

# CMPSC 465: LECTURE XVI

## Revisit Dijkstra's Algorithm

Ke Chen

October 06, 2025

# Dijkstra is weighted BFS

	BFS	Dijkstra
What		
Why		
How		

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How	Use queue (FIFO, earlier in queue, fewer links needed)	Use priority queue

# Dijkstra with priority queue

Dijkstra( $G = (V, E, \ell), s$ )

*// dist stores distances from s*

*// prev can be used to reconstruct paths*

**foreach**  $v \in V$  **do**  $dist[v] = \infty, prev[v] = \text{null}$

$dist[s] = 0$ , Insert( $Q, \{dist[s], s\}$ ) *// Q is a priority queue*

**while**  $Q$  is not empty **do**

$v = \text{GetMin}(Q)$ , Delete( $Q, v$ )

**foreach**  $(v, w) \in E$  **do**

**if**  $dist[w] > dist[v] + \ell(v, w)$  **then**

$dist[w] = dist[v] + \ell(v, w)$

$prev[w] = v$

*// pos[w] returns the index of w in Q*

**if**  $w$  in  $Q$  **then** DecreaseKey( $Q, pos[w], dist[w]$ )

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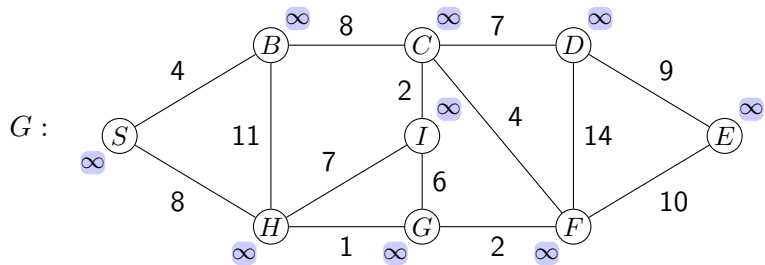
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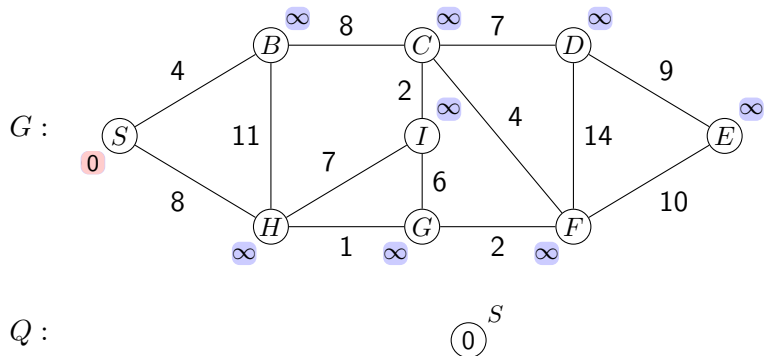
Time complexity? Calls at most  $|V|$  Insert/Delete, and at most  $|E|$  DecreaseKey, with a binary min-heap,  $O((|V| + |E|) \log |V|)$ .

## One more example

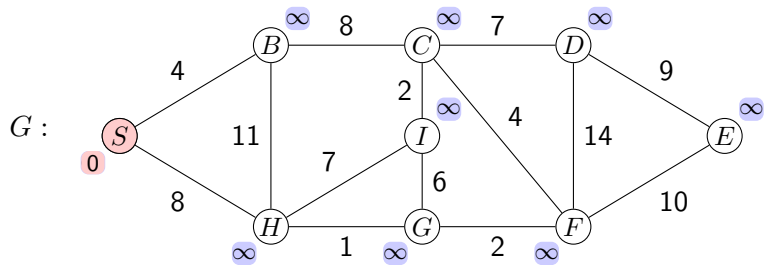


$Q :$  [empty]

## One more example

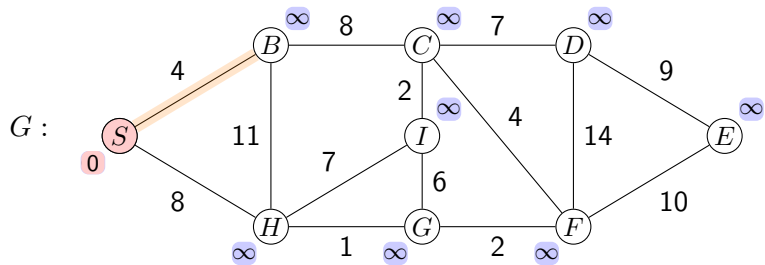


## One more example



$Q$  :

