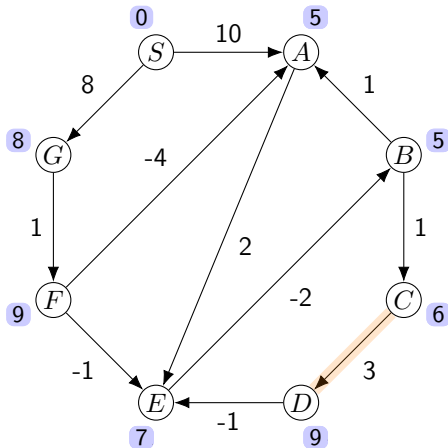


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

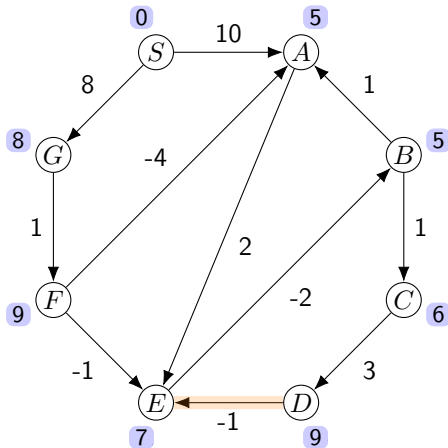


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

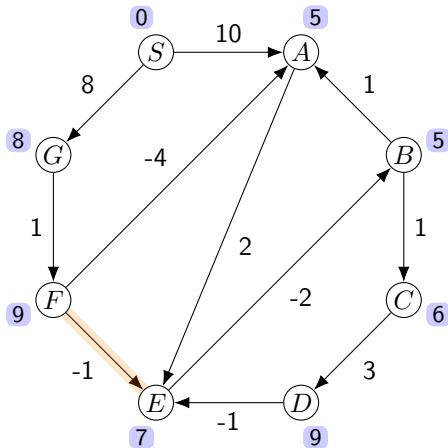


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

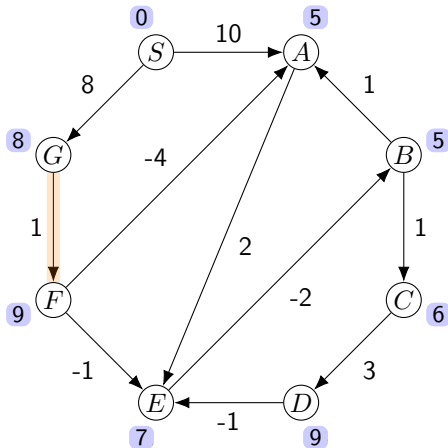


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

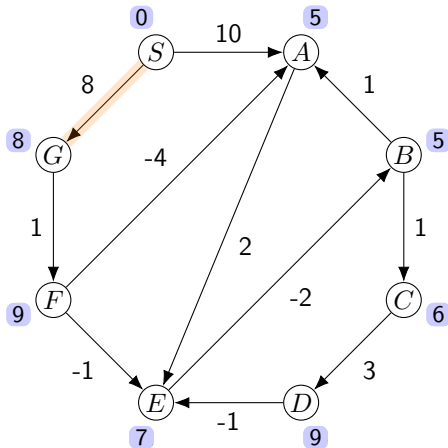


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

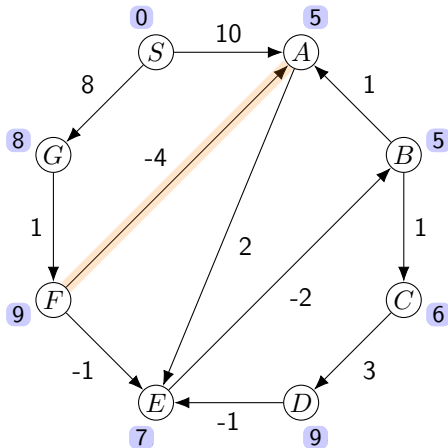


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

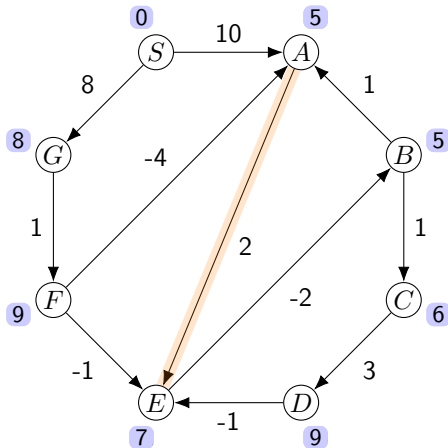


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

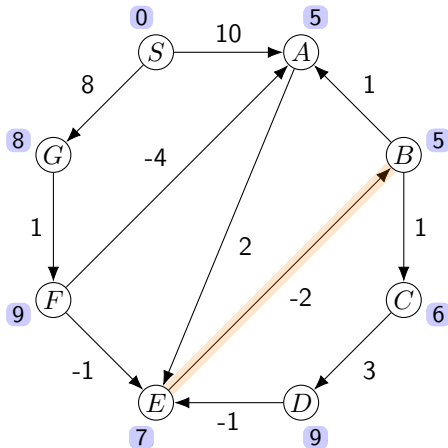


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4

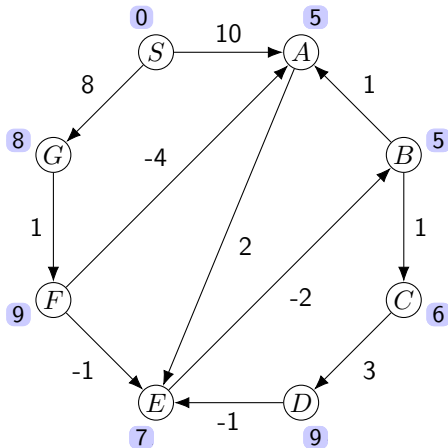


Bellman-Ford algorithm

Consider the following example:

Assume we Update edges in the order (S, A) , (B, A) , (B, C) , (C, D) , (D, E) , (F, E) , (G, F) , (S, G) , (F, A) , (A, E) , (E, B)

Round: 4



Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.
- ▶ Worst-case remains $O(|V| \cdot |E|)$.

