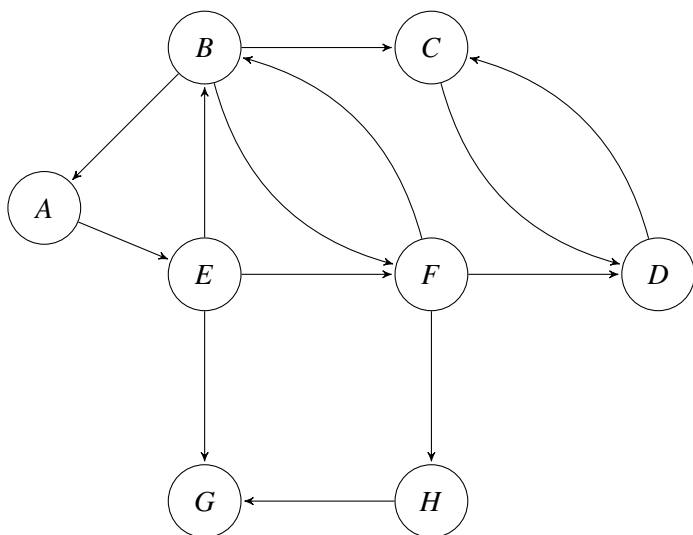


Monday, Oct 06, 2025

1. **SCC.** Run the strongly connected components algorithm on the following directed graph G . When doing DFS on G^R : whenever there is a choice of vertices to explore, always pick the one that is alphabetically first.



- (a) Give the pre and post number of each vertex in the reverse graph G^R .
 - (b) In what order are the connected components found?
 - (c) Which are source connected components and which are sink connected components?
 - (d) Draw the “metagraph” (each meta-node is a connected component of G).
2. **Edges for SCC.** Let $G = (V, E)$ be a finite directed graph. Determine the minimum number of edges that must be added to G so that the resulting graph becomes strongly connected.
 3. **Multi Source Shortest Path** Let $G = (V, E)$ be an unweighted graph (directed or undirected) and let $S \subseteq V$ be a set of source vertices. For every vertex $v \in V$ compute

$$d(v) = \min_{s \in S} \text{dist}_G(s, v),$$

the minimum number of edges from v to the closest source.

4. **Dijkstra with Edge Budget** Let $G = (V, E)$ be a directed graph with nonnegative edge weights, a source vertex $s \in V$, and an integer $k \leq |V| - 1$. The task is to compute the shortest path distance from s to every vertex $v \in V$ such that no path uses more than k edges. Design an algorithm. Prove that it is correct and analyse the runtime complexity.

- 5. Dijkstra with Maximum Edge Weight** Let $G = (V, E)$ be a directed graph with nonnegative edge weights. Given a source vertex $s \in V$ and a threshold $W_{\max} \geq 0$, a path is called *feasible* if all its edges have weights at most W_{\max} . Modify Dijkstra's algorithm to compute the shortest distances from s to all vertices along *feasible* paths only. Explain why your modification is correct and analyze its time complexity.
- 6. Dijkstra with a Pinned Node** You are given a strongly connected directed graph $G = (V, E)$ with positive edge weights along with a particular node $v_0 \in V$. Give an efficient algorithm for finding the shortest path between *all pairs of nodes*, with the one restriction that these paths must all pass through v_0 . Make your algorithm as efficient as you can, perhaps as fast as Dijkstra's algorithm. Explain why your algorithm is correct and justify its running time.