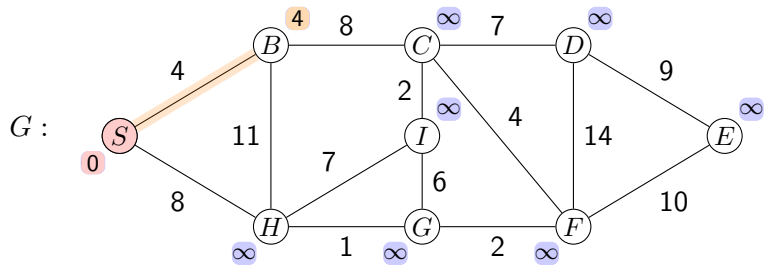
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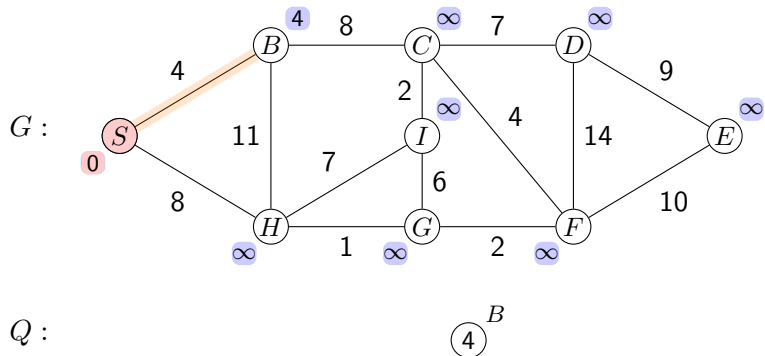


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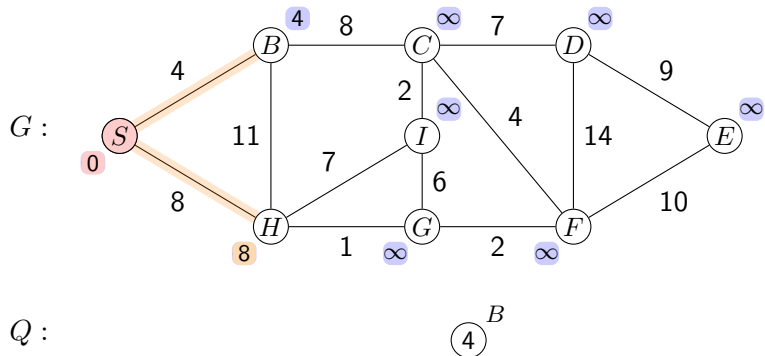


$Q$  :

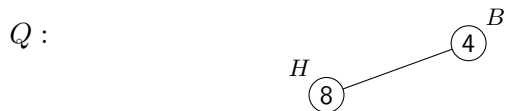
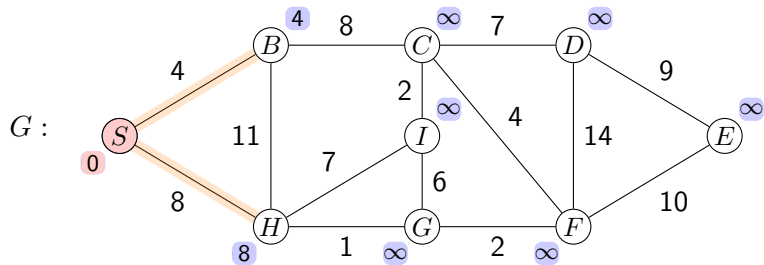
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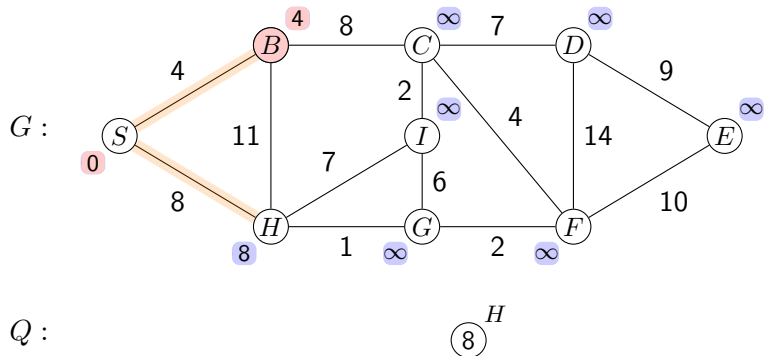
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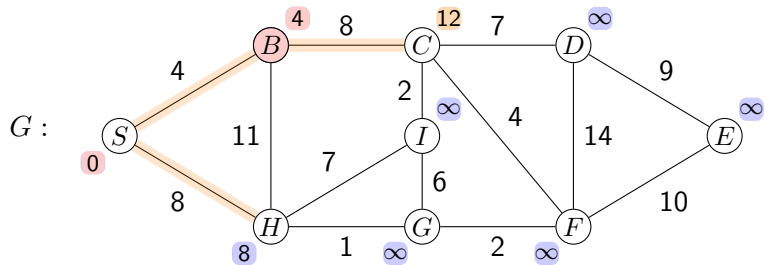
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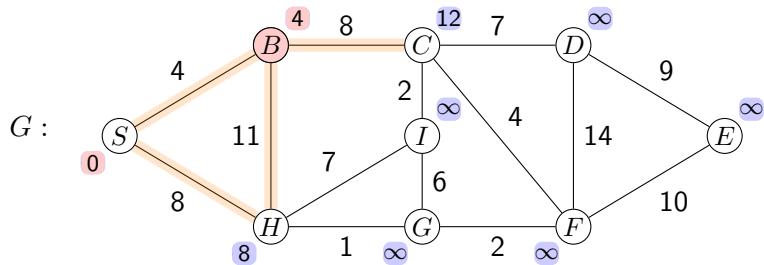
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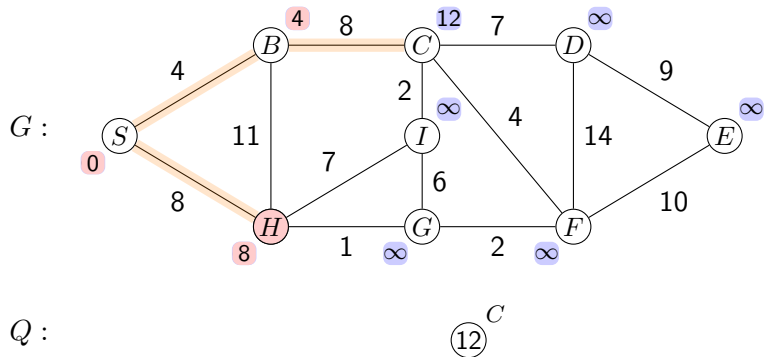
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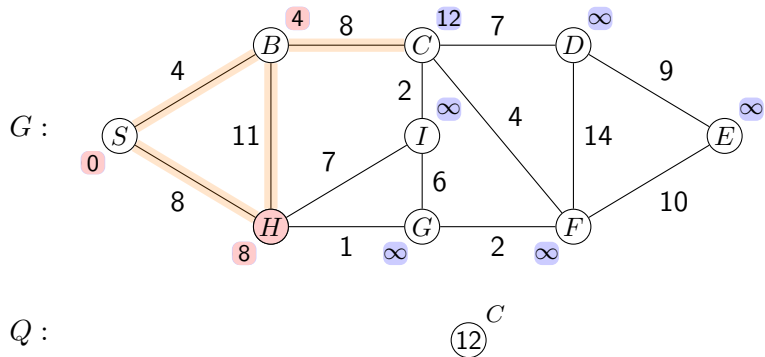