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.
- ▶ Worst-case remains $O(|V| \cdot |E|)$.
- ▶ JT Fineman improved it to $\tilde{O}\left(|V|^{\frac{8}{9}}|E|\right)$ in STOC 2024.

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.
- ▶ Worst-case remains $O(|V| \cdot |E|)$.
- ▶ JT Fineman improved it to $\tilde{O}\left(|V|^{\frac{8}{9}}|E|\right)$ in STOC 2024.

What happens if we run $|V|$ iterations?

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.
- ▶ Worst-case remains $O(|V| \cdot |E|)$.
- ▶ JT Fineman improved it to $\tilde{O}\left(|V|^{\frac{8}{9}}|E|\right)$ in STOC 2024.

What happens if we run $|V|$ iterations?

- ▶ Shouldn't be any Update in the last round...

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.
- ▶ Worst-case remains $O(|V| \cdot |E|)$.
- ▶ JT Fineman improved it to $\tilde{O}\left(|V|^{\frac{8}{9}}|E|\right)$ in STOC 2024.

What happens if we run $|V|$ iterations?

- ▶ Shouldn't be any Update in the last round... unless there are negative cycles!

Bellman-Ford algorithm

Can we do better?

- ▶ Can stop earlier if no Update happened in the previous iteration.
- ▶ Can skip edges from a node whose *dist* was not Updated in the previous iteration.
- ▶ Worst-case remains $O(|V| \cdot |E|)$.
- ▶ JT Fineman improved it to $\tilde{O}\left(|V|^{\frac{8}{9}}|E|\right)$ in STOC 2024.

What happens if we run $|V|$ iterations?

- ▶ Shouldn't be any Update in the last round... unless there are negative cycles!
- ▶ This can be used to detect negative cycles in a graph.

All pairs shortest path

What if we need pairwise shortest paths, not just from s ?

All pairs shortest path

What if we need pairwise shortest paths, not just from s ?

- ▶ We can run Bellman-Ford starting from each vertex. The running time is

All pairs shortest path

What if we need pairwise shortest paths, not just from s ?

- ▶ We can run Bellman-Ford starting from each vertex. The running time is $O(|V|^2 \cdot |E|)$, which can be $O(|V|^4)$ if the graph is dense.

All pairs shortest path

What if we need pairwise shortest paths, not just from s ?

- ▶ We can run Bellman-Ford starting from each vertex. The running time is $O(|V|^2 \cdot |E|)$, which can be $O(|V|^4)$ if the graph is dense.

Can we do better?

All pairs shortest path

- ▶ To store pairwise shortest distances, we need to upgrade our $dist[\cdot]$ array to a $dist[\cdot, \cdot]$ matrix.

All pairs shortest path

- ▶ To store pairwise shortest distances, we need to upgrade our $dist[\cdot]$ array to a $dist[\cdot, \cdot]$ matrix.
- ▶ Initially, $dist[a, b] = \begin{cases} \ell(a, b) & \text{if } (a, b) \in E \text{ is an edge} \\ \infty & \text{otherwise} \end{cases}$.

All pairs shortest path

- ▶ To store pairwise shortest distances, we need to upgrade our $dist[\cdot]$ array to a $dist[\cdot, \cdot]$ matrix.
- ▶ Initially, $dist[a, b] = \begin{cases} \ell(a, b) & \text{if } (a, b) \in E \text{ is an edge} \\ \infty & \text{otherwise} \end{cases}$.
- ▶ For simplicity, assume vertices are labeled by $\{1, 2, \dots, n\}$.

All pairs shortest path

- ▶ To store pairwise shortest distances, we need to upgrade our $dist[\cdot]$ array to a $dist[\cdot, \cdot]$ matrix.
- ▶ Initially, $dist[a, b] = \begin{cases} \ell(a, b) & \text{if } (a, b) \in E \text{ is an edge} \\ \infty & \text{otherwise} \end{cases}$.
- ▶ For simplicity, assume vertices are labeled by $\{1, 2, \dots, n\}$.
- ▶ Repeating Bellman-Ford fills $dist$ row by row, first compute all correct values for $dist[1, \cdot]$, then for $dist[2, \cdot]$, ..., each row takes $O(|V| \cdot |E|)$ time.

All pairs shortest path

- ▶ To store pairwise shortest distances, we need to upgrade our $dist[\cdot]$ array to a $dist[\cdot, \cdot]$ matrix.
- ▶ Initially, $dist[a, b] = \begin{cases} \ell(a, b) & \text{if } (a, b) \in E \text{ is an edge} \\ \infty & \text{otherwise} \end{cases}$.
- ▶ For simplicity, assume vertices are labeled by $\{1, 2, \dots, n\}$.
- ▶ Repeating Bellman-Ford fills $dist$ row by row, first compute all correct values for $dist[1, \cdot]$, then for $dist[2, \cdot]$, ..., each row takes $O(|V| \cdot |E|)$ time.
- ▶ Can we use information from other rows to speed things up?