

# Project Log: Removing the "Green Goo"

Goo Removal

Gradient Descendants

December 4, 2025

## Overview

The dataset contains synthetic green artifacts ("goo") overlaying the tissue samples. These must be removed to prevent the neural network from learning them.

## Phase 1: The Naive Approach

### Attempt 1: Simple Thresholding

*Hypothesis:* Since the artifacts are green and the tissue is pink/purple, a simple HSV color check should work.

We defined a standard green range in HSV space:

- Lower: [35, 100, 50]
- Upper: [85, 255, 255]

**The Result (Failure):** While it caught the center of the goo, it failed at the edges. The synthetic goo has **anti-aliasing** (semi-transparent edges). The simple threshold missed these faint pixels, leaving a distinct "green halo" or ring around the removal area. This would result in dirty labels.

## Phase 2: The Brute Force Fix

### Attempt 2: Aggressive Dilation

*Hypothesis:* If the mask is slightly too small (missing the halo), let's just force it to be bigger using Morphological Dilation.

We applied 'cv2.dilate' with 'iterations=5'.

```
1 # The Brute Force Logic
2 kernel = np.ones((3, 3), np.uint8)
3 # Expand blindly in all directions
4 dilated_mask = cv2.dilate(goo_mask, kernel, iterations=5)
```

**The Result (Failure):** This solved the halo problem but introduced a worse one: **Data Destruction**. Because dilation expands blindly in every direction, it expanded the mask *into* the valid tissue. On images where the goo was touching tissue cells, we ended up deleting actual biological data.

## Phase 3: The Final Solution

### Final Solution: Core & Shell Logic

*Epiphany:* We need a way to detect the faint halo (like Attempt 2) but stop expanding exactly where the green tint ends (unlike Attempt 2).

We implemented a **"Smart Connection"** algorithm inspired by Hysteresis Thresholding.

### Step A: Define Two Masks

Instead of one threshold, we use two:

1. **The Core (Strict):** High Saturation ( $> 100$ ). Captures the solid center.
2. **The Shell (Loose):** Low Saturation ( $> 30$ ). Captures the halo, but also captures noise in the tissue.

### Step B: Connected Components

We cannot use the Shell mask directly because it is noisy.

**The Logic:** We only keep a blob from the "Shell" mask if it is physically touching a blob from the "Core" mask.

- Isolated faint green blob  $\rightarrow$  Tissue Noise (Discard).
- Faint green blob touching Core  $\rightarrow$  Halo (Keep).

### Step C: The 1-Pixel Expansion

Even with the smart logic, a sub-pixel fringe often remained. We added a single iteration of dilation at the very end. Since the mask is now "clean" (no noise), expanding it by 1 pixel is safe and ensures the anti-aliasing is fully covered.

## Conclusion

The **Core & Shell + Expansion** method successfully removes 100% of the artifact (including the halo) while preserving the integrity of significant amount of adjacent tissue structures.

# Appendix A: Mathematical Formulation of the "Core & Shell" Algorithm

Let  $I : \Omega \rightarrow \mathbb{R}^3$  be the input image defined on the discrete domain  $\Omega \subset \mathbb{Z}^2$ . We first transform the image from the RGB color space to the HSV color space, denoted as  $I_{hsv}(x) = (H(x), S(x), V(x))$  for any pixel  $x \in \Omega$ .

The artifact removal pipeline is modeled as a **Geodesic Reconstruction** (a morphological transformation that reconstructs objects from a "marker" image based on their connectivity within a "mask" image).

## 1. Hysteresis Thresholding

We define the artifact segmentation based on two distinct predicates, forming a subset relationship  $M_{core} \subset M_{shell}$ .

Let  $\mathcal{H}_{green} = [35, 85]$  be the range of Hue values corresponding to the green artifact. Let  $\tau_{high} = 100$  and  $\tau_{low} = 30$  be the saturation thresholds.

We define the **Core Marker** ( $M_{core}$ ) as the set of pixels satisfying the strict condition:

$$M_{core} = \{x \in \Omega \mid H(x) \in \mathcal{H}_{green} \wedge S(x) > \tau_{high}\} \quad (1)$$

*Plain English:* Select pixels that are definitely solid green.

*This identifies the undeniable center of the artifact, ignoring edges and noise.*

We define the **Shell Mask** ( $M_{shell}$ ) as the set of pixels satisfying the relaxed condition:

$$M_{shell} = \{x \in \Omega \mid H(x) \in \mathcal{H}_{green} \wedge S(x) > \tau_{low}\} \quad (2)$$

*Plain English:* Select pixels that are even faintly green.

*This captures the semi-transparent "halo" around the artifact, but also mistakenly captures yellowish spots in the tissue.*

## 2. Topological Filtering (Reconstruction)

The set  $M_{shell}$  contains both the valid artifact halo and disjoint background noise (false positives). To isolate the artifact, we apply a connectivity constraint using **Connected Components** (graph-based algorithm that identifies distinct, isolated "blobs" of pixels).

Let  $\mathcal{C}(S)$  denote the set of connected components of a binary set  $S$ . For any component  $C_i \in \mathcal{C}(M_{shell})$ , we retain it if and only if it intersects with the Core marker:

$$M_{rec} = \bigcup_{C_i \in \mathcal{C}(M_{shell})} \{C_i \mid C_i \cap M_{core} \neq \emptyset\} \quad (3)$$

*Plain English:* Look at every "faint green blob." If it is physically touching a "solid green blob," keep it. If it is floating alone in the tissue, delete it.

This operation effectively reconstructs the full shape of the artifact from the high-confidence markers, filtering out all  $C_j$  where  $C_j \cap M_{core} = \emptyset$ .

## 3. Boundary Regularization (The "Nudge")

Due to interpolation artifacts in the source image generation, a sub-pixel fringe often exists outside the color detection range of  $M_{shell}$ .

Let  $B$  be a flat, unitary structuring element of size  $3 \times 3$ . We define the final artifact mask  $M_{final}$  as the **Morphological Dilation** (an operation that expands the boundaries of foreground pixels) of the reconstructed set:

$$M_{final} = M_{rec} \oplus B = \{z \in \Omega \mid (B_z \cap M_{rec}) \neq \emptyset\} \quad (4)$$

*Plain English:* Expand the final cleaned mask outward by exactly 1 pixel in all directions. This covers the invisible, microscopic color fringe at the very edge to ensure the training data is perfectly clean.