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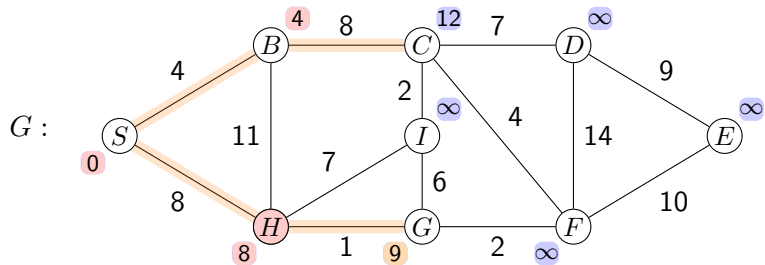




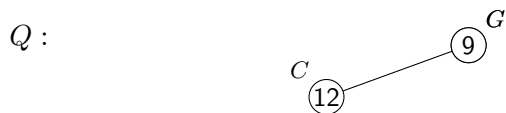
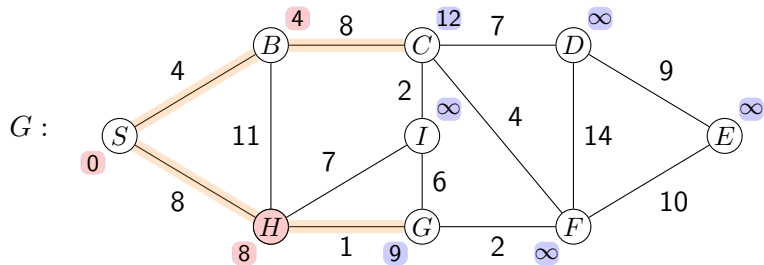
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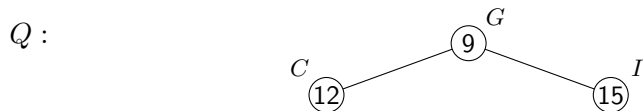
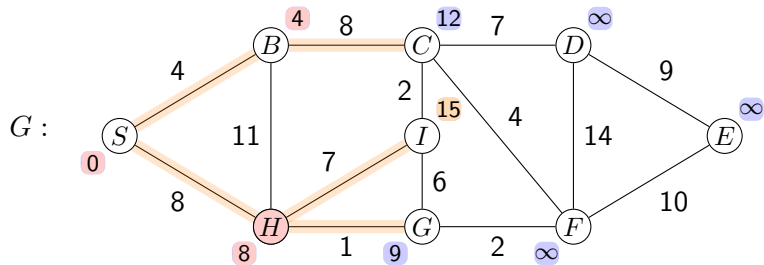
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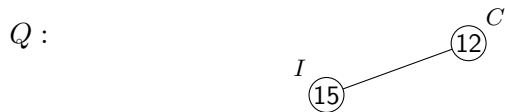
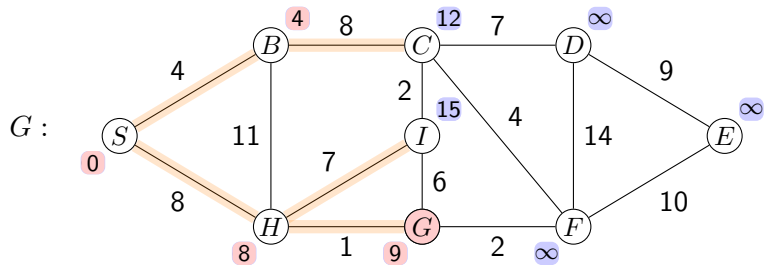
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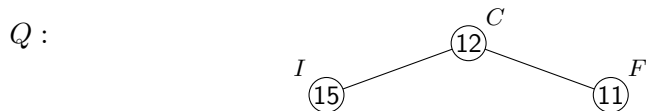
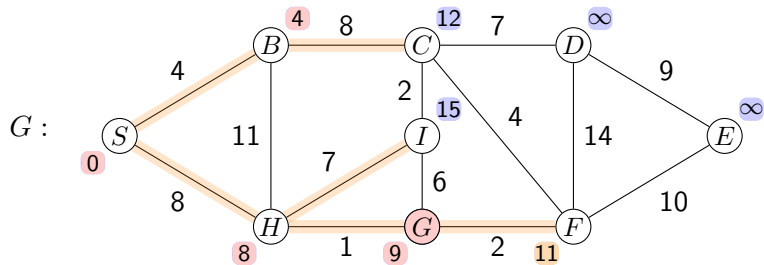
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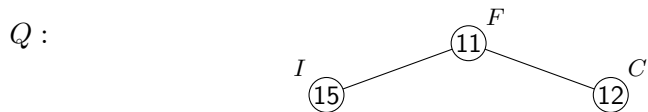
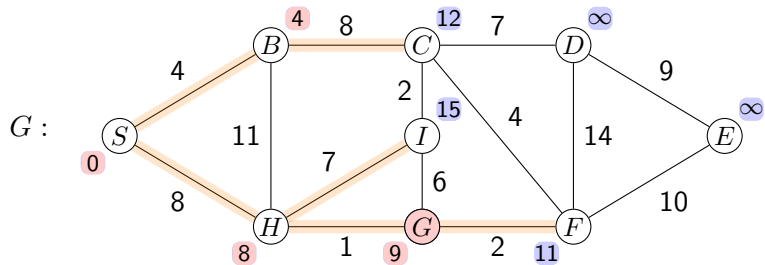
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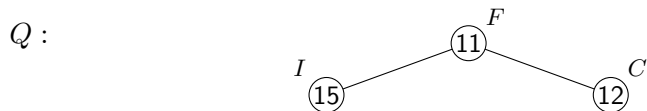
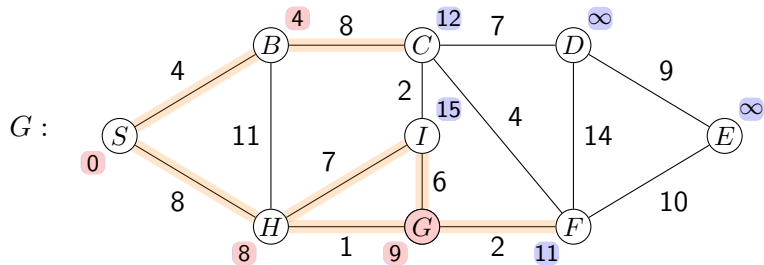
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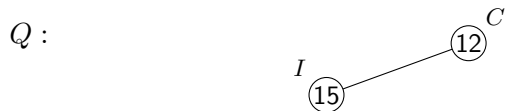
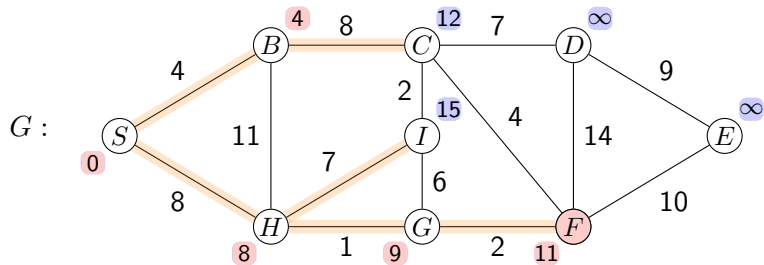


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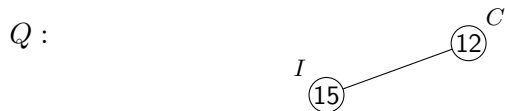
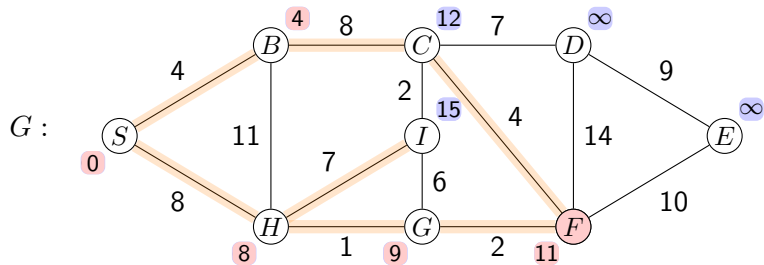




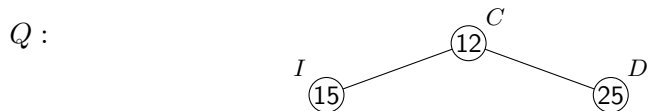
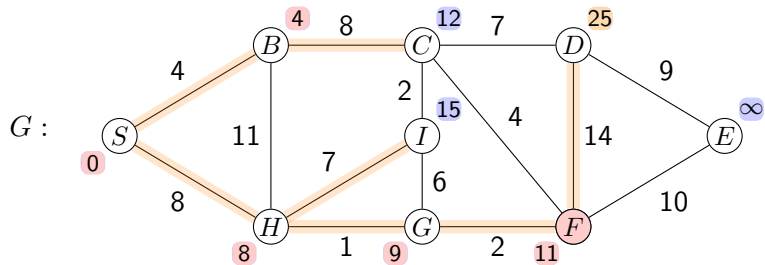
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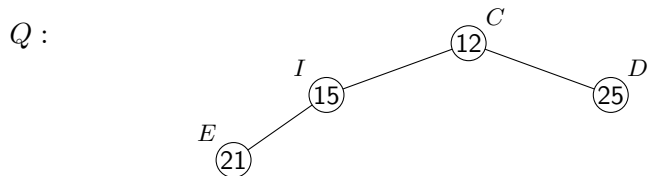
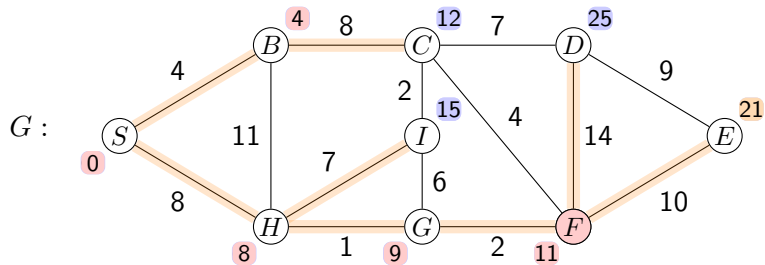
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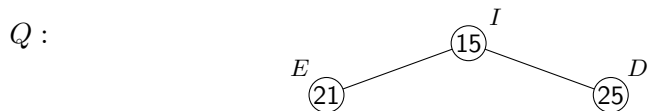
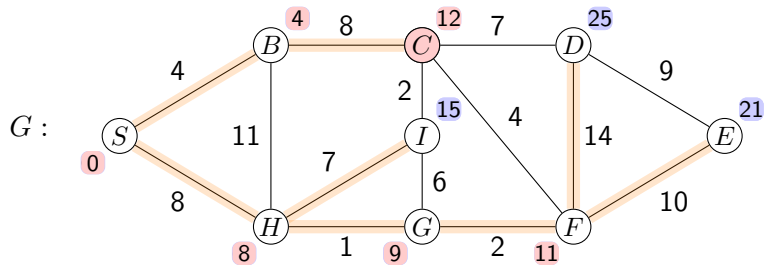
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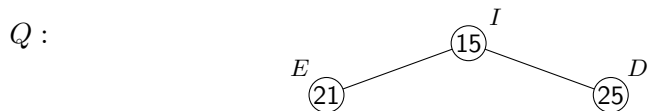
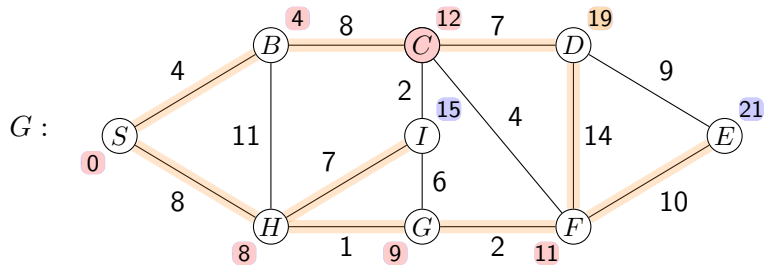
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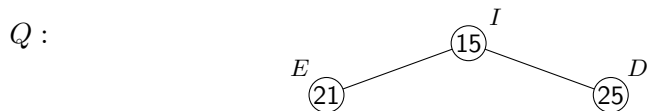
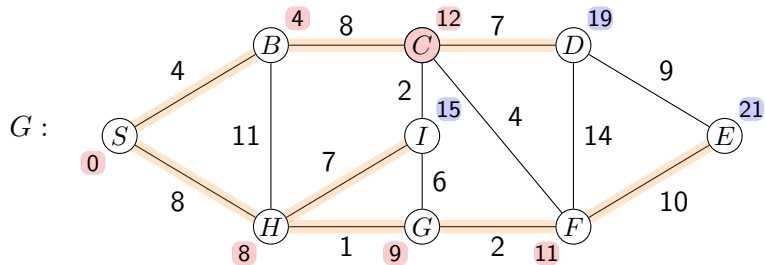
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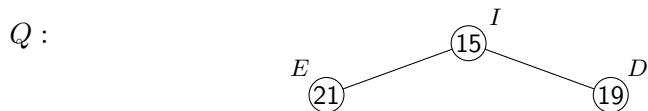
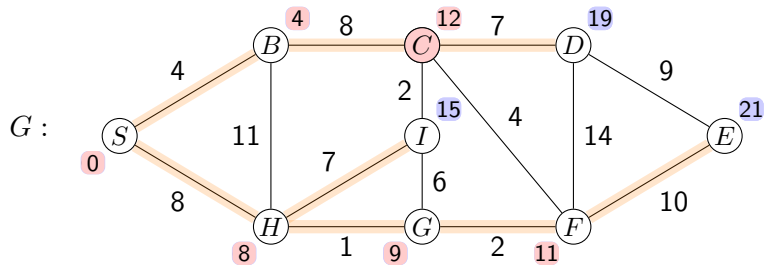
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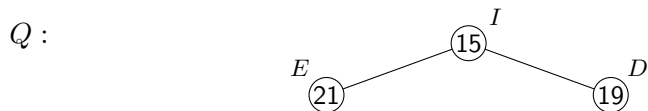
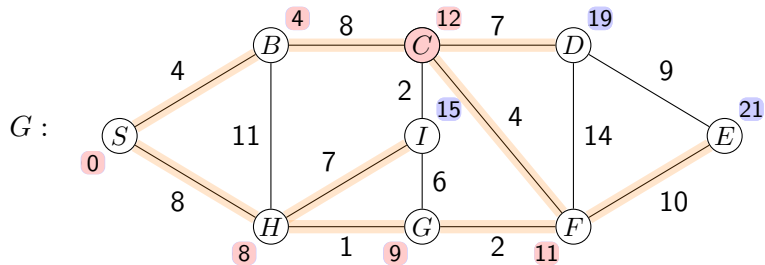


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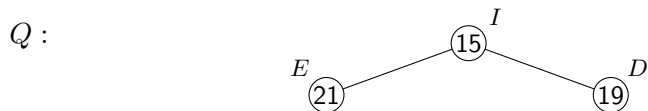
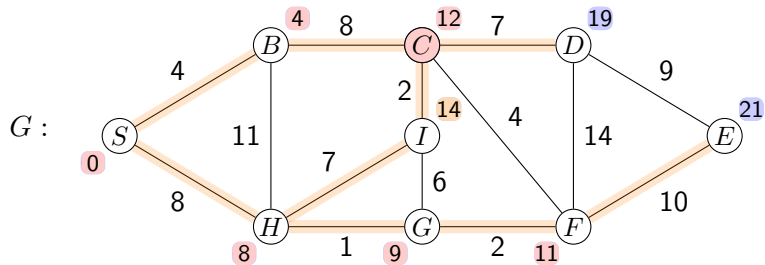




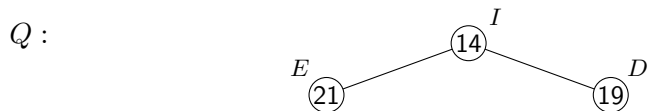
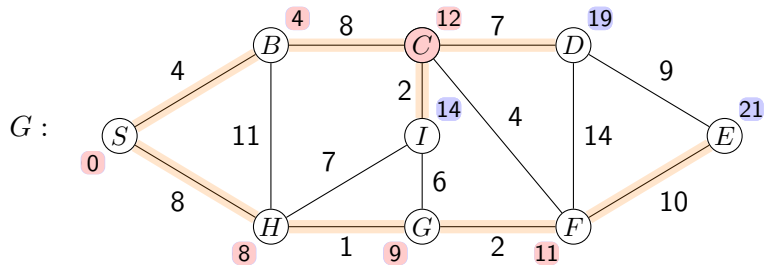
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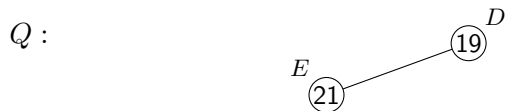
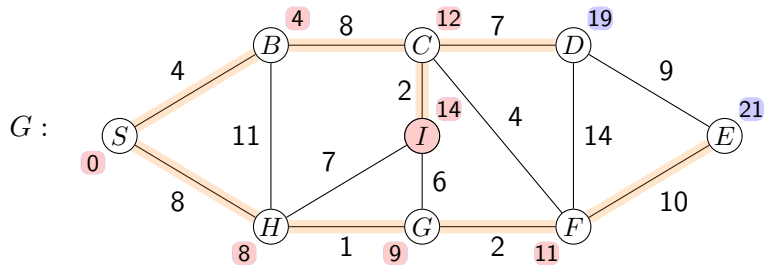
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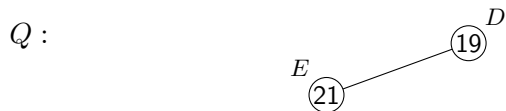
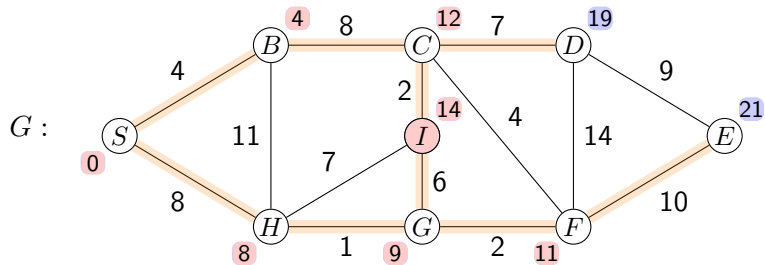
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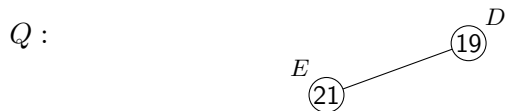
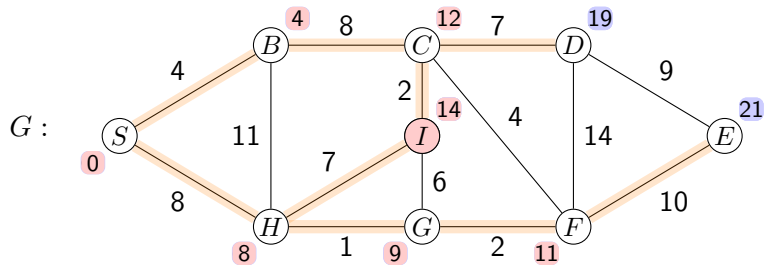
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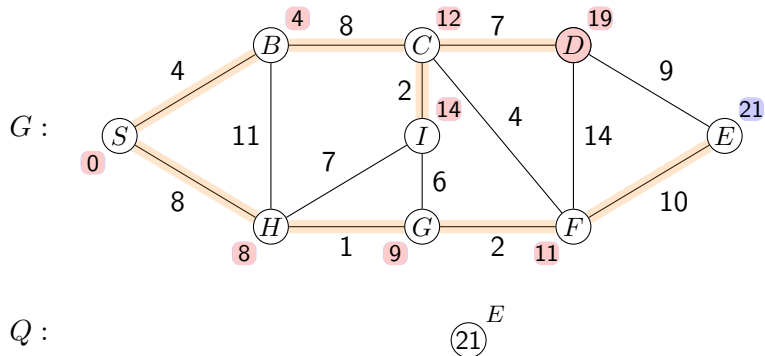
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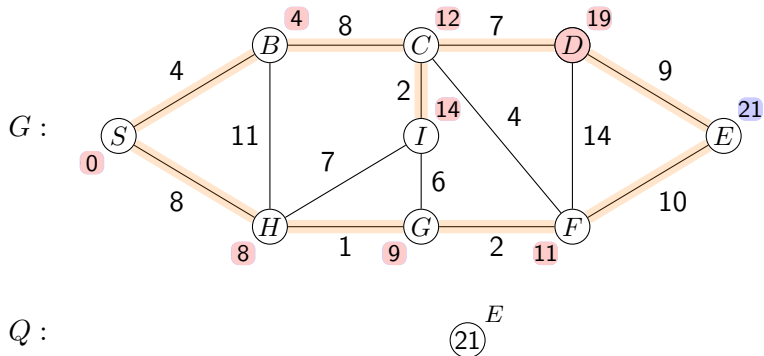
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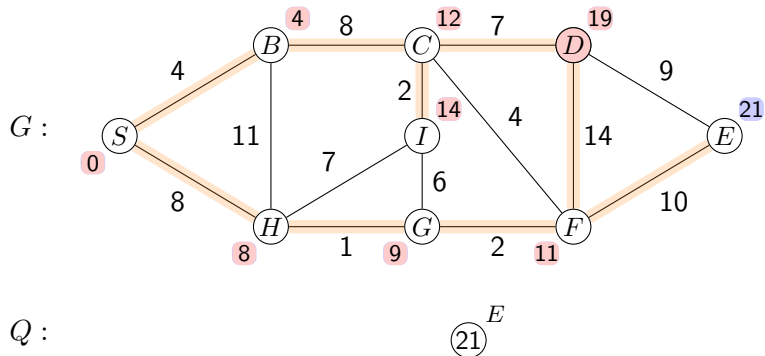


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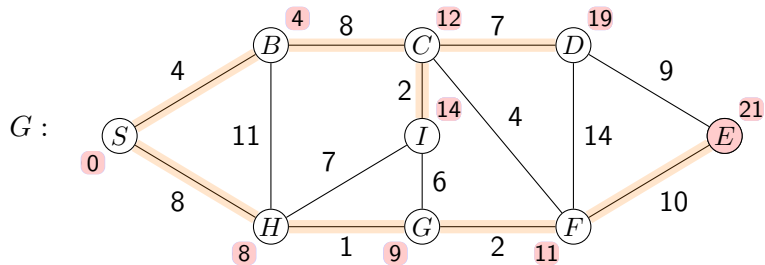




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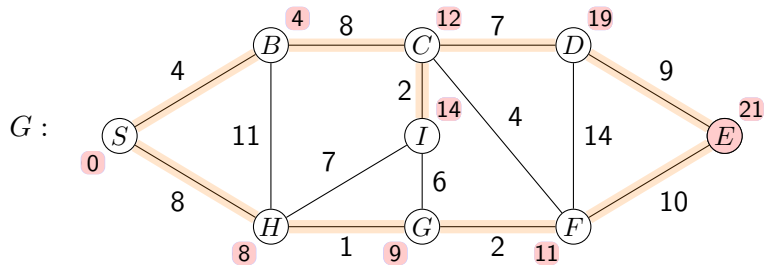


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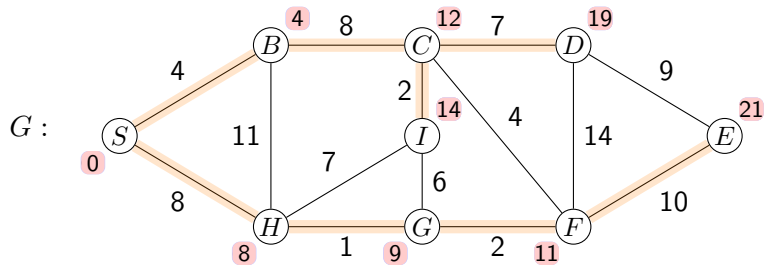
$Q$  : [empty]

## One more example



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# Dijkstra with priority queue

## Time complexity?

- ▶ Calls at most  $|V|$  Insert and Delete, and at most  $|E|$  DecreaseKey, with a binary min-heap,  $O((|V| + |E|) \log |V|)$ .

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- ▶ A breakthrough this year by Duan et al. won the best paper award at STOC 2025.

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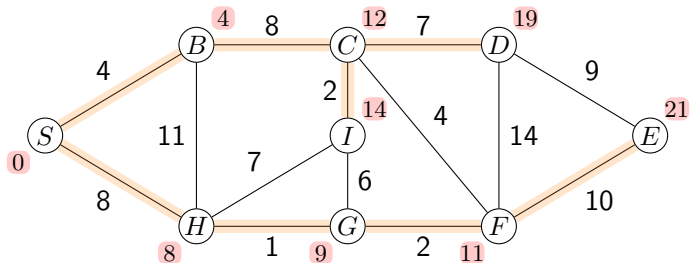
Update( $(v, w) \in E$ )

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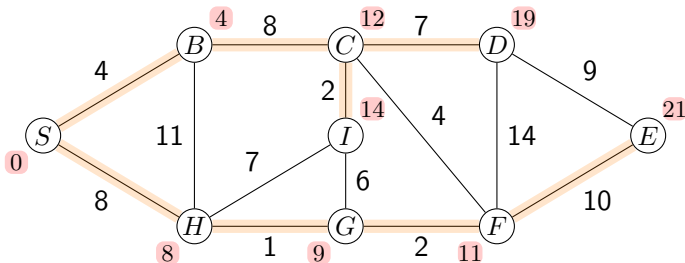
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- ▶ The bounds are tight for all vertices in  $R$  and the smallest one not in  $R$ .
- ▶ The only way an entry in  $dist[\cdot]$  is reduced is by the Update operation:  
$$\frac{\text{Update}((v, w) \in E)}{\left[ \begin{array}{l} \text{if } dist[w] > dist[w] + \ell(v, w) \text{ then} \\ \quad \lfloor \quad dist[w] = dist[w] + \ell(v, w) \end{array} \right]}$$
- ▶ Dijkstra's algorithm can be viewed as a clever sequence of Update operations.

## A third interpretation of Dijkstra



$(S, B)$   $(S, H)$   $(B, C)$   $(H, G)$   $(G, F)$   $(F, E)$   $(C, D)$   $(C, I)$

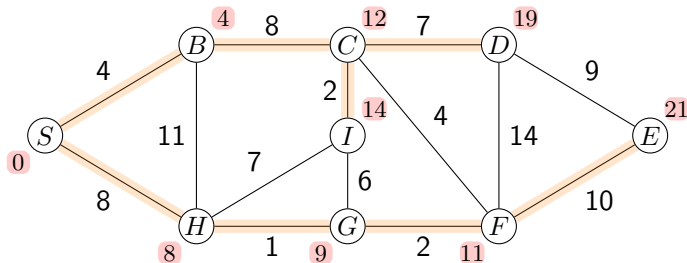
## A third interpretation of Dijkstra



$(S, B)$   $(S, H)$   $(B, C)$   $(H, G)$   $(G, F)$   $(F, E)$   $(C, D)$   $(C, I)$

- The computation is correct for a node as long as the sequence includes all edges on its shortest path in order.

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$(S, B)$   $(S, H)$   $(B, C)$   $(H, G)$   $(G, F)$   $(F, E)$   $(C, D)$   $(C, I)$

- ▶ The computation is correct for a node as long as the sequence includes all edges on its shortest path **in order**.
- ▶ Note that having additional Update calls doesn't hurt – Update is **safe**.